

I) D-modules

Weyl algebra (Heisenberg quantum mechanics)

$$pq - qp = i\hbar \quad (\text{Heisenberg uncertainty principle})$$

K field (char. zero): say $\mathbb{R}$ or $\mathbb{C}$

$K[x]$ $x = (x_1, \dots, x_n)$ ring of polynomials
in n variables
(commuting)

$\text{End}_K(K[x]) = \text{linear operators}$

$$L: K[x] \rightarrow K[x]$$

$K[x]$ ∞ -dim
vector space over K
(no topology for now)

- $\hat{x}_i = \text{multiplication operators}$

$$(\hat{x}_i f)(x) = x_i \cdot f(x)$$

- derivations $\partial_i(f) = \frac{\partial f}{\partial x_i}$

- n -th Weyl algebra W_n

subalgebra of $\text{End}_K(K[x])$ generated by
 $\hat{x}_i$ and $\partial_i \quad i=1, \dots, n$

noncommutative

$$\partial_i \hat{x}_i f = x_i \partial_i f + f$$

$$\partial_i \hat{x}_i - \hat{x}_i \partial_i = 1 \quad (\text{identity})$$

[2]

$$[\partial_i, \hat{x}_j] = \delta_{ij} \cdot 1$$

$$[\partial_i, \partial_j] = [\hat{x}_i, \hat{x}_j] = 0$$

relations in the Weyl algebra

$$x^\alpha = x_1^{\alpha_1} \cdots x_n^{\alpha_n}$$

$$\alpha = (\alpha_1, \dots, \alpha_n) \quad |\alpha| = \alpha_1 + \dots + \alpha_n$$

$$\beta = (\beta_1, \dots, \beta_n) \quad \partial^\beta = \partial_1^{\beta_1} \cdots \partial_n^{\beta_n}$$

$B = \{ x^\alpha \partial^\beta \}$ basis of W_n as k -vector space

so can think of W_n as the ring of diff. operators w/ polynomial coeff's

$D \in W_n$ diff op

Note: "degree" in Weyl alg not same as usual deg of diff op (max derivation order) but accounts also for deg of polynomial coeff's

e.g. $\deg_{W_n} (2x_1 \partial_2 + x_1 x_2^3 \partial_1 \partial_2) = 6$
while deg usual sense is 2

Reason: want to maintain "symmetry" between position & momentum variables x, ∂

$$\deg_{W_n} (D + D') \leq \max \{ \deg_{W_n} (D), \deg_{W_n} (D') \}$$

$$\deg_{W_n} (DD') = \deg_{W_n} (D) + \deg_{W_n} (D')$$

$$\deg_{W_n} [D, D'] \leq \deg_{W_n} (D) + \deg_{W_n} (D') - 2$$

$$[3] \quad [\partial^\beta, x^\alpha] = \partial_i [\partial^{\beta-e_i}, x^\alpha] + [\partial_i, x^\alpha] \partial^{\beta-e_i}$$

by induction $\deg_{W_n} [\partial^{\beta-e_i}, x^\alpha] \leq |\alpha| + |\beta| - 3$
 $(|\beta-e_i| = |\beta|-1)$

and $\deg_{W_n} [\partial_i, x^\alpha] \leq |\alpha| + 1 - 2 = |\alpha| - 1$

so $\deg_{W_n} [\partial^\beta, x^\alpha] \leq |\alpha| + |\beta| - 2$ (using sum est.)

then $\partial^\beta x^\alpha = [\partial^\beta, x^\alpha] + x^\alpha \partial^\beta$

$$\deg_{W_n} (x^\alpha \partial^\beta) = |\alpha| + |\beta|$$

$$\Rightarrow \deg_{W_n} (\partial^\beta x^\alpha) \leq \max\{|\alpha| + |\beta|, |\alpha| + |\beta| - 2\} = |\alpha| + |\beta|$$

then for $D = x^\sigma \partial^\beta$ $D' = x^\alpha \partial^\gamma$

$$DD' = x^{\sigma+\alpha} \partial^{\beta+\gamma} + x^\sigma \underbrace{P \partial^\gamma}_{Q_1}$$

$$P = [\partial^\beta, x^\alpha]$$

$$\deg(Q_1) \leq \deg(D) + \deg(D') - 2$$

by induction hyp.

$$\Rightarrow \deg(DD') \leq \deg(x^{\sigma+\alpha} \partial^{\beta+\gamma}) = \deg(D) + \deg(D')$$

similarly for $\deg(D'D) = x^{\sigma+\alpha} \partial^{\beta+\gamma} + Q_2$

$$\deg(Q_2) \leq \deg(D) + \deg(D') - 2$$

$$\Rightarrow [D, D'] = Q_1 - Q_2 \quad \deg[D, D'] \leq \max\{\deg Q_1, \deg Q_2\} = \deg D + \deg D' - 2$$

④ W_n is simple (no two-sided ideals)
non-zero $\curvearrowright a \in I \subset I, I b \subset I$

if $\exists D \neq 0$ in $I \subset W_n$ of min degree $\forall a, b \in W_n$

$\exists$ some i s.t. $[x_i, D] \neq 0$ (D contains x_i)

or $\exists$ some $i: [x_i, D] \neq 0$ (D contains x_i)

but then because ideal $[x_i, D]$ or $[x_i, D]$ also in I
but both are of lower degree $\checkmark$

$\Rightarrow$ consequence every endomorphism of W_n
is injective
(kernel would be a two-sided ideal)

question: is every endom of W_n an automorphism?
(since know injectivity: is every end surjective?)

this is Jacobian conjecture (major open problem in mathematics)

More general "rings of diff operators"

over a ring $R \leftarrow$ specifies type of
coefficients of the
diff operators

e.g. $R = C(\Omega)$ continuous functions

$R = C^\infty(\Omega)$ smooth functions etc.

$R = \mathbb{C}((z))$ rational functions

Weyl algebra is ring of diff op's where $R = K[x_1, \dots, x_n]$
polynomial ring

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Modules over the Weyl algebra

R is R -module M (sep $A(R)$)
 $m \mapsto r \cdot m$ (left/right mod if R n.c.)

e.g. $K[x] = K[x_1, \dots, x_n]$ is a module over $\mathcal{W}_n$

$$K[x] = \mathcal{W}_n / \sum_{i=1}^n \mathcal{W}_n x_i$$

also $K[\partial] = K[\partial_1, \dots, \partial_n]$ (diff. op's w/ constant coefficients)
 is mod over $\mathcal{W}_n$

$$K[\partial] = \mathcal{W}_n / \sum_{i=1}^n \mathcal{W}_n \cdot x_i$$

$U \subset \mathbb{C}$ open set $\mathcal{H}(U) = \text{holom. funct's on } U$
 $\cup$
 $\mathbb{C}[z]$

also $\mathcal{W}_1(\mathbb{C})$ module

z $\frac{d}{dz}$ generators acting by mult. & derivatn on $\mathcal{H}(U)$

a "torsion element" in this module (some $D \in \mathcal{W}_1(\mathbb{C})$ w/ $Df = 0$)

is = holom. function satisfy

a diff equation w/ polynomial coefficients

[6] $\mathcal{D}$ -module of a differential equation

$$\mathcal{D} \in \mathcal{W}_n \quad \text{diff operatn (w/ polyn. coeff's)}$$

$$\parallel$$

$$\sum_{\alpha} g_{\alpha} \partial^{\alpha} \quad \rightsquigarrow \quad \text{equation} \quad \mathcal{D}(f) = \sum_{\alpha} g_{\alpha} \partial^{\alpha}(f) = 0$$

or systems of equations:

$$(*) \quad \begin{cases} \mathcal{D}_1(f) = 0 \\ \vdots \\ \mathcal{D}_k(f) = 0 \end{cases} \quad \mathcal{D}_1, \dots, \mathcal{D}_k \in \mathcal{W}_n$$

$\mathcal{D}$ -module associated to equation $(*)$

$$\mathcal{M} = \mathcal{W}_n / \sum_{i=1}^k \mathcal{W}_n \cdot \mathcal{D}_i$$

a polynomial solution of $(*)$: $f \in K[x]$ s.t. $\mathcal{D}_i(f) = 0$
 $i=1, \dots, k$

Thm: vector space of polynomial solutions of $(*)$

is $\text{Hom}(\mathcal{M}, K[x])$ morphisms of $\mathcal{W}_n$ -modules

in fact: if $f \in K[x]$ polyn. sol'n of $(*)$

$$\sigma_f: \mathcal{W}_n \rightarrow K[x] \quad \left(\begin{array}{l} \text{mapping } 1 \in \mathcal{W}_n \text{ to } f \\ \& \mathcal{D} \in \mathcal{W}_n \mapsto \mathcal{D}(f) \end{array} \right)$$

$$\text{then if } \tilde{\mathcal{D}} \in \mathcal{J} = \sum_{i=1}^k \mathcal{W}_n \mathcal{D}_i \quad \text{i.e. } \tilde{\mathcal{D}} = \sum_{i=1}^k \delta_i \mathcal{D}_i$$

$$\rightsquigarrow \tilde{\mathcal{D}}(f) = 0 \quad (\text{since all } \mathcal{D}_i(f) = 0)$$

$$\Rightarrow \sigma_f: \mathcal{M} \rightarrow K[x]$$

[7] so polyn. M'nf $\longrightarrow \sigma_f \in \text{Hom}(M, K[x])$
 $f \mapsto \sigma_f$ linear map (since D_i linear operators)

conversely:

$$\tau \in \text{Hom}(M, K[x])$$

take $1 \in M$ (i.e. $1 \in W_n$ modulo $\sum_i W_n D_i$)

$\rightarrow \tau(1)$ some polynomial in $K[x]$
 $\parallel$
 h this h is a solution of $D_i(h) = 0$

(and $\tau = \sigma_h$)

$$\tau(1 + \sum_i \delta_i D_i) = h$$

$$\tau(\sum_i \delta_i D_i) = 0$$

Note:
 $\text{Hom}(M, K[x])$
 is a K -vector space (co-dim)
 (not a module over W_n
 nor over $K[x]$)

but $\tau(1) = h \Rightarrow \tau(\tilde{D}) = \tilde{D}(h)$
 so $\tau(\sum_i \delta_i D_i) = \sum_i \delta_i D_i(h) = 0$
 for all δ_i
 $\Rightarrow D_i(h) = 0$

Not only polyn. solutions e.g.

$\mathcal{C}^\infty(\Omega)$ solutions would be (same argument)

$\text{Hom}(M, \mathcal{C}^\infty(\Omega))$ same $M = D$ -module of the equation
 homomorphisms of W_n -modules

If look for solutions of $D(f) = 0$ of a
 certain type $f \in \mathcal{F} \Rightarrow \text{Hom}(M, \mathcal{F})$

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Note: "microfunctions"

"microlocal analysis"

→ direct limits of modules

e.g. $H(D_\varepsilon^*)$ hol. funct's on a punctured
disc D_ε^* of radius ε

and direct limit as $\varepsilon \rightarrow 0$ as $\mathcal{W}_1$ -modules

objects of this lim "microfunctions"

can again interpret in this way
convergence of smooth funct's $f_\varepsilon \rightarrow \delta$ distributions
(Malgrange)

Maximally overdetermined systems in PDEs

there is a notion of dimension for

modules M over $\mathcal{W}_n$ (generalizing notion
of dim for vector spaces)

(uses a filtration Γ of M)

and Hilbert polyn. $\chi(t, \Gamma, M) = \sum_{i=0}^t \dim_K(\Gamma_i / \Gamma_{i-1}) = \dim_K(\Gamma_t)$

degree of as polyn. in t is $\dim(M)$

→ $M = \bigoplus_{i \geq 0} M_i$ $\sum_{i=0}^s \dim_K(M_i) = \chi(s)$ Hilbert polyn.)

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Holonomic D-modules $\mathcal{M}$ s.t. $\dim(\mathcal{M}) = n$
modules over $\mathcal{W}_n$

examples $K[x_1, \dots, x_n]$ $\nwarrow$ hol D-modules for $\mathcal{W}_n$
 $K[\partial_1, \dots, \partial_n]$ $\swarrow$ (dim $2n$ as mod)

like Lagrangians (only positions / only momenta)
in symplectic space (q, p) of positions & momenta
w/ symplectic form $\omega = d\lambda = \sum_i dp_i \wedge dq_i$
 $\uparrow$ Liouville 1-form

Lagrangian:
middle dim. & in
ker of ω

$$\lambda = \sum_i p_i dq_i$$

(pairs q, p w/ canonical relations
 $[\hat{q}, \hat{p}] = 1$ give pairs
of Lagra. that count
(pos/momenta))

this relation to sympl. geometry can
be made more precise
through a geom. construction

This is in fact the description of
the symplectic structure of the
cotangent bundle $T^*\Omega$

$$q \in \Omega \quad p \in T_x^*\Omega$$

$$\lambda = \sum_i p_i dq_i \quad \text{Liouville 1-form on } T^*\Omega$$

what does it describe? $T^*\Omega$ or sections are
1-forms on Ω

10 $q \in \Omega$ $\lambda_q \in T_q^* \Omega$ $\lambda_q = df_q$ or combn. of such

if want 1-form on $T^* \Omega$ (not on Ω)

at each $(q, w) \in T^* \Omega$ $w \in T_q^* \Omega$

assign $\lambda_{(q, w)}$ 1-form

but w is a 1-form on Ω and have

projection $T^* \Omega \xrightarrow{\pi} \Omega$
 $(q, w) \mapsto q$

so $\pi^* w =$ 1-form on $T^* \Omega$

$\lambda_{(q, w)} = \pi^* w$ Liouville form

i.e. if $V = \sum_i a_i \partial_{q_i} + \sum_j b_j \partial_{p_j}$

$$\pi_* V = \sum_i a_i \partial_{q_i}$$

$$\lambda(V) = p(\pi_* V)_q$$

Symplectic form: 2-form on $T^* \Omega$ $(V, W) \mapsto \omega(V, W)$
 $\omega = \sum_{i,j} \omega_{ij} dq_i \wedge dp_j$ $\omega: T\Omega \otimes T\Omega \rightarrow \mathbb{R}$ pairs w/ vecm fields

$d\omega = 0$ closed and $\omega^n = \omega \wedge \dots \wedge \omega \neq 0$
 $\uparrow$ nowhere vanishing scalar density (vol. form)

Classical Hamiltonian

mechanics is closely related to the symplectic geometry of $T^* \Omega$

$T^* \Omega =$ phase space

$\boxed{II}$ $f: \Omega \rightarrow \mathbb{R}$ smooth function df 1-form
 X_f vector field defined by $\omega(V, X_f) = df(V)$
 Poisson bracket $\{f, g\} = \omega(X_g, X_f)$ for any $V \in T\Omega$ vector field

$H = H(q, p)$ Hamiltonian (smooth function on symplectic $T^*\Omega$)

Hamiltonian equations of classical mechanics

$$\begin{cases} \frac{dq_i}{dt} = \frac{\partial H}{\partial p_i} \\ \frac{dp_i}{dt} = -\frac{\partial H}{\partial q_i} \end{cases} \Leftrightarrow \frac{df}{dt} = \{f, H\}$$

Poisson brackets evolution of classical observables
 applied to $f = q_i$ or $f = p_i$ $\{f, H\} = 0$
 invariants: conserved quantities

Lagrangians in $(T^*\Omega, \omega)$ symplectic

L Lagrangian if $\omega|_L \equiv 0$ and

$\dim L = n$ half-dimensional in $T^*\Omega$

$S_\alpha: \Omega \rightarrow T^*\Omega$ section of cotg bundle:

$$\pi \circ S_\alpha = \text{id}_\Omega$$

$S_\alpha(x) = \alpha_x$ 1-form $\alpha_x \in T_x^*\Omega$

$$\boxed{12} \quad \Omega_\alpha = s_\alpha(\Omega) \subset T^*\Omega \quad \text{image of section}$$

$\uparrow$ Lagrangian of $\omega|_{\Sigma_\alpha} \stackrel{=}{=} 0$

$$\begin{aligned} \omega|_{\Omega_\alpha} &= s_\alpha^*(\omega)_x = s_\alpha^*(d\lambda)_{(x, \alpha_x)} \quad \omega = d\lambda \\ &= s_\alpha^* d\pi^* \alpha_x = d(\pi \circ s_\alpha)^* \alpha_x = d\alpha_x \end{aligned}$$

$d\alpha = 0$ So Ω_α Lagrangian iff $d\alpha = 0$

So $f: \Omega \rightarrow \mathbb{R}$ $\{ (x, df|_x) \} = \text{Lagrangian}$
in $T^*\Omega$

associated to $\mathcal{M} \rightsquigarrow \text{Ch}(\mathcal{M})$

characteristic
variety of D -module M

holonomic D-module $\leftrightarrow$ char variety
 $\text{Ch}(M)$ Lagrangian
 (standard sympl. str. in $\mathbb{C}^{2n}$)

$\text{Ch}(M)$ characteristic variety of the D -module M

- for D single differential eqn

13 $\sigma(D) = \text{principal symbol of } D$

$$\sigma(D)(\xi) = \sum_{|\alpha|=m} a_\alpha \xi^\alpha \quad \text{for} \quad D = \sum_{|\alpha| \leq m} a_\alpha \partial^\alpha$$

$$\text{Ch}(M) = \{ \xi \mid \sigma(D)\xi = 0 \} \text{ hypersurface}$$

M D -module of equation $D(f) = 0$

(not holonomic unless $n = 1$ as

$$\xi \in T^*\Sigma \text{ dim } 2n$$

and $\text{Ch}(M)$ hypersurf
dim $2n-1$

not dim n)

• for a system of PDEs

$$D_i f = 0$$

then $\text{Ch}(M)$ has codimension at most n
 $\text{codim Ch}(M) \leq n$

$$\text{Ch}(M) = \{ \xi \mid \sigma(D_i)\xi = 0 \}$$

if $\text{Ch}(M)$ has $\text{codim} = n$ (hence also $\text{dim} = n$) and
Lagrangian submanifold of $T^*\Sigma$

Holom. D -modules are

max overdetermined systems of PDE's

$$\begin{cases} D_1(f) = 0 \\ \vdots \\ D_n(f) = 0 \end{cases}$$

$$D_i \in \mathcal{W}_n$$

and all lin. indep.
($\text{codim} = n$)

[14] In general: overdetermined systems of PDE's

$$\begin{cases} \sum_{i=1}^m D_{i,1}(f_i) = 0 \\ \vdots \\ \sum_{i=1}^m D_{i,r}(f_i) = 0 \end{cases}$$

$\underline{f} = (f_1, \dots, f_m)$ unknown function

$D_{i,j} =$ linear diff. operators
 $j = 1, \dots, r$ in n -variables
 $\underline{x} = (x_1, \dots, x_n)$
 Say first order for simplicity

overdetermined if
 $m < r' \leq r$

↖ member of lin ind. equations

maximally overdetermined:

$m=1$ single f unknown

$$\begin{cases} D_1(f) = 0 \\ \vdots \\ D_r(f) = 0 \end{cases}$$

and $r' \leq r$ as large as possible

case of first order D_i

if $r=1$ $m=1$ single eq.

$$D(f) = a_1 \frac{\partial f}{\partial x_1} + \dots + a_n \frac{\partial f}{\partial x_n} = 0$$

consider a system of ODE's

$$\frac{dx_1}{ds} = a_1 \quad \dots \quad \frac{dx_n}{ds} = a_n$$



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suppose that $f_1, \dots, f_{n-1}$ are integrals of motion of $f_i(x_1, \dots, x_n)$

$$\text{i.e. } \frac{df_i}{ds} = \frac{\partial f_i}{\partial x_1} \frac{dx_1}{ds} + \dots + \frac{\partial f_i}{\partial x_n} \frac{dx_n}{ds} = 0$$

then general solution of $D(f) = 0$

$$f = \phi(f_1, \dots, f_{n-1})$$

as integral curves of vector field $a_1 \frac{\partial}{\partial x_1} + \dots + a_n \frac{\partial}{\partial x_n}$

are curves cut out by eq'n

$$\begin{cases} f_1 = c_1 \\ \vdots \\ f_{n-1} = c_{n-1} \end{cases}$$

$r \geq 1$: since at most n indep. equations $r \leq n$

& when $r = n$ only the trivial constant solutions as for n lin indep eq'ns can $\leadsto \frac{\partial f_i}{\partial x_i} = 0$ for each i

in other words: for first order lin. eqn's

$$\sigma(D_i)(\xi) = \sum_{k=1}^n a_{k,i}(\xi) \xi_k = 0 \quad \text{hyperplane in } T_x^* \Omega$$

$$\text{Ch}(M) = \{ \xi \mid \sigma(D_i)\xi = 0 \} \quad \text{intersection of } n \text{ hyperplanes}$$

$$\{0\} \subset T_x^* \Omega \quad \leadsto \text{Ch}(M) = \Omega \text{ as zero section of } T^* \Omega$$

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for higher order more interesting loci

$$\sigma(D_i)(\xi) = 0 \quad \text{e.g. for order 2 quadratic forms}$$



$$\sum_{j,k} q_{jk,i}(x) \xi_j \xi_k = 0 \quad i=1, \dots, r$$

intersection of r quadrics $Q_i(x) = \left\{ \sum_{j,k} q_{jk,i}(x) \xi_j \xi_k = 0 \right\}$
 $\tilde{u} \in T_x^* \Omega$ family over $x \in \Omega$

etc.
