

Neural networks and physical systems with emergent collective computational abilities

(associative memory/parallel processing/categorization/content-addressable memory/fail-soft devices)

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Contributed by John J. Hopfield, January 15, 1982

Luke Frankiw and Jonathan Kenny

Topics in Systems Neuroscience
California Institute of Technology
April 26th, 2017

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- Revitalized interest into neural network research during the early 1980s.
- Still an active researcher, proposed a model uniting associative memory and deep learning networks at *NIPS* 2016.



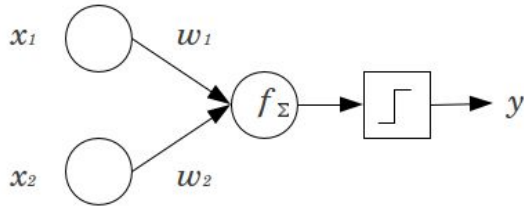
Neurons performing complex computational tasks in nature

- Do collective phenomena simply result from having many simple units working together?
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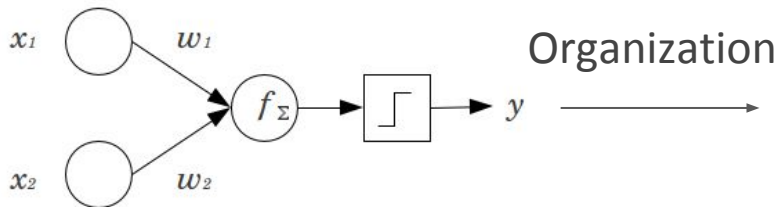
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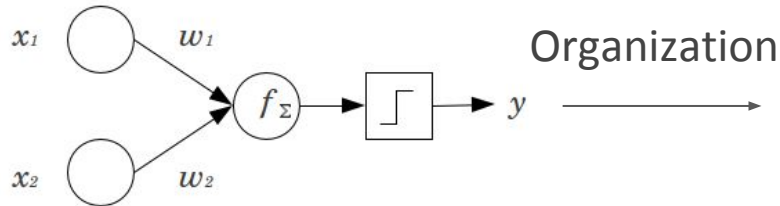


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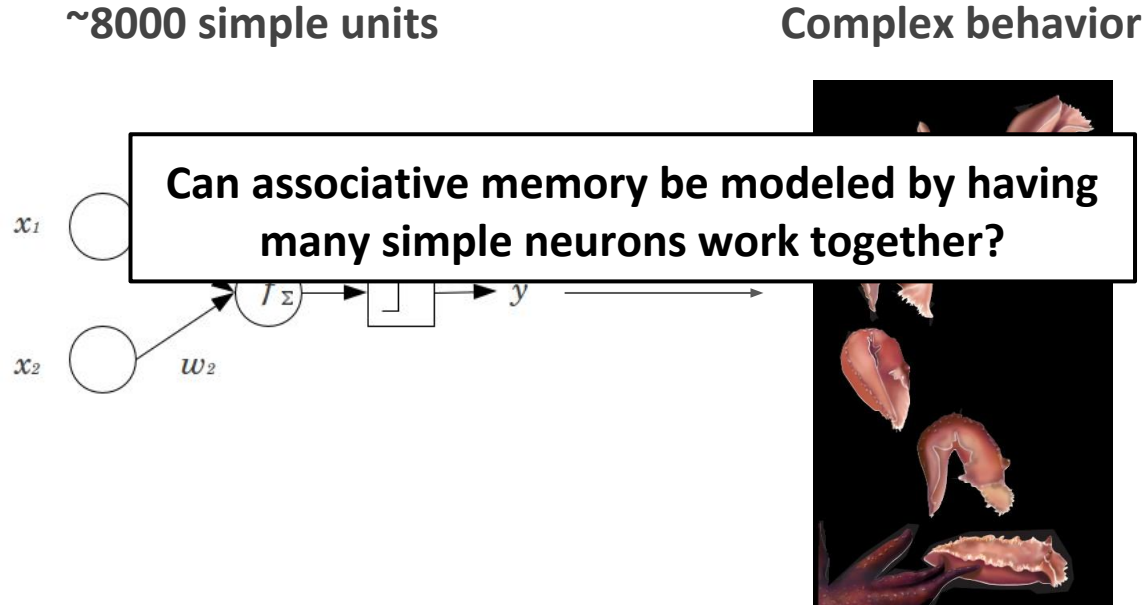
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Complex behavior



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Associative memory

- Also known as *content-addressable memory*, associative memory is crucial for pattern completion in the brain/hardware systems:

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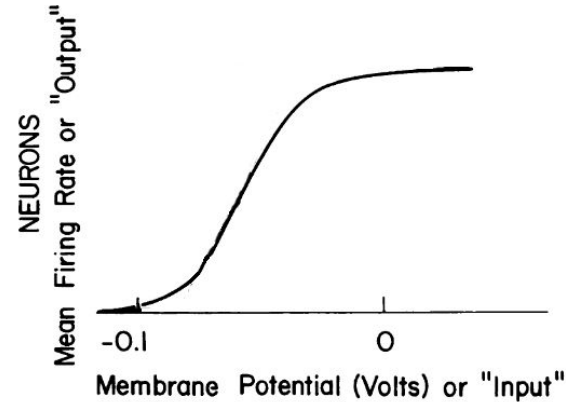
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Access with partial inputs

Associative memory (Hopfield) network structure

Short-term mean firing rate (neglect individual spikes)

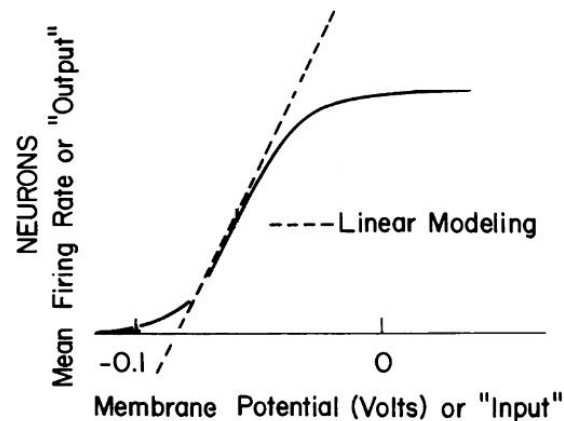
Neuron/unit (s)



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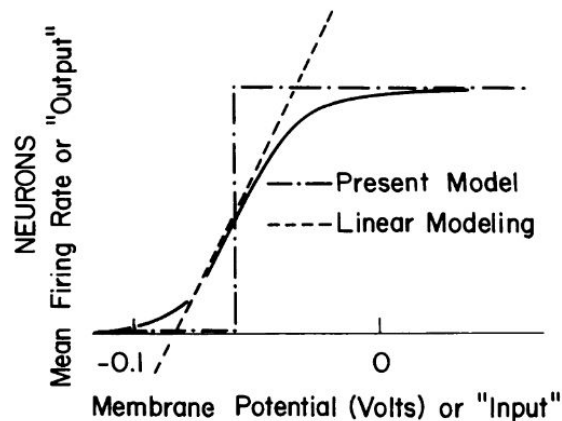
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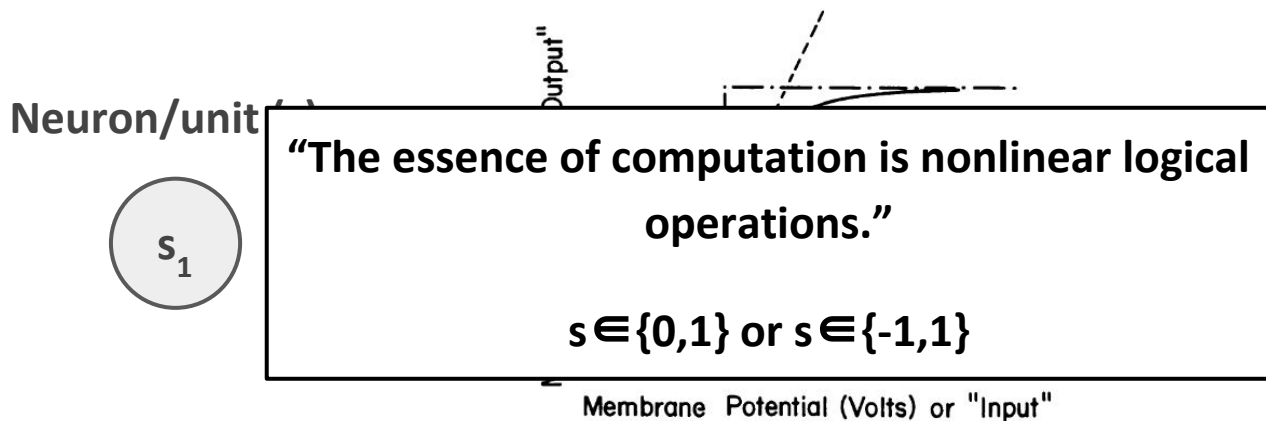
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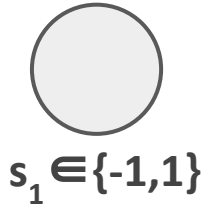
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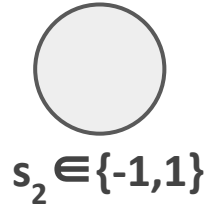
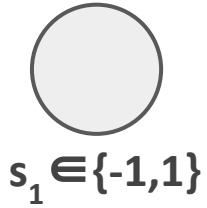
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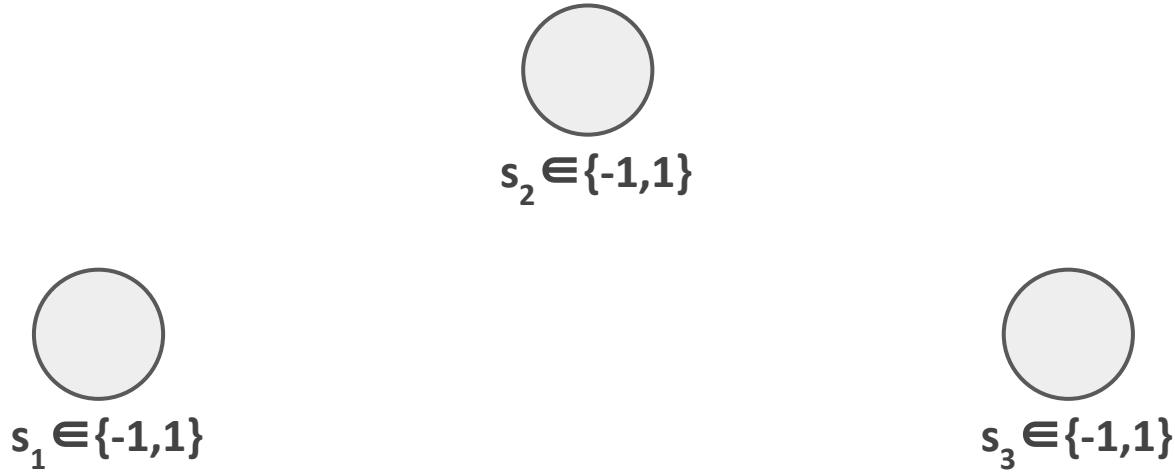
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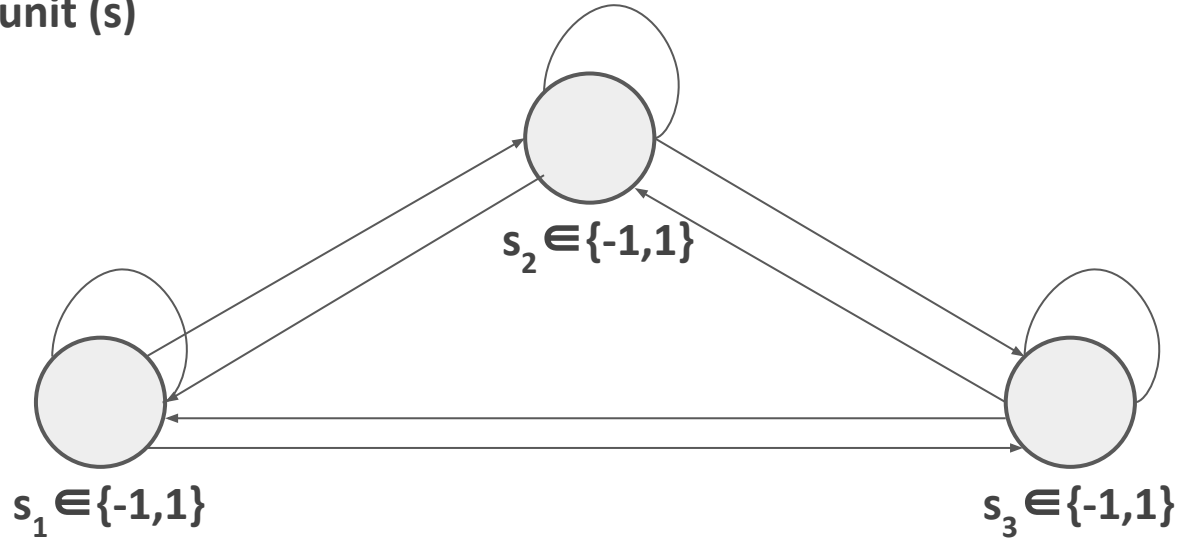
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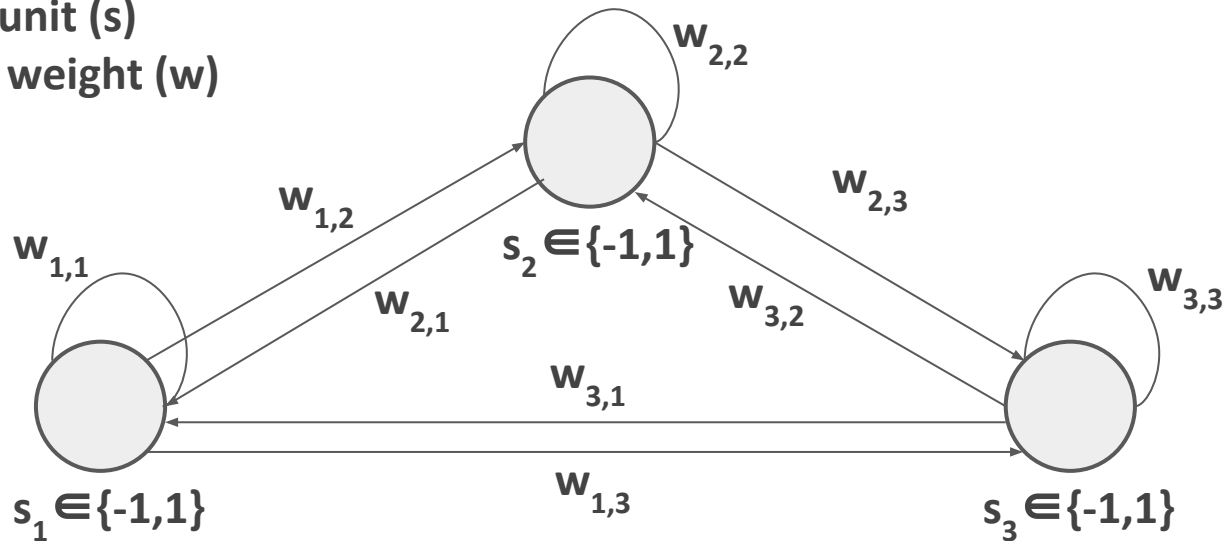
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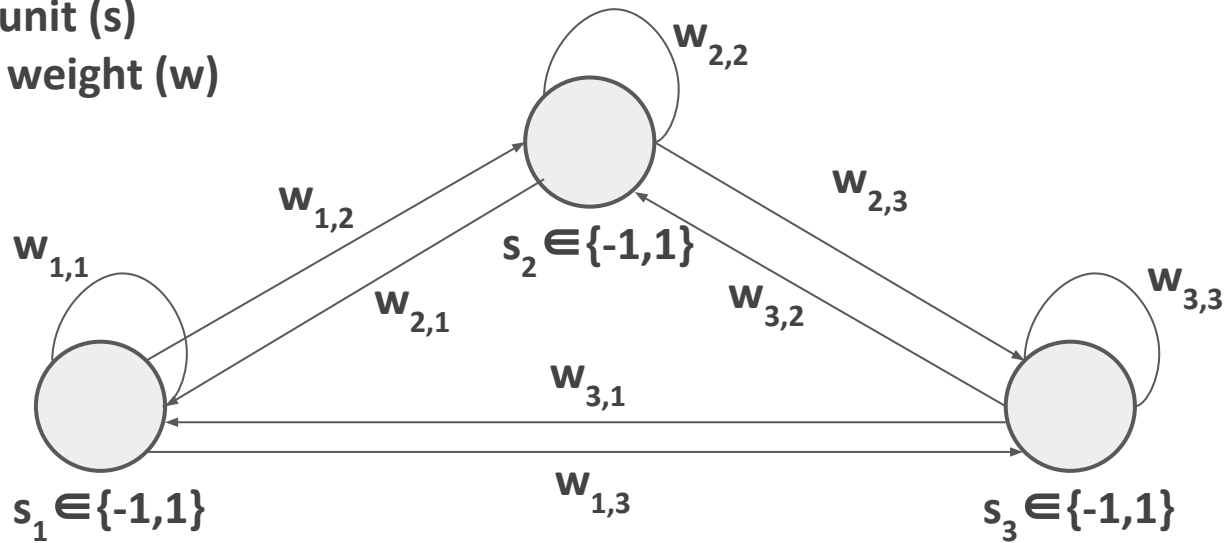
Synaptic weight (w)



Associative memory (Hopfield) network structure

Neuron/unit (s)

Synaptic weight (w)

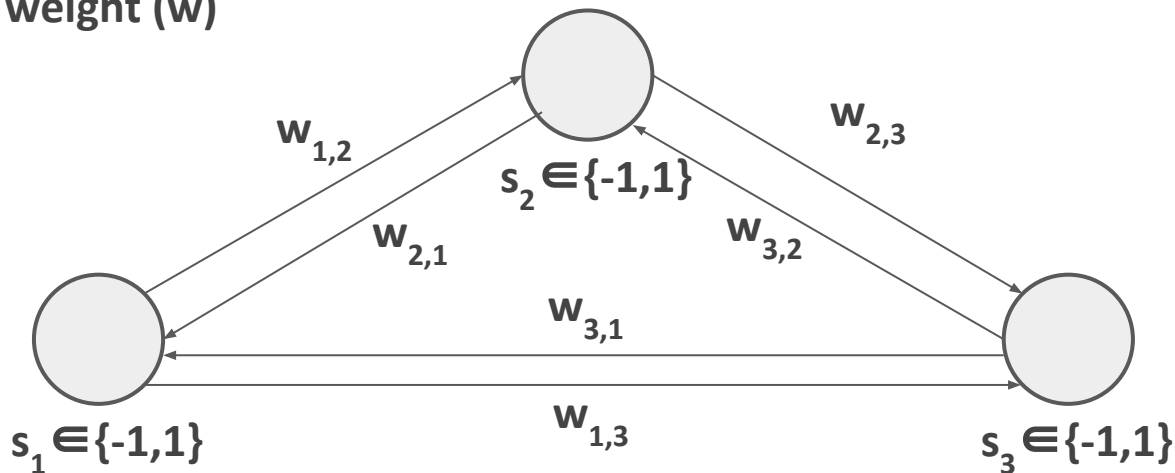


Some restrictions on weights (w) and neurons (s):

Associative memory (Hopfield) network structure

Neuron/unit (s)

Synaptic weight (w)



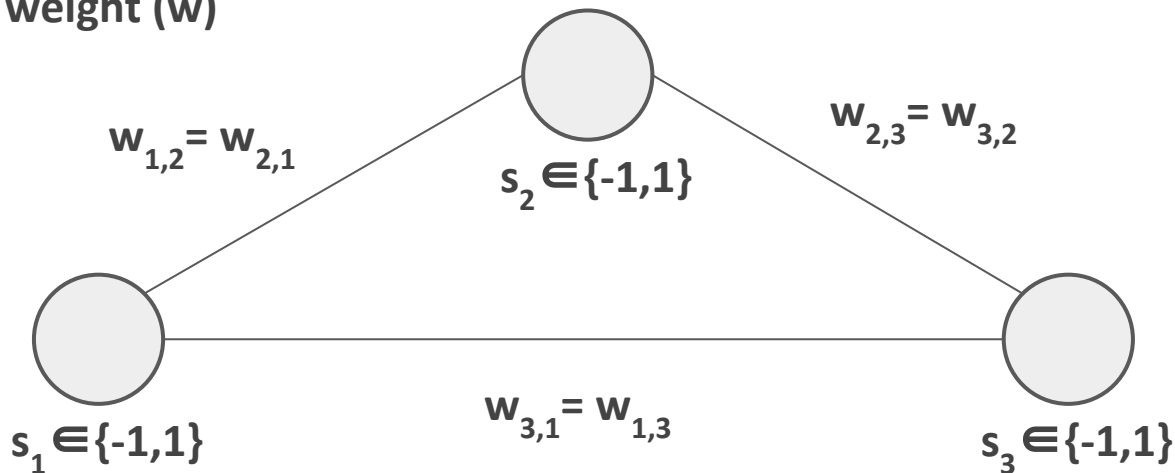
Some restrictions on weights (w) and neurons (s):

- No recursive connections

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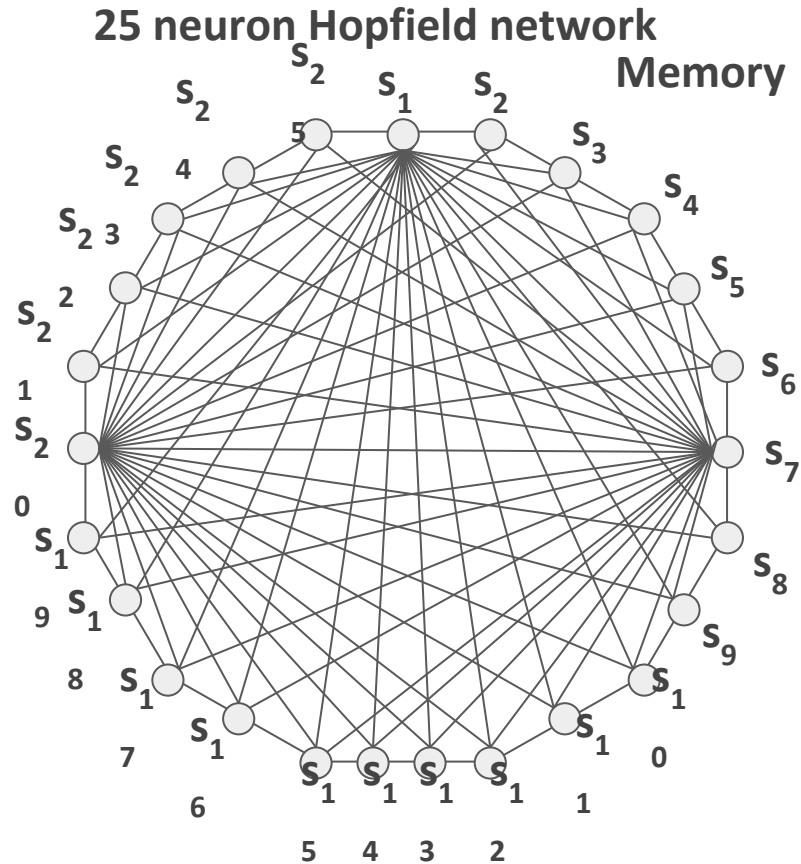
Synaptic weight (w)



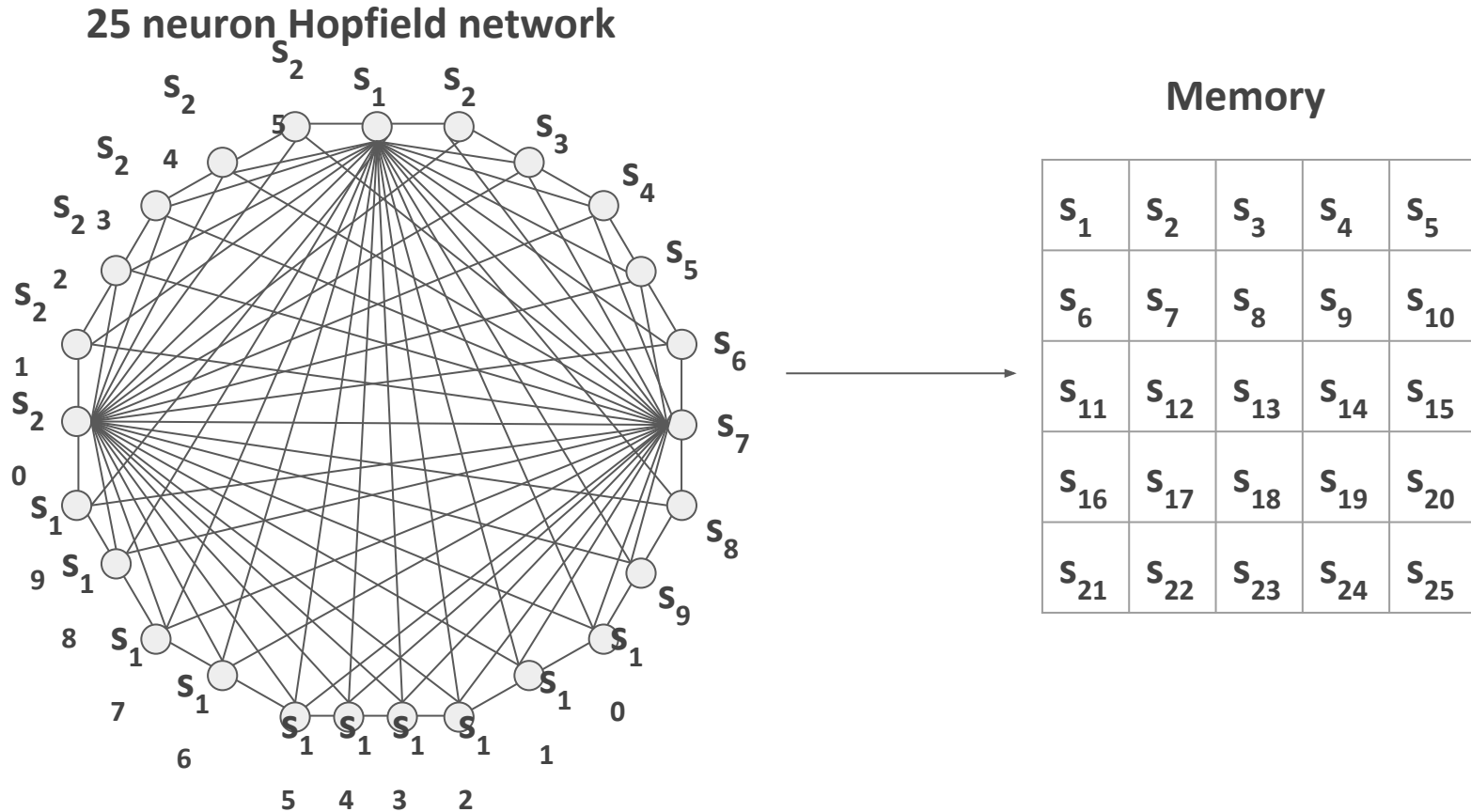
Some restrictions on weights (w) and neurons (s):

- No recursive connections
- No directed connections ($w_{i,j} = w_{j,i}$)

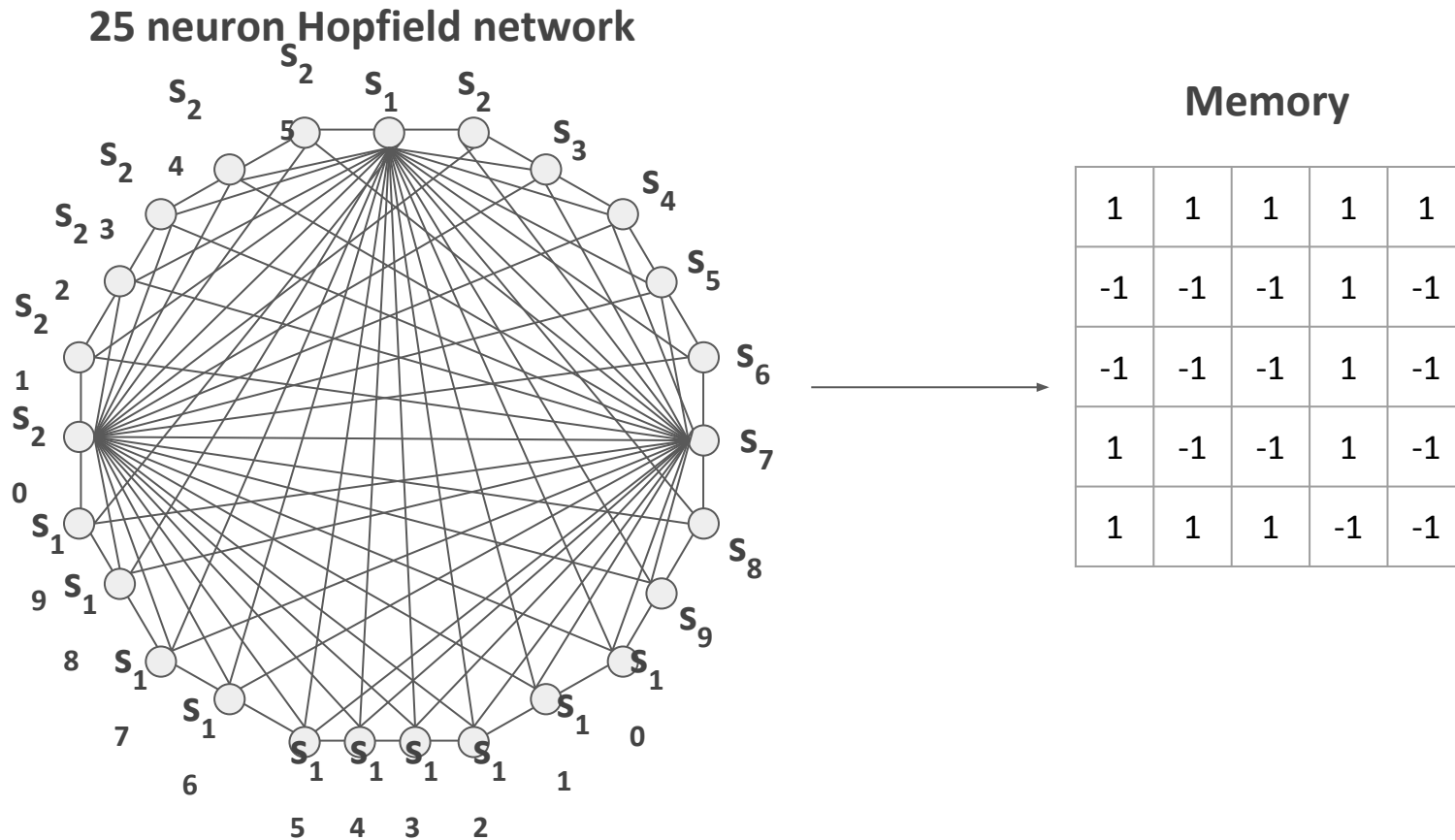
Associative memory (Hopfield) network example



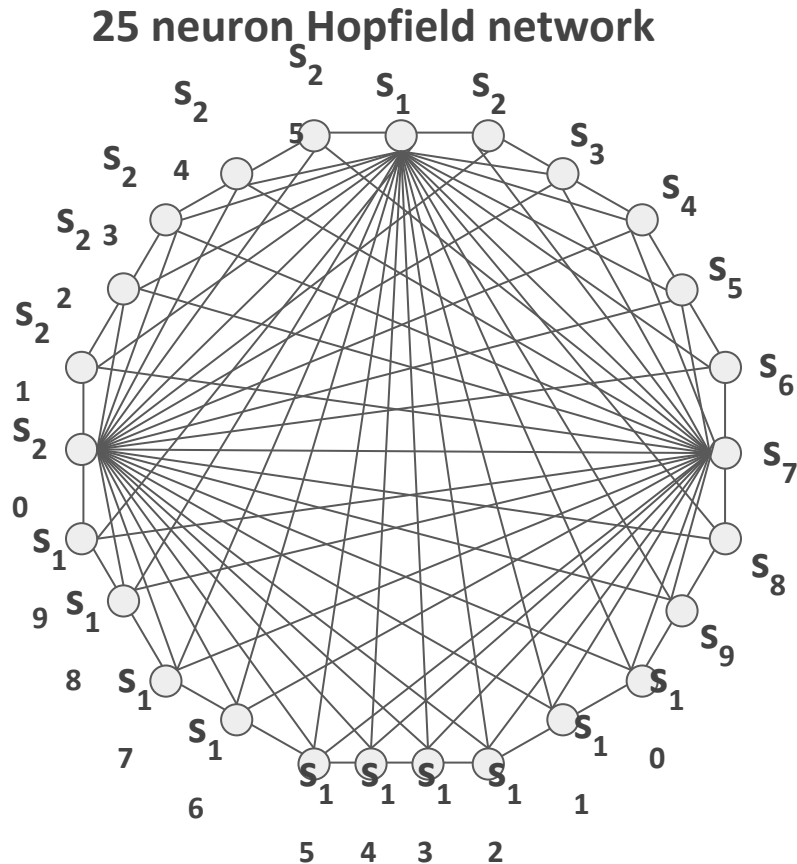
Associative memory (Hopfield) network example



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Associative memory (Hopfield) network example



Memory

1	1	1	1	1
-1	-1	-1	1	-1
-1	-1	-1	1	-1
1	-1	-1	1	-1
1	1	1	-1	-1

Train weights to include this memory, with **weight update algorithm**.

Associative memory (Hopfield) network example

Partial/incorrect pattern → Memory

1	1	1	1	1
-1	-1	-1	1	-1
-1	-1	-1	1	-1
1	-1	-1	1	-1
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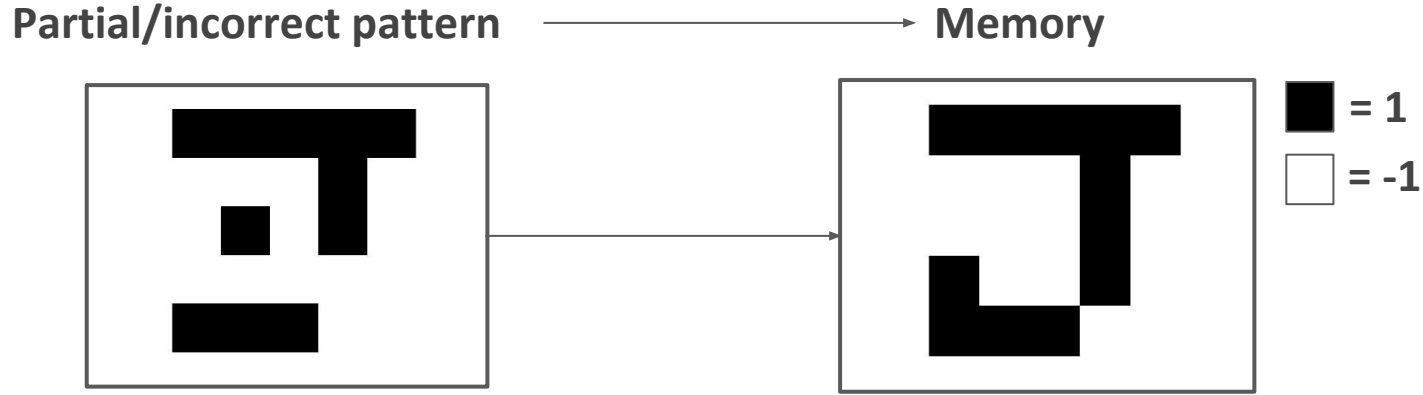
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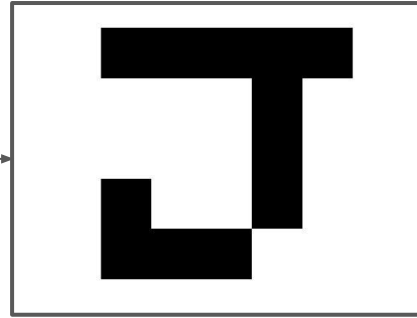
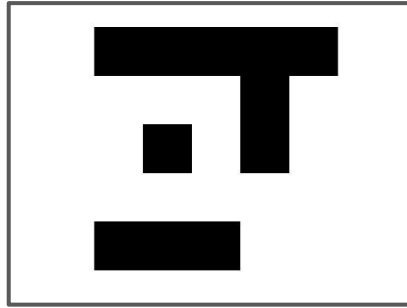


Perform pattern completion using
neuron update algorithm.

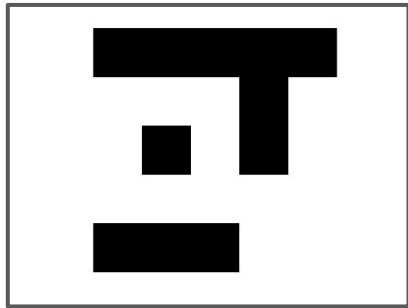
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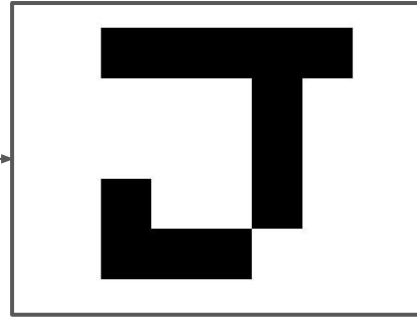
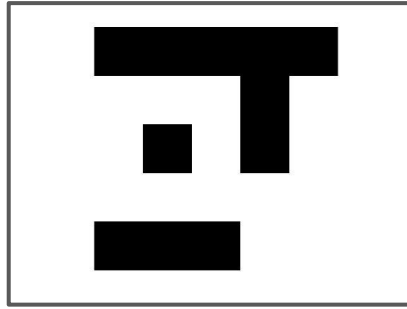
■ = 1
□ = -1



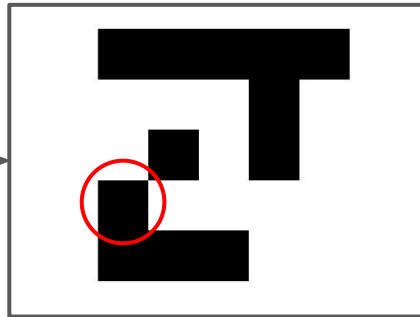
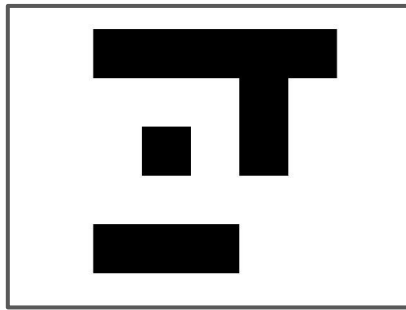
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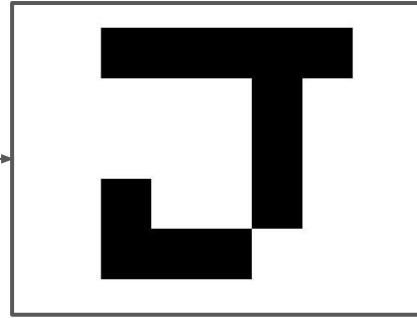
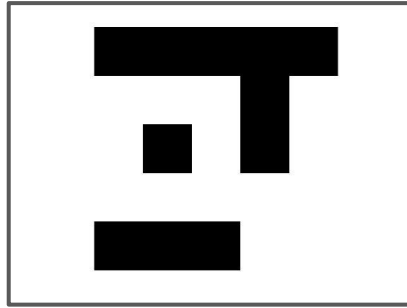
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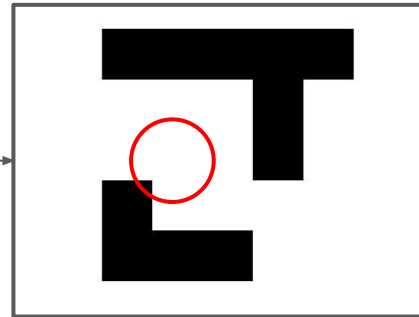
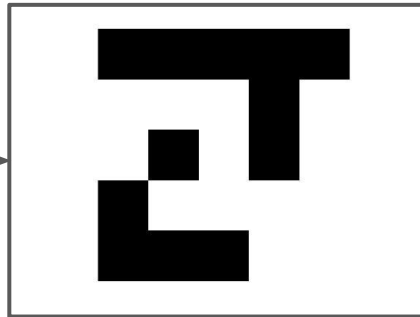
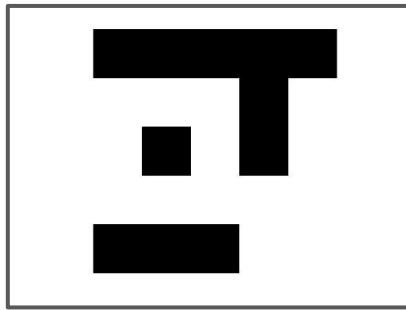
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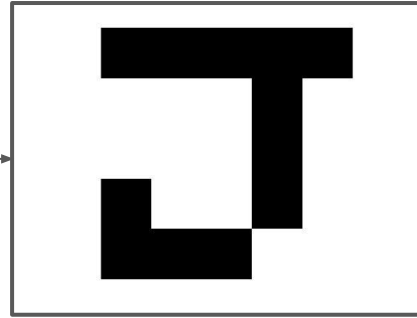
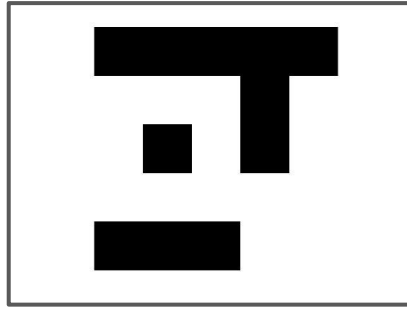
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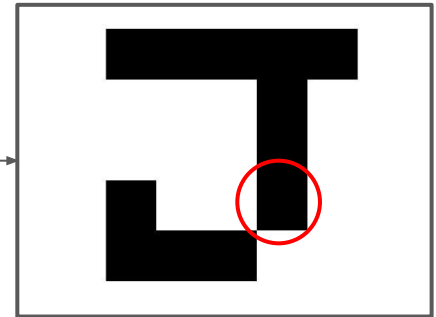
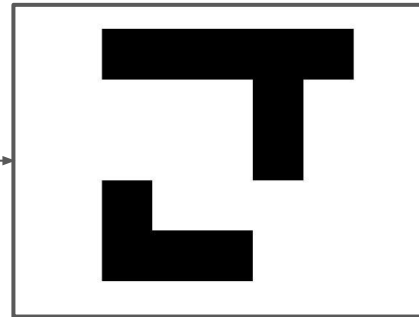
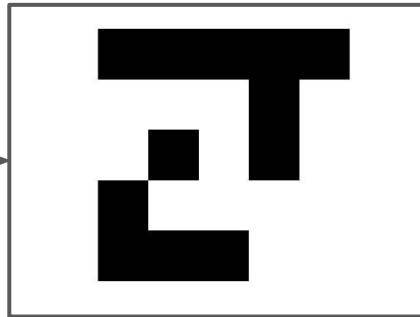
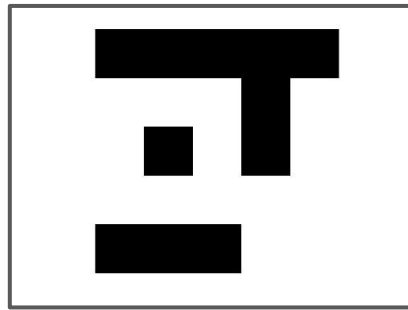
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□ = -1



Large Hopfield network

4,096 neuron Hopfield network (8.3 million weights)

Memory encoding in the neurons



Weight training

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Memory encoding in the neurons



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Memory encoding in the neurons

Weight training



Store memory
in network



(weight update
algorithm)

Large Hopfield network

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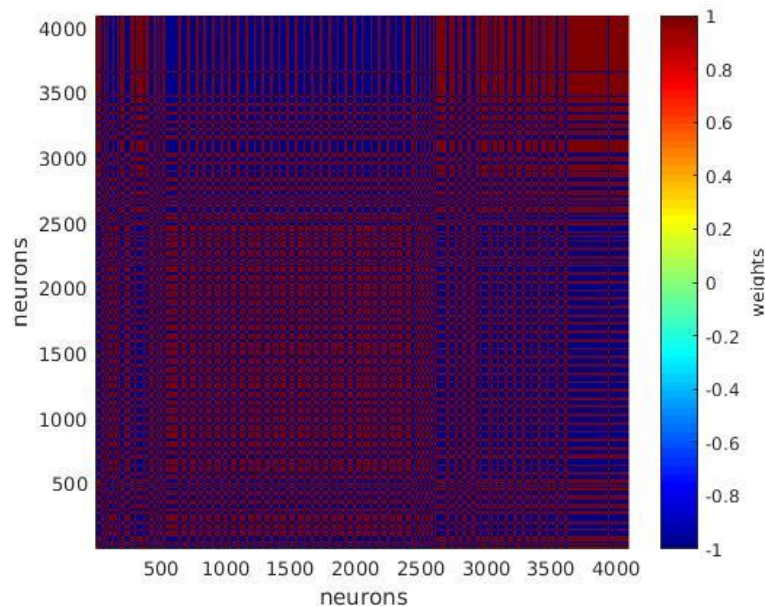
Memory encoding in the neurons



Store memory
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→
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Weight training



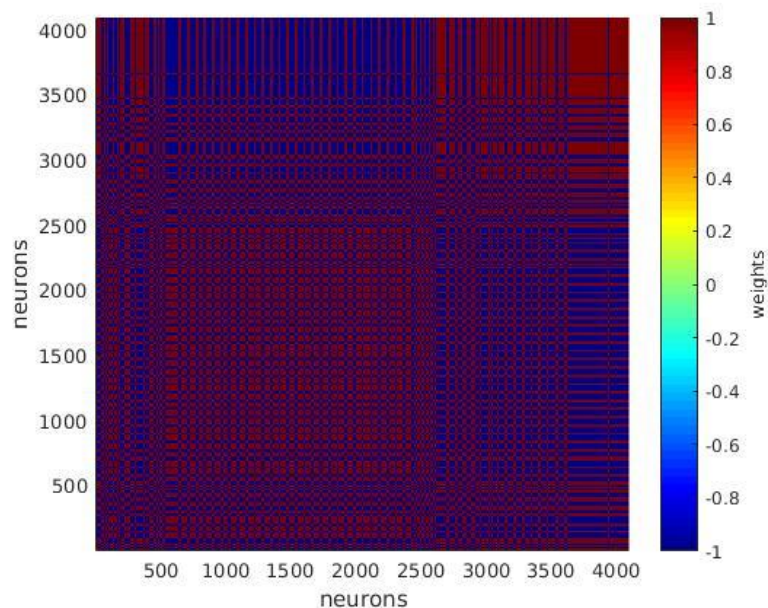
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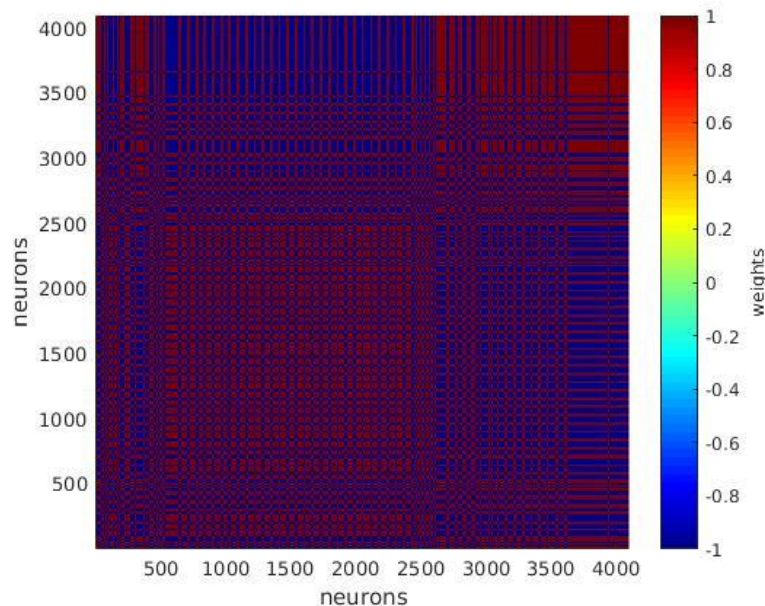
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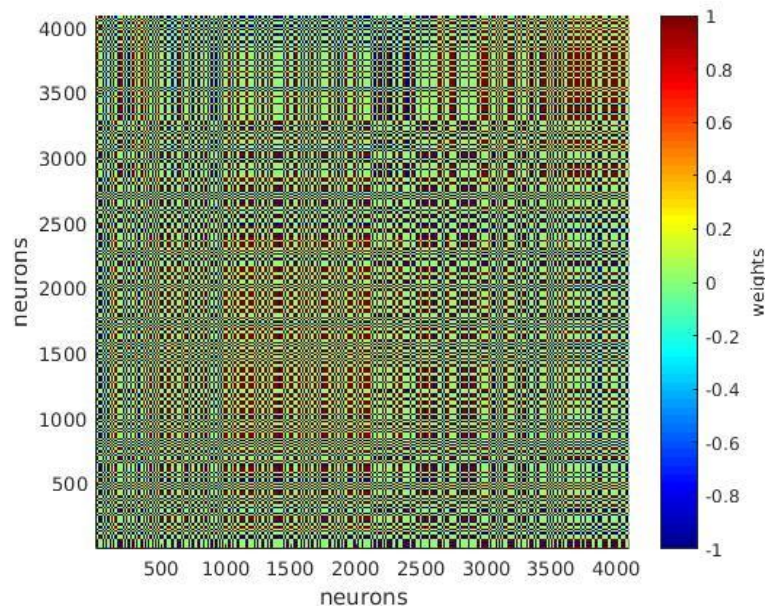
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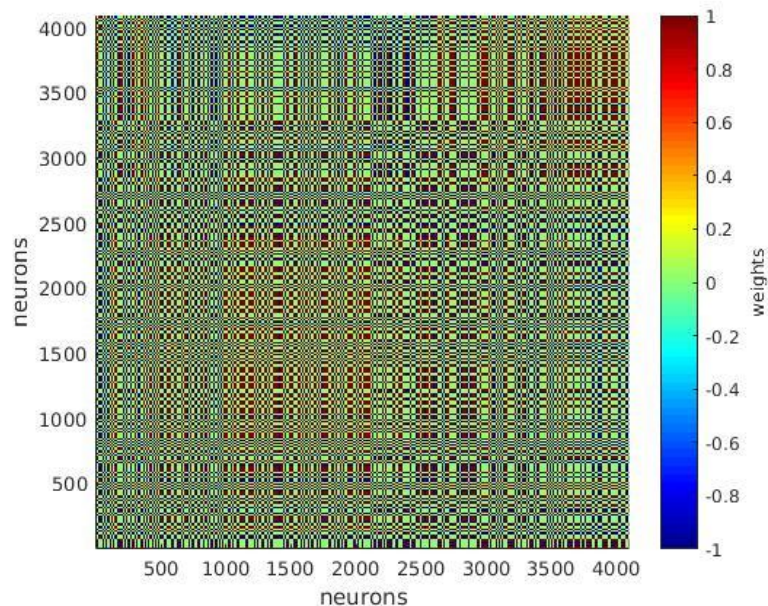
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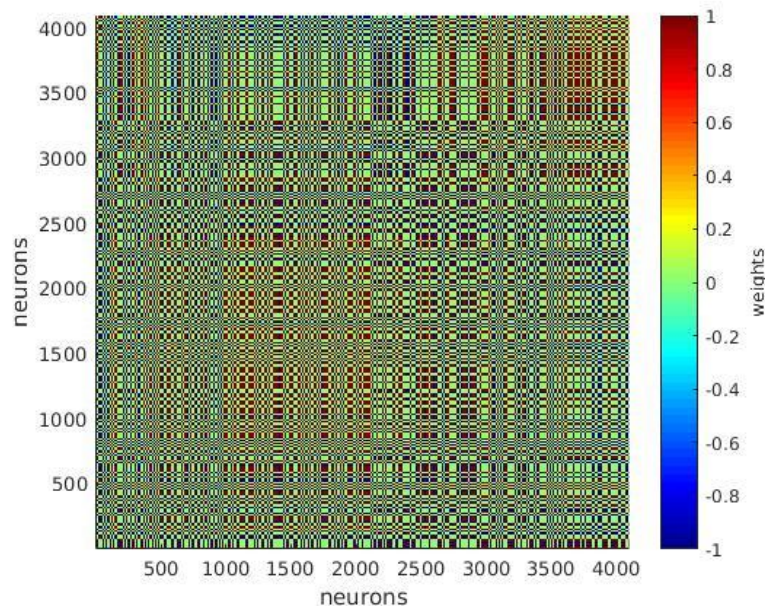
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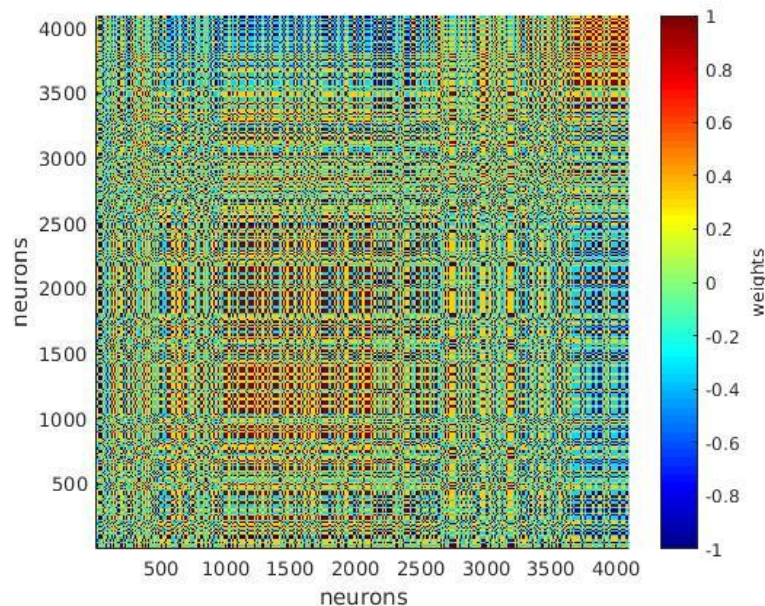
Memory encoding in the neurons



Store memory
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→
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Weight training



Large Hopfield network

4,096 neuron Hopfield network (8.3 million weights)

Memory



Add noise
(20% bit flip)



Incomplete Memory



Large Hopfield network

4,096 neuron Hopfield network (8.3 million weights)

Memory



Add noise
(20% bit flip)



(neuron update
algorithm)

Pattern completion



Large Hopfield network

4,096 neuron Hopfield network (8.3 million weights)

Memory



Add noise
(50% bit flip)



Incomplete Memory



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Memory



Add noise
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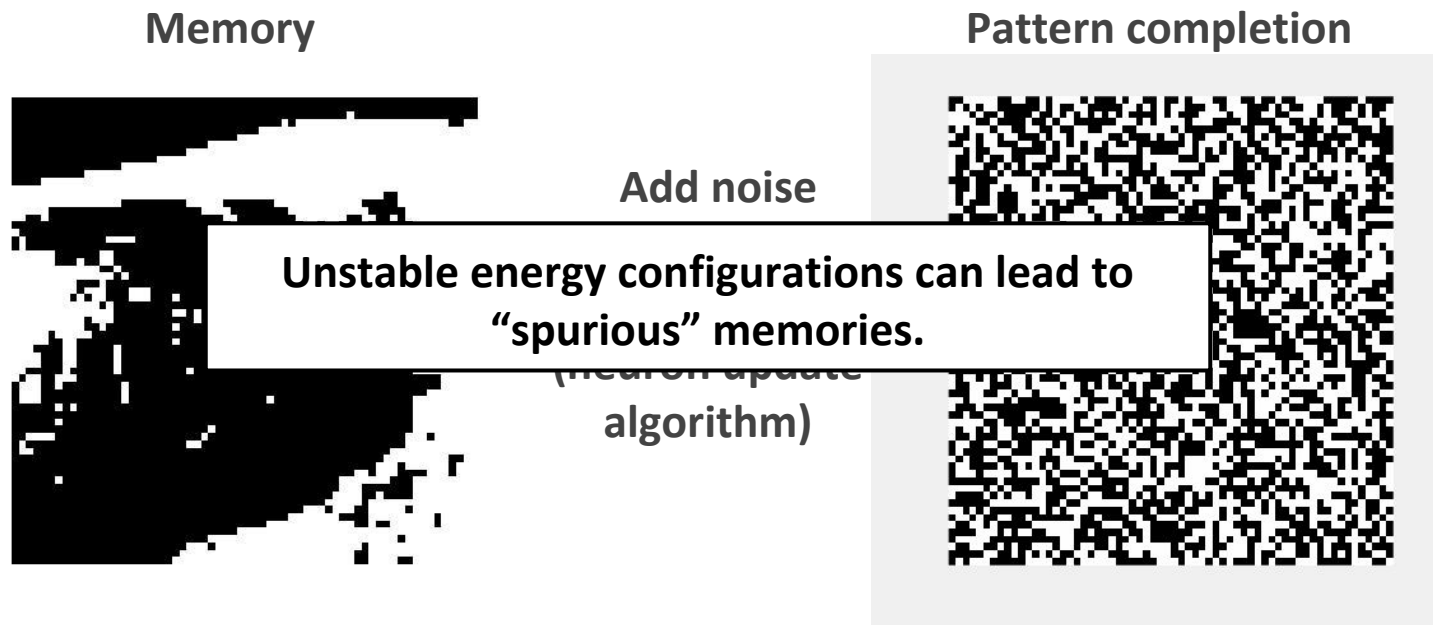
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Pattern completion



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Five neuron example

- Let's consider the case where we have a five node Hopfield net made up of 0's and 1's.

Five neuron example

- Let's consider the case where we have a five node Hopfield net made up of 0's and 1's.
- We will use the model system described in the paper.
 - Each node has two states: 0 when “not firing” and 1 when “firing”.

$$\begin{array}{l} V_i \rightarrow 1 \\ V_i \rightarrow 0 \end{array} \quad \text{if} \quad \sum_{j \neq i} T_{ij} V_j \quad \begin{array}{l} > U_i \\ < U_i \end{array} \quad . \quad [1]$$

- Suppose we want to store two patterns V^1 and V^2 .

$$V^1 = (0 \ 1 \ 1 \ 0 \ 1)$$

$$V^2 = (1 \ 0 \ 1 \ 0 \ 1)$$

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$$V^1 = (0 \ 1 \ 1 \ 0 \ 1)$$

$$V^2 = (1 \ 0 \ 1 \ 0 \ 1)$$

- We will use the prescribed information storage algorithm from Hopfield's paper.
 - Note: in this example we use 0's and 1's as did Hopfield in his paper. If we were to use -1's and 1's, the information algorithm simplifies.

$$T_{ij} = \sum_s (2V_i^s - 1)(2V_j^s - 1) \quad [2]$$

Weight Matrix

0	T_{12}	T_{13}	T_{14}	T_{15}
T_{21}	0	T_{23}	T_{24}	T_{25}
T_{31}	T_{32}	0	T_{34}	T_{35}
T_{41}	T_{42}	T_{43}	0	T_{45}
T_{51}	T_{52}	T_{53}	T_{54}	0

- Begin by calculating the upper diagonal for the first pattern:

$$\mathbf{V}^1 = (\mathbf{0} \ \mathbf{1} \ \mathbf{1} \ \mathbf{0} \ \mathbf{1})$$

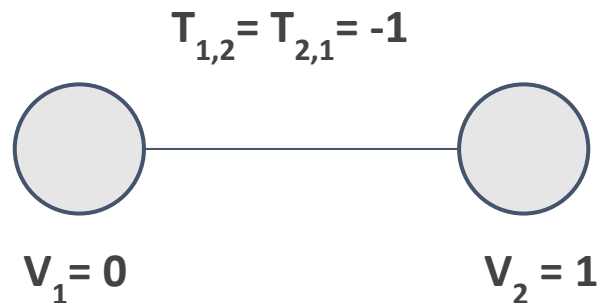
- Let's look at T_{12} .

$$T_{12} = (2\mathbf{V}_1 - 1)(2\mathbf{V}_2 - 1)$$

$$T_{12} = (2 * \mathbf{0} - 1)(2 * \mathbf{1} - 1)$$

$$T_{12} = (-1)(1)$$

$$T_{12} = -1$$



Weight Matrix

0	-1	T_{13}	T_{14}	T_{15}
-1	0	T_{23}	T_{24}	T_{25}
T_{31}	T_{32}	0	T_{34}	T_{35}
T_{41}	T_{42}	T_{43}	0	T_{45}
T_{51}	T_{52}	T_{53}	T_{54}	0

$$T_{13} = (2V_1 - 1)(2V_3 - 1) = (0 - 1)(2 - 1) = (-1)(1) = -1$$

$$T_{14} = (2V_1 - 1)(2V_4 - 1) = (0 - 1)(0 - 1) = (-1)(-1) = 1$$

$$T_{15} = (2V_1 - 1)(2V_5 - 1) = (0 - 1)(2 - 1) = (-1)(1) = -1$$

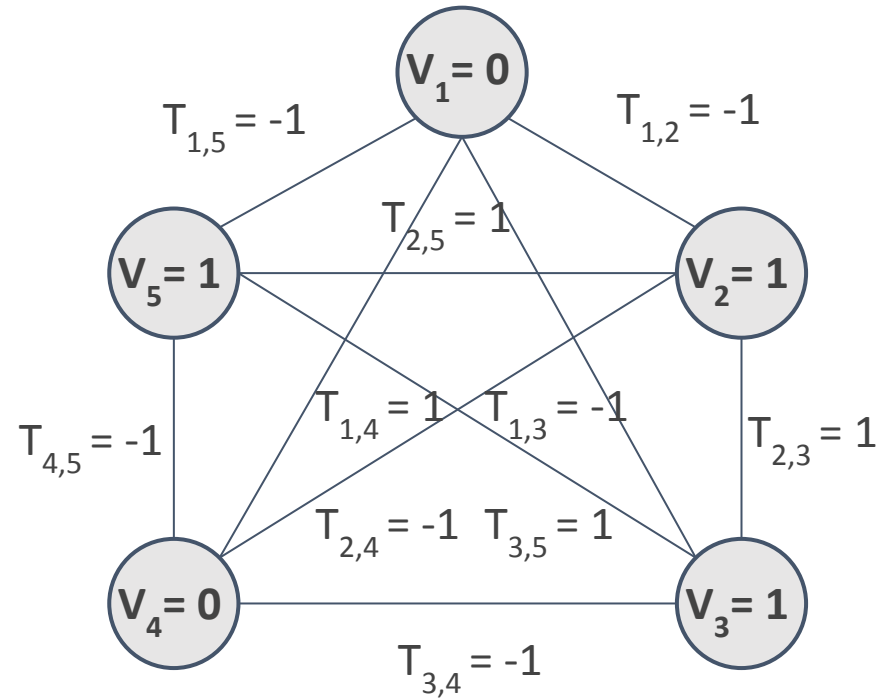
$$T_{23} = (2V_2 - 1)(2V_3 - 1) = (2 - 1)(2 - 1) = (1)(1) = 1$$

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$$T_{34} = (2V_3 - 1)(2V_4 - 1) = (2 - 1)(0 - 1) = (1)(-1) = -1$$

$$\mathbf{V}^1 = (0, 1, 1, 0, 1)$$



Weight Matrix

	0	-1	-1	1	-1
T_{21}	0	1	-1	1	
T_{31}	T_{32}	0	-1	1	
T_{41}	T_{42}	T_{43}	0	-1	
T_{51}	T_{52}	T_{53}	T_{54}	0	

- We know by the formula below, our weight matrix is symmetrical:

$$\mathbf{T}_{ij} = (2V_i - 1)(2V_j - 1) = (2V_j - 1)(2V_i - 1) = \mathbf{T}_{ji}$$

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$$T_{ij} = (2V_i - 1)(2V_j - 1) = (2V_j - 1)(2V_i - 1) = T_{ji}$$

- Thus, we can reflect and fill in the rest of the matrix.

$$\begin{array}{ccccc} 0 & -1 & -1 & 1 & -1 \\ -1 & 0 & 1 & -1 & 1 \\ -1 & 1 & 0 & -1 & 1 \\ 1 & -1 & -1 & 0 & -1 \\ -1 & 1 & 1 & -1 & 0 \end{array}$$

Now lets calculate the matrix for the second pattern:

$$\mathbf{V}^2 = (1 \ 0 \ 1 \ 0 \ 1)$$

$$T_{12} = (2V_1 - 1)(2V_2 - 1) = (2 - 1)(0 - 1) = (1)(-1) = -1$$

$$T_{13} = (2V_1 - 1)(2V_3 - 1) = (2 - 1)(2 - 1) = (1)(1) = 1$$

$$T_{14} = (2V_1 - 1)(2V_4 - 1) = (2 - 1)(0 - 1) = (1)(-1) = -1$$

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$$T_{35} = (2V_3 - 1)(2V_5 - 1) = (2 - 1)(2 - 1) = (1)(1) = 1$$

$$T_{45} = (2V_4 - 1)(2V_5 - 1) = (0 - 1)(2 - 1) = (-1)(1) = -1$$



$$\begin{matrix} 0 & -1 & 1 & -1 & 1 \\ -1 & 0 & -1 & 1 & -1 \\ 1 & -1 & 0 & -1 & 1 \\ -1 & 1 & -1 & 0 & -1 \\ 1 & -1 & 1 & -1 & 0 \end{matrix}$$

Now, as in [2], we add the matrices together to get a final weight matrix.

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Final Weight Matrix

0	-2	0	0	0
-2	0	0	0	0
0	0	0	-2	2
0	0	-2	0	-2
0	0	2	-2	0

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- The Hamming distance between the two patterns is 2. The smaller this distance, the harder it is to tell these patterns apart.
- As an analogy, consider how it might be more difficult to discriminate between an "O" and a "Q" as compared to two letters that are much different (i.e. have a greater hamming distance).

Updating the nodes

- Quite simply, to update the nodes of the Hopfield network you do a weighted sum of the inputs from the other nodes.
 - If the value is less than your threshold (in this case $U = 0$), you output 0.
 - Otherwise, the output is 1.
 - We will also make the stipulation that if the weighted sum = 0, the output is 1.
 - This is directly from [1] below:

$$\begin{array}{l} V_i \rightarrow 1 \\ V_i \rightarrow 0 \end{array} \quad \text{if} \quad \sum_{j \neq i} T_{ij} V_j \quad \begin{array}{l} > U_i \\ < U_i \end{array} \quad . \quad [1]$$

- **There are two ways to update the nodes:**
 - **Asynchronous:** one picks one neuron, calculates the weighted input sum and updates immediately. This can be done in a fixed order, or neurons can be picked at random, which is called asynchronous random updating
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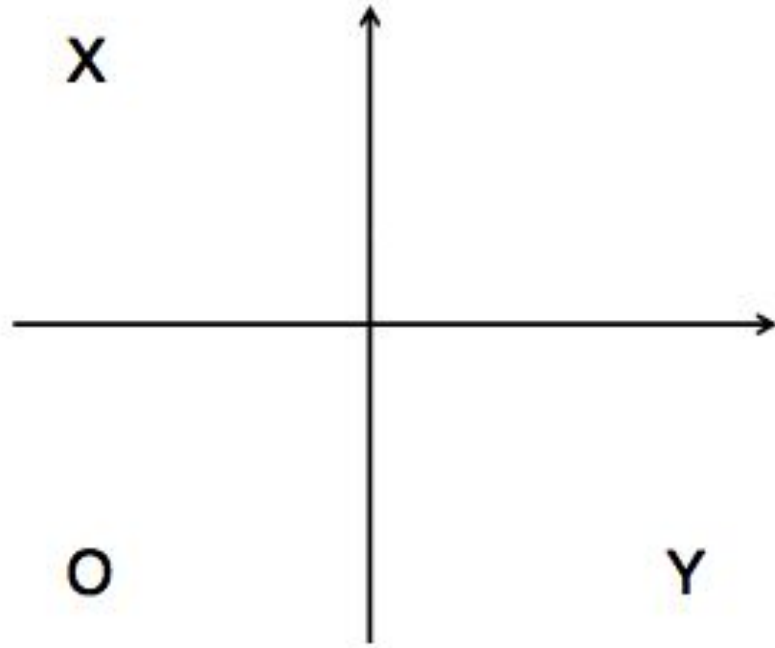
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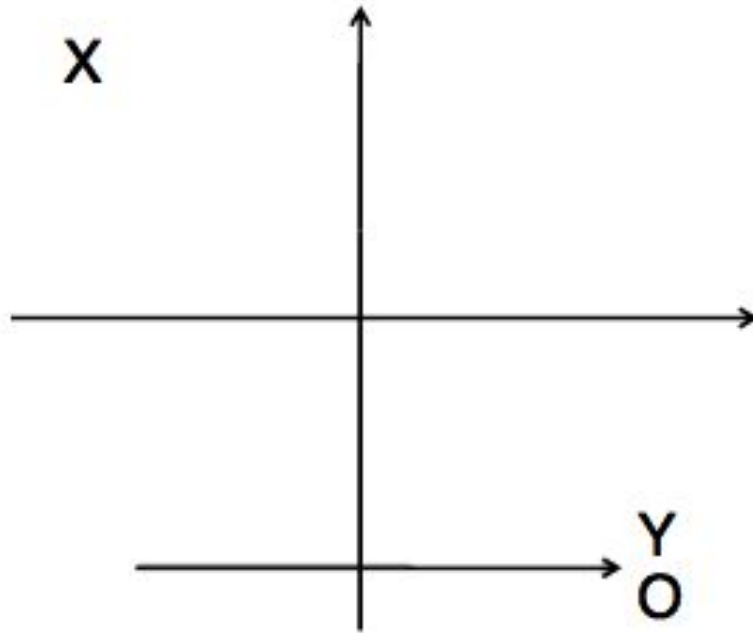
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- The original network proposed by Hopfield involved asynchronous processing where the nodes were randomly updated.
- Asynchronous processing is believed to better model how our neurons fire.
- Additionally, problems involving oscillatory states arise with synchronous updating.
- For the sake of simplicity, we will update the nodes one by one in order a fixed order **1, 5, 2, 4, 3**.

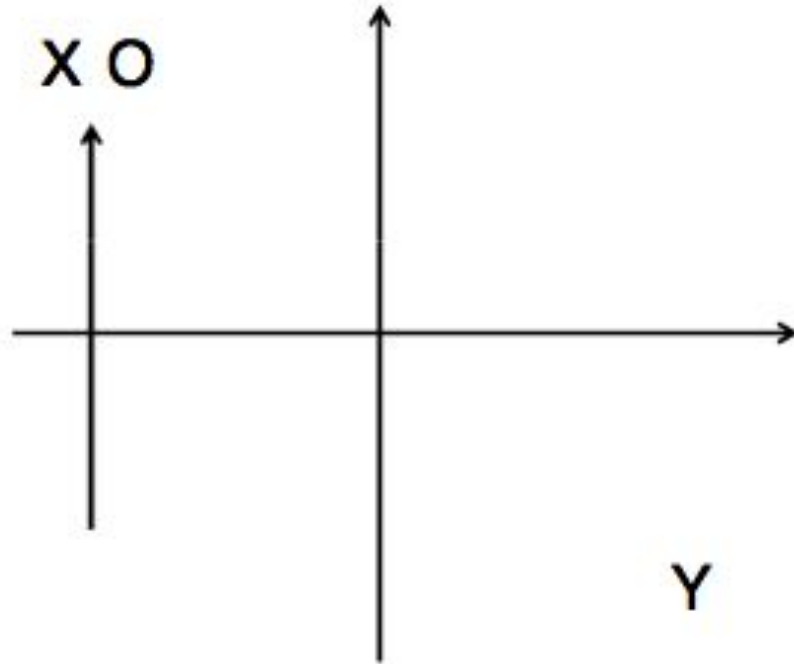
Asynchronous



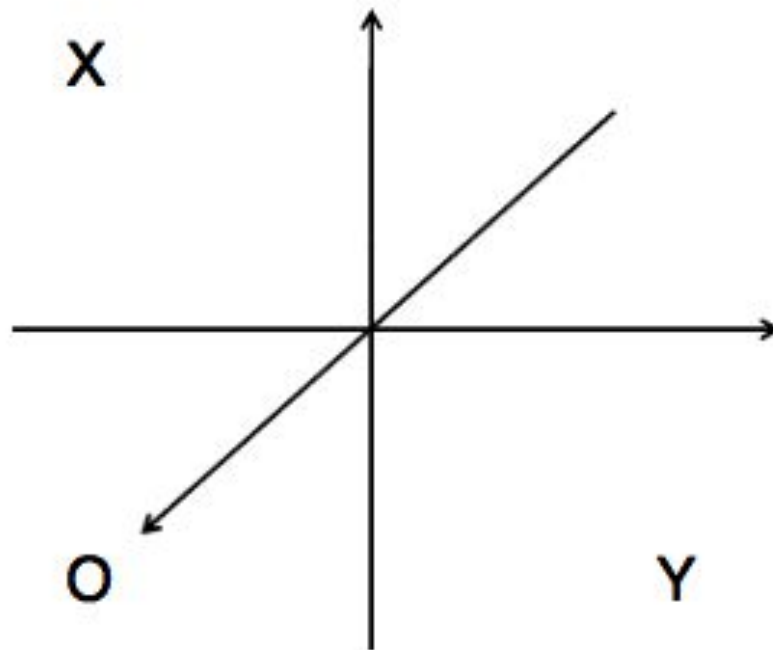
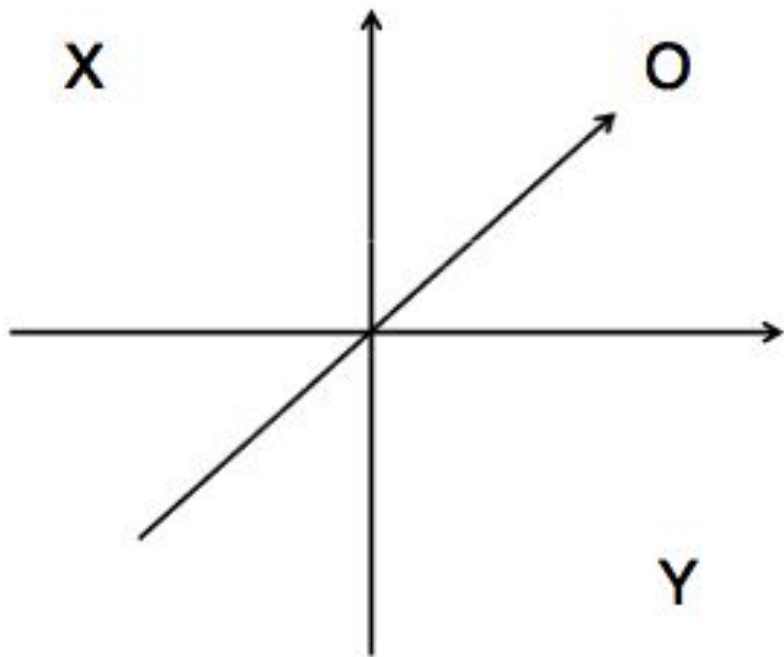
Asynchronous



Asynchronous



Synchronous



$$v_1^{in} = \sum w_{j1} v_j$$

$$= T_{21} V_1 + T_{31} V_2 + T_{41} V_4 + T_{51} V_5$$

$$= (-2*1) + (0*1) + (0*1) + (0*1)$$

$$= -2$$

-2 is less than threshold so **V1 = 0** and our current state = **(0 1 1 1 1)**

State = (0 1 1 1 1)

V_5 in = (0 0 2 -2 0) * (0 1 1 1 1) = 0

since $0 \geq 0$, $V_5 = 1$ (*it didn't change*)

State = (0 1 1 1 1)

$$\mathbf{V}_5 \mathbf{in} = (0 \ 0 \ 2 \ -2 \ 0) * (0 \ 1 \ 1 \ 1 \ 1) = 0$$

since $0 \geq 0$, $V_5 = 1$ (*it didn't change*)

State = (0 1 1 1 1)

$$\mathbf{V}_2 \mathbf{in} = (-2 \ 0 \ 0 \ 0 \ 0) * (0 \ 1 \ 1 \ 1 \ 1) = 0$$

since $0 \geq 0$, $V_2 = 1$ (*it didn't change*)

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State = (0 1 1 1 1)

$$\mathbf{V}_4 \mathbf{in} = (0 \ 0 \ -2 \ 0 \ -2) * (0 \ 1 \ 1 \ 1 \ 1) = -4$$

since $-4 < 0$, $V_4 = 0$ (*it changed*)

State = (0 1 1 1 1)

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State = (0 1 1 0 1)

$$\mathbf{V}_1 \mathbf{in} = (0 \ -2 \ 0 \ 0 \ 0) * (0 \ 1 \ 1 \ 0 \ 1) = -2$$

since $-2 < 0$, $V_1 = 0$ (*it didn't change*)

State = (0 1 1 1 1)

$$\mathbf{V}_5 \mathbf{in} = (0 \ 0 \ 2 \ -2 \ 0) * (0 \ 1 \ 1 \ 1 \ 1) = 0$$

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since $-4 < 0$, $V_4 = 0$ (*it didn't change*)

- We can stop when we cycle through all the nodes once and none of them change (thus the reason a fixed order was selected).
- The network ends up at the pattern **(0 1 1 0 1)**.
- In saying this, in this case the network will end up at a pre-learned pattern using a different fixed order of updating or if the nodes are updated randomly.

Energy Function

- Energy function [7] is derived from two-state Ising model:

$$E = -\frac{1}{2} \sum_{i \neq j} \sum T_{ij} V_i V_j . \quad [7]$$

- [8] can be derived from [7] by simple subtraction:

$$\Delta E = -\Delta V_i \sum_{j \neq i'} T_{ij} V_j . \quad [8]$$

$$\Delta E = -\Delta V_i \sum_{i \neq j} T_{ij} V_j$$

- A simple proof shows that ΔE in [8] is **never** > 0 .
- Consider the weighted sum describing the input to unit i :

$$\sum_{i \neq j} T_{ij} V_j$$

- **CASE 1:** The weighted sum is negative
 - Because the weighted sum is negative we know from [1] that V_i must be 0.

$$\begin{matrix} V_i \rightarrow 1 \\ V_i \rightarrow 0 \end{matrix} \quad \text{if} \quad \sum_{j \neq i} T_{ij} V_j \begin{matrix} > U_i \\ < U_i \end{matrix} \quad . \quad [1]$$

$$\Delta E = -\Delta V_i \sum_{i \neq j} T_{ij} V_j$$

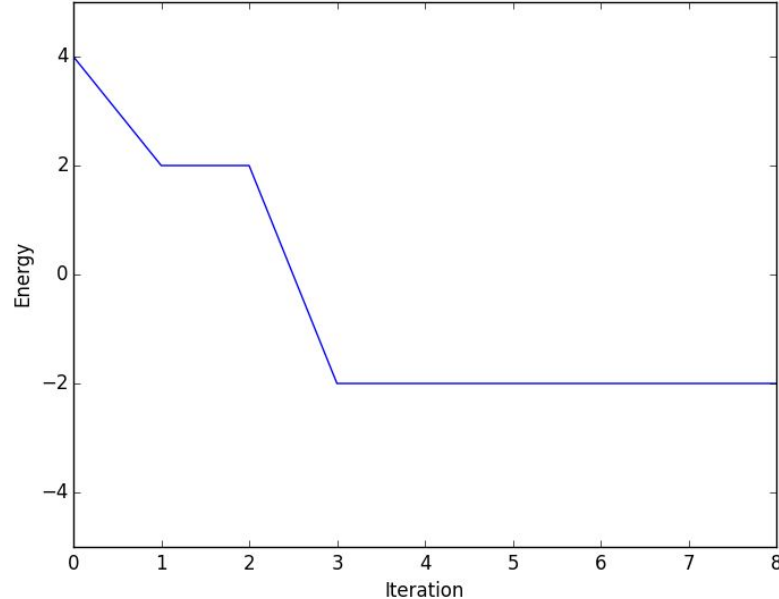
- Either it changed from a one to a zero and thus $V_i = -1$, or it was zero and remained so and thus $\Delta E = 0$.
- In the former case, the weighted sum is negative, V_i is negative, and there is a negative term in [8] and thus ΔE must be negative.
- **CASE 2:** The weighted sum is positive
 - Because the weighted sum is positive, via [1] V_i must be +1
 - V_i was either a one and remained so, and thus $\Delta E = 0$, or it was 0 and changed to +1. In the latter case, ΔV_i is positive, the weighted sum is positive, and we have a negative term in [8] and thus, ΔE must be negative.

- Going back to our example, let's calculate the energy following each update.

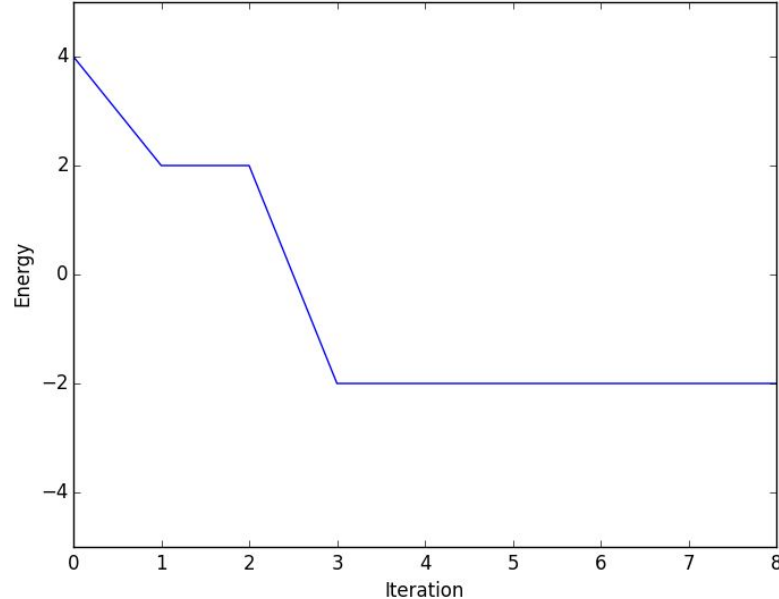
$$\bullet (-1/2) * \begin{bmatrix} 0 & -2 & 0 & 0 & 0 \\ -2 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & -2 & 2 \\ 0 & 0 & -2 & 0 & -2 \\ 0 & 0 & 2 & -2 & 0 \end{bmatrix} * \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} =$$

$$(-1/2)[(-2*1)+(-2*1)+(-2*1)+(2*1)+(-2*1)+(-2*1)+(2*1)+(-2*1)] = 4$$

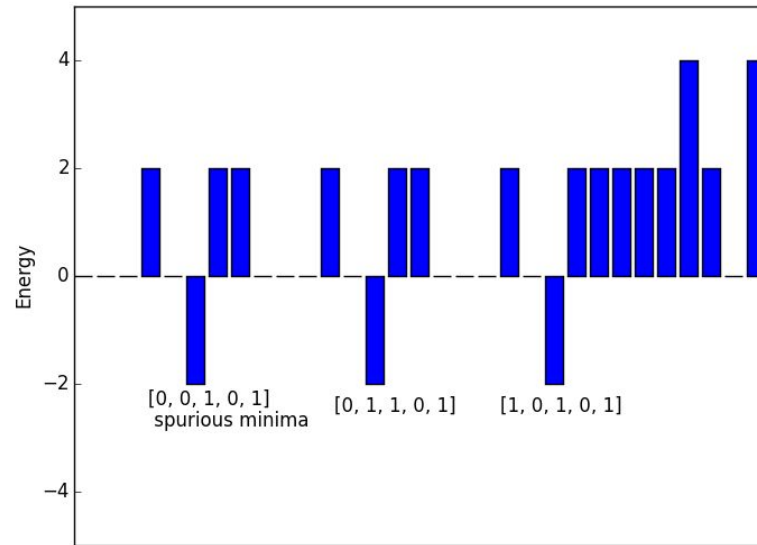
- Following this step, the state was **(0 1 1 1 1)**. For the sake of brevity:
 $E = 2.0$
- The final state was **(0 1 1 0 1)**. **$E = -2.0$ <- Minimum**



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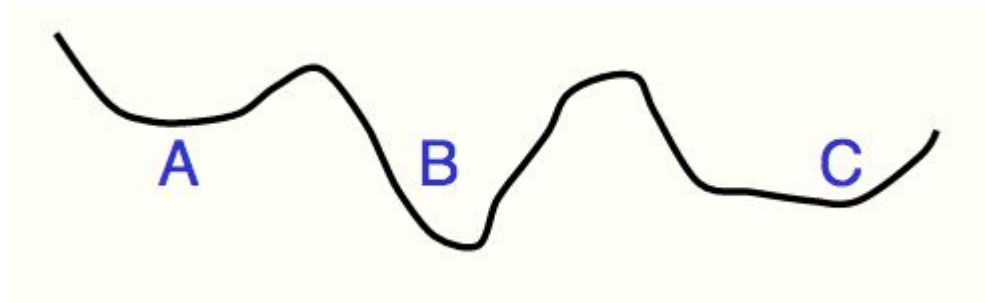


- Because our example was only five neurons (and thus 2^5 possible combinations), it is possible to represent the energy of all states.
- In doing so, you can see that the trained patterns are lowest in energy.
- Additionally, we have a spurious minima. It is worth noting this spurious minima occurs when **[0, 1, 1, 0, 1]** changes from **[0, 0, 1, 0, 1]** and thus, ΔE in this case is 0.



Local Minima

- Because a Hopfield net always makes decisions that lead to lower and lower energy, it makes it impossible to escape true local minima.
- In the figure below, B and C are learned patterns where A is not.
- If the state starts near state A and falls into A, it will be impossible with asynchronous updating to escape A and reach a trained pattern.

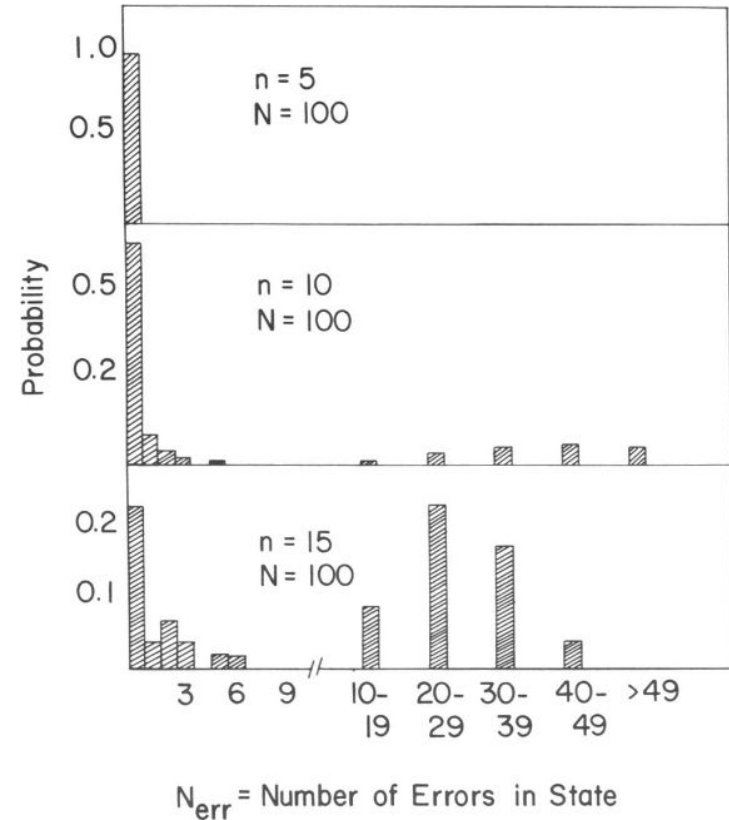


The memory capacity

- How many memories can a Hopfield network hold?

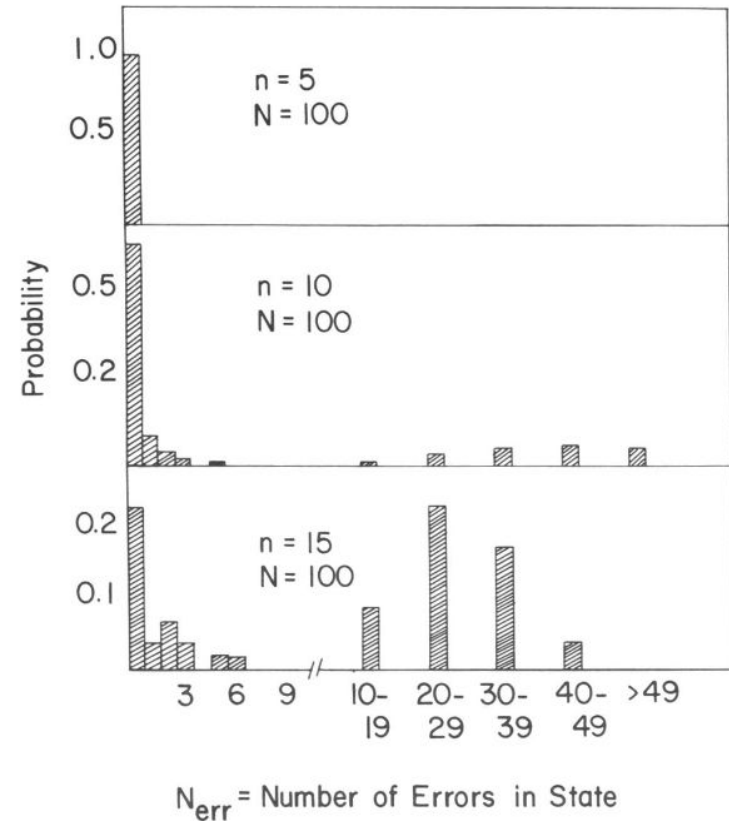
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The memory capacity

- How many memories can a Hopfield network hold?
- Empirical evidence suggests $0.15 * \#$ of neurons.
- The addition of new memories beyond the capacity overloads the network and makes all retrieval impossible.
- Clipping training weights to “forget” distant memories can prevent this from occurring.



Preventing “spurious” memories

- You can prevent two energy minima/memories from combining by “unlearning” spurious memories.
- Francis Crick proposed that this “unlearning” procedure could be what REM sleep is for; preventing spurious memory formation using random inputs from the thalamus.



JJ Hopfield. ‘Unlearning’ has a stabilizing effect in collective memories. Nature. 1983.

F Crick. The function of dream sleep. Nature. 1983.