

## Lecture 25

### The utility of the Laplace transform in solving ODE's

Recall that if  $f$  is a function on  $[0, \infty)$  which is piecewise continuous and is “ $a$ -nice,” i.e.,  $|f(t)| \leq ce^{at}$ , for large enough  $t$ , for a positive constant  $c$ , then its Laplace transform

$$\mathcal{L}(f(t)) = F(s) = \int_0^\infty f(t)e^{-st} dt \quad \left( = \lim_{A \rightarrow \infty} \int_0^A f(t)e^{-st} dt \right)$$

is well defined. (In fact,  $F(s)$  makes sense for any complex number  $s$  as long as  $\operatorname{Re}(s) > a$ .) Note:

$$\begin{aligned} \mathcal{L}(1) &= \int_0^\infty e^{-st} dt = \lim_{A \rightarrow \infty} \int_0^A e^{-st} dt = \lim_{A \rightarrow \infty} \left( \frac{e^{-st}}{-s} \right) \Big|_0^A \\ &= \lim_{A \rightarrow \infty} \left( -\frac{e^{-sA}}{s} + \frac{1}{s} \right) \\ &= \frac{1}{s}, \text{ since } e^{-sA} \rightarrow 0 \text{ as } A \rightarrow \infty, \text{ for } s > 0. \end{aligned}$$

An oft-used function is the Heaviside function  $u_c$  attached to any  $c > 0$ :

$$u_c(t) = \begin{cases} 1, & \text{if } t \geq c \\ 0, & \text{if } 0 \leq t < c \end{cases}$$

The Laplace transform of  $t^n$  can be calculated by using induction and integration by parts (using  $e^{-st} dt = -\frac{1}{s} d(e^{-st})$ ):

$$\mathcal{L}(t^n) = \int_0^\infty t^n e^{-st} dt = - \lim_{A \rightarrow \infty} \frac{1}{s} \left( t^n e^{-st} \Big|_0^A - n \int_0^A t^{n-1} e^{-st} dt \right) = \frac{n}{s} \mathcal{L}(t^{n-1}).$$

$f(t)$	$F(s) = \mathcal{L}(f(t))$
1	$\frac{1}{s}$ (for $s > 0$ )
$e^{at}$	$\frac{1}{s-a}$ ( $s > a$ )
$u_c(t)$	$\frac{e^{-at}}{s}$ (for $s > 0$ )
$e^{at} \cos(bt)$	$\frac{s-a}{(s-a)^2+b^2}$ (for $s > 0$ )
$e^{at} \sin(bt)$	$\frac{b}{(s-a)^2+b^2}$ ( $s > 0$ )
$t^n$ ( $n \geq 0$ )	$\frac{n!}{s^{n+1}}$ ( $n > 0$ )

### Important properties of $\mathcal{L}$

- 1)  $\mathcal{L}$  is linear, i.e.,  $\mathcal{L}(af + bg) = a\mathcal{L}(f) + b\mathcal{L}(g)$ , for all constants  $a, b$
- 2)  $\mathcal{L}(f(t)) = \frac{1}{c}F(\frac{s}{c})$ , if  $c > 0$  and  $F(s) = \mathcal{L}(f(t))$
- 3)  $\mathcal{L}(u_c(t)f(t-c)) = e^{-cs}\mathcal{L}(f(t))$  (check this!)
- 4) If  $f$  is *continuous* (not just piecewise continuous) and  $F(s) = 0$  for all  $s > M$ , for some  $M > 0$ , then  $f(t) = 0$  for all  $t$ .
- 5) Suppose  $f$  is  $n$ -times differentiable with  $f^{(n)}$  being piecewise continuous and  $a$ -nice, then

$$\mathcal{L}(f^{(n)}(t)) = s^n \mathcal{L}(f(t)) - s^{n-1}f(0) - s^{n-2}f'(0) - \dots - f^{(n-1)}(0).$$

### Consequence of 4) and 1):

Given *continuous* functions  $f, g$  on  $[0, \infty)$ , if  $F(s) = G(s)$  for all  $s > c$  for some  $c > 0$ , then  $f(t) = g(t)$ , for all  $t$ .

*Reason:* By 1),

$$\mathcal{L}(f(t) - g(t)) = \mathcal{L}(f(t)) - \mathcal{L}(g(t)) = F(s) - G(s),$$

which is 0 by hypothesis. So by 4),

$$f(t) - g(t) = 0, \quad \forall t.$$

Thanks to the consequence above,  $\mathcal{L}$  is a one-to-one linear transformation on the vector space of all continuous functions which are  $a$ -nice for some  $a > 0$ . Hence, it has an inverse, called the *inverse Laplace transformation*, and denoted  $\mathcal{L}^{-1}$ .

$\mathcal{L}^{-1}$  is also linear.

### Example

Consider the 1st order inhomogeneous ODE:

$$\frac{dy}{dt} - by = e^t, \quad y(0) = 0, \quad b \neq 1 \quad (*)$$

- (i) Recall: Before using  $\mathcal{L}$ , let us review how we solved this by our earlier methods. The homogeneous equation

$$\frac{dy}{dt} - by = 0$$

which has eigenvalue  $\lambda = b$ , has the general solution

$$y_c(t) = ce^{bt}, \quad \text{with } c : \text{ a constant.}$$

So the general solution of (\*) is:

$$y(t) = y_c(t) + y_p(t)$$

where  $y_p(t)$  is a particular solution of (\*). Try

$$\begin{aligned} y_p(t) &= Ae^t \\ \implies Ae^t - bAe^t &= e^t \\ \implies A &= \frac{1}{1-b}, \quad b \neq 1. \end{aligned}$$

So the general solution of (\*) is given by

$$y_p(t) = ce^{bt} + \frac{1}{1-b}e^t.$$

The initial condition is

$$\begin{aligned} y(0) &= 0 \\ \Rightarrow 0 &= c + \frac{1}{1-b} \\ c &= \frac{1}{b-1} \\ \Rightarrow y(t) &= \frac{1}{1-b}(e^{bt} - e^t) \end{aligned}$$

- (ii) Now let's see if we get the same result by using  $\mathcal{L}$ , assuming that  $y'$  is continuous. ( $f$  is continuous since it is differentiable.) Applying  $\mathcal{L}$  to both sides of (\*), we get, by the linearity of  $\mathcal{L}$ ,

$$\begin{aligned} \underbrace{\mathcal{L}(y')}_{sY(s)-y(0)} - b \underbrace{\mathcal{L}(y)}_{Y(s)} &= \underbrace{\mathcal{L}(e^t)}_{\frac{1}{s-1}, \text{ for } s>1} \\ \Rightarrow (s-b)Y(s) &= \frac{1}{s-1} \\ \Rightarrow Y(s) &= \frac{1}{(s-1)(s-b)} \end{aligned}$$

Applying  $\mathcal{L}$  to both sides, we get

$$y(t) = \mathcal{L}^{-1}(Y(s)) = \mathcal{L}^{-1}\left(\frac{1}{(s-1)(s-b)}\right)$$

*Idea:* Use partial fractions!

$$\begin{aligned} \frac{1}{(s-1)(s-b)} &= \frac{c_1}{s-1} + \frac{c_2}{s-b} \\ \Rightarrow 1 &= c_1(s-b) + c_2(s-1) \\ c_2 = -c_1 &= \frac{1}{b-1} \\ \frac{1}{(s-1)(s-b)} &= \frac{1}{b-1} \left( \frac{1}{s-b} - \frac{1}{s-1} \right) \\ y(t) &= \frac{1}{b-1} \left[ \mathcal{L}^{-1}\left(\frac{1}{s-b}\right) - \mathcal{L}^{-1}\left(\frac{1}{s-1}\right) \right] \Rightarrow y(t) = \frac{1}{b-1}(e^{bt} - e^t), \end{aligned}$$

since  $\mathcal{L}^{-1}\left(\frac{1}{s-a}\right) = e^{-at}$ .

### Post's formula for $\mathcal{L}^{-1}$

$$F(s) = \mathcal{L}(f(t))$$

$$\Rightarrow \mathcal{L}^{-1}(F(s)) = \lim_{n \rightarrow \infty} \frac{(-1)^n}{n!} \left(\frac{n}{t}\right)^{n+1} F^{(n)}\left(\frac{n}{t}\right)$$

### Example

Let  $F(s) = \frac{1}{s-a}$ . Let us make sure that this formula gives us the answer we know, namely  $f(t) = e^{at}$ .

$$\begin{aligned} F'(s) &= \frac{1}{(s-a)^2}, \dots, F^{(n)}(s) = \frac{(-1)^n n!}{(s-a)^{n+1}} \\ \Rightarrow f(t) &= \lim_{n \rightarrow \infty} \frac{(-1)^n}{n!} \left(\frac{n}{t}\right)^{n+1} \frac{(-1)^n n!}{\left(\frac{n}{t} - a\right)^{n+1}} \\ &= \lim_{n \rightarrow \infty} \frac{1}{\left(1 - \frac{at}{n}\right)^{n+1}} \\ \ln f(t) &= at \Rightarrow f(t) = e^{at}. \end{aligned}$$

## Lecture 26

We will discuss two more topics related the the Laplace transform method of solving ODE's:

- (i) Discontinuous forcing: This pertains to *inhomogeneous* ODE's of the form

$$y'' + p(x)y' + q(x) = F(x),$$

where  $F$  is not continuous, but piecewise continuous, for example a step function;

- (ii) Convolution of functions, which allows us to calculate the inverse Laplace transform of a product of two or more functions of  $s$ .

**Review of some basic and useful formulae:**

$$\mathcal{L}(1) = \frac{1}{s}$$

$$\mathcal{L}(u_c(t)) = \frac{e^{-cs}}{s}$$

$$\mathcal{L}(u_c f(t-c)) = e^{-cs} \mathcal{L}(f(t))$$

$$\mathcal{L}^{-1} \left( \frac{b}{(s-a)^2 + b^2} \right) = e^{at} \sin(bt) \quad (\text{a})$$

$$\mathcal{L}^{-1} \left( \frac{s-a}{(s-a)^2 + b^2} \right) = e^{at} \cos(bt) \quad (\text{b})$$

**Example:**

$$u'' + \frac{1}{4}u' + u = f(t), \quad u(0) = u'(0) = 0, \quad (*)$$

where

$$f(t) = u_{3/2}(t) - u_{5/2}(t).$$

Apply  $\mathcal{L}$  to both sides of (\*) to get (by the linearity of  $\mathcal{L}$ ):

$$\mathcal{L}(u'') + \frac{1}{4}\mathcal{L}(u') + \mathcal{L}(u) = \mathcal{L}(f(t))$$

$$\mathcal{L}(u') = s \underbrace{\mathcal{L}(u)}_{=U(s)} - \underbrace{u(0)}_{=0}$$

$$\mathcal{L}(u'') = s^2 \mathcal{L}(u) - \underbrace{su'(0) - u(0)}_{=0}$$

Get

$$U(s) \left( s^2 + \frac{1}{4}s + 1 \right) = F(s),$$

where

$$F(s) = \mathcal{L}(f(t)) = \mathcal{L}(u_{3/2}(t)) - \mathcal{L}(u_{5/2}(t)) = \frac{e^{-3s/2} - e^{-5s/2}}{s}.$$

$$\Rightarrow U(s) = \frac{e^{-3s/2} - e^{-5s/2}}{s(s^2 + \frac{1}{4}s + 1)}, \quad \text{if } s^2 + \frac{1}{4}s + 1 \neq 0.$$

The roots of  $s^2 + \frac{1}{4}s + 1$  are  $s = -\frac{1}{8} \pm \frac{1}{2}\sqrt{\frac{1}{16} - 4}$ , which are not real! Hence  $s^2 + \frac{1}{4}s + 1$  cannot be 0 for any real  $s$ .

Use partial fractions:

$$G(s) := \frac{1}{s(s^2 + \frac{1}{4}s + 1)} = \frac{A}{s} + \frac{Bs + C}{s^2 + \frac{1}{4}s + 1}.$$

Clearing the denominator,

$$\begin{aligned} 1 &= As^2 + \frac{1}{4}As + A + Bs^2 + Cs \\ 1 &= (A + B)s^2 + \left(\frac{1}{4}A + C\right)s + A \\ \Rightarrow A &= 1, \quad B = -A = -1, \quad C = -\frac{1}{4}A = -\frac{1}{4} \end{aligned}$$

Hence

$$G(s) = \frac{1}{s} - \frac{s + \frac{1}{4}}{s^2 + \frac{1}{4}s + 1}.$$

Recall that

$$\mathcal{L}^{-1}(e^{cs}G(s)) = u_c(t)g(t - c),$$

so that

$$\begin{aligned} u(t) &= \mathcal{L}^{-1}(U(s)) = \mathcal{L}^{-1}(e^{-3s/2}G(s)) - \mathcal{L}^{-1}(e^{-5s/2}G(s)) \\ &= u_{3/2}(t)f\left(t - \frac{3}{2}\right) - u_{5/2}(t)f\left(t - \frac{5}{2}\right) \end{aligned}$$

Need to find  $f$ , and for this we use formulae (a) and (b) from the previous page. It is left as an exercise to get the final explicit answer.

## Convolution

Suppose  $F(s) = \mathcal{L}(f(t))$  and  $G(s) = \mathcal{L}(g(t))$  in  $s > a \geq 0$ . Put

$$H(s) = F(s)G(s).$$

**Question:** Can we find a function  $h(t)$  st  $H(s) = \mathcal{L}(h(t))$  for  $s > a$ ? In other words,

*What is  $\mathcal{L}^{-1}(F(s)G(s))$ ?*

**Answer:** Yes.  $h(t)$  is the “convolution” of  $f$  and  $g$ , denoted  $f * g$ .

**Definition:**

$$h(t) = (f * g)(t) = \int_0^t f(t-u)g(u)du$$

which also equals

$$\int_0^t f(u)g(t-u)du.$$

These two integral expressions are equal because we can use change of variables:  $v = t - u$ ,  $dv = -du$ , yielding

$$\int_0^t f(t-u)g(u)du = - \int_t^0 f(v)g(t-v)dv = \int_0^t f(v)g(t-v)dv$$

$\Rightarrow f * g = g * f$  (commutativity of convolution)

**Examples:**

1.  $(f * 1)(t) = \int_0^t f(t-u)du = \int_0^t f(u)du.$

In particular,  $(1 * 1)(t) = t \neq 1$

2.  $f = \sin t,$

$$(f * 1)(t) = \int_0^t \sin u du = -\cos u|_0^t = 1 - \cos t$$

3.  $f * f$  need not be  $\geq 0$ . For example, if  $f = \sin(t)$ , then

$$\begin{aligned}(f * f)(t) &= \int_0^t \sin(t-u)\sin(u)du \\ &= \frac{1}{2}(\sin t - t \cos t),\end{aligned}$$

which is negative at  $t = 2n\pi$ , for any positive integer  $n$ .



### Reason for importance of convolution to the solving of ODE's

Given

$$y'' + ay' + by = f(x), \quad y(0) = y'(0) = 0,$$

with  $a, b$  constants, apply  $\mathcal{L}$  to both sides to get

$$Y(s)(s^2 + as + b) = F(s),$$

so that for  $s$  large enough so that  $s^2 + as + b \neq 0$ ,

$$Y(s) = F(s)G(s), \quad \text{where } G(s) = \frac{1}{s^2 + as + b}.$$

By using partial fractions and the formulae from an earlier page, we can find  $g(t)$  such that  $G(s)$  is the Laplace transform of  $g(t)$ . This implies that

$$y(t) = \mathcal{L}^{-1}(F(s)G(s)) = (f * g)(t).$$

This method is also useful, if applied with care, when  $a, b$  are not constants.

**Example:**

$$y'' + 2y' + 2y = \sin(\omega t), \quad y(0) = y'(0) = 0,$$

where  $\omega$  is called the *forcing frequency* (or external frequency).

Apply  $\mathcal{L}$  to both sides, and use the linearity of  $\mathcal{L}$ , to obtain, with  $f(t) = \sin \omega t$ ,

$$\begin{aligned} Y(s)(s^2 + 2s + 2) &= \mathcal{L}(\sin \omega t) = F(s) \\ s^2 + s + 2 &= (s^2 + 2s + 1) + 1 \\ &= (s + 1)^2 + 1 \geq 1 \end{aligned}$$

$$\Rightarrow Y(s) = F(s)G(s), \quad \text{with } G(s) = \frac{1}{(s + 1)^2 + 1}$$

$$g(t) = \mathcal{L}^{-1}\left(\frac{1}{(s + 1)^2 + 1}\right) = e^{-t} \sin t$$

$$\Rightarrow y(t) = \text{convolution of } f(t) = \sin \omega t \text{ and } g(t) = e^{-t} \sin t$$

$$y(t) = \int_0^t f(t - u)g(u)du = \int_0^t \sin(\omega(t - u))e^{-u} \sin u du.$$

The integral on the right can be explicitly calculated using the addition formula

$$\sin A \sin B = \frac{1}{2} [\cos(A - B) - \cos(A + B)],$$

and integration by parts.

Note that we did not use here our prior knowledge that  $F(s) = \frac{\omega}{s^2 + \omega^2}$ .