# The prism manifold realization problem III 

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#### Abstract

Every prism manifold can be parametrized by a pair of relatively prime integers $p>1$ and $q$. In our earlier papers, we determined a complete list of prism manifolds $P(p, q)$ that can be realized by positive integral surgeries on knots in $S^{3}$ when $q<0$ or $q>p$; in the present work, we solve the case when $0<q<p$. This completes the solution of the realization problem for prism manifolds.


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## 1 | INTRODUCTION

Let $P(p, q)$ be an oriented prism manifold with Seifert invariants

$$
(-1 ;(2,1),(2,1),(p, q)),
$$

where $q$ and $p>1$ are relatively prime integers. See [1, Section 2] for the convention of Seifert invariants and basic topological properties of prism manifolds. In [1, 2], we solved the Dehn surgery realization problem of prism manifolds for $q<0$ and for $q>p$. The theme of the present work is to settle the remaining case $0<q<p$. In [1, Tables 1 and 2], the authors give a tabulation of prism manifolds that can be obtained by positive integral Dehn surgery on Berge-Kang knots [4]. The tables conjecturally account for all realizable prism manifolds; in particular, [1, Table 2] suggests that for a realizable $P(p, q)$ with $q>0$, we must have $p \leqslant 2 q+1$. Indeed, this is the case:

[^0]TABLE $1 \mathcal{P}$, table of $P(p, q)$ that are realizable

| Type | $\boldsymbol{P}(\boldsymbol{p}, \boldsymbol{q})($ let $\boldsymbol{P}(-\boldsymbol{p},-\boldsymbol{q})=\boldsymbol{P}(\boldsymbol{p}, \boldsymbol{q})$ ) | Range of parameters ( $p$ and $r$ are always odd, $\|p\|>1$ ) |
| :---: | :---: | :---: |
| 1A | $P\left(p,-\frac{1}{2}\left(p^{2}-3 p+4\right)\right)$ | $p \neq 3,5$ |
| 1B | $P\left(p,-\frac{1}{22}\left(p^{2}-3 p+4\right)\right)$ | $\begin{aligned} & p \equiv 17 \text { or } 19(\bmod 22) \\ & \|p\|>22 \end{aligned}$ |
| 2 | $P\left(p,-\frac{1}{\|4 r+2\|}\left\|r^{2} p+1\right\|\right)$ | $\begin{aligned} & p \equiv 2 r-3(\bmod 4 r+2) \\ & r \equiv-1(\bmod 4) \\ & r \neq-1,3 \end{aligned}$ |
| 3A | $P\left(p,-\frac{1}{2 r}(p+1)(p+4)\right)$ | $\begin{aligned} & p \equiv-1(\bmod 2 r) \\ & r \geqslant 1 \text { and } p \geqslant 4 r-1 \text { if } p>0 \\ & r \geqslant 5 \text { and } p \leqslant-4 r-1 \text { if } p<0 \end{aligned}$ |
| 3B | $P\left(p,-\frac{1}{2 r}(p+1)(p+4)\right)$ | $\begin{aligned} & p \equiv r-4(\bmod 2 r) \\ & r \geqslant 5 \text { and } p \geqslant 3 r-4 \text { if } p>0 \\ & r \geqslant 1 \text { and } p \leqslant-3 r-4 \text { if } p<0 \end{aligned}$ |
| 4 | $P\left(p,-\frac{1}{2 r^{2}}\left\|(2 r+1)^{2} p+1\right\|\right)$ | $\begin{aligned} & p \equiv 4 r-1\left(\bmod 2 r^{2}\right) \\ & r \neq-3,-1,1 \end{aligned}$ |
| 5 | $P\left(p,-\frac{1}{r^{2}-2 r-1}\left\|r^{2} p+1\right\|\right)$ | $\begin{aligned} & p \equiv 2 r-5\left(\bmod r^{2}-2 r-1\right) \\ & r \neq 1 \end{aligned}$ |
| Sporadic | $\begin{aligned} & P(11,-30), P(17,-31) \\ & \quad P(13,-47), P(23,-64) \\ & P(11,19), P(13,34) \end{aligned}$ |  |

Theorem 1.1. If $P(p, q)$ with $q>0$ can be obtained by surgery on a knot $K \subset S^{3}$, then $p \leqslant 2 q+1$. If $p=2 q+1$, then $K$ is the torus knot $T(2 q+1,2)$.

Doig, in [7, Conjecture 12], conjectured that if $P(p, q)$ is realizable, then $p \leqslant 2|q|+1$. The main result of [1] settles the conjecture for $q<0$; Theorem 1.1 verifies it for $q>0$.

Our second main result, Theorem 1.2, provides the solution of the realization problem for those $P(p, q)$ with $q<p<2 q$.

Theorem 1.2. The prism manifold $P(p, q)$ with $q<p<2 q$ can be obtained by $4 q$-surgery on a knot $K \subset S^{3}$ if and only if $q=\frac{1}{r^{2}-2 r-1}\left(r^{2} p-1\right)$, with $r \leqslant-3$ odd and $p \equiv-2 r+5\left(\bmod r^{2}-2 r-1\right)$, $p \geqslant-2 r+5$. Moreover, in this case, there exists a Berge-Kang knot $K_{0}$ such that $P(p, q) \cong S_{4 q}^{3}\left(K_{0}\right)$, and that $K$ and $K_{0}$ have isomorphic knot Floer homology groups.

Remark 1.3. If we allow $r=-1$ in Theorem 1.2, we get $p=2 q+1$ : see Theorem 1.1.

## 1.1 | The complete list of realizable prism manifolds

Theorems 1.1 and 1.2 and our earlier results [1, 2] give a complete classification of prism manifolds which can be obtained by Dehn surgery on knots in $S^{3}$. These prism manifolds are tabulated in Table 1.

Remark 1.4. Table 1 is essentially the union of [1, Table 1 and Table 2], with input of the range of parameters from [2, Table 2] and Theorem 1.2. There are two differences from [1, Table 2]. The first difference is that we adapt the convention that $P(-p,-q)=P(p, q)$ in the table, so that the cases $p q>0$ and $p q<0$ can be unified in one expression. The second difference is that we move the family $P\left(p,-\frac{25 p+1}{18}\right), p<0$, from Type 4 to Type 2 , so that the ranges of $r$ are the same despite of the sign of $p q$.

Remark 1.5. In the arXiv version of [1], for each prism manifold in Table 1, we listed a BergeKang knot realizing the corresponding surgery following the work of Berge-Kang [4]. However, since Berge-Kang's work is not publicly available, we did not include this list of Berge-Kang knots in the published version of [1]. An explicit list of primitive/Seifert-fibered knots admitting prism manifold surgeries was given in [21], independent of [4]. The existence of such Berge-Kang knots now follows from [21].

Remark 1.6. In Table 1, we divide the surgeries into six different types so that no surgery appears in more than one type. However, a prism manifold may appear in different types, in the sense that it arises from multiple changemaker vectors and it is obtained from surgeries on Berge-Kang knots belonging to different families. Such prism manifolds are the two infinite families

$$
P(8 s+3,-(16 s+14)) \text { and } P(8 s+13,16 s+18), \quad s \geqslant 0,
$$

and

$$
P(11,-18), P(5,22), P(25,36), P(43,117) .
$$

(The two infinite families are essentially the same family, if we allow $s<0$ and the surgery slope to be negative.) More information about these surgeries can be found in [1, Table 3] and [2, Table 3].

## 1.2 | The spherical manifold realization problem

The spherical manifold realization problem asks which spherical manifolds arise from positive integral surgery along a knot in $S^{3}$. Theorems 1.1 and 1.2 and our earlier results [1, 2], combined with Gu's work [11] and Greene's work [9], provide a complete classification of realizable spherical manifolds. The interest is in finding a complete classification of knots in $S^{3}$ on which Dehn surgery produce spherical manifolds. In [3], Berge proposed a complete list of knots in $S^{3}$ with lens space surgeries. Indeed, Berge's conjecture states that the $P / P$ knots form a complete list of knots in $S^{3}$ that admit lens space surgeries. All the known examples of knots on which surgeries will result in non-lens space spherical manifolds are $P / S F$ knots. We repeat the following conjecture from $[1$, Conjecture 1.7]: it is a generalization of Berge's conjecture.

Conjecture 1.7. Let $K$ be a knot in $S^{3}$ that admits an integral surgery to a spherical manifold. Then $K$ is either a $P / S F$ or a $P / P$ knot.

## 1.3 | Methodology

We first provide a brief overview of the methodology undertaken to solve the prism manifold realization problem in the cases $q<0$ and $q>p$ : the proof in both cases draws inspiration from that of Greene for lens spaces [9]. We then discuss how (and why) the methodology is modified for the case of the present work.

We first require a combinatorial definition.
Definition 1.8. A vector $\sigma=\left(\sigma_{0}, \sigma_{1}, \ldots, \sigma_{n+1}\right) \in \mathbb{Z}^{n+2}$ that satisfies $0 \leqslant \sigma_{0} \leqslant \sigma_{1} \leqslant \cdots \leqslant \sigma_{n+1}$ is a changemaker vector if for every $k$, with $0 \leqslant k \leqslant \sigma_{0}+\sigma_{1}+\cdots+\sigma_{n+1}$, there exists a subset $S \subset$ $\{0,1, \ldots, n+1\}$ such that $k=\sum_{i \in S} \sigma_{i}$.

The key idea is to use the correction terms in Heegaard Floer homology in tandem with Donaldson's Theorem A. The following is immediate from [9, Theorem 3.3].

Theorem 1.9. Suppose that $P(p, q)$ bounds a sharp four-manifold $X(p, q)$. If $P(p, q)$ arises from positive integer surgery on a knot $K$ in $S^{3}$, then the intersection lattice on $X(p, q)$ embeds as the orthogonal complement $\sigma^{\perp}$ of some changemaker vector $\sigma \in \mathbb{Z}^{n+2}$, with $n+1=b_{2}(X)$.

See Section 5 for the definition of a sharp four-manifold, and see Subsection 1.4 for the definition of the intersection lattice. When $q<0$ or $q>p$, it turns out that $P(p, q)$ bounds a sharp four-manifold $X(p, q)$. We then solved a combinatorial problem: we classified all lattices isomorphic to the intersection lattice of $X(p, q)$, whose complements are changemakers in $\mathbb{Z}^{n+2}$. There is a heavy analysis of lattices involved that forms the main body of [1, 2]. Finally, we verified that for every $(p, q)$ corresponding to such a lattice, $P(p, q)$ is indeed realized by surgery on a P/SF knot.

We now turn our attention to the case $0<q<p$. In light of Theorem 1.1, it suffices to consider $q<p<2 q$. When $q<p<2 q, P(p, q)$ does not bound a sharp four-manifold. Thus, we cannot use the embedding restriction of Theorem 1.9 - an essential step to the classification of realizable prism manifolds in the previous two cases. Our strategy to prove Theorem 1.2 is to replace Theorem 1.9 with another lattice theoretic obstruction for $P(p, q)$ to being realizable, as follows. The prism manifold $P(2,1)$ bounds a rational homology four-ball $Z_{2}$ (the left two components of Figure 2 where the 0 -framed unknot is replaced by a dotted circle and $a_{-1}=2$ ); and that there exists a negative definite cobordism $W$ from $P(2,1)$ to $P(p, q)$ (the right $n+1$ components of Figure 2). Suppose that $P(p, q)$ arises from surgery on a knot $K \subset S^{3}$, and let $W_{4 q}=W_{4 q}(K)$ be the corresponding two-handle cobordism obtained by attaching a two-handle to the four-ball along the knot $K$ with framing $4 q$. Form $Z:=Z_{2} \cup_{P(2,1)} W$; it will be a smooth four-manifold with boundary $P(p, q)$. The intersection lattice on $Z$ is $\Lambda(q,-p)$, which is defined in Definition 3.1. Form $X:=W \cup\left(-W_{4 q}\right)$. We prove that the intersection lattice on $X$ is isomorphic to $D_{4} \oplus \mathbb{Z}^{n-2}$, where $D_{4}$ is the sublattice of $\mathbb{Z}^{4}$ consisting of vectors the sum of whose coordinates is even. Finally, form $\widehat{X}:=Z \cup\left(-W_{4 q}\right)$; see Figure 1. It follows that $\widehat{X}$ is a smooth, closed, simply connected, negative definite four-manifold with $b_{2}(Z)=n+2$ for some $n \geqslant 0$. Now, Donaldson's Theorem A [8] implies that the intersection lattice on $\widehat{X}$ is the Euclidean integer lattice $\mathbb{Z}^{n+2}$. This provides a necessary condition for $P(p, q)$ to be realizable: the lattice $\Lambda(q,-p)$ embeds as a codimension one sublattice of $\mathbb{Z}^{n+2}$. Our new obstruction now reads as follows:


FIGURE 1 Schematic picture of the closed four-manifold $\widehat{X}=Z_{2} \cup W \cup-W_{4 q}$. We have $X=W \cup_{P(p, q)}-W_{4 q}, Z=Z_{2} \cup_{P(2,1)} W$

Theorem 1.10. Suppose $P(p, q)$ with $q<p<2 q$ arises from positive integer surgery on a knot $K$ in $S^{3}$.
(a) The linear lattice $\Lambda(q,-p)$ embeds as the orthogonal complement to a changemaker $\sigma \in$ $\mathbb{Z}^{n+2}, n+1=b_{2}(Z)$.
(b) There is an embedding of $D_{4} \oplus \mathbb{Z}^{n-2}$ into $\mathbb{Z}^{n+2}$ such that there exists some short characteristic covector $\chi$ for $D_{4} \oplus \mathbb{Z}^{n-2}$ with $\langle\chi, \sigma\rangle=i$ if and only if $-2 q+g(K) \leqslant i \leqslant 2 q-g(K)$.

The strategy is now apparent: determine the list of all pairs $(p, q)$ which pass the embedding restriction of Theorem 1.10. Finally, we verify that every manifold in our list is indeed realized by a knot surgery: we do so by comparing the list with the list of realizable manifolds tabulated in [1, Table 2]. The fact that the manifolds in [1, Table 2] are realizable is proved in [21]. It must be noted that Part (a) of Theorem 1.10 only provides a necessary condition for the prism manifold $P(p, q)$ to be realizable. Indeed, it is easy to find pairs $(p, q)$ that satisfy Part (a) of Theorem 1.10, but the corresponding prism manifolds are not realizable; for example, $P(13,9)$ and $P(16,9)$. The 9 -surgery on the torus knot $T(2,5)$ is $L(9,13) \cong L(9,16)$, then work of Greene [9] shows that the corresponding linear lattice satisfies Part (a) of Theorem 1.10. However, the manifold $P(16,9)$ is not realizable because of the parity of 16 ( $p$ is always odd for a realizable $P(p, q)[1]$ ); and neither is $P(13,9)$ by Theorem 1.2.

In the previous cases $q<0$ and $q>p$ as well as in the lens space realization problem [9], the first step was finding a sharp four-manifold bounded by $P(p, q)$ (respectively, the lens space $L(p, q))$ : in each case, a negative definite four-manifold was found; then it was almost immediate from the previous works of Ozsváth and Szabó $[16,18]$ that the four-manifold is sharp. For the case at hand, however, $P(p, q)$ does not bound a sharp four-manifold. We need to carefully analyze the d-invariants of $P(p, q)$ in each Spin $^{c}$ structure in terms of the d-invariants of certain Spin ${ }^{c}$ structures of $P(2,1)$ and the grading shift of the cobordism $W$. In particular, we generalize the notion of sharpness to cobordisms between rational homology spheres, and show that the cobordism $W$ is sharp (Proposition 5.3): again, see Figure 1. Using that the intersection lattice on $X$ is isomorphic to $D^{4} \oplus \mathbb{Z}^{n-2}$, it will be immediate that $X$ is a sharp four-manifold (Corollary 6.4). Using this finding, we are able to prove Theorem 1.10 and translate it into a more practical condition on the changemaker vector $\sigma$ (Proposition 6.11).

## 1.4 | Notations

We use homology groups with integer coefficients throughout the paper. For a compact fourmanifold $X$, regard $H_{2}(X)$ as equipped with the intersection pairing $Q_{X}$ on $X$. Also, we refer to $\left(H_{2}(X),-Q_{X}\right)$ as the intersection lattice on $X$, where $-Q_{X}$ denotes the negation of the pairing of
$Q_{X}$. Finally, we call an oriented three-manifold $Y$ a realizable manifold if it can be obtained by positive integral surgery on a knot in $S^{3}$.

## 1.5 | Organization

This paper is organized as follows. In Section 2, we prove Theorem 1.1, thus solve the case of the realization problem when $2 q<p$. In Section 3, we collect some basic results about linear lattices and changemaker lattices from [9]. In Section 4, we study the topology of a certain type of cobordism between rational homology 3-spheres. In Section 5, we define sharp cobordisms, and prove that the cobordism $W$ between $P(2,1)$ and $P(p, q)$ is sharp. In Section 6 , we use the result in Section 5 to prove a strengthened changemaker condition in the case $q<p<2 q$. In Sections 7 and 8, we use the strengthened changemaker condition to enumerate all the possible changemaker lattices we can have. In Section 9, we determine the pairs ( $p, q$ ) corresponding to the changemaker lattices, thus finish the proof of Theorem 1.2.

## 2 | PROOF OF THEOREM 1.1

The goal of this section is to prove the following upper bound of $p$, and then to prove Theorem 1.1. Recall that we assume $q>0$.

Proposition 2.1. If $P(p, q)$ is realizable, then $p \leqslant 2 q+1$.
Remark 2.2. If $P(p, q)$ is realizable with $p=2|q| \pm 1$, then $K$ must be a torus knot [14, Theorem 1.6]. Recall that for a realizable $P(p, q), p$ is odd [1]. In particular, if we restrict attention to hyperbolic knots on which surgeries will result in $P(p, q)$, then $p \leqslant 2|q|-3$.

### 2.1 The Casson-Walker invariant of $\boldsymbol{P}(\boldsymbol{p}, \boldsymbol{q})$

Let

$$
\begin{equation*}
\Delta_{K}(T)=\alpha_{0}+\sum_{i>0} \alpha_{i}\left(T^{i}+T^{-i}\right) \tag{1}
\end{equation*}
$$

be the normalized Alexander polynomial of $K$. If $K$ admits an L-space surgery, then $\left|\alpha_{i}\right| \leqslant 1$, $\alpha_{g(K)}=1$, and +1 and -1 appear alternatingly among the non-zero $\alpha_{i}$ [17, Theorem 1.2].

Given a real number $x$, let $\{x\}=x-\lfloor x\rfloor$ be the fractional part of $x$. Given a pair of coprime integers $n$, $m$ with $n>0$, let $\mathbf{s}(m, n)$ be the Dedekind sum

$$
\mathbf{s}(m, n)=\sum_{i=1}^{n-1}\left(\left(\frac{i}{n}\right)\right)\left(\left(\frac{i m}{n}\right)\right)
$$

where

$$
((x))= \begin{cases}\{x\}-\frac{1}{2}, & \text { if } x \in \mathbb{R} \backslash \mathbb{Z} \\ 0, & \text { if } x \in \mathbb{Z}\end{cases}
$$

Let $\lambda(\cdot)$ be the Casson-Walker invariant [22], normalized so that

$$
\lambda\left(S_{1}^{3}(T(3,2))\right)=2 .
$$

By [12, Proposition 6.1.1], the Casson-Walker invariant of $P(p, q)$ can be computed by the formula

$$
\lambda(P(p, q))=\frac{1}{12}\left(-\frac{p}{q}\left(\frac{1}{p^{2}}-\frac{1}{2}\right)-\frac{q}{p}+3+12 \mathbf{s}(q, p)\right) .
$$

Since the Dedekind sum satisfies the reciprocity law

$$
\mathbf{s}(q, p)+\mathbf{s}(p, q)=\frac{1}{12}\left(\frac{p}{q}+\frac{q}{p}+\frac{1}{p q}\right)-\frac{1}{4},
$$

we get

$$
\begin{equation*}
\lambda(P(p, q))=\frac{p}{8 q}-\mathbf{s}(p, q) \tag{2}
\end{equation*}
$$

On the other hand, the surgery formula for the Casson-Walker invariant [5, Theorem 2.8] implies

$$
\begin{align*}
\lambda\left(S_{4 q}^{3}(K)\right) & =-\mathbf{s}(1,4 q)+\frac{1}{4 q} \Delta_{K}^{\prime \prime}(1) \\
& =-\frac{(2 q-1)(4 q-1)}{24 q}+\frac{1}{4 q} \Delta_{K}^{\prime \prime}(1) . \tag{3}
\end{align*}
$$

Lemma 2.3. For realizable $P(p, q)$ with $q$ odd, $p \equiv-1(\bmod 4)$.
Proof. By combining (2) and (3), we have

$$
\begin{aligned}
- & \frac{(2 q-1)(4 q-1)}{24 q}+\frac{1}{4 q} \Delta_{K}^{\prime \prime}(1) \\
& =\lambda(P(p, q)) \\
& \equiv \frac{p}{8 q}-\sum_{i=1}^{q-1}\left(\frac{i}{q}-\frac{1}{2}\right)\left(\frac{p i}{q}-\frac{1}{2}\right) \quad(\bmod 1) \\
& =\frac{p}{8 q}-\frac{p(q-1)(2 q-1)}{6 q}+\frac{p(q-1)}{4} .
\end{aligned}
$$

Multiplying both sides by $24 q$, we get

$$
1-6 q+8 q^{2}+p\left(-1+6 q-2 q^{2}\right) \equiv 6 \Delta_{K}^{\prime \prime}(1) \quad(\bmod 24 q)
$$

Since $\Delta_{K}^{\prime \prime}(1)$ is even and $p, q$ are odd, we get

$$
2 q+1+p(2 q+1) \equiv 0 \quad(\bmod 4)
$$

So $p \equiv-1(\bmod 4)$.

## 2.2 | The Spin ${ }^{c}$ structures

The $i$ th torsion coefficient of a knot $K$ is defined to be

$$
t_{i}(K)=\sum_{j \geqslant 1} j \alpha_{i+j},
$$

for $i \geqslant 0$, where the $\alpha_{i}$ are as in (1). Let

$$
\varepsilon_{i}=t_{i}-t_{i+1} .
$$

When $K$ admits an L-space surgery, it is proved in [20, Proposition 7.6] that

$$
\varepsilon_{i} \in\{0,1\} .
$$

Suppose $4 q$-surgery on $K$ is $P(p, q)$, then $4 q \geqslant 2 g(K)-1$ [19]. So

$$
\begin{equation*}
g(K) \leqslant 2 q . \tag{4}
\end{equation*}
$$

Since $\alpha_{g(K)}=1$ and $\alpha_{i}=0$ when $i>g(K)$, it follows from the definition of $t_{i}$ that

$$
\begin{equation*}
t_{i}=0 \quad \text { if and only if } i \geqslant g(K) \tag{5}
\end{equation*}
$$

In particular, by (4), we get

$$
\begin{equation*}
t_{2 q}=0 . \tag{6}
\end{equation*}
$$

For $i>0$,

$$
\begin{aligned}
\alpha_{i} & =t_{i-1}-2 t_{i}+t_{i+1} \\
& =\varepsilon_{i-1}-\varepsilon_{i} .
\end{aligned}
$$

Since $1=\Delta_{K}(1)=\alpha_{0}+2 \sum_{i>0} \alpha_{i}$, we can also get

$$
\alpha_{0}=1-2 \sum_{i>0} \alpha_{i} .
$$

Thus

$$
\begin{align*}
\Delta_{K}(-1) & =\alpha_{0}+2 \sum_{i>0}(-1)^{i} \alpha_{i} \\
& =1-4 \sum_{i \geqslant 0}(-1)^{i} \varepsilon_{i} . \tag{7}
\end{align*}
$$

Given a knot $K \subset S^{3}$ and an integer $n>0$, there is an affine isomorphism [15]

$$
\varphi: \mathbb{Z} / n \mathbb{Z} \rightarrow \operatorname{Spin}^{\mathrm{c}}\left(S_{n}^{3}(K)\right) .
$$

For simplicity, let $d\left(S_{n}^{3}(K), i\right)=d\left(S_{n}^{3}(K), \varphi(i)\right)$.

From [15], we have

$$
\begin{equation*}
d(L(n, 1), i)=-\frac{1}{4}+\frac{(2 i-n)^{2}}{4 n} \tag{8}
\end{equation*}
$$

Using [19, Theorem 1.2], we get

$$
\begin{equation*}
d\left(S_{n}^{3}(K), i\right)=d(L(n, 1), i)-2 t_{\min \{i, n-i\}} . \tag{9}
\end{equation*}
$$

Lemma 2.4. Suppose that $P(p, q)$ is obtained by the $4 q$-surgery on $K$. Let $i$ be an integer with $0 \leqslant$ $i \leqslant q$. If $i$ is even, we have

$$
d\left(S_{4 q}^{3}(K), q-i\right)=d\left(S_{4 q}^{3}(K), q+i\right)
$$

and

$$
t_{q-i}-t_{q+i}=\frac{i}{2}
$$

If is odd, we have

$$
d\left(S_{4 q}^{3}(K), q-i\right)=d\left(S_{4 q}^{3}(K), q+i\right) \pm 1
$$

and

$$
t_{q-i}-t_{q+i}=\frac{i \mp 1}{2} .
$$

Proof. Since $S_{4 q}^{3}(K)$ is a prism manifold, it contains a Klein bottle. So the order-2 element in $H_{1}\left(S_{4 q}^{3}(K)\right)$ is represented by a curve in the Klein bottle, such that the complement of the curve in the Klein bottle is an annulus. By [13, Theorem 1.1], for any $j \in \mathbb{Z} / 4 q \mathbb{Z}$, we have

$$
\begin{equation*}
\left|d\left(S_{4 q}^{3}(K), j\right)-d\left(S_{4 q}^{3}(K), j+2 q\right)\right| \leqslant 1 . \tag{10}
\end{equation*}
$$

Since the conjugate of $\varphi(j+2 q)$ is $\varphi(2 q-j)$, we have

$$
\begin{equation*}
d\left(S_{4 q}^{3}(K), j+2 q\right)=d\left(S_{4 q}^{3}(K), 2 q-j\right) \tag{11}
\end{equation*}
$$

Let $j=q-i$. Using (8) and (9), we get

$$
\begin{align*}
& d\left(S_{4 q}^{3}(K), q-i\right)-d\left(S_{4 q}^{3}(K), q+i\right) \\
& \quad=-\frac{1}{4}+\frac{(2 q-2 i-4 q)^{2}}{16 q}-2 t_{q-i}-\left(-\frac{1}{4}+\frac{(2 q+2 i-4 q)^{2}}{16 q}-2 t_{q+i}\right) \\
& \quad=i-2 t_{q-i}+2 t_{q+i} \in \mathbb{Z}, \tag{12}
\end{align*}
$$

so $d\left(S_{4 q}^{3}(K), q-i\right)-d\left(S_{4 q}^{3}(K), q+i\right)$ has the same parity as $i$. Using (10) and (11), we get

$$
\left|d\left(S_{4 q}^{3}(K), q-i\right)-d\left(S_{4 q}^{3}(K), q+i\right)\right| \leqslant 1 .
$$

So $d\left(S_{4 q}^{3}(K), q-i\right)-d\left(S_{4 q}^{3}(K), q+i\right)=0$ when $i$ is even, and $d\left(S_{4 q}^{3}(K), q-i\right)-d\left(S_{4 q}^{3}(K), q+\right.$ $i)= \pm 1$ when $i$ is odd. Now $t_{q-i}-t_{q+i}$ can be computed from (12).

## 2.3 | The proof of Proposition 2.1

Proof of Proposition 2.1. By Lemma 2.4 and (6),

$$
t_{0}=t_{0}-t_{2 q} \leqslant\left\lfloor\frac{q+1}{2}\right\rfloor .
$$

By [14, Lemma 6.1], $p=\left|\Delta_{K}(-1)\right|$. Using (7), we get

$$
\begin{aligned}
p & \leqslant 1+4 \sum_{i \geqslant 0} \varepsilon_{i} \\
& =1+4 t_{0} \\
& \leqslant 1+4\left\lfloor\frac{q+1}{2}\right\rfloor .
\end{aligned}
$$

When $q$ is even, $p \leqslant 2 q+1$. When $q$ is odd, $p \leqslant 2 q+3$. By Lemma $2.3, p \neq 2 q+3$, so we must have $p \leqslant 2 q+1$.

Proof of Theorem 1.1. The first statement is Proposition 2.1. The second statement follows from combining [14, Theorem 1.6] and [1, Lemma 2.1].

## 3 | INPUT FROM LATTICE THEORY

This section assembles facts about lattices that will be used in the paper. We mainly follow the treatment of [1, 2, 9, 10].

Recall that an integral lattice is a finitely generated free abelian group $L$ endowed with a positive definite symmetric bilinear form $\langle\rangle:, L \times L \rightarrow \mathbb{Z}$. Given $v \in L$, let $|v|=\langle v, v\rangle$ be the norm of $v$. We can extend $\langle$,$\rangle to a \mathbb{Q}$-valued pairing on $L \otimes \mathbb{Q}$; using it we define

$$
L^{*}=\{x \in L \otimes \mathbb{Q} \mid\langle x, y\rangle \in \mathbb{Z}, \forall y \in L\} .
$$

The pairing on $L$ descends to a non-degenerate, symmetric bilinear form on the discriminant group $\bar{L}=L^{*} / L$

$$
\begin{array}{r}
b: \bar{L} \times \bar{L} \rightarrow \mathbb{Q} / \mathbb{Z} \\
b(\bar{x}, \bar{y}) \equiv\langle x, y\rangle \quad(\bmod 1),
\end{array}
$$

the linking form, where $\bar{x}$ denotes the class of $x \in L$ in $\bar{L}$. The discriminant of $L$ is the order of the finite group $\bar{L}$. Let

$$
\operatorname{Char}(L)=\left\{x \in L^{*} \mid\langle x, y\rangle \equiv\langle y, y\rangle \quad(\bmod 2), \forall y \in L\right\}
$$

denote the set of characteristic covectors for $L$. The set $C(L)=\operatorname{Char}(L) / 2 L$ forms a torsor over the discriminant group $\bar{L}$. Given $\chi \in C(L)$, define

$$
\begin{equation*}
d_{L}([\chi])=\min \left\{\left.\frac{\left|\chi^{\prime}\right|-\operatorname{rk}(L)}{4} \right\rvert\, \chi^{\prime} \in[\chi]\right\}, \tag{13}
\end{equation*}
$$

and call an element $\chi \in \operatorname{Char}(L)$ short if its norm is minimal in $[\chi]$. We call the pair ( $\left.C(L), d_{L}\right)$ the $d$-invariant of the lattice $L$; in particular it is an invariant of the stable isomorphism type of the lattice $L$ [18, Theorem 4.7]. We drop $L$ from the notation when the lattice $L$ is understood from the context.

## 3.1 | Linear lattices

Given a pair of relatively prime positive integers $p, q$, write $\frac{p}{q}$ in a Hirzebruch-Jung continued fraction

$$
\begin{equation*}
\frac{p}{q}=a_{-1}-\frac{1}{a_{0}-\frac{1}{\ddots-\frac{1}{a_{n}}}}=\left[a_{-1}, a_{0}, \ldots, a_{n}\right]^{-}, \tag{14}
\end{equation*}
$$

with $a_{i} \geqslant 2$ when $i \geqslant 0$ in equation (14).
Definition 3.1. The linear lattice $\Lambda(q,-p)$ has a basis

$$
\begin{equation*}
\left\{x_{0}, \ldots, x_{n}\right\} \tag{15}
\end{equation*}
$$

and inner product given by

$$
\left\langle x_{i}, x_{j}\right\rangle= \begin{cases}a_{i}, & i=j  \tag{16}\\ -1, & |i-j|=1 \\ 0, & |i-j|>1\end{cases}
$$

where the coefficients $a_{i}$, for $i \in\{0, \ldots, n\}$, are defined by the continued fraction (14). We call (15) the vertex basis of $\Lambda(q,-p)$.

Remark 3.2. The reason that we use $\Lambda(q,-p)$ instead of $\Lambda(q, p)$ is that our convention for lens spaces is different from that of [9]. In our paper, the lens space $L(q, p)$ is oriented as the $\frac{q}{p}$-surgery on the unknot, and $P(p, q)$ is the $\frac{q}{p}$-surgery on $\mathbb{R} P^{1} \# \mathbb{R} P^{1} \subset \mathbb{R} P^{3} \# \mathbb{R} P^{3}$, so they both bound 4manifolds with intersection lattice $\Lambda(q,-p)$.

An element $\ell \in L$ is reducible if $\ell=x+y$ for some non-zero $x, y \in L$ with $\langle x, y\rangle \geqslant 0$, and irreducible otherwise. An element $\ell \in L$ is breakable if $\ell=x+y$ with $|x|,|y| \geqslant 3$ and $\langle x, y\rangle=-1$, and unbreakable otherwise.

Definition 3.3. In a linear lattice, if $I$ is any subset of $\left\{x_{0}, x_{1}, \ldots, x_{n}\right\}$ then write $[I]=\sum_{x \in I} x$. An interval is an element of the form $[I]$ with $I=\left\{x_{a}, x_{a+1}, \ldots, x_{b}\right\}$ for $0 \leqslant a \leqslant b \leqslant n$. We say that $a$ is the left endpoint of the interval, and $b$ is the right endpoint of the interval. Say that [ $I$ ] contains $x_{i}$ if $I$ does: we often write $x_{i} \in[I]$ in this case.

When [ $I$ ] is an interval, it is easy to compute

$$
\begin{equation*}
|[I]|=2+\sum_{x_{i} \in[I]}\left(\left|x_{i}\right|-2\right) . \tag{17}
\end{equation*}
$$

Proposition 3.4 [9, Proposition 3.3]. If $v \in \Lambda(q,-p)$ is irreducible, $v=\epsilon[I]$ for some $\epsilon= \pm 1$ and [I] an interval.

From now on, let $[v]$ be the interval corresponding to $v$ when $v$ is irreducible.

Definition 3.5. A vertex $x_{i}$ has high weight if $\left|x_{i}\right|=a_{i}>2$.
Proposition 3.6 [9, Corollary 3.5(4)]. An element $\epsilon[I] \in \Lambda(q,-p)$ with $\epsilon \in\{ \pm 1\}$ is unbreakable if and only if $[I]$ contains at most one vertex with high weight.

Definition 3.7. For two intervals [ $I$ ] and [ $J$ ] with left endpoints $i_{0}$, $j_{0}$ and right endpoints $i_{1}, j_{1}$, say that [I] and [J] are distant if either $i_{1}+1<j_{0}$ or $j_{1}+1<i_{0}$, that [I] and [J] share a common end if $i_{0}=j_{0}$ or $i_{1}=j_{1}$, and that [I] and [ $J$ ] are consecutive if $i_{1}+1=j_{0}$ or $j_{1}+1=i_{0}$. Write $[I]<[J]$ if $I \subset J$ and $[I]$ and $[J]$ share a common end, and $[I] \dagger[J]$ if they are consecutive. If $[I]$ and $[J]$ are either consecutive or share a common end, say that they abut. If $I \cap J$ is non-empty and $[I]$ and $[J]$ do not share a common end, write $[I] \pitchfork[J]$.

Direct computations show the following lemma.
Lemma 3.8. Let $[I],[J]$ be two intervals. Then

$$
\langle[I],[J]\rangle= \begin{cases}0, & {[I] \text { and }[J] \text { are distant, }} \\ |[I \cap J]|-1, & {[I] \text { and }[J] \text { share a common end, }} \\ -1, & {[I] \text { and }[J] \text { are consecutive, }} \\ |[I \cap J]|-2, & {[I] \oplus[J]}\end{cases}
$$

Proposition 3.9 [9, Corollary 3.5(2)]. The lattice $\Lambda(q,-p)$ is indecomposable; that is, $\Lambda(q,-p)$ is not the direct sum of two non-trivial lattices.

Proposition 3.10 (Proposition 3.6 of [9]). If $\Lambda(q, p) \cong \Lambda\left(q^{\prime}, p^{\prime}\right)$, then $q=q^{\prime}$ and either $p \equiv p^{\prime}$ or $p p^{\prime} \equiv 1(\bmod q)$.

## 3.2 | Changemaker lattices

When a lattice $L$ is isomorphic to $\sigma^{\perp}$, the orthogonal complement of a changemaker vector $\sigma \in$ $\mathbb{Z}^{n+2}, L$ is called a changemaker lattice.

Definition 3.11. The standard basis of $\sigma^{\perp}$ is the collection $S=\left\{v_{1}, \ldots, v_{n+1}\right\}$, where

$$
v_{j}=\left(2 e_{0}+\sum_{i=1}^{j-1} e_{i}\right)-e_{j},
$$

whenever $\sigma_{j}=1+\sigma_{0}+\cdots+\sigma_{j-1}$, and

$$
v_{j}=\left(\sum_{i \in A} e_{i}\right)-e_{j}
$$

whenever $\sigma_{j}=\sum_{i \in A} \sigma_{i}$, with $A \subset\{0, \ldots, j-1\}$ chosen to maximize the quantity $\sum_{i \in A} 2^{i}$. A vector $v_{j} \in S$ is called tight in the first case, just right in the second case as long as $i<j-1$ and $i \in A$ implies that $i+1 \in A$, and gappy if there is some index $i$ with $i \in A, i<j-1$, and $i+1 \notin A$. Such an index, $i$, is a gappy index for $v_{j}$.

Definition 3.12. For $v \in \mathbb{Z}^{n+2}$, $\operatorname{supp} v=\left\{i \mid\left\langle e_{i}, v\right\rangle \neq 0\right\}$.
Lemma 3.13 (Lemma 3.12 (3) in [9]). If $\left|v_{k+1}\right|=2$, then $k$ is not a gappy index for any $v_{j}$ with $j \in\{1, \ldots, n+1\}$.

Lemma 3.14 (Lemma 3.13 in [9]). Each $v_{j} \in S$ is irreducible. Furthermore, for any $A \subset\{0,1, \ldots, j-$ 1 \}, if the vector

$$
-e_{j}+\sum_{i \in A} e_{i}
$$

is in $\sigma^{\perp}$, then it is irreducible.
Lemma 3.15. Let $v=\sum_{i \in A} b_{i} e_{i} \in \sigma^{\perp}$, with $A \subset\{0,1, \ldots, n+1\}$ and each $b_{i} \in\{-1,1\}$. If $v=x+y$ with $\langle x, y\rangle \geqslant 0$, then there exists $a$ subset $B \subset A$ such that

$$
x=\sum_{i \in B} b_{i} e_{i}, y=\sum_{i \in A \backslash B} b_{i} e_{i} .
$$

Proof. Let $x=\sum x_{i} e_{i}, y=\sum y_{i} e_{i}$. Since $x_{i}+y_{i} \in\{-1,0,1\}, x_{i} y_{i} \leqslant 0$. If $\langle x, y\rangle \geqslant 0$, then each $x_{i} y_{i}=$ 0 , namely, one of $x_{i}, y_{i}$ is 0 . So our conclusion holds.

Lemma 3.16 (Lemma 3.15 in [9]). If $v_{j} \in S$ is breakable, then it is tight.
Lemma 3.17 (Lemma 4.2(1) in [9]). If $\Lambda(q,-p)$ is isomorphic to a changemaker lattice, then it contains at most one tight standard basis vector.

Lemma 3.18 (Lemma 3.12(1) in [9]). For any $v_{j} \in S$, we have $j-1 \in \operatorname{supp}\left(v_{j}\right)$.
Definition 3.19. If $T$ is a set of irreducible vectors in a linear lattice $\Lambda(q,-p)$, the intersection graph $G(T)$ has vertex set $T$, and an edge between $v$ and $w$ if the intervals corresponding to $v$ and $w$ abut. We write $v \sim w$ if $v$ and $w$ are connected in $G(T)$.

Lemma 3.20. If $v, w$ are irreducible elements of a linear lattice and the intervals corresponding [ $v$ ] and $[w]$ abut, then $\langle v, w\rangle \neq 0$.

Lemma 3.21 (Lemma 4.4 in [9]). If $v_{i}$ and $v_{j}$ are distinct unbreakable standard basis vectors with $\left|v_{i}\right|,\left|v_{j}\right| \geqslant 3$, then $\left|\left\langle v_{i}, v_{j}\right\rangle\right| \leqslant 1$, with equality if and only if $\left[v_{i}\right] \dagger\left[v_{j}\right]$.

Lemma 3.22 (Corollary 4.5 in [9]). If $v_{i}$ and $v_{j}$ are distinct unbreakable standard basis vectors with $\left|v_{i}\right|,\left|v_{j}\right| \geqslant 3$, then the high weight vertices contained in $\left[v_{i}\right],\left[v_{j}\right]$ are different.

Definition 3.23. A claw in a graph $G$ is a quadruple $\left(v ; w_{1}, w_{2}, w_{3}\right)$ of vertices such that $v$ neighbors all the $w_{i}$, but no two of the $w_{i}$ neighbor each other.

Lemma 3.24 (Lemma 4.8 of [9]). For any set $T$ of irreducible elements in a linear lattice, the intersection graph $G(T)$ has no claws.

Definition 3.25. Given a set $T$ of unbreakable elements in a linear lattice and $v_{1}, v_{2}, v_{3} \in T$, ( $v_{1}, v_{2}, v_{3}$ ) is a heavy triple if $\left|v_{i}\right| \geqslant 3$, and if each pair among the $v_{i}$ is connected by a path in $G(T)$ disjoint from the third.

Lemma 3.26 (Based on Lemma 4.10 of [9]). For any set $T$ of unbreakable elements in a linear lattice, $G(T)$ has no heavy triples.

## 4 | THE TOPOLOGY OF CERTAIN COBORDISMS

In this section, we will consider the topology of a certain cobordism $W: Y_{0} \rightarrow Y_{1}$. We assume that $W$ is obtained by adding $n+1$ two-handles along a link $L \subset Y_{0}$, such that one component $L_{0}$ of $L$ represents a 2-torsion in $H_{1}\left(Y_{0}\right)$, and all other components of $L$ are null-homologous in $Y_{0}$. Moreover, we assume that $\left|H_{1}\left(Y_{0}\right)\right|=4$ and $W$ is negative definite. Under these assumptions, $Y_{1}$ is a rational homology sphere. Let $\iota_{i}: Y_{i} \rightarrow W$ be the inclusion map, $\iota_{i}^{*}: H^{2}(W) \rightarrow H^{2}\left(Y_{i}\right)$ be the induced maps on cohomology, and $\iota_{i}^{s}: \operatorname{Spin}^{c}(W) \rightarrow \operatorname{Spin}^{c}\left(Y_{i}\right)$ be the induced maps on $\operatorname{Spin}^{\mathrm{c}}$, $i=0,1$.

We make the further assumption that $Y_{0}$ is the boundary of a compact 4-manifold $Z_{0}$ with $H_{1}\left(Z_{0}\right) \cong \mathbb{Z} / 2 \mathbb{Z}$ and $H_{2}\left(Z_{0}\right)=0$, and $L_{0}$ is null-homologous in $Z_{0}$. Let $Z=Z_{0} \cup_{Y_{0}} W$.

From the handle structure of $W$, we can compute

$$
H_{1}(W) \cong \mathbb{Z} / 2 \mathbb{Z}, H_{2}(W) \cong \mathbb{Z}^{n+1}, H_{1}\left(W, Y_{i}\right)=0, H_{2}\left(W, Y_{i}\right) \cong \mathbb{Z}^{n+1}, i=0,1
$$

By the Universal Coefficient Theorem,

$$
H^{2}(W) \cong \mathbb{Z}^{n+1} \oplus \mathbb{Z} / 2 \mathbb{Z}
$$

In particular, there exists a unique torsion class $\alpha \in H^{2}(W)$. Let $\alpha_{i}=t_{i}^{*}(\alpha), i=0,1$.
Since $Z$ is obtained by adding two-handles to $Z_{0}$, such that all attaching curves are null-homologous in $Z_{0}$, we have

$$
H_{1}(Z) \cong H_{1}\left(Z_{0}\right) \cong \mathbb{Z} / 2 \mathbb{Z}
$$

and the map $H_{2}(Z) \rightarrow H_{2}\left(Z, Z_{0}\right)$ is an isomorphism.

Lemma 4.1. The map $\iota_{W, Z}^{*}: H^{2}(Z) \rightarrow H^{2}(W)$ is injective with image containing $\alpha$. The map $\iota_{Y_{0}, Z_{0}}^{*}: H^{2}\left(Z_{0}\right) \rightarrow H^{2}\left(Y_{0}\right)$ is injective with image generated by $\alpha_{0}$. Moreover, $\left[L_{0}\right] \in H_{1}\left(Y_{0}\right)$ is the Poincaré dual of $\alpha_{0}$.

Proof. Using the long exact sequences

$$
H^{2}(Z, W) \rightarrow H^{2}(Z) \rightarrow H^{2}(W), \quad H^{2}\left(Z_{0}, Y_{0}\right) \rightarrow H^{2}\left(Z_{0}\right) \rightarrow H^{2}\left(Y_{0}\right),
$$

and the fact that $0=H^{2}\left(Z_{0}, Y_{0}\right) \cong H^{2}(Z, W)$, we get that $\iota_{W, Z}^{*}$ and $\iota_{Y_{0}, Z_{0}}^{*}$ are injective.
By the Universal Coefficient Theorem, $H^{2}(Z) \cong \operatorname{Hom}\left(H_{2}(Z), \mathbb{Z}\right) \oplus \mathbb{Z} / 2 \mathbb{Z}$, so it has a unique 2torsion $\bar{\alpha}$. Since $\iota_{W, Z}^{*}$ is injective, $\iota_{W, Z}^{*}(\bar{\alpha})$ is a 2-torsion in $H^{2}(W)$, which must be $\alpha$. Let $\bar{\alpha}_{0}$ be the restriction of $\bar{\alpha}$ to $H^{2}\left(Z_{0}\right)$. Using the commutative diagram

we see that $\iota_{Y_{0}, Z_{0}}^{*}\left(\bar{\alpha}_{0}\right)=\alpha_{0}$. Since $H^{2}\left(Z_{0}\right) \cong \mathbb{Z} / 2 \mathbb{Z}$, the image of $\iota_{Y_{0}, Z_{0}}^{*}$ is generated by $\alpha_{0}$.
Since $L_{0}$ is null-homologous in $Z_{0}$, there exists a properly embedded oriented surface $F_{0} \subset Z_{0}$ such that $\partial F_{0}=L_{0}$. Thus the image of the Poincare dual of $\left[F_{0}\right]$ under $\iota_{Y_{0}, Z_{0}}^{*}$ is the Poincare dual of $\left[L_{0}\right]$. Since both $\left[L_{0}\right]$ and $\left[\alpha_{0}\right]$ have order 2, and $\iota_{Y_{0}, Z_{0}}^{*}\left(\bar{\alpha}_{0}\right)=\alpha_{0}$, we get that $\left[L_{0}\right]$ is the Poincaré dual of $\alpha_{0}$.

## Lemma 4.2.

(1) For $i=0$, 1 , we have $\operatorname{ker} \iota_{i}^{*} \cong H^{2}\left(W, Y_{i}\right)$, and $\iota_{i}^{*}$ is surjective. In particular, $\alpha_{i} \neq 0$ in $H^{2}\left(Y_{i}\right)$.
(2) The kernel of the restriction map $\left(\iota_{0}^{\prime}\right)^{*}: \operatorname{ker} \iota_{1}^{*} \rightarrow H^{2}\left(Y_{0}\right)$ is isomorphic to $H^{2}(W, \partial W)$, and its image is generated by $\alpha_{0}$.

Proof.
(1) The first statement follows from the long exact sequence

$$
0=H^{1}\left(Y_{i}\right) \rightarrow H^{2}\left(W, Y_{i}\right) \rightarrow H^{2}(W) \xrightarrow{\iota_{i}^{*}} H^{2}\left(Y_{i}\right) \rightarrow H^{3}\left(W, Y_{i}\right)=0
$$

It follows that ker $\iota_{i}^{*}$ is torision-free, so $\alpha \notin \operatorname{ker} \iota_{i}^{*}$. Thus $\alpha_{i} \neq 0$.
(2) By (1), the map $\left(\iota_{0}^{\prime}\right)^{*}$ can be identified with $H^{2}\left(W, Y_{1}\right) \rightarrow H^{2}\left(Y_{0}\right)$, which is part of the long exact sequence

$$
0=H^{1}\left(\partial W, Y_{1}\right) \rightarrow H^{2}(W, \partial W) \rightarrow H^{2}\left(W, Y_{1}\right) \rightarrow H^{2}\left(\partial W, Y_{1}\right)=H^{2}\left(Y_{0}\right) .
$$

Thus $\operatorname{ker}\left(\iota_{0}^{\prime}\right)^{*}$ is $H^{2}(W, \partial W)$.
By Poincaré duality, $\left(\iota_{0}^{\prime}\right)^{*}$ can be identified with the boundary map $\partial_{0}^{\prime}: H_{2}\left(W, Y_{0}\right) \rightarrow H_{1}\left(Y_{0}\right)$. By the handle decomposition of $W$, we see that the image of $\partial_{0}^{\prime}$ is generated by $\left[L_{0}\right]$. By Lemma 4.1, $\operatorname{im}\left(\iota_{0}^{\prime}\right)^{*}$ is generated by $\alpha_{0}$.

Corollary 4.3. For each $\mathrm{t} \in \operatorname{Spin}^{\mathrm{c}}\left(Y_{1}\right)$, there exists a subset

$$
\mathfrak{R}(\mathfrak{t})=\left\{\mathfrak{r}_{0}, \mathfrak{r}_{1}=\mathfrak{r}_{0}+\alpha_{0}\right\} \subset \operatorname{Spin}^{\mathrm{c}}\left(Y_{0}\right)
$$

such that for each $\mathfrak{r} \in \operatorname{Spin}^{c}\left(Y_{0}\right)$, the set

$$
\begin{equation*}
\left(\iota_{0}^{S}, l_{1}^{S}\right)^{-1}(\mathfrak{r}, \mathfrak{t}):=\left(\iota_{0}^{S}\right)^{-1}(\mathfrak{r}) \cap\left(l_{1}^{S}\right)^{-1}(\mathfrak{t}) \tag{18}
\end{equation*}
$$

is non-empty if and only if $\mathfrak{r} \in \mathfrak{R}(\mathrm{t})$. Moreover, the set (18) is an $H^{2}(W, \partial W)$-torsor when it is nonempty.

Proof. This follows from Lemma 4.2 and the fact that $\operatorname{Spin}^{\mathrm{c}}$ is an $H^{2}$-torsor.

By the long exact sequence

$$
0=H_{2}\left(Y_{0}\right) \rightarrow H_{2}(W) \rightarrow H_{2}\left(W, Y_{0}\right) \rightarrow H_{1}\left(Y_{0}\right),
$$

$H_{2}(W)$ embeds as an index-2 subgroup of $H_{2}\left(W, Y_{0}\right) \cong \mathbb{Z}^{n+1}$. Thus we can extend the intersection form on $H_{2}(W)$ to $H_{2}\left(W, Y_{0}\right)$, with value in $\frac{1}{4} \mathbb{Z}$. Let

$$
\mathcal{L} \cong H_{2}\left(W, Y_{0}\right) \cong H_{2}\left(Z, Z_{0}\right) \cong H_{2}(Z)
$$

be the intersection lattice on the pair $\left(W, Y_{0}\right)$. Suppose that the generators corresponding to the two-handles are $x_{0}, \ldots, x_{n}$, where $x_{0}$ corresponds to the two-handle attached along $L_{0}$. Let

$$
\mathcal{L}_{0}=\left\langle 2 x_{0}, x_{1}, \ldots, x_{n}\right\rangle
$$

be the sublattice of $\mathcal{L}$ generated by $2 x_{0}, x_{1}, \ldots, x_{n}$; then $\mathcal{L}_{0}$ can be identified with the intersection lattice $\mathrm{H}_{2}(W)$. Let

$$
\mathcal{L}^{*}=\operatorname{Hom}(\mathcal{L}, \mathbb{Z}), \mathcal{L}_{0}^{*}=\operatorname{Hom}\left(\mathcal{L}_{0}, \mathbb{Z}\right) \supset \mathcal{L}^{*}
$$

Using the inner product on $\mathcal{L}$, we can embed $\mathcal{L}^{*}$ and $\mathcal{L}_{0}^{*}$ as sublattices of $\mathcal{L} \otimes \mathbb{Q}$.
Let

$$
\widetilde{\mathcal{C}}=\left\{y \in \mathcal{L}_{0}^{*} \mid\left\langle y, 2 x_{0}\right\rangle \equiv\left\langle 2 x_{0}, 2 x_{0}\right\rangle,\left\langle y, x_{j}\right\rangle \equiv\left\langle x_{j}, x_{j}\right\rangle \quad(\bmod 2), \quad j>0\right\} .
$$

Let $\bar{H}^{2}(W)=H^{2}(W) /$ Tors $=\mathcal{L}_{0}^{*}$, and let $\bar{c}_{1}: \operatorname{Spin}^{\mathrm{c}}(W) \rightarrow \bar{H}^{2}(W)$ be the composition of the map $c_{1}: \operatorname{Spin}^{\mathrm{c}}(W) \rightarrow H^{2}(W)$ and the quotient map $H^{2}(W) \rightarrow \bar{H}^{2}(W)$. Then $\widetilde{C}$ is the image of $\bar{c}_{1}$.

## Proposition 4.4.

(1) The quotient $\operatorname{Spin}^{\mathrm{c}}\left(Y_{1}\right) /\left\langle\alpha_{1}\right\rangle$ can be identified with $\widetilde{\mathcal{C}} / 2 \mathcal{L}$.
(2) Under the previous identification, suppose that the $\left\langle\alpha_{1}\right\rangle$-orbit $\left\{\mathrm{t}, \mathrm{t}+\alpha_{1}\right\}$ is identified with $y+2 \mathcal{L}$ for some $y \in \widetilde{\mathcal{C}}$. Let $\Re(\mathrm{t})=\left\{\mathfrak{r}_{0}, \mathfrak{r}_{1}\right\}$. Then there exist $y_{0}, y_{1} \in y+2 \mathcal{L}$, such that

$$
\bar{c}_{1}\left(\left(\iota_{0}^{s}, l_{1}^{s}\right)^{-1}\left(\mathfrak{r}_{0}, \mathfrak{t}\right)\right)=y_{0}+2 \mathcal{L}_{0}, \quad \bar{c}_{1}\left(\left(\iota_{0}^{s}, l_{1}^{s}\right)^{-1}\left(\mathfrak{r}_{1}, \mathfrak{t}\right)\right)=y_{1}+2 \mathcal{L}_{0},
$$

and

$$
\bar{c}_{1}\left(\left(l_{0}^{s}, l_{1}^{s}\right)^{-1}\left(\mathfrak{r}_{0}, \mathfrak{t}+\alpha_{1}\right)\right)=y_{1}+2 \mathcal{L}_{0}, \quad \bar{c}_{1}\left(\left(l_{0}^{s}, l_{1}^{s}\right)^{-1}\left(\mathfrak{r}_{1}, \mathfrak{t}+\alpha_{1}\right)\right)=y_{0}+2 \mathcal{L}_{0} .
$$

Proof.
(1) By Lemma 4.2, every $\mathrm{t} \in \operatorname{Spin}^{\mathrm{c}}\left(Y_{1}\right)$ is in the image of $\iota_{1}^{s}$, and $\mathfrak{B}_{1}, \mathfrak{B}_{2} \in \operatorname{Spin}^{\mathrm{c}}(W)$ restrict to the same $\mathfrak{t} \in \operatorname{Spin}^{c}\left(Y_{1}\right)$ if and only if $\mathfrak{\Xi}_{1}-\mathfrak{\xi}_{2} \in H^{2}\left(W, Y_{1}\right) \cong H_{2}\left(W, Y_{0}\right)=\mathcal{L}$. $\operatorname{So} \operatorname{Spin}^{c}\left(Y_{1}\right) \cong$ $\operatorname{Spin}^{\mathrm{c}}(W) / \mathcal{L}$. Consider the map $\bar{c}_{1}: \operatorname{Spin}^{\mathrm{c}}(W) \rightarrow \widetilde{\mathcal{C}}$. It is surjective, and $\bar{c}_{1}\left(\mathfrak{\mathfrak { G }}_{1}\right)=\bar{c}_{1}\left(\mathfrak{G}_{2}\right)$ if and only if $\mathfrak{\mathfrak { l }}_{1}-\mathfrak{\xi}_{2} \in\langle\alpha\rangle$. Using the formula

$$
c_{1}\left(\mathfrak{I}_{1}\right)-c_{1}\left(\mathfrak{F}_{2}\right)=2\left(\mathfrak{\mathfrak { g }}_{1}-\mathfrak{\mathfrak { G }}_{2}\right)
$$

we get that $\operatorname{Spin}^{\mathrm{c}}\left(Y_{1}\right) /\left\langle\alpha_{1}\right\rangle \cong \operatorname{Spin}^{\mathrm{c}}(W) /(\mathcal{L}+\langle\alpha\rangle) \cong \widetilde{\mathcal{C}} / 2 \mathcal{L}$.
(2) By Corollary 4.3 , there exist $\mathfrak{\mathfrak { J }}_{0}, \mathfrak{B}_{1} \in \operatorname{Spin}^{\mathrm{c}}(W)$, such that

$$
\left(\iota_{0}^{s}, \iota_{1}^{s}\right)^{-1}\left(\mathfrak{r}_{0}, \mathfrak{t}\right)=\mathfrak{z}_{0}+\mathcal{L}_{0}, \quad\left(\iota_{0}^{s}, \iota_{1}^{s}\right)^{-1}\left(\mathfrak{r}_{1}, \mathfrak{t}\right)=\mathfrak{\mathfrak { G }}_{1}+\mathcal{L}_{0} .
$$

Since

$$
\iota_{0}^{s}\left(\mathfrak{g}_{1}+\alpha\right)=\iota_{0}^{s}\left(\mathfrak{g}_{1}\right)+\alpha_{0}=\mathfrak{r}_{1}+\alpha_{0}=\mathfrak{r}_{0}, l_{0}^{s}\left(\mathfrak{g}_{0}+\alpha\right)=\mathfrak{r}_{1},
$$

we also have

$$
\left(l_{0}^{s}, l_{1}^{s}\right)^{-1}\left(\mathfrak{r}_{0}, \mathfrak{t}+\alpha_{1}\right)=\mathfrak{s}_{1}+\alpha+\mathcal{L}_{0}, \quad\left(l_{0}^{s}, l_{1}^{s}\right)^{-1}\left(\mathfrak{r}_{1}, \mathfrak{t}+\alpha_{1}\right)=\mathfrak{s}_{0}+\alpha+\mathcal{L}_{0}
$$

Applying $\bar{c}_{1}$ to the above equalities, we get our conclusion.
For any $\mathfrak{\mathfrak { E }} \in \operatorname{Spin}^{\mathrm{c}}(W)$, let

$$
\begin{equation*}
g r(W, \mathfrak{\mathfrak { z }})=\frac{c_{1}^{2}(\mathfrak{\mathfrak { }})+b_{2}(W)}{4} . \tag{19}
\end{equation*}
$$

For any $\mathrm{t} \in \operatorname{Spin}^{\mathrm{c}}\left(Y_{1}\right)$, let

$$
\begin{align*}
& D_{W}\left(Y_{1}, \mathfrak{t}\right)=\max _{\mathfrak{\mathfrak { b }} \in \operatorname{Spin}^{\mathrm{c}}(W)}\left(d\left(Y_{0}, \mathfrak{\mathfrak { l }} \mid Y_{0}\right)+g r(W, \mathfrak{\mathfrak { W }})\right) .  \tag{20}\\
& \text { § } \mid Y_{1}=\mathrm{t}
\end{align*}
$$

Lemma 4.5. There are exactly two Spinc structures $\mathfrak{e}_{0}, \mathfrak{e}_{1} \in \operatorname{Spin}^{c}\left(Y_{0}\right)$ which can be extended over $Z_{0}$. Moreover,

$$
\mathfrak{e}_{1}=\mathfrak{e}_{0}+\alpha_{0}, \quad d\left(Y_{0}, \mathfrak{e}_{i}\right)=0, \quad i=0,1
$$

Proof. By Lemma 4.1, $\alpha_{0}$ is the restriction of a cohomology class in $H^{2}\left(Z_{0}\right)$. Let $\mathfrak{e}_{0} \in \operatorname{Spin}^{\mathrm{c}}\left(Y_{0}\right)$ be a $\operatorname{Spin}^{c}$ structure which is the restriction of a Spin ${ }^{c}$ structure on $Z_{0}$, then $\mathfrak{e}_{1}:=\mathfrak{e}_{0}+\alpha_{0}$ also extends over $Z_{0}$. Since $H^{2}\left(Z_{0}\right) \cong \mathbb{Z} / 2 \mathbb{Z}, \mathfrak{e}_{0}, \mathfrak{e}_{1}$ are the only two $\operatorname{Spin}^{c}$ structures which can be extended over $Z_{0}$. It follows from [15, Proposition 9.9] that $d\left(Y_{0}, \mathfrak{e}_{i}\right)=0$.

Lemma 4.6. The image of

$$
\bar{c}_{1}:\left(v_{0}^{s}\right)^{-1}\left(\left\{\mathfrak{e}_{0}, \mathfrak{e}_{1}\right\}\right) \rightarrow \bar{H}^{2}(W)
$$

is $C:=\operatorname{Char}(\mathcal{L})$.
Proof. Let $\mathfrak{s}_{0}$ be the restriction of a $\operatorname{Spin}^{c}$ structure on $Z$ to $W$, then $\mathfrak{s}_{0} \in\left(l_{0}^{s}\right)^{-1}\left(\left\{\mathfrak{e}_{0}, \mathfrak{e}_{1}\right\}\right)$. Clearly, $\bar{c}_{1}\left(\mathfrak{s}_{0}\right) \in \mathcal{C}$. By Lemma 4.1, $\iota_{W, Z}^{*}$ is injective, so the image of $H^{2}(Z)$ in $\bar{H}^{2}(W)$ can be identified with $\operatorname{Hom}\left(H_{2}(Z), \mathbb{Z}\right)=\operatorname{Hom}\left(H_{2}\left(W, Y_{0}\right), \mathbb{Z}\right)=\mathcal{L}^{*}$. Thus $\bar{c}_{1}\left(\left(\iota_{0}^{s}\right)^{-1}\left(\left\{e_{0}, \mathfrak{e}_{1}\right\}\right)\right)$ is a $2 \mathcal{L}^{*}$-torsor. Since $\mathcal{C}$ is the unique $2 \mathcal{L}^{*}$-torsor containing $\bar{c}_{1}\left(\mathfrak{F}_{0}\right)$, our conclusion holds.

Corollary 4.7. The sum

$$
\begin{equation*}
\sum_{\mathfrak{t} \in \operatorname{Spin}^{\mathrm{c}}\left(Y_{1}\right)} D_{W}\left(Y_{1}, \mathfrak{t}\right) \tag{21}
\end{equation*}
$$

only depends on the lattice $\mathcal{L}$ and the correction terms of $Y_{0}$. In fact, if we write (21) as a function

$$
\mathscr{D}\left(\mathcal{L},\left\{d_{0}, d_{1}\right\}\right)
$$

of $\mathcal{L}$ and the multiset $\left\{d_{0}, d_{1}\right\}$ of the correction terms of the two Spin ${ }^{c}$ structures other than $\mathfrak{e}_{0}, \mathfrak{e}_{1}$, then

$$
\begin{equation*}
\mathscr{D}\left(\mathcal{L},\left\{d_{0}+c, d_{1}+c\right\}\right)=\mathscr{D}\left(\mathcal{L},\left\{d_{0}, d_{1}\right\}\right)+c\left|\mathcal{L}_{0}^{*} / \mathcal{L}\right| \tag{22}
\end{equation*}
$$

for any $c \in \mathbb{Q}$. Note that, by Proposition 4.4, $\left|H_{1}\left(Y_{1}\right)\right|=2\left|\mathcal{L}_{0}^{*} / \mathcal{L}\right|$.
Proof. We will give the procedure of computing (21) from $\mathcal{L}$ and the correction terms of $Y_{0}$. Let $\mathfrak{o}_{0}, \mathfrak{p}_{1}$ be the two $\operatorname{Spin}^{c}$ structures other than $\mathfrak{e}_{0}, \mathfrak{e}_{1}$ on $Y_{0}$. We choose $[z] \in \widetilde{C} / 2 \mathcal{L}$. By Proposition 4.4, $[z]$ corresponds to a pair of $\operatorname{Spin}^{c}$ structures $\mathrm{t}_{0}, \mathrm{t}_{1}=\mathrm{t}_{0}+\alpha_{1} \in \operatorname{Spin}^{c}\left(Y_{1}\right)$. There are exactly two $2 \mathcal{L}_{0}$-torsors contained in $z+2 \mathcal{L}$, denoted by $\mathcal{T}_{0}, \mathcal{T}_{1}$.

Next we check whether $z+2 \mathcal{L}$ is contained in $\mathcal{C}$. If it is contained in $\mathcal{C}$, it follows from Lemma 4.6 that each $\mathfrak{t}_{i}$ is cobordant to $\mathfrak{e}_{0}$ and $\mathfrak{e}_{1}, i=0$, 1 . Since $d\left(Y_{0}, \mathfrak{e}_{0}\right)=d\left(Y_{0}, \mathfrak{e}_{1}\right)=0$, by Proposition 4.4,

$$
D_{W}\left(Y_{1}, \mathrm{t}_{0}\right)=D_{W}\left(Y_{1}, \mathrm{t}_{1}\right)=0+\max _{y \in z+2 \mathcal{L}} \frac{-\langle y, y\rangle+b_{2}(W)}{4}
$$

If $z+2 \mathcal{L}$ is not contained in $\mathcal{C}$, then each $\mathfrak{t}_{i}$ is cobordant to $\mathfrak{v}_{0}$ and $\mathfrak{v}_{1}$. By Proposition 4.4, the multiset $\left\{D_{W}\left(Y_{1}, \mathbf{t}_{0}\right), D_{W}\left(Y_{1}, \mathbf{t}_{1}\right)\right\}$ is equal to

$$
\begin{aligned}
& \left\{\max \left\{d\left(Y_{0}, \mathfrak{v}_{0}\right)+\max _{y \in \mathcal{T}_{0}} \frac{-\langle y, y\rangle+b_{2}(W)}{4}, d\left(Y_{0}, \mathfrak{o}_{1}\right)+\max _{y \in \mathcal{T}_{1}} \frac{-\langle y, y\rangle+b_{2}(W)}{4}\right\}\right. \\
& \left.\quad \max \left\{d\left(Y_{0}, \mathfrak{v}_{0}\right)+\max _{y \in \mathcal{T}_{1}} \frac{-\langle y, y\rangle+b_{2}(W)}{4}, d\left(Y_{0}, \mathbf{v}_{1}\right)+\max _{y \in \mathcal{T}_{0}} \frac{-\langle y, y\rangle+b_{2}(W)}{4}\right\}\right\} .
\end{aligned}
$$

Finally, to get (21), we add all the $D_{W}\left(Y_{1}, \mathfrak{t}_{0}\right)+D_{W}\left(Y_{1}, \mathbf{t}_{1}\right)$ together, for all $[z] \in \widetilde{C} / 2 \mathcal{L}$.

The equality (22) follows from the above procedure, since exactly $\frac{1}{2}\left|H_{1}\left(Y_{1}\right)\right|$ values of $D_{W}\left(Y_{1}, \mathbf{t}\right)$ are increased by $c$ after increasing $d\left(Y_{0}, \mathfrak{v}_{i}\right)$ by $c, i=0,1$.

## 5 | SHARP COBORDISMS

In this section, we will generalize the notion of sharp 4-manifolds defined by Greene [10] to 4dimensional cobordisms, and prove that certain cobordisms between prism manifolds are sharp. Recall that a smooth, compact, negative definite 4-manifold $X$ with $\partial X=Y$ is sharp if for every $\mathfrak{t} \in \operatorname{Spin}^{c}(Y)$, there exists some $\mathfrak{z} \in \operatorname{Spin}^{c}(X)$ extending $\mathfrak{t}$ such that

$$
c_{1}(\mathfrak{\mathfrak { j }})^{2}+b_{2}(X)=4 d(Y, \mathfrak{t})
$$

Definition 5.1. Let $W: Y_{0} \rightarrow Y_{1}$ be a smooth, connected, negative definite cobordism between two rational homology spheres $Y_{0}$ and $Y_{1}$. We say $W$ is sharp, if for any $\mathrm{t} \in \operatorname{Spin}^{\mathrm{c}}\left(Y_{1}\right)$, we have

$$
d\left(Y_{1}, \mathbf{t}\right)=D_{W}\left(Y_{1}, \mathbf{t}\right)
$$

Here $D_{W}$ is defined using the formula (20).
Lemma 5.2. Let $Y_{1}, Y_{2}, Y_{3}$ be rational homology spheres, $W_{1}: Y_{1} \rightarrow Y_{2}$ and $W_{2}: Y_{2} \rightarrow Y_{3}$ be two negative definite cobordisms. If $W=W_{1} \cup_{Y_{2}} W_{2}$ is sharp, then $W_{2}$ is sharp.

Proof. Let $\mathfrak{\mathfrak { G }} \in \operatorname{Spin}^{\mathfrak{C}}(W)$ and let $\mathfrak{\mathfrak { B }}_{i}=\mathfrak{\mathfrak { l }} \mid W_{i}, i=1,2$, then

$$
c_{1}^{2}(\mathfrak{\mathfrak { g }})=c_{1}^{2}\left(\mathfrak{I}_{1}\right)+c_{1}^{2}\left(\mathfrak{I}_{2}\right) .
$$

Our conclusion follows from the above equality.

## 5.1 | A Kirby diagram of $\boldsymbol{P}(\boldsymbol{p}, \boldsymbol{q})$

Suppose that

$$
\frac{p}{q}=\left[a_{-1}, a_{0}, \ldots, a_{n}\right]^{-}
$$

as in (14), where each $a_{i}$ is $\geqslant 2$ when $i \geqslant 0$.
Figure 2 is a surgery diagram of $P(p, q)$. The leftmost two components give rise to a surgery diagram of $P\left(a_{-1}, 1\right)$, and other components give rise to a negative definite cobordism

$$
W(p, q): P\left(a_{-1}, 1\right) \rightarrow P(p, q)
$$

If we replace the leftmost component, which is unknotted with slope 0 , with a dotted circle representing a one-handle, we get a negative definite 4-manifold $Z(p, q)$ bounded by $P(p, q)$, and the two leftmost components give rise to a rational homology ball $Z_{a_{-1}}$ bounded by $P\left(a_{-1}, 1\right)$, with $H_{1}\left(Z_{a_{-1}}\right)=\mathbb{Z} / 2 \mathbb{Z}$.

The main result of this section is the following proposition.

Proposition 5.3. The cobordism $W(p, q)$ is sharp.


FIGURE 2 A manifold bounded by $P(p, q)$. If we replace the leftmost component with a dotted circle, we get a negative definite 4-manifold $Z(p, q)$

For simplicity, we only prove the case $q<p<2 q$. The proof of the general case is similar. From now on, let $W=W(p, q)$.

## 5.2 | More Kirby diagrams

We will consider three other cobordisms.
When $q<p<2 q, a_{-1}=2$. We have

$$
\frac{2 q-(p-q)}{q-(p-q)}=1+\frac{q}{2 q-p}=\left[a_{0}+1, a_{1}, \ldots, a_{n}\right]^{-}
$$

Consider the following surgery diagram of $P(p-q, q)$. By [2], this diagram gives rise to a sharp 4-manifold bounded by $P(p-q, q)$. The component with label -4 gives rise to $P(1,1)=L(4,-1)$, and the other two-handles give rise to a cobordism

$$
W_{1}: P(1,1) \rightarrow P(p-q, q) .
$$

Let

$$
\frac{p+q}{p}=\left[a_{0}^{\prime}, a_{1}^{\prime}, \ldots, a_{m}^{\prime}\right]^{-} .
$$

By [1], $P(p,-q)$ has a surgery diagram as in Figure 4, which gives rise to a sharp 4-manifold bounded by $P(p,-q)$. The two components with label -2 give rise to $P(0,1)=\mathbb{R} P^{3} \# \mathbb{R} P^{3}$, and the other two-handles give rise to a cobordism

$$
W^{\prime}: P(0,1) \rightarrow P(p,-q)
$$

Using the continued fraction

$$
\frac{-2 q-(p-q)}{-q-(p-q)}=\frac{p+q}{p}=\left[a_{0}^{\prime}, a_{1}^{\prime}, \ldots, a_{m}^{\prime}\right]^{-}
$$

by [2], we get a surgery diagram of $P(p-q,-q)$ as in Figure 5, which gives rise to a sharp 4manifold bounded by $P(p-q,-q)$. The component with label -4 gives rise to $P(1,1)=L(4,-1)$, and the other two-handles give rise to a cobordism

$$
W_{1}^{\prime}: P(1,1) \rightarrow P(p-q,-q)
$$



FIGURE 3 A sharp 4-manifold $X(p-q, q)$ bounded by $P(p-q, q)$

By Lemma 5.2, $W_{1}, W^{\prime}, W_{1}^{\prime}$ are all sharp cobordisms.
Lemma 5.4. The intersection lattices on $(W, P(2,1))$ and $\left(W_{1}, P(1,1)\right)$ are isomorphic; also, the intersection lattices on $\left(W^{\prime}, P(0,1)\right)$ and $\left(W_{1}^{\prime}, P(1,1)\right)$ are isomorphic.

Proof. In Figure 2, consider the knot $L_{0}$ with label $-a_{0}$. The canonical longitude on $L_{0}$ is clearly rationally null-homologous in $P(2,1) \backslash L_{0}$. As a result, the square of the generator of $H_{2}(W, P(2,1))$ corresponding to the two-handle attached along $L_{0}$ is $-a_{0}$. In Figure 3, consider the knot $K_{0}$ with label $-\left(a_{0}+1\right)$. If the framing on $K_{0}$ is -1 , the manifold we get by doing surgery on the two leftmost components is $P(1,0)$ which has $b_{1}>0$. Thus the slope -1 on $K_{0}$ is rationally null-homologous in $P(1,1) \backslash K_{0}$. As a result, the square of the generator of $H_{2}\left(W_{1}, P(1,1)\right)$ corresponding to the two-handle attached along $K_{0}$ is $-a_{0}$. So the intersection lattices on ( $W, P(2,1)$ ) and $\left(W_{1}, P(1,1)\right)$ are isomorphic.

Similarly, we see that the square of the generator of $H_{2}\left(W^{\prime}, P(0,1)\right)$ and $H_{2}\left(W_{1}^{\prime}, P(1,1)\right)$ corresponding to the two-handle attached along the knot with label $-a_{0}^{\prime}$ is $-\left(a_{0}^{\prime}-1\right)$. So the intersection lattices are isomorphic.

Lemma 5.5. All four cobordisms $W, W_{1}, W^{\prime}, W_{1}^{\prime}$ satisfy the assumptions in the beginning of Section 4.

Proof. The cobordism $W$ satisfies the assumptions by its construction.
For $W_{1}, W_{1}^{\prime}$, note that $P(1,1)$ bounds a rational homology ball $Z_{1}$ with $H_{1}\left(Z_{1}\right) \cong \mathbb{Z} / 2 \mathbb{Z}$. Since $H_{1}(P(1,1))$ is cyclic, the kernel of the surjective map $H_{1}(P(1,1)) \rightarrow H_{1}\left(Z_{1}\right)$ is $2 H_{1}(P(1,1))$. From Figures 3 and 5, we see that the knot with label $-\left(a_{0}+1\right)$ or $-a_{0}^{\prime}$ represents an element in $2 H_{1}(P(1,1))$. So $W_{1}, W_{1}^{\prime}$ satisfy the assumptions.

For $W^{\prime}$, the rational ball bounded by $\mathbb{R} P^{3} \# \mathbb{R} P^{3}$ is $Z_{0}=\left(\mathbb{R} P^{3} \backslash B^{3}\right) \times I$. Clearly, the knot labeled with $-a_{0}^{\prime}$ in Figure 4 is null-homologous in $Z_{0}$.

## 5.3 | The proof of Proposition 5.3

Recall from Section 5.1 that $P(a, 1)$ bounds a rational homology ball $Z_{a}$ with $H_{1}\left(Z_{a}\right) \cong \mathbb{Z} / 2 \mathbb{Z}$. There are exactly two $\operatorname{Spin}^{c}$ structures $\mathfrak{e}_{0}, \mathfrak{e}_{1} \in \operatorname{Spin}^{c}(P(a, 1))$ which extend over $Z_{a}$. Let $\mathfrak{p}_{0}, \mathfrak{v}_{1} \in$ $\operatorname{Spin}^{c}(P(a, 1))$ be two other $\operatorname{Spin}^{c}$ structures, such that $d\left(P(a, 1), \mathfrak{v}_{1}\right) \geqslant d\left(P(a, 1), \mathfrak{p}_{0}\right)$.


FIGURE 4 A sharp 4-manifold bounded by $P(p,-q)$


FIGURE 5 A sharp 4-manifold bounded by $P(p-q,-q)$

Lemma 5.6. The correction terms of $P(a, 1)$ are

$$
\begin{gathered}
d\left(P(a, 1), \mathfrak{e}_{0}\right)=d\left(P(a, 1), \mathfrak{e}_{1}\right)=0 \\
d\left(P(a, 1), \mathfrak{s}_{0}\right)=-\frac{a+2}{4}, \quad d\left(P(a, 1), \mathfrak{o}_{1}\right)=-\frac{a-2}{4}
\end{gathered}
$$

Proof. The correction terms of $P(a, 1)$ are computed in [6, Example 15], and they are $\left\{0,0,-\frac{a+2}{4}, \frac{a-2}{4}\right\}$. It is a standard fact that $d\left(P(a, 1), \mathfrak{e}_{i}\right)=0, i=0,1$ [15, Proposition 9.9]. So we must have $d\left(P(a, 1), \mathfrak{v}_{i}\right)=-\frac{a+2}{4}+i, i=0,1$, by our choice of $\mathfrak{p}_{0}, \mathfrak{v}_{1}$.

Proof of Proposition 5.3 in the case $q<p<2 q$. By [15, Theorem 9.6],

$$
\begin{equation*}
d(P(p, q), \mathbf{t}) \geqslant D_{W}(P(p, q), \mathfrak{t}) . \tag{23}
\end{equation*}
$$

Also, since $W_{1}, W^{\prime}, W_{1}^{\prime}$ are sharp, we have

$$
\begin{aligned}
d\left(P(p-q, q), \mathbf{t}_{1}\right) & =D_{W_{1}}\left(P(p-q, q), \mathbf{t}_{1}\right) \\
d(P(p,-q), \mathfrak{t}) & =D_{W^{\prime}}(P(p,-q), \mathfrak{t}) \\
d\left(P(p-q,-q), \mathbf{t}_{1}\right) & =D_{W_{1}^{\prime}}\left(P(p-q,-q), \mathbf{t}_{1}\right)
\end{aligned}
$$

By Corollary 4.7, Lemma 5.4 and Lemma 5.6,

$$
\begin{array}{r}
\sum_{\mathfrak{t}^{\operatorname{S\operatorname {Sin}^{\mathrm {c}}(P(p,q))}} D_{W}(P(p, q), \mathfrak{t})}=-\frac{2 q}{4}+\sum_{\mathrm{t}_{1} \in \operatorname{Sin}^{\mathrm{c}}(P(p-q, q))} D_{W_{1}}\left(P(p-q, q), \mathrm{t}_{1}\right), \\
-\frac{2 q}{4}+\sum_{\mathrm{t} \in \operatorname{Spin}^{\mathrm{c}}(P(p,-q))} D_{W^{\prime}}(P(p,-q), \mathfrak{t})=\sum_{\mathrm{t}_{1} \in \operatorname{Spin}^{\mathrm{c}}(P(p-q,-q))} D_{W_{1}^{\prime}}\left(P(p-q,-q), \mathfrak{t}_{1}\right) .
\end{array}
$$

Adding the above two equalities together, and using (23) and the three equalities after it, we get

$$
\begin{aligned}
& 0=\sum_{\mathrm{t} \in \operatorname{Sin}^{\mathrm{c}}(P(p, q))} d(P(p, q), \mathrm{t})+\sum_{\mathrm{t} \in \operatorname{Spin}^{\mathrm{c}}(P(p,-q))} d(P(p,-q), \mathfrak{t}) \quad(\text { since } P(p, q)=-P(p,-q)) \\
& \geqslant \sum_{\mathfrak{t} \in \operatorname{Spin}^{\mathrm{c}}(P(p, q))} D_{W}(P(p, q), \mathfrak{t})+\sum_{\mathrm{t} \in \operatorname{Spin}^{\mathrm{c}}(P(p,-q))} D_{W^{\prime}}(P(p,-q), \mathfrak{t}) \\
& =\sum_{\mathfrak{t}_{1} \in \operatorname{Sin}^{c}(P(p-q, q))} D_{W_{1}}\left(P(p-q, q), \mathbf{t}_{1}\right)+\sum_{\mathbf{t}_{1} \in \operatorname{Spin}^{c}(P(p-q,-q))} D_{W_{1}^{\prime}}\left(P(p-q,-q), \mathbf{t}_{1}\right) \\
& =\sum_{\mathbf{t}_{1} \in \operatorname{Sin}^{c}(P(p-q, q))} d\left(P(p-q, q), \mathrm{t}_{1}\right)+\sum_{\mathbf{t}_{1} \in \operatorname{Sin}^{\mathrm{c}}(P(p-q,-q))} d\left(P(p-q,-q), \mathrm{t}_{1}\right) \\
& =0 \text {. }
\end{aligned}
$$

So the equality in (23) must hold.

## 6 I THE CHANGEMAKER CONDITION WHEN $q<p<2 q$

## 6.1 | Positive definite manifold with boundary $\boldsymbol{P}(2,1)$

The goal of this subsection is to prove the following proposition.
Proposition 6.1. If $X$ is a positive definite, simply connected four-manifold with $\partial X \cong P(2,1)$, then the intersection form of $X$ is isomorphic to $D_{4} \oplus \mathbb{Z}^{n-4}$ for some $n$.

Here, $D_{k}$ is the sublattice of $\mathbb{Z}^{k}$ consisting of vectors for which the sum of the coefficients is even.

Lemma 6.2. If $L \subset \mathbb{Z}^{n}$ is an index-two sublattice, then $L \cong D_{k} \oplus \mathbb{Z}^{n-k}$ for some $k \geqslant 1$. In fact, there are indices $i_{1}, \ldots, i_{k}$ such that $L$ contains exactly the elements of $\mathbb{Z}^{n}$ that have even pairing with $e_{i_{1}}+$ $\cdots+e_{i_{k}}$. There are always two elements $x \in \bar{L}$ with $b(x, x)=0(\bmod 1)$, and the other two elements satisfy $b(x, x)=k / 4(\bmod 1)$.

Proof. Let $L \subset \mathbb{Z}^{n}$ have index two, and let $i_{1}, \ldots, i_{k}$ be an enumeration of the indices $i$ for which $e_{i} \notin L$. Since $L$ has index two, the elements $\pm e_{i_{j}} \pm e_{i_{j}}$, are all in $L$. Since these elements generate $D_{k}$, we have $L \cong D_{k} \oplus \mathbb{Z}^{n-k}$.

The dual lattice $L^{*}$ is the set of elements of $\mathbb{Q}^{n}$ with integral inner product with each element of $L$, and in this representation we have that $L^{*}$ is the set of vectors with integer components in
all entries other than $i_{1}, \ldots, i_{k}$, and with the components in entries $i_{1}, \ldots, i_{k}$ either all integers or all half integers. Therefore, the discriminant group $\bar{L}$ can be represented by the four vectors 0 , $z=e_{i_{1}}$, and

$$
\begin{aligned}
& a=\frac{1}{2}\left(e_{i_{1}}+e_{i_{2}}+\cdots+e_{i_{k}}\right), \\
& b=\frac{1}{2}\left(-e_{i_{1}}+e_{i_{2}}+\cdots+e_{i_{k}}\right) .
\end{aligned}
$$

We have $\langle z, z\rangle=1 \equiv 0(\bmod 1)$, and $\langle a, a\rangle=\langle b, b\rangle=k / 4$.
Lemma 6.3. The d-invariant of $L=D_{k} \oplus \mathbb{Z}^{n-k}$ takes on the values $0,0,-k / 4,1-k / 4$.
Proof. The d-invariant is invariant under stable isomorphisms, so we can assume $L=D_{k}$. Then a set of short representatives of the classes of characteristic covectors is $(1, \ldots, 1),(-1,1, \ldots, 1)$, $(0, \ldots, 0)$, and $(2,0, \ldots, 0)$. These have norms $k, k, 0$, and 4 . The result now follows: see equation (13).

Proof of Proposition 6.1. As in Section 5.1, $P(2,1)$ bounds a rational homology ball $Z_{2}$ with

$$
H_{1}\left(Z_{2}\right) \cong \mathbb{Z} / 2 \mathbb{Z}, H_{2}\left(Z_{2}\right)=0
$$

If $X$ is any simply connected positive definite 4 -manifold with boundary $P(2,1)$, then $\widehat{X}:=$ $X \cup_{P(2,1)}\left(-Z_{2}\right)$ is a closed, positive definite 4-manifold. Since $\widehat{X}$ can be obtained from $X$ by attaching a two-handle, a three-handle and a four-handle, $\widehat{X}$ is also simply connected. By [8], $\widehat{X}$ has intersection form $\mathbb{Z}^{n}$.

In the long exact sequence for the pair $(\hat{X}, X)$, we have

$$
H_{3}(\widehat{X}, X) \rightarrow H_{2}(X) \rightarrow H_{2}(\widehat{X}) \rightarrow H_{2}(\widehat{X}, X) \rightarrow H_{1}(X)
$$

We have

$$
H_{3}(\widehat{X}, X) \cong H_{3}\left(Z_{2}, \partial Z_{2}\right) \cong H^{1}\left(Z_{2}\right)=0, \quad H_{2}(\widehat{X}, X) \cong H^{2}\left(Z_{2}\right) \cong \mathbb{Z} / 2 \mathbb{Z}, \quad H_{1}(X)=0
$$

and both $H_{2}(X)$ and $H_{2}(\widehat{X})$ are torsionfree. Therefore, we have a short exact sequence

$$
0 \rightarrow H_{2}(X) \rightarrow H_{2}(\widehat{X}) \rightarrow \mathbb{Z} / 2 \mathbb{Z} \rightarrow 0,
$$

so $H_{2}(X)$ is an index-two subgroup of $H_{2}(\widehat{X})$ under the natural inclusion map. Since $\widehat{X}$ has intersection lattice $\mathbb{Z}^{n}$, the intersection lattice of $X$ is an index-two sublattice of $\mathbb{Z}^{n}$, so, by Lemma 6.2, is isomorphic to $D_{k} \oplus \mathbb{Z}^{n-k}$.

Let $X_{0}$ be the positive definite plumbing 4-manifold with intersection form $D_{4}$, then $P(2,1)=$ $\partial X_{0}$. Since the discriminant group and linking pairing of the intersection form of a 4-manifold are invariants of its boundary, Lemma 6.2 implies that $k$ must be divisible by 4 . Since the d-invariant of the intersection form of a positive definite 4-manifold gives an upper bound on the d-invariant of its boundary [15] and $-X_{0}$ is sharp [16], Lemma 6.3 implies $k \leqslant 4$. Therefore, $k=4$, and the result follows.

Corollary 6.4. Any negative definite, simply connected 4 -manifold with boundary $-P(2,1)$ is sharp.

Proof. The 4-manifold $-X_{0}$ is sharp. By Proposition 6.1, any negative definite, simply connected 4manifold with boundary $-P(2,1)$ has the same intersection form as that of $-X_{0} \#(n-4) \overline{\mathbb{C} P^{2}}$.

## 6.2 | The changemaker condition

Whenever $q<p<2 q$, using Proposition 5.3, there is a sharp cobordism $W$ from $P(2,1)$ to $P(p, q)$. Suppose $P(p, q)$ is positive surgery on some knot $K \subset S^{3}$. Let $X=W \cup_{P(p, q)}\left(-W_{4 q}(K)\right)$, then $X$ is a negative definite manifold with boundary $-P(2,1)$. Since $X$ is obtained from $W_{4 q}$ (which is simply connected) by adding two-handles, $X$ is simply connected. By combining Corollary 6.4 and Proposition 6.1, $X$ is sharp and has intersection lattice $-\left(D_{4} \oplus \mathbb{Z}^{n-2}\right)$. Also, for $Z_{2}$ the rational homology ball with boundary $P(2,1)$, the manifold $\widehat{X}=X \cup_{P(2,1)}\left(-Z_{2}\right)$ is closed, simply connected and negative definite, so has intersection lattice $-\mathbb{Z}^{n+2}$. From Kirby diagrams for $W$ and $Z=W \cup_{P(2,1)}\left(-Z_{2}\right)$ (see Figure 2), we can also see that the intersection lattice of $Z$ is the linear lattice $\Lambda(q,-p)$ with vertex basis $x_{0}, \ldots, x_{n}$, and the intersection lattice of $W$ is (as a sublattice of $\Lambda(q,-p))$ spanned by $2 x_{0}, x_{1}, \ldots, x_{n}$. Therefore, the following diagram of homology groups

with maps induced by inclusions is isomorphic to the diagram


Lemma 6.5. As subgroups of $\mathrm{H}_{2}(\widehat{X})$,

$$
H_{2}(W)=H_{2}(Z) \cap H_{2}(X) .
$$

Proof. By the exact sequence $H_{2}(Z) \rightarrow H_{2}(\widehat{X}) \rightarrow H_{2}(\widehat{X}, Z)$, an element $\beta \in H_{2}(\widehat{X})$ is contained in the image of $H_{2}(Z)$ if and only if the image of $\beta$ in $H_{2}(\widehat{X}, Z) \cong H_{2}\left(W_{4 q}(K), \partial W_{4 q}(K)\right)$ is zero. Similarly, $\beta$ is contained in the image of $H_{2}(X)$ if and only if the image of $\beta$ in $H_{2}(\widehat{X}, X) \cong H_{2}\left(Z_{2}, \partial Z_{2}\right)$ is zero, and $\beta$ is contained in the image of $H_{2}(W)$ if and only if the image of $\beta$ in $H_{2}(\widehat{X}, W) \cong$ $H_{2}\left(Z_{2}, \partial Z_{2}\right) \oplus H_{2}\left(W_{4 q}(K), \partial W_{4 q}(K)\right)$ is zero. Our conclusion follows easily.

The last piece of data we need is the class $[\widehat{F}] \in H_{2}\left(-W_{4 q}(K)\right) \subset H_{2}(X)$, where $\widehat{F}$ is obtained by smoothly gluing the core of the handle attachment to a copy of a minimal genus Seifert surface $F$ for $K$; its homology class generates the second homology. Note that $H_{2}\left(-W_{4 q}(K)\right)$ is orthogonal to all of $H_{2}(W)$ and satisfies $\langle[\widehat{F}],[\widehat{F}]\rangle=-4 q$ since $-W_{4 q}(K)$ is negative definite. Let

$$
\varphi: \mathbb{Z} / 4 q \mathbb{Z} \rightarrow \operatorname{Spin}^{\mathrm{c}}(P(p, q))
$$

be the correspondence with $\varphi(i)$ equal $\left.\mathfrak{I}_{0}\right|_{P(p, q)}$ for $\mathfrak{S}_{0}$ any $\operatorname{Spin}^{\mathrm{c}}$ structure on $-W_{4 q}(K)$ satisfying

$$
\left\langle c_{1}\left(\mathfrak{I}_{0}\right),[\widehat{F}]\right\rangle \equiv-4 q+2 i \quad(\bmod 8 q)
$$

Proposition 6.6. There is an extension $\mathfrak{r} \in \operatorname{Spin}^{c}(X)$ of $\varphi(i)$ over $X$ with $c_{1}(\mathfrak{r})$ a short characteristic covector of $D_{4} \oplus \mathbb{Z}^{n-2}$ if any only if $g(K) \leqslant i \leqslant 4 q-g(K)$.

Proof. Since $X$ has boundary $-P(2,1)$ and $b_{2}(X)=n+2$, we have that for any $\mathfrak{r} \in \operatorname{Spin}^{\mathrm{c}}(X)$,

$$
\begin{equation*}
d\left(-P(2,1),\left.\mathfrak{r}\right|_{P(2,1)}\right) \geqslant \frac{\left(c_{1}(\mathfrak{r})\right)^{2}+(n+2)}{4} \tag{24}
\end{equation*}
$$

and since $X$ is sharp this is an equality if and only if $c_{1}(\mathfrak{r})$ is a short characteristic covector of $-H_{2}(X)=D_{4} \oplus \mathbb{Z}^{n-2}$. Similarly, for any $\mathfrak{G}_{1} \in \operatorname{Spin}^{c}(W)$,

$$
\begin{equation*}
d\left(P(p, q),\left.\mathfrak{l}_{1}\right|_{P(p, q)}\right) \geqslant d\left(P(2,1),\left.\mathfrak{F}_{1}\right|_{P(2,1)}\right)+\frac{\left(c_{1}\left(\mathfrak{F}_{1}\right)\right)^{2}+(n+1)}{4} \tag{25}
\end{equation*}
$$

and since $W$ is sharp as a cobordism, for each $\mathrm{t} \in \operatorname{Spin}^{\mathrm{c}}(P(p, q))$ there is some $\mathfrak{B}_{1} \in \operatorname{Spin}^{\mathrm{c}}(W)$ such that this is an equality and $\left.\mathfrak{\Xi}_{1}\right|_{P(p, q)}=\mathbf{t}$.

For $\mathfrak{\Xi}_{0} \in \operatorname{Spin}^{\mathrm{c}}\left(-W_{4 q}(K)\right)$ with

$$
\left\langle c_{1}\left(\mathfrak{B}_{0}\right),[\widehat{F}]\right\rangle=-4 q+2 i
$$

(so that in particular $\varphi(i)=\left.\mathfrak{\mathfrak { g }}_{0}\right|_{P(p, q)}$ ), we have

$$
\left(c_{1}\left(\mathfrak{F}_{0}\right)\right)^{2}=-\frac{(-4 q+2 i)^{2}}{4 q}
$$

Using (8) and (9), we have

$$
d\left(P(p, q),\left.\mathfrak{\mathfrak { G }}_{0}\right|_{P(p, q)}\right)=\frac{-\left(c_{1}\left(\mathfrak{S}_{0}\right)\right)^{2}-1}{4}-2 t_{\min \{i, 4 q-i\}}(K) .
$$

Since $t_{i}(K) \geqslant 0$ and (5),

$$
\begin{equation*}
d\left(P(p, q),\left.\mathfrak{\mathfrak { g }}_{0}\right|_{P(p, q)}\right) \leqslant \frac{-\left(c_{1}\left(\mathfrak{F}_{0}\right)\right)^{2}-1}{4} \tag{26}
\end{equation*}
$$

with equality if and only if $\left\langle c_{1}\left(\mathfrak{B}_{0}\right),[\widehat{F}]\right\rangle=-4 q+2 i$ for some $i$ with $g(K) \leqslant i \leqslant 4 q-g(K)$. Note that inequality (24) is the difference of inequalities (26) and (25) if $\left.\mathfrak{\Xi}_{0}\right|_{P(p, q)}=\left.\mathfrak{\Xi}_{1}\right|_{P(p, q)}$. If $g(K) \leqslant$ $i \leqslant 4 q-g(K)$, then there is some extension $\mathfrak{\Xi}_{0}$ of $\varphi(i)$ over $-W_{4 q}(K)$ that achieves equality in (26), and there is always some extension $s_{1}$ of $\varphi(i)$ over $W$ achieving equality in (25). These two Spin ${ }^{\text {c }}$ structures glue to a Spin ${ }^{\text {c }}$ structure $\mathfrak{r}$ on $X=W \cup\left(-W_{4 q}(K)\right)$ that will achieve equality in (24), so $c_{1}(\mathfrak{r})$ is short and $\left.\mathfrak{r}\right|_{P(p, q)}=\varphi(i)$.

Conversely, if $\mathfrak{r} \in \operatorname{Spin}^{\mathfrak{c}}(X)$ has $\boldsymbol{c}_{1}(\mathfrak{r})$ short, then $\mathfrak{r}$ achieves equality in (24), so $\mathfrak{\Xi}_{0}=\left.\mathfrak{r}\right|_{-W_{4 q}(K)}$ and $\mathfrak{\mathfrak { G }}_{1}=\left.\mathfrak{r}\right|_{W}$ will achieve equality in (25) and (26), respectively. Therefore, $\left.\mathfrak{g}_{0}\right|_{P(p, q)}=\left.\mathfrak{r}\right|_{P(p, q)}$ will equal $\varphi(i)$ for some $g(K) \leqslant i \leqslant 4 q-g(K)$.

Putting all of these together, we have a Euclidean lattice $\mathbb{Z}^{n+2}=-H_{2}(\widehat{X})$, with a corank -1 , linear sublattice

$$
-H_{2}(W) \cong \Lambda(q,-p)=\left\langle x_{0}, \ldots, x_{n}\right\rangle
$$

and a sublattice $D_{4} \oplus \mathbb{Z}^{n-2}=-H_{2}(X)$ such that

$$
\begin{equation*}
\left\langle 2 x_{0}, \ldots, x_{n}\right\rangle=\left\langle x_{0}, \ldots, x_{n}\right\rangle \cap\left(D_{4} \oplus \mathbb{Z}^{n-2}\right) . \tag{27}
\end{equation*}
$$

Since $\Lambda(q,-p)$ has discriminant $q$ and corank 1 and is embedded primitively in $\mathbb{Z}^{n+2}$ (this follows from the long exact sequence of the pair ( $X \cup Z_{0}, W \cup Z_{0}$ ) , the orthogonal complement of $\Lambda(q,-p)$ has discriminant $q$ and rank 1 , so is generated by a vector $\sigma$ with $\langle\sigma, \sigma\rangle=q$. Since $|\langle[\widehat{F}],[\widehat{F}]\rangle|=4 q$ and $[\widehat{F}]$ is contained in the orthogonal complement of $\Lambda(q,-p)$, we must have $[\widehat{F}]=2 \sigma$. Therefore, Proposition 6.6 gives the following:

Proposition 6.7. If $P(p, q)$ is the result of $4 q$ surgery on some knot $K \subset S^{3}$ and $q<p<2 q$, then there is an embedding of $\Lambda(q,-p)$ into $\mathbb{Z}^{n+2}$ as the orthogonal complement of a vector $\sigma$ and an embedding $D_{4} \oplus \mathbb{Z}^{n-2} \hookrightarrow \mathbb{Z}^{n+2}$ such that there exists some short characteristic covector $\chi$ for $D_{4} \oplus$ $\mathbb{Z}^{n-2}$ with $\langle\chi, \sigma\rangle=i$ if and only if $-2 q+g(K) \leqslant i \leqslant 2 q-g(K)$.

Pushing the logic of Proposition 6.6 a little further, the Alexander polynomial of $K$ can be recovered from $\sigma$ :

Proposition 6.8. For $0 \leqslant i \leqslant 2 q$, the torsion coefficient $t_{i}(K)$ satisfies

$$
t_{i}(K)=\min _{\substack{\chi \in \operatorname{Char}^{\left(D_{4} \oplus \mathbb{Z}^{n-2}\right)} \\\langle\chi, \sigma\rangle=2 q-i}}\left\lceil\frac{\langle\chi, \chi\rangle-n-2}{8}\right\rceil .
$$

Proof. Since $[\widehat{F}]=2 \sigma$ and the intersection lattice on $X$ is $D_{4} \oplus \mathbb{Z}^{n-2}$, any characteristic covector $\chi$ for $D_{4} \oplus \mathbb{Z}^{n-2}$ with $\langle\chi, \sigma\rangle=2 q-i$ is the first Chern class of a Spin ${ }^{\text {c }}$ structure $\mathfrak{r}$ on $X$ with

$$
\begin{equation*}
\left\langle c_{1}(\mathfrak{r}),[\widehat{F}]\right\rangle=-4 q+2 i . \tag{28}
\end{equation*}
$$

(Note that we need to change the sign of the inner product.) Then, exactly as in the proof of Proposition 6.6, the restriction of $\mathfrak{r}$ to $-W_{4 q}=-W_{4 q}(K)$ satisfies

$$
\begin{equation*}
d\left(P(p, q),\left.\mathfrak{r}\right|_{P(p, q)}\right)=\frac{-\left(c_{1}\left(\left.\mathfrak{r}\right|_{-W_{4 q}}\right)\right)^{2}-1}{4}-2 t_{i}(K) \tag{29}
\end{equation*}
$$

Let $\mathfrak{\mathfrak { l }}_{1}$ be the restriction of $\mathfrak{r}$ to $W$, then $\mathfrak{\mathfrak { l }}_{1}$ satisfies

$$
\begin{equation*}
d\left(P(p, q),\left.\mathfrak{s}_{1}\right|_{P(p, q)}\right) \geqslant d\left(P(2,1),\left.\mathfrak{F}_{1}\right|_{P(2,1)}\right)+\frac{\left(c_{1}\left(\mathfrak{F}_{1}\right)\right)^{2}+(n+1)}{4} \tag{30}
\end{equation*}
$$

Combining (29) and (30) together,

$$
\begin{equation*}
t_{i}(K) \leqslant \frac{-\left(c_{1}(\mathfrak{r})\right)^{2}-(n+2)}{8}-\frac{d\left(P(2,1),\left.\mathfrak{r}\right|_{P(2,1)}\right)}{2} . \tag{31}
\end{equation*}
$$

Using Proposition 5.3 , some $\mathfrak{\mathfrak { G }}_{1} \in \operatorname{Spin}^{\text {c }}(W)$ achieves equality in (30) with $\left.\mathfrak{I}_{1}\right|_{P(p, q)}=\varphi(i)$. Let $\mathfrak{r} \in \operatorname{Spin}^{\mathrm{c}}(X)$ be the extension of $\mathfrak{\mathfrak { F }}_{1}$ with (28), then $\mathfrak{r}$ achieves equality in (31). Therefore,

$$
\begin{equation*}
t_{i}(K)=\min _{\substack{\mathfrak{r} \in \operatorname{Sin}^{c}(X) \\\left\langle c_{1}(\mathfrak{r}),[\hat{F}]\right\rangle=-4 q+2 i}} \frac{-\left(c_{1}(\mathfrak{r})\right)^{2}-(n+2)}{8}-\frac{d\left(P(2,1),\left.\mathfrak{r}\right|_{P(2,1)}\right)}{2} \tag{32}
\end{equation*}
$$

Since $t_{i}(K)$ is an integer and $d\left(P(2,1),\left.\mathfrak{r}\right|_{P(2,1)}\right)$ will always be either 0 or -1 , we get

$$
\begin{equation*}
t_{i}(K)=\min _{\substack{\mathfrak{r} \in \operatorname{Sin}^{c}(X) \\\left\langle c_{1}(\mathfrak{r}),[\hat{F}]\right\rangle=-4 q+2 i}}\left\lceil\frac{-\left(c_{1}(\mathfrak{r})\right)^{2}-(n+2)}{8}\right\rceil \tag{33}
\end{equation*}
$$

Finally, $\operatorname{Spin}^{\text {c }}$ structures $\mathfrak{r}$ on $X$ with (28) correspond (under the first Chern class and a change in the sign of the inner product) with characteristic covectors $\chi$ of $D_{4} \oplus \mathbb{Z}^{n-2}$ with $\langle\chi, \sigma\rangle=2 q-i$, and $-\left(c_{1}(\mathfrak{r})\right)^{2}=\langle\chi, \chi\rangle$, so the desired formula follows.

By Proposition 6.2, specifying a sublattice $D_{4} \oplus \mathbb{Z}^{n-2} \subset \mathbb{Z}^{n+2}$ is equivalent to choosing four indices $a>b>c>d$ such that for $v \in \mathbb{Z}^{n+2}, v \in D_{4} \oplus \mathbb{Z}^{n-2}$ if and only if $\left\langle v, e_{a}+e_{b}+e_{c}+e_{d}\right\rangle$ is even. The characteristic covectors for $D_{4} \oplus \mathbb{Z}^{n-2}$ come in two types: those that are the restrictions of characteristic covectors of $\mathbb{Z}^{n+2}$, which can be represented by elements of $\mathbb{Z}^{n+2}$ with all entries odd, and those that are not, which can be represented by elements of $\mathbb{Z}^{n+2}$ with the entries in positions $a, b, c$, and $d$ even and all other entries odd. Call these two types of covectors even and $o d d$, respectively. The short characteristic covectors are exactly the ones with all odd entries equal to $\pm 1$, and the even entries (if any) equal to $\pm 2,0,0$, and 0 in some order.

As in [9], we will assume $\sigma=\left(\sigma_{0}, \sigma_{1}, \ldots, \sigma_{n+1}\right)$ with

$$
0 \leqslant \sigma_{0} \leqslant \sigma_{1} \leqslant \cdots \leqslant \sigma_{n+1} .
$$

Moreover, we can assume that for any two indices $i, j \in\{0,1, \ldots, n+1\}$, we always have

$$
\begin{equation*}
i>j, \quad \text { if } \sigma_{i}=\sigma_{j}, i \in\{a, b, c, d\}, \text { and } j \notin\{a, b, c, d\} \tag{34}
\end{equation*}
$$

Definition 6.9. Let $\operatorname{Short}\left(D_{4} \oplus \mathbb{Z}^{n-2}\right)=\operatorname{Short}_{0} \cup$ Short $_{1}$, with $\operatorname{Short}_{0}=\operatorname{Short}\left(\mathbb{Z}^{n}\right)$ the set of even short characteristic covectors and $\operatorname{Short}_{1}=\operatorname{Short}\left(D_{4} \oplus \mathbb{Z}^{n-2}\right)-$ Short $_{0}$ the set of odd characteristic covectors. Let

$$
\chi^{0}=-\sum_{i=0}^{n+3} e_{i}
$$

and

$$
\chi^{1}=-2 e_{a}-\sum_{i \notin\{a, b, c, d\}} e_{i}
$$

be the elements of Short $_{0}$ and Short $_{1}$, respectively, minimizing $\langle\chi, \sigma\rangle$. Let

$$
\mathcal{T}_{0}=\left\{\left.\frac{1}{2}\left(\chi-\chi^{0}\right) \right\rvert\, \chi \in \text { Short }_{0}\right\}
$$

and

$$
\mathcal{T}_{1}=\left\{\left.\frac{1}{2}\left(\chi-\chi^{1}\right) \right\rvert\, \chi \in \text { Short }_{1}\right\}
$$

be called the sets of even and odd test vectors, respectively.
For $\chi \in \mathbb{Z}^{n+2}$, let $\chi_{i}$ denote the component of $\chi$ corresponding to the index $i$. The following result is easy to see.

Proposition 6.10. For $\chi \in \mathcal{\tau}_{1},\left(\chi_{d}, \chi_{c}, \chi_{b}, \chi_{a}\right)$ is one of $( \pm 1,0,0,1)$, or $(0, \pm 1,0,1)$, or $(0,0, \pm 1,1)$, or ( $0,0,0,2$ ), or ( $0,0,0,0$ ).

Proposition 6.11. The sets $\left\{\langle\chi, \sigma\rangle \mid \chi \in \mathcal{T}_{0}\right\}$ and $\left\{\langle\chi, \sigma\rangle \mid \chi \in \mathcal{T}_{1}\right\}$ are both intervals of integers beginning at 0. Also,

$$
\begin{equation*}
\sum_{i=0}^{n+1} \sigma_{i}=\max \left\{\langle\chi, \sigma\rangle \mid \chi \in \mathcal{T}_{0}\right\}=\max \left\{\langle\chi, \sigma\rangle \mid \chi \in \mathcal{T}_{1}\right\} \pm 1 \tag{35}
\end{equation*}
$$

Proof. By Proposition 6.7, the set $\left\{\langle\chi, \sigma\rangle \mid \chi \in \operatorname{Short}\left(D_{4} \oplus \mathbb{Z}^{n-2}\right)\right\}$ is an interval of integers. For each $i \in\{0,1\}$, the set $\left\{\langle\chi, \sigma\rangle \mid \chi \in\right.$ Short $\left._{i}\right\}$ contains the elements of this interval with the same parity. So the parities are different for $i=0$ and $i=1$. In particular, both sets are arithmetic progressions of step size 2 , so subtracting off the smallest element and dividing by 2 gives intervals beginning at 0 .

Corollary 6.12. $\sigma$ is a changemaker.
Proof. The set $\mathcal{T}_{0}$ consists of just vectors with all entries 0 or 1 .

Proof of Theorem 1.10. This follows from the combination of Corollary 6.12 and Proposition 6.7.

Corollary 6.13. $\sigma_{a}=\sigma_{b}+\sigma_{c}+\sigma_{d}+\theta$, where $\theta \in\{-1,1\}$.
Proof. Using (35), we see that

$$
\sum_{i=0}^{n+1} \sigma_{i}=2 \sigma_{a}+\left(\sum_{j \notin\{a, b, c, d\}} \sigma_{j}\right) \pm 1
$$

The result is now immediate.
Lemma 6.14. An irreducible vector $v \in \sigma^{\perp}$ has an odd pairing with the vector $e_{a}+e_{b}+e_{c}+e_{d}$ if and only if $[v]$ contains $x_{0}$.

Proof. Suppose $v \in \sigma^{\perp}$ is irreducible. The pairing $\left\langle v, e_{a}+e_{b}+e_{c}+e_{d}\right\rangle$ is even if and only if $v \in$ $D_{4} \oplus \mathbb{Z}^{n-2}$, which is equivalent to $v \in\left\langle 2 x_{0}, \ldots, x_{n}\right\rangle$ by (27). Since $v$ is irreducible, $v \notin\left\langle 2 x_{0}, \ldots, x_{n}\right\rangle$ if and only if $[v]$ contains $x_{0}$.

Let

$$
\begin{equation*}
G=1+\sigma_{0}+\sigma_{1}+\cdots+\sigma_{d-1} . \tag{36}
\end{equation*}
$$

Lemma 6.15. There exists $\chi \in \mathcal{T}_{1}$ with $\langle\chi, \sigma\rangle=G$. Let $f$ be the minimal index such that $f>d$ and $f \notin\{a, b, c\}$. If $\chi_{a}=0$, then

$$
G \geqslant \sigma_{f} .
$$

If $\chi_{a} \neq 0$, then

$$
G \geqslant \sigma_{a}-\sigma_{b}=\sigma_{c}+\sigma_{d}+\theta .
$$

Proof. Using Proposition 6.11, there exists $\chi \in \mathcal{T}_{1}$ with $\langle\chi, \sigma\rangle=G$. If $\chi_{a}=0$, by Proposition 6.10 we have $\chi_{b}=\chi_{c}=\chi_{d}=0$, then there must be an index $i>d, i \notin\{a, b, c\}$, with $\chi_{i} \neq 0$ as otherwise $\langle\chi, \sigma\rangle<G$. So

$$
G=\langle\chi, \sigma\rangle \geqslant \sigma_{i} \geqslant \sigma_{f} .
$$

If $\chi_{a} \neq 0$, by Proposition 6.10, we have

$$
G=\langle\chi, \sigma\rangle \geqslant \sigma_{a}-\sigma_{b}=\sigma_{c}+\sigma_{d}+\theta .
$$

## 7 | BOUNDING THE INDEX $\boldsymbol{d}$

In Sections 7 and 8, we will classify the linear changemaker lattices restricted by Theorem 1.10. As in our previous papers [1, 2], we will use the techniques introduced by Greene [9]. The basic strategy is, for such a lattice $\sigma^{\perp}$, we will analyze the standard basis vectors, which are irreducible by Lemma 3.14, and other irreducible vectors of interest. By Proposition 3.4, irreducible vectors are intervals up to sign reversal, hence the pairings between them can be computed (up to sign reversal) by (17) and Lemma 3.8, which only involve the weights of high weight vertices and the relative positions of intervals.

In this section, we will prove that $d=0$, where $d$ is the index defined after the proof of Proposition 6.8. We assume that $d>0$ for contradiction.

Recall that we write $\left(e_{0}, e_{1}, \ldots, e_{n+1}\right)$ for the orthonormal basis of $\mathbb{Z}^{n+2}$, and $\sigma=\sum_{i} \sigma_{i} e_{i}$. Since $\Lambda(q,-p)$ is indecomposable (Proposition 3.9), $\sigma_{0} \neq 0$, otherwise $\sigma^{\perp}$ would have a direct summand $\mathbb{Z}$. So $\sigma_{0}=1$. By Lemma 6.14 , we have that $\left[v_{d}\right]$ contains $x_{0}$. Set

$$
\begin{equation*}
w=\theta e_{0}+e_{d}+e_{c}+e_{b}-e_{a} \tag{37}
\end{equation*}
$$

where $\theta \in\{-1,1\}$ is as in Corollary 6.13. The strategy in this section is to analyze $v_{d}$ and $w$.
Lemma 7.1. $w$ is an irreducible vector of $\sigma^{\perp}$. Also, $x_{0} \notin[w]$.
Proof. Corollary 6.13 shows that $w$ is in $\sigma^{\perp}$. Suppose $w=x+y$ with $x, y \in \sigma^{\perp}$ and $\langle x, y\rangle \geqslant 0$. If both $x, y$ are non-zero, by Lemma 3.15 we may assume that one of the vectors is $e_{d}-e_{0}$ and the other is $-e_{a}+e_{b}+e_{c}$. Both vectors will then be irreducible and $x_{0} \in[x]$, $[y]$ by Lemma 6.14.

That implies $\langle x, y\rangle \neq 0$, which is a contradiction. The second statement is immediate from Lemma 6.14.

Corollary 7.2. If one of the following two conditions holds, then $\theta=1$ :
(1) $\sigma_{d}=1$;
(2) there exists a vector $v$ with $\left\langle v, e_{0}\right\rangle=-\left\langle v, e_{d}\right\rangle=1$, max $\operatorname{supp}(v)=d$ and $|\langle v, w\rangle| \leqslant 1$.

Proof. If $\sigma_{d}=1$ and $\theta=-1$, then $w=\left(-e_{0}+e_{d}\right)+\left(e_{c}+e_{b}-e_{a}\right)$ is reducible, a contradiction to Lemma 7.1.

If there exists a vector $v$ as in the statement, then since $\left\langle v, e_{0}\right\rangle=-\left\langle v, e_{d}\right\rangle=1$ and $\max \operatorname{supp}(v)=d$, we have $\langle v, w\rangle=\theta-1$. Using $|\langle v, w\rangle| \leqslant 1$, we have $\theta=1$.

Remark 7.3. When $d>0$, we have $\left[v_{d}\right]$ contains $x_{0}$. For any $0<i<d,\left[v_{i}\right]$ does not contain $x_{0}$. Also, $\operatorname{supp}\left(v_{i}\right) \cap \operatorname{supp}(w)=\emptyset$ or $\{0\}$, so $\left|\left\langle w, v_{i}\right\rangle\right| \leqslant 2$.

Lemma 7.4. Suppose that $0 \notin \operatorname{supp}\left(v_{d}\right)$, then $\left[v_{d}\right] \dagger[w]$.
Proof. Since $0 \notin \operatorname{supp}\left(v_{d}\right)$, we can compute

$$
\begin{equation*}
\left\langle w, v_{d}\right\rangle=-1 \tag{38}
\end{equation*}
$$

Note that $x_{0} \in\left[v_{d}\right]$ and $x_{0} \notin[w]$. Assume that $\left[v_{d}\right] \dagger[w]$ does not happen, then either $[w]<\left[v_{d}\right]$ or $\left[v_{d}\right] \pitchfork[w]$.

If $[w]<\left[v_{d}\right]$, then by Lemma 3.8 we have $\left|\left\langle w, v_{d}\right\rangle\right|=|w|-1=4$, contradicting (38).
If $\left[v_{d}\right] \pitchfork[w]$, by Lemma 3.8 and (38), we have $\left|\left[v_{d}\right] \cap[w]\right|=3$, and there exists $\epsilon \in\{-1,1\}$ such that $w=\epsilon[w]$ and $v_{d}=-\epsilon\left[v_{d}\right]$. So $w+v_{d}=\epsilon\left([w]-\left[v_{d}\right]\right)=x+y$ with $[x]$ and $[y]$ being distant, and we may assume $x_{0} \in[x]$. Since $v_{d}$ is not tight, $v_{d}$ is unbreakable (Lemma 3.16). By Proposition 3.6 and (17), $\left|v_{d}\right|=\left|[w] \cap\left[v_{d}\right]\right|=3$, and $|x|=2$. We get $v_{d}=e_{i}+e_{d-1}-e_{d}$ for some $0<i<d-1$, and

$$
w+v_{d}=\theta e_{0}+e_{i}+e_{d-1}+e_{c}+e_{b}-e_{a} .
$$

Using Lemmas 3.15 and 6.14, and the fact that $x_{0} \in[x]$, we have either $x=e_{j}-e_{a}$ for some $j \in$ $\{0, i, d-1\}$ or $x=-e_{0}+e_{k}$ for some $k \in\{c, b\}$. If $x=e_{j}-e_{a}$, then $\sigma_{j}=\sigma_{a}$, which forces $\sigma_{a}=$ $\sigma_{b}$, contradicting Corollary 6.13. If $x=-e_{0}+e_{k}$, then $\theta=-1$ and $\sigma_{k}=1$, which forces $\sigma_{d}=1$, contradicting Corollary 7.2.

Lemma 7.5. Suppose that $0 \notin \operatorname{supp}\left(v_{d}\right)$ and $\left|\left\langle v_{i}, v_{d}\right\rangle\right|=1$ for some $i$ with $0<i<d$. Then $i=1$.

Proof. Since $i<d, x_{0} \notin\left[v_{i}\right]$ by Lemma 6.14. We have $\left[v_{d}\right] \dagger[w]$ by Lemma 7.4.
If $\left[v_{i}\right] \dagger\left[v_{d}\right]$, then $\left[v_{i}\right]$ and $[w]$ share their left end. If $\left|v_{i}\right|>2$, by Lemma 3.8 we have $2 \leqslant$ $\left|\left\langle v_{i}, w\right\rangle\right|$, and the equality holds only when $\left|v_{i}\right|=3$. Since $\left\langle v_{i}, w\right\rangle=\left\langle v_{i}, e_{0}\right\rangle$, we have $\left\langle v_{i}, e_{0}\right\rangle=2$ and $\left|v_{i}\right|=3$, which is not possible. So $\left|v_{i}\right|=2$ in this case.

If $\left[v_{i}\right]$ and $\left[v_{d}\right]$ share their right end, then we must have $\left|v_{i}\right|=2$ by Lemma 3.8.
In the above two cases, we have $\left|v_{i}\right|=2$ and $\left[v_{i}\right]$ abuts the right end of $\left[v_{d}\right]$, so $\left|\left\langle v_{i}, w\right\rangle\right|=1$, which implies $i=1$ since $v_{i}=e_{i-1}-e_{i}$ by Lemma 3.18.

If $\left[v_{i}\right] \pitchfork\left[v_{d}\right]$, then $\left|\left[v_{i}\right] \cap\left[v_{d}\right]\right|=\left|v_{d}\right|=3$. By Lemma 3.22, $v_{i}$ is tight. If $i>1,\left|v_{i}\right| \geqslant 6=|w|+$ $\left|v_{d}\right|-2=\left|\left[v_{d}\right] \cup[w]\right|$. Since $\left[v_{d}\right] \dagger[w]$, the interval $\left[v_{i}\right]$ must contain all high weight vertices of [ $w$ ] by (17). Thus $\left|\left\langle w, v_{i}\right\rangle\right| \geqslant|w|-2=3$, a contradiction (Remark 7.3).

Lemma 7.6. $v_{d}$ is not gappy.
Proof. Suppose for contradiction that $v_{d}$ is gappy. Take the index $i$ to be the smallest gappy index of $v_{d}$. First suppose that $i=0$. Then, using Lemma 3.13, $v_{1}$ will be tight with $\left|v_{1}\right|=5$. Note that $\left\langle w, v_{1}\right\rangle=2 \theta,\left|v_{1}\right|=|w|=5$, so $[w] \pitchfork\left[v_{1}\right]$ with $\left|\left[v_{1}\right] \cap[w]\right|=4$, and there exists $\epsilon \in\{-1,1\}$ such that $w=\epsilon[w]$ and $v_{1}=\theta \epsilon\left[v_{1}\right]$. It follows that $w-\theta v_{1}=x+y$ with $[x]$ and $[y]$ being distant, $|x|=|y|=3$. Now

$$
w-\theta v_{1}=-\theta e_{0}+\theta e_{1}+e_{d}+e_{c}+e_{b}-e_{a} .
$$

Since $x_{0} \notin[w],\left[v_{1}\right]$, we have $x_{0} \notin[x],[y]$. Using Lemma 3.15, one of $x, y$ has the form $\pm e_{j}+e_{k}+$ $e_{l}$, where $j \in\{0,1\},\{k, l\} \subset\{d, c, b\}$, but this vector is not in $\sigma^{\perp}$, a contradiction.

Suppose $i>0$. Then $i=\min \operatorname{supp}\left(v_{d}\right)$ by [9, Paragraph 2 in Section 6, and Propositions 8.6, 8.7, 8.8]. Since $\left\langle v_{i+1}, v_{d}\right\rangle=1$ (Lemma 3.18), by Lemma 7.5 we have $i+1=1$, a contradiction.

Proposition 7.7. $\min \operatorname{supp}\left(v_{d}\right) \leqslant 1$.
Proof. Set $i=\min \operatorname{supp}\left(v_{d}\right)$. If $i>0$, since $\left\langle v_{i}, v_{d}\right\rangle=-1$, by Lemma 7.5 we have $i=1$.
Let $G$ be defined as in (36). Our strategy is to first find a bound for $G$, and then find a bound for the integer $d$. Next, we do a case-by-case analysis to find that indeed $d=0$.

Lemma 7.8. $v_{d}$ is not tight.
Proof. Suppose for contradiction that $v_{d}$ is tight. Using Lemma 6.15, we get

$$
\sigma_{d}=G \geqslant \min \left\{\sigma_{f}, \sigma_{d}+\sigma_{c}+\theta\right\} \geqslant \min \left\{\sigma_{f}, 2 \sigma_{d}-1\right\},
$$

which is not possible by (34) and Corollary 7.2.
Combining Proposition 7.7 and Lemmas 7.6 and 7.8, we have:

Corollary 7.9. $v_{d}=v_{d, 0} e_{0}+e_{1}+\cdots-e_{d}$ with $v_{d, 0} \in\{0,1\}$.
With the notation of Corollary 7.9 in place, we start the analysis to deduce $d=0$. The following identity will be useful to keep in mind:

$$
\begin{equation*}
\sigma_{d}=G-2+v_{d, 0} . \tag{39}
\end{equation*}
$$

Lemma 7.10. If either $\left|v_{d}\right|>2$ or $d=1$, then

$$
G \geqslant \sigma_{d}+\sigma_{c}+\theta .
$$

Proof. Let $\chi$ be the vector as in Lemma 6.15. By that lemma, it will suffice to show $\chi_{a} \neq 0$. Assume that $\chi_{a}=0$, then Lemma 6.15 implies that $G \geqslant \sigma_{f}>\sigma_{d}$. Using (39), we have that $G \leqslant \sigma_{d}+2$, so $\sigma_{f} \in\left\{\sigma_{d}+1, \sigma_{d}+2\right\}$. Moreover, if $\sigma_{f}=\sigma_{d}+2$, then $v_{d, 0}=0$, hence $d>1$ by Corollary 7.9.

If $\sigma_{f}=\sigma_{d}+1$, set $v_{f}^{\prime}=-e_{f}+e_{d}+e_{0}$. If $\sigma_{f}=\sigma_{d}+2$, set

$$
v_{f}^{\prime}= \begin{cases}-e_{f}+e_{d}+e_{1}+e_{0}, & \text { if } \sigma_{1}=1, \\ -e_{f}+e_{d}+e_{1}, & \text { if } \sigma_{1}=2\end{cases}
$$

In either case, $v_{f}^{\prime}$ is irreducible and also in $\sigma^{\perp}$. Since $\left\langle v_{f}^{\prime}, e_{a}+e_{b}+e_{c}+e_{d}\right\rangle=1$, we get that $x_{0} \in$ $\left[v_{f}^{\prime}\right]$. So $\left[v_{d}\right]$ and $\left[v_{f}^{\prime}\right]$ share their left endpoint. If $\left|v_{d}\right|>2$, then $\left|\left\langle v_{d}, v_{f}^{\prime}\right\rangle\right| \geqslant 2$ by Lemma 3.8, which contradicts the direct computation $\left|\left\langle v_{d}, v_{f}^{\prime}\right\rangle\right| \leqslant 1$. If $d=1$, then $v_{d}=e_{0}-e_{1}$ by Corollary 7.9, and $v_{f}^{\prime}=-e_{f}+e_{1}+e_{0}$. We get $\left\langle v_{d}, v_{f}^{\prime}\right\rangle=0$ : this is still giving a contradiction since the intervals $\left[v_{d}\right]$ and $\left[v_{f}^{\prime}\right]$ share their left endpoints, and so $\left\langle v_{d}, v_{f}^{\prime}\right\rangle \neq 0$.

Proposition 7.11. If $\left|v_{d}\right|=2$, then either $d=1, G=2$, or else $d=2, G \in\{3,4\}$.
If $\left|v_{d}\right|>2$, then $d \in\{3,4\}, \theta=-1, v_{d, 0}=0$, and $1+d \leqslant G \leqslant 5$.
Proof. If $\left|v_{d}\right|=2$, our conclusion follows from Corollary 7.9 and (39).
Now we assume $\left|v_{d}\right|>2$. Using Lemma 7.10 and (39), we have

$$
G \geqslant \sigma_{d}+\sigma_{c}+\theta \geqslant 2 \sigma_{d}+\theta=2\left(G-2+v_{d, 0}\right)+\theta,
$$

thus

$$
\begin{equation*}
G \leqslant 4-\theta-2 v_{d, 0} . \tag{40}
\end{equation*}
$$

If $d \leqslant 2$, by Corollary 7.9 and the assumption that $\left|v_{d}\right|>2$ we have $v_{d, 0}=1$ and $d=2$. We have $x_{0} \in\left[v_{2}\right]$ while $x_{0} \notin[w]$. Since $\left|v_{2}\right|=3<|w|,\left[v_{2}\right]$ and $[w]$ do not share their right endpoint, so we must have $\left|\left\langle v_{2}, w\right\rangle\right| \leqslant 1$ by Lemma 3.8. Then $\theta=1$ by Corollary 7.2. So $G \leqslant 1$ by (40), which is not possible.

If $d \geqslant 3$, it follows from (40) and (36) that

$$
4-\theta-2 v_{d, 0} \geqslant G \geqslant d+1 \geqslant 4,
$$

so $\theta=-1, v_{d, 0}=0, d \leqslant 4$ and $G \leqslant 5$.
Proposition 7.11 implies $d \in\{0,1,2,3,4\}$. We now argue that $d=0$.

Proposition 7.12. $d=0$.
Proof. Suppose that $d=1$. Using Lemma 7.8, we get that $v_{1}=-e_{1}+e_{0}$. By (40), $G=2$ and $\sigma_{1}=1$. By Corollary 7.2 and Lemma 7.10, we get that

$$
2=G \geqslant \sigma_{c}+\sigma_{1}+1 \geqslant 3,
$$

which is a contradiction.
Suppose $d=2$. It follows from Proposition 7.11 that $\left|v_{2}\right|=2$. We separate the cases to whether $\sigma_{1}\left(=\sigma_{2}\right)$ is 1 or 2 .

First assume that $\sigma_{1}=\sigma_{2}=1$. If $c \neq 3$, then $x_{0} \in\left[v_{3}\right]$ by Lemma 6.14, thus $\left[v_{2}\right]$ and $\left[v_{3}\right]$ share their left endpoint. So $\left\langle v_{3}, v_{2}\right\rangle \neq 0$. In particular, $1 \notin \operatorname{supp}\left(v_{3}\right)$. Since $\sigma_{0}=\sigma_{1}=1,0 \notin \operatorname{supp}\left(v_{3}\right)$, so $\left|v_{3}\right|=2$, which is impossible as $\sigma_{3}>1$ by (34). If $c=3$, note that $\theta=1$ by Corollary 7.2, by Lemma 6.15 we have

$$
3=G \geqslant \min \left\{\sigma_{f}, \sigma_{3}+2\right\} .
$$

$\operatorname{By}$ (34), $\sigma_{f}>\sigma_{3}$, so we have $\sigma_{3} \leqslant 2$. If $\sigma_{3}=1$, then $\left|v_{3}\right|=2,\left\langle v_{3}, w\right\rangle=0$ and $\left\langle v_{3}, v_{2}\right\rangle=-1$. Since $x_{0} \notin\left[v_{3}\right],\left[v_{3}\right]$ abuts the right endpoint of $\left[v_{2}\right]$. Since $\left[v_{2}\right] \dagger[w]$ by Lemma 7.4 , we get $\left\langle v_{3}, w\right\rangle \neq 0$, a contradiction. If $\sigma_{3}=2$, then $v_{3}=-e_{3}+e_{2}+e_{1}$. We have $v_{3} \sim v_{1} \sim v_{2},\left|v_{1}\right|=\left|v_{2}\right|=2,\left[v_{2}\right] \dagger[w]$, so $\left[v_{3}\right]$ contains the leftmost high weight vertex of $[w]$, which contradicts the fact that $\left\langle v_{3}, w\right\rangle=0$.

Next we suppose ( $d=2$ and) $\sigma_{1}=\sigma_{2}=2$. Then $v_{1}=2 e_{0}-e_{1}, v_{2}=e_{1}-e_{2}$. We have $x_{0} \in\left[v_{2}\right]$, $x_{0} \notin\left[v_{1}\right],[w],\left[v_{2}\right]$ abuts both $\left[v_{1}\right]$ and $[w]$, and $2=\left|v_{2}\right|<\left|v_{1}\right|=|w|$. So $\left[v_{1}\right]$ and $[w]$ share their left endpoint. It follows from Lemma 3.8 that $\left|\left\langle v_{1}, w\right\rangle\right|=4$, which is not possible by Remark 7.3.

Suppose $d \in\{3,4\}$. Proposition 7.11 implies $v_{d}=-e_{d}+e_{d-1}+\cdots+e_{1}, \theta=-1$. Also, by Proposition 7.11 and (36), we have $5 \geqslant G \geqslant 2+\sigma_{1}+\sigma_{2}$, so $\sigma_{1}=1$. Let $v_{d}^{\prime}=v_{d}-e_{1}+e_{0}$, then $v_{d}^{\prime}$ is irreducible by Lemma 3.15, $\left|v_{d}^{\prime}\right|=d<|w|=5$, and $\left\langle v_{d}^{\prime}, w\right\rangle=-2$. Since $x_{0} \in\left[v_{d}^{\prime}\right]$ and $x_{0} \notin[w]$, by Lemma 3.8 we must have $\left[v_{d}^{\prime}\right] \pitchfork[w]$ with $\left|\left[v_{d}^{\prime}\right] \cap[w]\right|=4$, and there exists $\epsilon= \pm 1$, such that $v_{d}^{\prime}=\epsilon\left[v_{d}^{\prime}\right]$ and $w=-\epsilon[w]$. Hence

$$
v_{d}^{\prime}+w=\epsilon\left(\left[v_{d}^{\prime}\right]-[w]\right)=-e_{a}+e_{b}+e_{c}+e_{d-1}+\cdots+e_{2}
$$

is reducible, a contradiction to Lemma 3.15.

## 8 | THE CASE $\boldsymbol{d}=\mathbf{0}$

We now turn our attention to the classification in the case $d=0$ : in what follows, we classify all changemaker linear lattices of this sort.

Lemma 8.1. $c=1, \sigma_{c}=1$, and $\sigma_{a}=\sigma_{b}+1$.
Proof. By Lemma 6.15, we have

$$
1=G \geqslant \min \left\{\sigma_{f}, \sigma_{a}-\sigma_{b}\right\} \geqslant \min \left\{\sigma_{f}, \sigma_{c}+\sigma_{0}-1\right\}=\min \left\{\sigma_{f}, \sigma_{c}\right\} .
$$

If $f=1$, then $1 \geqslant \sigma_{f}$, which contradicts (34). So $f>1$, thus $c=1$ and $\sigma_{c}=1$. Hence the above inequality becomes an inequality, which means $\sigma_{a}=\sigma_{b}+1$.

For the rest of the section, we will replace $w$ in (37) with

$$
\begin{equation*}
w^{\prime}=-e_{a}+e_{b}+e_{c} . \tag{41}
\end{equation*}
$$

The following is an immediate corollary of Lemma 8.1.

Corollary 8.2. The vector $w^{\prime}$ is an irreducible, unbreakable vector in $\sigma^{\perp}$, and $x_{0} \in\left[w^{\prime}\right]$.
Proof. It follows from Lemma 8.1 that $w^{\prime} \in \sigma^{\perp}$. Since $\left|w^{\prime}\right|=3$, it is irreducible and unbreakable. The fact that $x_{0} \in\left[w^{\prime}\right]$ follows from Lemma 6.14.

Lemma 8.3. $b=2, \sigma_{b}=1$, and $\sigma_{a}=2$. Hence $\left(\sigma_{0}, \ldots, \sigma_{a}\right)=\left(1,1,1,2^{[s]}, 2\right)$ for some $s \geqslant 0$.
Proof. Suppose toward a contradiction that $b>2$. Since $\sigma_{0}=\sigma_{1}=1$ and $b>2, \sigma_{2} \in\{2,3\}$.
If $\sigma_{2}=2$, then $\left\langle v_{2}, v_{1}\right\rangle=0,\left\langle v_{2}, w^{\prime}\right\rangle=1$ and $\left\langle v_{1}, w^{\prime}\right\rangle=-1$. Since $\left|v_{1}\right|=2$ and $x_{0} \notin\left[v_{1}\right],\left[v_{1}\right]$ abuts the right end of $\left[w^{\prime}\right]$. If $\left[v_{2}\right]$ also abuts $\left[w^{\prime}\right]$, noting that $x_{0} \notin\left[v_{2}\right]$, it abuts the right end of $\left[w^{\prime}\right]$, so $\left[v_{2}\right]$ abuts $\left[v_{1}\right]$, contradicting the fact that $\left\langle v_{2}, v_{1}\right\rangle=0$. Thus by Lemma 3.8 we must have $\left[v_{2}\right] \pitchfork\left[w^{\prime}\right],\left|\left[v_{2}\right] \cap\left[w^{\prime}\right]\right|=3, v_{2}=\epsilon\left[v_{2}\right]$ and $w^{\prime}=\epsilon\left[w^{\prime}\right]$ for some $\epsilon \in\{1,-1\}$. It follows that $w^{\prime}-v_{2}$ is reducible. However, $w^{\prime}-v_{2}=-e_{a}+e_{b}+e_{2}-e_{0}$ is irreducible by Lemma 3.15 and the fact that $\sigma_{a}=\sigma_{b}+1$, a contradiction.

If $\sigma_{2}=3$, then $\left[v_{2}\right]$ contains $x_{0}$, so $\left[w^{\prime}\right]<\left[v_{2}\right]$. However, since $\left|w^{\prime}\right|=3$, Lemma 3.8 implies that $\left|\left\langle v_{2}, w^{\prime}\right\rangle\right|=2$, contradicting the direct computation $\left\langle v_{2}, w^{\prime}\right\rangle=1$.

Having proved $b=2$, we must have $\sigma_{2} \in\{1,2,3\}$. If $\sigma_{2}=2$, the interval [ $v_{2}$ ] contains $x_{0}$, so $\left[v_{2}\right]$ and $\left[w^{\prime}\right]$ share their left end, a contradiction to the direct computation $\left\langle v_{2}, w^{\prime}\right\rangle=0$. If $\sigma_{2}=$ 3 , using Proposition 6.11, there must be some $\chi \in \mathcal{T}_{1}$ with $\langle\chi, \sigma\rangle=2$. Moreover, since $\{0,1,2\}=$ $\{d, c, b\}, \sigma_{f}>\sigma_{2}=3$. Therefore, $\chi_{a} \neq 0$ by Proposition 6.10. Using Lemma 8.1, $\sigma_{a}=4$. So $\sigma_{k} \geqslant 4$ if $k>b=2$ by (34). To get $\langle\chi, \sigma\rangle=2$, it must be the case that for some $i \in\{b, c, d\}, \chi_{i}=-1$ and $\chi_{j}=0$ for $j \neq i, a$. Then $\langle\chi, \sigma\rangle$ is either 1 or 3, a contradiction.

Therefore, $b=2, \sigma_{2}=1$, and $\sigma_{a}=\sigma_{b}+1=2$.
Lemma 8.4. $\sigma_{i}=2 s+3$ for $i>a$. That is, $\sigma=\left(1,1,1,2^{[s]}, 2,2 s+3^{[t]}\right)$ with $s, t \geqslant 0$.
Proof. First, consider $v_{a+1}$. By (34), $\sigma_{a+1}>2$, so $m:=\min \operatorname{supp}\left(v_{a+1}\right)<a$. If $m \geqslant 3$, then $s:=a-3>0$. Let $j=\min \operatorname{supp}\left(v_{m}\right)$, by Lemma $8.3, j=m-1$ if $m>3$, and $j=m-2$ if $m=3$. There would be a claw ( $v_{m} ; v_{a+1}, v_{m+1}, v_{j}$ ), a contradiction to Lemma 3.24. Therefore, $\operatorname{supp}\left(v_{a+1}\right) \cap\{0,1,2\}$ is non-empty, thus is one of $\{0,1,2\},\{1,2\}$, or $\{2\}$ by Lemma 3.13.

We note that $x_{0} \in\left[v_{a}\right]$ no matter $s=0$ or $s>0$.
We claim that there is no index $j$ such that $v_{j}$ is tight. Otherwise, we have $j>a$ and $\left[v_{j}\right]$ contains $x_{0}$, so $\left[v_{a}\right]<\left[v_{j}\right]$. If $s>0,\left\langle v_{a}, v_{j}\right\rangle=0$, a contradiction to $\left[v_{a}\right]<\left[v_{j}\right]$. If $s=0$, then $\left|v_{a}\right|=3$, hence $\left|\left\langle v_{a}, v_{j}\right\rangle\right|=2$ by Lemma 3.8, contradicting the direct computation $\left\langle v_{a}, v_{j}\right\rangle=1$.

If $m \in\{0,1\}$, then $3 \in \operatorname{supp}\left(v_{a+1}\right)$ since otherwise $\left\langle v_{3}, v_{a+1}\right\rangle=2$, a contradiction to Lemma 3.21. Then since $\left|v_{i}\right|=2$ for $3<i \leqslant a, v_{a+1}$ is just right by Lemma 3.13 and the claim in the last paragraph.

If $m=0$, we have $\left\langle v_{3}, v_{a+1}\right\rangle=1$, and $x_{0} \notin\left[v_{a+1}\right]$. We also have $\left\langle v_{3}, v_{1}\right\rangle=-1$, and $x_{0} \notin\left[v_{1}\right]$. If $s>0$, then $\left(v_{3} ; v_{4}, v_{1}, v_{a+1}\right)$ will give a claw, a contradiction (Lemma 3.24). If $s=0$ then [ $v_{3}$ ] contains $x_{0}$, so $\left[v_{1}\right]$ and $\left[v_{a+1}\right]$ must both abut the right end of $\left[v_{3}\right]$, contradicting the fact that they are orthogonal.

If $m=1$, since $\left|\{a, b, c, d\} \cap \operatorname{supp}\left(v_{a+1}\right)\right|=3, x_{0} \in\left[v_{a+1}\right]$. So $\left[v_{a}\right]<\left[v_{a+1}\right]$ and $\left|\left\langle v_{a+1}, v_{a}\right\rangle\right|=$ $\left|v_{a}\right|-1$. This contradicts the direct computation of $\left\langle v_{a}, v_{a+1}\right\rangle$ no matter $s=0$ or $s>0$.

If $m=2$, then $v_{a+1}=e_{2}+e_{k}+\cdots+e_{a}-e_{a+1}$ for some $3 \leqslant k \leqslant a$. If $3<k<a$, there is a claw $\left(v_{k} ; v_{k-1}, v_{k+1}, v_{a+1}\right)$ (Lemma 3.24). If $k=a$ and $a>3$, then $x_{0} \in\left[v_{a}\right]$ but $x_{0} \notin\left[v_{a+1}\right]$. Since $\left\langle v_{a}, v_{a+1}\right\rangle=-1$ and $\left|v_{a}\right|=2<\left|v_{a+1}\right|$, we have $\left[v_{a}\right] \dagger\left[v_{a+1}\right]$. If $s=1$, then since $\left|v_{a}\right|=$ $2,\left\langle v_{3}, v_{a}\right\rangle=-1$, $\left[v_{3}\right]$ and $\left[v_{a+1}\right]$ will share a hight weight vertex, which is not possible by Lemma 3.22. If $s>1$, then $\left\langle v_{a}, v_{a-1}\right\rangle=-1$ and $x_{0} \notin\left[v_{a-1}\right]$, so $\left[v_{a-1}\right]$ abuts the right endpoint of $\left[v_{a}\right]$. Recall that $\left[v_{a+1}\right]$ also abuts the right endpoint of $\left[v_{a}\right]$, hence $\left\langle v_{a+1}, v_{a-1}\right\rangle= \pm 1$, a contradiction to the direct computation $\left\langle v_{a+1}, v_{a-1}\right\rangle=0$. Therefore, $k=3$, so $v_{a+1}$ is just right and $\sigma_{a+1}=2 s+3$.

Finally, suppose that for some $j>a+1,\left|v_{j}\right|>2$. Take $j$ to be the smallest such index. Then $v_{j}$ is unbreakable by our earlier claim. Let $\ell=\min \operatorname{supp}\left(v_{j}\right)$. If either $\ell \geqslant a+1$ or $3 \leqslant \ell<$ $a$, there will be a claw $\left(v_{\ell} ; v_{\ell-1}, v_{\ell+1}, v_{j}\right)$ (when $\ell>3$ ) or ( $v_{\ell} ; v_{\ell-2}, v_{\ell+1}, v_{j}$ ) (when $\ell=3$ ), contradicting Lemma 3.24.

If $\ell=a$, then $\left[v_{j}\right]$ contains $x_{0}$, so $\left[v_{a}\right]$ and $\left[v_{j}\right]$ share their left endpoint. No matter $s=0$ or $s>0,\left[v_{3}\right]$ is connected to $\left[v_{a}\right]$ via a (possibly empty) sequence of norm 2 vectors, so the intervals [ $v_{3}$ ] and $\left[v_{j}\right]$ will share a high weight vertex, a contradiction to Lemma 3.22.

If $\ell<3$, then $v_{j}$ is connected to the path $v_{3} \sim v_{1} \sim v_{2} \sim v_{a+1}$ in the intersection graph $G(S)$. If $\ell \in\{1,2\}, v_{j} \sim v_{\ell}$, so there is a heavy triple $\left(v_{3}, v_{a+1}, v_{j}\right)$, contradicting Lemma 3.26. If $\ell=0$, it follows from Lemma 3.13 that $1,2 \in \operatorname{supp}\left(v_{j}\right)$. By Lemma 3.21, $\left|\left\langle v_{3}, v_{j}\right\rangle\right| \leqslant 1$, so $3 \in \operatorname{supp}\left(v_{j}\right)$ and $v_{j} \sim v_{3}$. Now $4, \ldots, a \in \operatorname{supp}\left(v_{j}\right)$ by Lemma 3.13, so $\left\langle v_{a+1}, v_{j}\right\rangle \geqslant s+2-1 \geqslant 1$, so $v_{j} \sim v_{a+1}$. We again have a heavy triple $\left(v_{3}, v_{a+1}, v_{j}\right)$, contradicting Lemma 3.26.

## 9 | PROOF OF THEOREM 1.2

Lemma 8.4 specifies a changemaker vector in $\mathbb{Z}^{n+2}$ whose orthogonal complement is the linear changemaker lattice $\Lambda(q,-p)$. From the integers $a_{0}, a_{1}, \ldots a_{n}$ in (16), we can recover $p$ and $q$ using (14). Since $q<p<2 q$, we have

$$
\frac{p}{q}=\left[2, a_{0}, a_{1}, \ldots, a_{n}\right]^{-} .
$$

We use the following facts:

Lemma 9.1 [9, Lemma 9.5 (2) and (3)]. For integers $s, t, b$ with $b \geqslant 2$ and $s, t \geqslant 0$ :
(1) $\left[\cdots, b, 2^{[t-1]}\right]^{-}=[\cdots, b-1,-t]^{-}$;
(2) If $\left[2^{[s+1]}, b, \ldots\right]^{-}=\frac{p}{q}$, then $[-(s+2), b-1, \ldots]^{-}=\frac{p}{q-p}$.

We have

$$
\sigma=\left(1,1,1,2^{[s]}, 2,2 s+3^{[t]}\right)
$$

with $s, t \geqslant 0$. One can check that the standard basis of the linear changemaker lattice

$$
S=\left\{v_{s+3}, \ldots, v_{3}, v_{1}, v_{2}, v_{s+4}, \ldots, v_{s+t+3}\right\}
$$

coincides with its vertex basis with norms given by

$$
\left\{2^{[s]}, 3,2,2, s+3,2^{[t-1]}\right\} .
$$

By Lemma 6.14, $\left[v_{s+3}\right]$ contains $x_{0}$, so $v_{s+3}=x_{0}$. Hence, we have

$$
\frac{p}{q}=\left[2^{[s+1]}, 3,2,2, s+3,2^{[t-1]}\right]^{-} .
$$

Using Lemma 9.1, we see that

$$
\begin{aligned}
& q=7+4 s+9 t+12 s t+4 s^{2} t, \text { and } \\
& p=11+4 s+14 t+16 s t+4 s^{2} t
\end{aligned}
$$

It is straightforward to check that

$$
q=\frac{1}{r^{2}-2 r-1}\left(r^{2} p-1\right)
$$

with $r=-2 s-3$ and $p=t\left(r^{2}-2 r-1\right)-2 r+5$.
Proof of Theorem 1.2. Suppose $P(p, q) \cong S_{4 q}^{3}(K)$, the above computation shows that $(p, q)$ must be as in the statement. On the other hand, if $(p, q)$ is as in the statement, it follows from [1, Table 2] and [21] that there exists a Berge-Kang knot $K_{0}$ such that $P(p, q) \cong S_{4 q}^{3}\left(K_{0}\right)$. For the second statement, we note that $K$ and $K_{0}$ correspond to the same changemaker vector. Using Proposition 6.8, we know that $\Delta_{K}=\Delta_{K_{0}}$, so $\widehat{H F K}(K) \cong \widehat{H F K}\left(K_{0}\right)$ by [17, Theorem 1.2].

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