# Estimating a Dynamic Oligopolistic Game with Serially Correlated Unobserved Production Costs 

SS223B-Empirical IO

## Motivation

- There have been substantial recent developments in the empirical literature on estimation of dynamic games.
- However, incorporating unobserved (to the researcher) state variables that are serially correlated and endogenous remains prohibitively difficult.
- In this paper the authors propose a likelihood based method relying on sequential importance sampling to estimate dynamic discrete games of complete information with serially correlated unobserved endogenous state variables.


## Motivation

- They apply the method to a dynamic oligopolistic model of entry for the generic pharmaceutical industry.
- This application is interesting because the firm specific production costs are serially correlated unobserved state variables that are endogenous to past entry decisions.
- It is worth to note that the proposed method is applicable to similar games that have a Markovian representation of the latent dynamics and an algorithm to solve the game.


## Motivation

- The paper also provides evidence on the dynamic spillover effects of experience in one product market on subsequent performance in the market for another product.
- In order to evaluate the effects of current experience on future market performance as measured by future costs and entry, they formulate and estimate a dynamic game theoretic model of oligopolistic competition.
- In a dynamic setting, current entry can have a potential spillover effect on future entry.


## Motivation

- In the case of a generic pharmaceutical firm there can be economies of scope that come from experience working with a particular ingredient, therapeutic class, or form of drug (e.g., oral liquid or liquid injectable).
- It allows for serially correlated firm specific costs that evolve endogenously based on past entry decisions.
- Furthermore, endogeneity of costs to past entry decisions induces heterogeneity among firms even if they are identical ex ante, which they need not be.
- They estimate the model parameters using Bayesian MCMC methods.


## THE MODEL

- Firms maximize profits over an infinite horizon $t=1, \ldots . \infty$ where each time the market is open counts as one time increment.
- A market opening is defined to be an entry opportunity that becomes available to generic manufacturers each time a branded product goes off patent.
- The actions available to firm $i$ when market $t$ opens are to enter or not, which is denoted as

$$
A_{i, t}= \begin{cases}1, & \text { If firm } i \text { enter } \\ 0, & \text { otherwise }\end{cases}
$$

## THE MODEL

- There are I firms in total so that the number of entrants in market t is given by

$$
\begin{equation*}
N_{t}=\sum_{i=1}^{\prime} A_{i, t} \tag{1}
\end{equation*}
$$

- The evolution of current costs, $C_{i t}$, is determined by past entry decisions and random shocks.
- They consider the convention of $c_{i t}=\log \left(C_{i t}\right)$.
- The equation governing the log cost of firm $i$ at market $t$ is

$$
\begin{equation*}
c_{i t}=\mu_{c}+\rho_{c}\left(c_{i, t-1}-\mu_{c}\right)-\kappa_{c} A_{i, t-1}+\sigma_{c} e_{i t} \tag{2}
\end{equation*}
$$

## THE MODEL

- The term $e_{i t}$ is a normally distributed shock with mean zero and unit variance, $\sigma_{c}$ is a scale parameter, $\kappa_{c}$ is the entry spillover or immediate impact on cost at market $t$ if there was entry in market $t-1$.
- $\mu_{c}$ is a location parameter that represents the overall average of the log cost over a long period of time.
- The autoregressive parameter $\rho_{c}$ represents the degree of persistence between the current cost and its long run stationary level


## THE MODEL

## Assumption

All firms are ex ante identical, with the effects of current decisions on future costs creating heterogeneity between firms.

- The log cost can be decomposed into a sum of two components, a known component (or observable to the researcher based on past actions), $c_{k, i, t}$ and a component unobservable to the researcher, $c_{u, i, t}$ as follows:


## THE MODEL

$$
\begin{align*}
c_{i, t} & =c_{u, i, t}+c_{k, i, t}  \tag{3}\\
c_{u, i, t} & =\mu_{c}+\rho_{c}\left(c_{u, i, t-1}-\mu_{c}\right)+\sigma_{c} e_{i t}  \tag{4}\\
c_{k, i, t} & =\rho_{c} c_{k, i, t-1}-\kappa_{c} A_{i, t-1} \tag{5}
\end{align*}
$$

- The total (lump sum) revenue to be divided among firms who enter a market at time $t$ is $R_{t}=\exp \left(r_{t}\right)$, which is realized from the following independent and identical distribution,

$$
\begin{equation*}
r_{t}=\mu_{r}+\sigma_{r} e_{I+1, t} \tag{6}
\end{equation*}
$$

where $e_{I+1, t}$ is normally distributed with mean zero and unit variance.

## THE MODEL

- In order to solve the model the authors consider dominant firms (3 or 4)
- Under this simplification, they suggest that a reasonable functional form for dominant firm is per period profit at time $t$ is

$$
\begin{equation*}
\Pi_{i t}=A_{i, t} \times\left\{\frac{R_{t}^{\gamma}}{N_{t}}-C_{i t}\right\} \tag{7}
\end{equation*}
$$

where $\gamma \in(0.908,1)$.

- The firms total discounted profit at time $t$ is

$$
\begin{equation*}
\sum_{j=0}^{\infty} \beta^{j} \Pi_{i t+j}, \quad 0<\beta<1 \tag{8}
\end{equation*}
$$

## Solving The Model

- The Bellman equation for the choice specific value function for firm $i$ 's dynamic problem at time $t$ is given by

$$
\begin{equation*}
V_{i}\left(A_{i, t}, A_{-i, t}, C_{i, t}, C_{-i, t}, R_{t}\right)=\Pi_{i, t}+\mathbb{E}_{\mid \Omega_{t}}\left(V_{i}\left(A_{i, t}, A_{-i, t}, C_{i, t}, C_{-i, t}, R_{t}\right)\right) \tag{9}
\end{equation*}
$$

where $\Omega_{t}=\left(A_{i, t}, A_{-i, t}, C_{i, t}, C_{-i, t}, R_{t}\right)$

- The solution concept is given by "Pure Strategy Perfect Markov Equilibrium".
- The numerical scheme is as follows:


## Estimation: general scheme

- "Nested" Bayesian (MCMC) estimation: equilibrium computation nested within successive iteration of MCMC iteration
- Successive draws of parameters $\theta$ drawn according to Metropolis-Hastings approach
- Difficulty is evaluating likelihood function at given $\theta$ : use a particle-filtering importance sampling approach.


## Details of particle filter

- Observables: $Y_{t}=\left(\vec{r}_{t}, \vec{A}_{t}\right)$. Choice variable $A_{t}$, obsd state variable $r_{t}$
- Unobservables: $\epsilon_{t}=\left(\vec{C}_{u t}\right)$ : unobserved component of costs
- Likelihood (simplified):

$$
\begin{aligned}
\mathcal{L}(\theta) & =\prod_{t=1}^{T} p\left(y_{t} \mid y^{t-1} ; \theta\right) \\
& =\prod \int p\left(y_{t} \mid y^{t-1}, \epsilon^{t} ; \theta\right) p\left(\epsilon^{t} \mid y^{t-1}\right) d \epsilon^{t} \\
& =\prod\left[p\left(A_{t} \mid r_{t}, y_{t-1}, \epsilon_{t} ; \theta\right) \cdot p\left(r_{t} \mid y_{t-1}, \epsilon_{t} ; \theta\right) p\left(\epsilon^{t} \mid y^{t-1}\right) d \epsilon^{t}\right] \\
& =\prod\left[\left(\prod_{i} \mathbb{1}\left\{A_{i t}=A_{i t}^{*}\left(\epsilon_{t}, y_{t-1}, r_{t}: \theta\right)\right\}\right) \cdot \text { Eq. (6) } \cdot p\left(\epsilon^{t} \mid y^{t-1}\right) d \epsilon^{t}\right]
\end{aligned}
$$

- $t=0$ : fix $y_{0}, \epsilon_{0}$
- $t=1$ : need draws from $p\left(\epsilon^{1} \mid y_{0}, \epsilon_{0}\right)=p\left(\epsilon_{1} \mid \epsilon_{0}\right)$, which is easy. Draw $\epsilon^{1 \mid 0, s}$ for $s=1, \ldots, S$. Simulate LL for $t=1$ : $\approx \frac{1}{s} \sum_{s} p\left(y_{t} \mid y_{0}, \epsilon^{1 \mid 0, s} ; \theta\right)$
- $t=2$ : need draws from $p\left(\epsilon^{2} \mid y^{1}\right)=p\left(\epsilon^{1} \mid y^{1}\right) p\left(\epsilon_{2} \mid \epsilon^{1}\right)$. First term is $p\left(\epsilon^{1} \mid y^{1}\right) \propto p\left(y_{1} \mid \epsilon^{1}, y_{0} ; \theta\right) p\left(\epsilon^{1} \mid y_{0}\right)$. So

1. resample $\epsilon^{1 \mid 1, s}$ from $\epsilon^{10, s}$ using weights

$$
w_{1}^{s} \propto p\left(y_{1} \mid \epsilon^{1}, y_{0} ; \theta\right)
$$

2. Draw $\epsilon_{2}^{s} \sim p\left(\cdot \mid \epsilon^{1 \mid 1, s}\right)$.
3. Combine for $\epsilon^{2 \mid 1, s}=\left(\epsilon^{1 \mid 1, s}, \epsilon_{2}^{s}\right)$.

Simulate LL for $t=2: \approx \frac{1}{s} \sum_{s} p\left(y_{t} \mid y_{0}, \epsilon_{2}^{2 \mid 1, s} ; \theta\right)$

- $t=3: ? ?$

