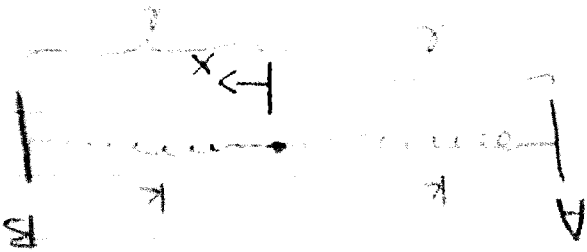


3-19

(a)



for small oscillations in the x-direction we have

1/2

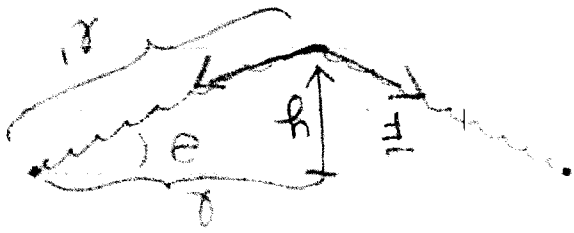
$$m\ddot{x} = -k(x-x_0) + k(x-x_0) = -2kx$$

$$= -kx - kx$$

$$= -kx - kx_0 - kx_0 - kx + kx$$

$$= -2kx$$

(b)



where  $x^2 + y^2 = l^2$

note  $l \sin(\theta) = y$   
 $l \tan(\theta) = x'$   
 $\tan(\theta) \approx \sin(\theta)$   
 $\theta \ll 1 \quad l' \approx l$

$$\vec{F} = F_x \hat{i} + F_y \hat{j}$$

$$F_x = F \cos(\theta)$$

$$F_y = F \sin(\theta)$$

1/2

$$m\ddot{y} = 2F_y = 2F \sin(\theta) = 2F \frac{y}{l}$$

and  $F = -k(l-l_0) \approx -k(l-l_0)$

since  $l' \approx l$

$$m\ddot{y} = -2ky \quad (l-l_0)$$

$$\boxed{\begin{matrix} X(t) = A_0 \cos(\omega t) \\ y(t) = A_0 \cos(\omega t) \end{matrix}}$$

$$\begin{matrix} X(0) = A_0 & B_x = A_0 \\ y(0) = A_0 & B_y = A_0 \end{matrix}$$

and since

So  $A_x = 0$  and  $A_y = 0$  b/c @ rest,  $t=0$

$$\begin{aligned} v_x(t) &= A_x \omega \cos(\omega t) - B_x \omega \sin(\omega t) \\ v_y(t) &= A_y \omega \cos(\omega t) - B_y \omega \sin(\omega t) \end{aligned}$$

1/2

$$\begin{aligned} x(t) &= A_x \sin(\omega t) + B_x \cos(\omega t) \\ y(t) &= A_y \sin(\omega t) + B_y \cos(\omega t) \end{aligned}$$

(d) In general:

$$\boxed{\frac{\omega x}{\omega y} = \frac{T_y}{T_x} = \frac{\ell \cdot \lambda_0}{\ell}}$$

$$\text{so } x: \omega x = \sqrt{\frac{2k}{m}} \quad y: \omega y = \sqrt{\frac{2k(\ell - \lambda_0)}{m}}$$

$$m\ddot{x} = -kx$$

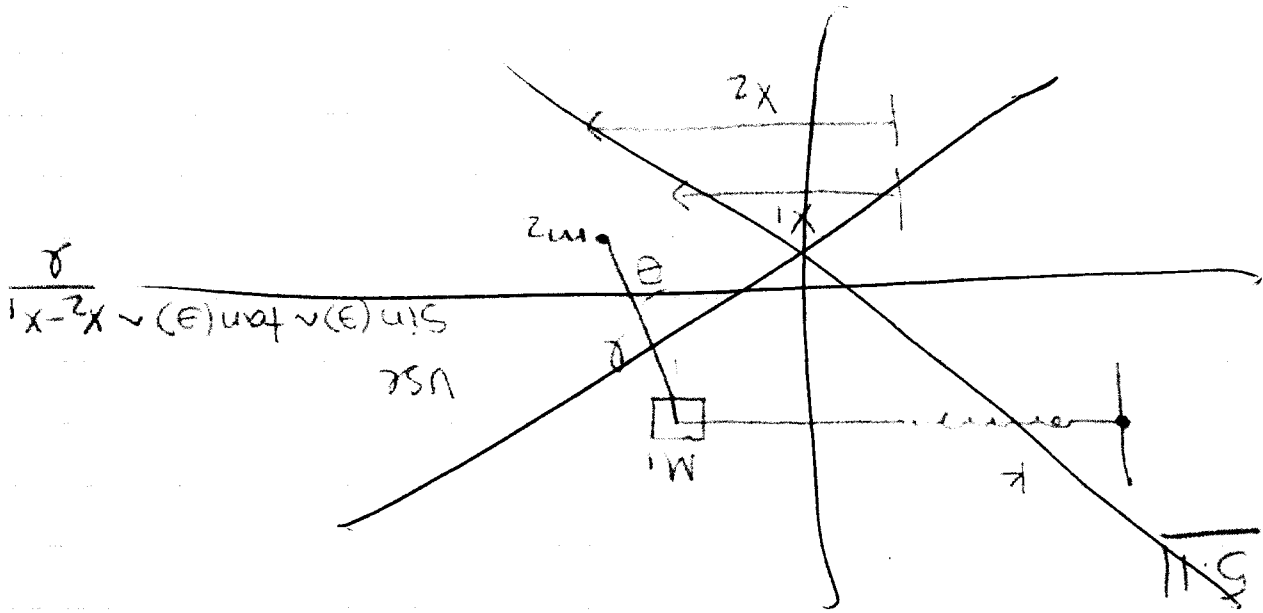
and  $k$  is what appears in the SHO equation.

where  $m$  is the mass

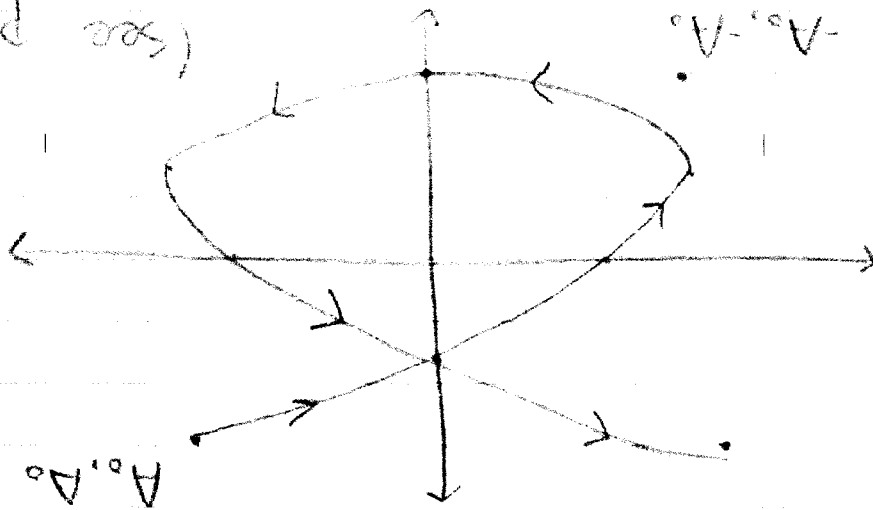
$$(c) \text{ for oscillation } \omega = \sqrt{\frac{k}{m}}$$

1/2

3



(see pg 36)



1/2

$$x(t) = A_0 \cos(\omega t)$$

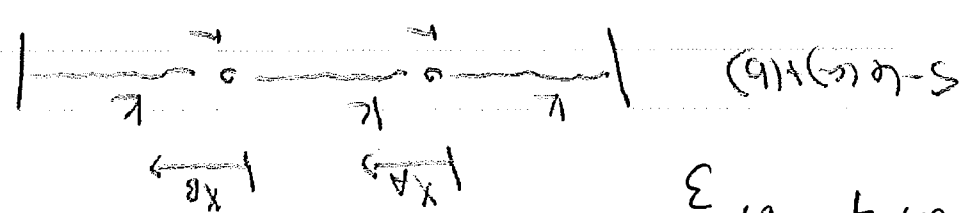
$$y(t) = A_0 \cos\left(\frac{3}{2}\omega t\right)$$

$$\omega_y = \frac{3}{2}\omega_x$$

(c) if  $\delta = \frac{9}{5}\delta_0$  then  $\frac{\omega_y}{\omega_x} = \frac{2}{3}$

4

a) 4  
b) 3



5-6 (g) (16)

$$m \frac{d^2 x_A}{dt^2} = -k x_A - k(x_A - x_B)$$

$$m \frac{d^2 x_B}{dt^2} = -k x_B - k(x_B - x_A)$$

assume

$$x_A = A e^{i\omega t} \quad x_B = B e^{i\omega t}$$

$$-A \omega^2 e^{i\omega t} = -\omega_0^2 A e^{i\omega t} - \omega_0^2 (A - B) e^{i\omega t}$$

$$-B \omega^2 e^{i\omega t} = -\omega_0^2 B e^{i\omega t} - \omega_0^2 (B - A) e^{i\omega t}$$

$$-A \omega^2 + \omega_0^2 A = \omega_0^2 (A - B) \quad -B \omega^2 + \omega_0^2 B = \omega_0^2 (B - A)$$

$$\begin{bmatrix} \omega_0^2 - \omega^2 & -\omega_0^2 \\ \omega_0^2 & \omega_0^2 - \omega^2 \end{bmatrix} \begin{bmatrix} A \\ B \end{bmatrix} = 0$$

$$\det \begin{vmatrix} \omega_0^2 - \omega^2 & -\omega_0^2 \\ \omega_0^2 & \omega_0^2 - \omega^2 \end{vmatrix} = 0$$

$$\omega^2 = 3\omega_0^2, \omega_0^2$$

$$T_{\omega_0} = 3\sqrt{2}$$

$$T_{\omega} = 3\sqrt{2}$$

$$T_{\omega_0} = \sqrt{6}$$

oo

if  $\omega^2 = \omega_0^2$

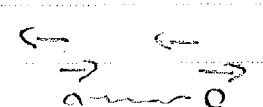
$$-A \cdot \omega^2 + \omega_0^2 A = \omega_0^2 (A - B) \Rightarrow -A + \omega_0^2 A = \omega_0^2 (A - B) \Rightarrow A = B$$

$$-B \omega^2 + \omega_0^2 B = \omega_0^2 (B - A) \Rightarrow -B + \omega_0^2 B = \omega_0^2 (B - A) \Rightarrow B = 0$$

$$-3A + \omega_0^2 A = \omega_0^2 (A - 0) \Rightarrow -3A + \omega_0^2 A = \omega_0^2 A \Rightarrow A = -B$$

eigen modes:

$$\begin{bmatrix} x_A \\ x_B \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^{i\omega_0 t}$$

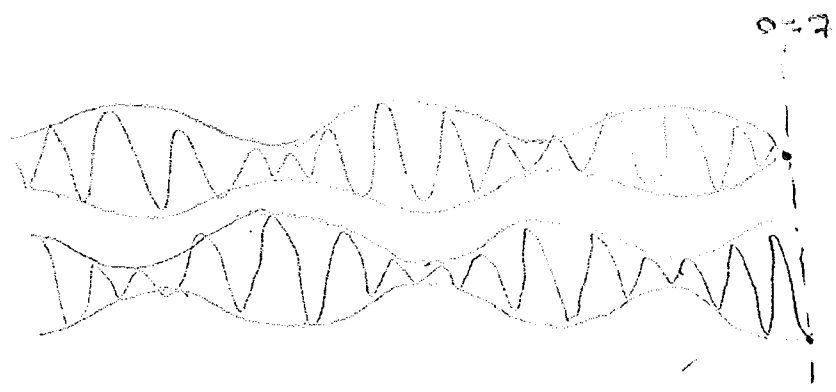


and

$$\begin{bmatrix} x_A \\ x_B \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \end{bmatrix} e^{i\sqrt{3}\omega_0 t}$$



Time axis



$$X_A = 5 \cos\left(\frac{\sqrt{3}-1}{2} \omega t\right) \cos\left(\frac{\sqrt{3}+1}{2} \omega t\right) \quad //$$

$$X_B = 5 \sin\left(\frac{\sqrt{3}-1}{2} \omega t\right) \sin\left(\frac{\sqrt{3}+1}{2} \omega t\right) \quad //$$

from trig identities

$$X_A = 2.5 \cos(\omega t) + 2.5 \cos(\sqrt{3} \omega t)$$

$$X_B = 2.5 \cos(\omega t) - 2.5 \cos(\sqrt{3} \omega t)$$

So  $X_B = 5 = 2C_1$   $C_1 = 2.5$

$$X_A = C_1 \cos(\omega t + \alpha) + C_2 \cos(\sqrt{3} \omega t + \beta)$$

$$X_B = C_1 \cos(\omega t + \alpha) - C_2 \cos(\sqrt{3} \omega t + \beta)$$

$$V_A = C_1 \sin(\omega t + \alpha) - C_2 \sqrt{3} \sin(\omega \sqrt{3} t + \beta)$$

$$V_B = C_1 \sin(\omega t + \alpha) + C_2 \sqrt{3} \sin(\omega \sqrt{3} t + \beta)$$

$\alpha$  and  $\beta = 0$  so  $V_A, V_B = 0$  @  $t=0$

$C_1 = -C_2$  so  $X_A = 0$  @  $t=0$

@  $t=0$ ,  $X_A = 0$ ,  $X_B = 5$   
 $V_A = 0$ ,  $V_B = 0$

$$\begin{bmatrix} X_A \\ X_B \end{bmatrix} = C_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^{i(\omega t + \alpha)} + C_2 \begin{bmatrix} 1 \\ -1 \end{bmatrix} e^{i(\omega \sqrt{3} t + \beta)}$$

S-to (a) cont.

S-10 (c)

3

$$\frac{\sqrt{3}-1}{2} \omega_0 t = \pi \quad \text{time of 2nd peak (slow)}$$

$$\frac{\sqrt{3}+1}{2} \omega_0 t = \pi \quad \text{time of 2nd fast peak}$$

$$t_s = \frac{\pi}{\omega_0} \frac{2}{\sqrt{3}-1} \rightarrow \boxed{t_s = 5.1955}$$

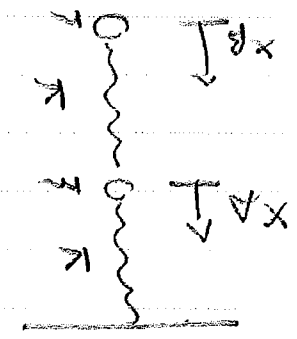
but notice

$$\frac{t_f}{t_s} = \frac{\pi}{\omega_0} \frac{2}{\sqrt{3}+1} \approx 0.33$$

non integer

but not exact state as before!

S-10 (a) Finding ratios of frequencies is 50%, ratio of amplitudes is 50%



$$m \frac{d^2 x_A}{dt^2} = -k x_A - k(x_A - x_B)$$

$$m \frac{d^2 x_B}{dt^2} = -k(x_B - x_A)$$

Assume  $\begin{bmatrix} x_A \\ x_B \end{bmatrix} = \begin{bmatrix} A \\ B \end{bmatrix} e^{i\omega t}$

our D.E's becomes. A:  $A m e^{i\omega t} (-\omega^2) = -2A k e^{i\omega t} + B k e^{i\omega t}$

B:  $B m e^{i\omega t} (-\omega^2) = -B k e^{i\omega t} + A k e^{i\omega t}$

$$2A \frac{k}{m} - B \frac{k}{m} - A \omega^2 = 0$$

$$B \frac{k}{m} - A \frac{k}{m} - B \omega^2 = 0$$

S-10 (a) cont.

$$\begin{bmatrix} \omega_0^2 - \omega^2 & A \\ -\omega^2 & B \end{bmatrix} \begin{bmatrix} A \\ B \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

find  $\omega^2$  by  $\det = 0$

$$(\omega_0^2 - \omega^2)(\omega_0^2 - \omega^2) - \omega^4 = 0$$

$$\omega_0^4 - 2\omega_0^2\omega^2 + \omega^4 - \omega^4 = 0$$

$$\omega^4 + (-2\omega_0^2)\omega^2 + \omega_0^4 = 0$$

Quadratic:  
eg.

$$3\omega^2 \pm \sqrt{9\omega_0^4 - 4\omega_0^4} = \frac{2}{2}$$

$$\boxed{3 \pm \sqrt{5} \frac{\omega_0^2}{2} = \omega^2}$$

$$\left(\frac{\omega_1}{\omega_2}\right)^2 = \frac{3 + \sqrt{5}}{3 - \sqrt{5}} = \frac{(3 + \sqrt{5})(3 + \sqrt{5})}{(3 - \sqrt{5})(3 + \sqrt{5})} = \frac{14 + 6\sqrt{5}}{4}$$

$$= \left(\frac{6 + 2\sqrt{5}}{4}\right)^2 = \left(\frac{5 + 2\sqrt{5} + 1}{5 - 1}\right)^2 = \left(\frac{(\sqrt{5} + 1)(\sqrt{5} + 1)}{(\sqrt{5} - 1)(\sqrt{5} + 1)}\right)^2$$

$$= \left(\frac{\sqrt{5} + 1}{\sqrt{5} - 1}\right)^2 = \left(\frac{\omega_1}{\omega_2}\right)^2$$

aside over

To find ratio of amplitudes stick the two  $\omega$ 's back into DE's. i.e.

$$(\omega_0^2 - \omega^2)A - \omega^2 B = 0$$

over

S-10 cont.

for  $\omega^2 = 3 + \sqrt{5} \omega^2$

$$A(2\omega^2 - 3 + \sqrt{5} \omega^2) = B \omega^2$$

$$4 - 3 - \sqrt{5} = \frac{A}{B} = 1 - \sqrt{5}$$

Note take (absolute value to make amplitude)

$$\omega^2 = 3 - \sqrt{5} \omega^2 ; A(2\omega^2 - 3 - \sqrt{5} \omega^2) = B \omega^2$$

$$4 - 3 + \sqrt{5} = \frac{A}{B} = 1 + \sqrt{5}$$

ore mode amplitude ratio =  $\frac{\sqrt{5}-1}{2}$

other " " =  $\frac{\sqrt{5}+1}{2}$

15

Q.P.1

(a)

(1)

$$\omega = \sqrt{\frac{10}{5}} = \sqrt{2} \text{ s}^{-1}$$

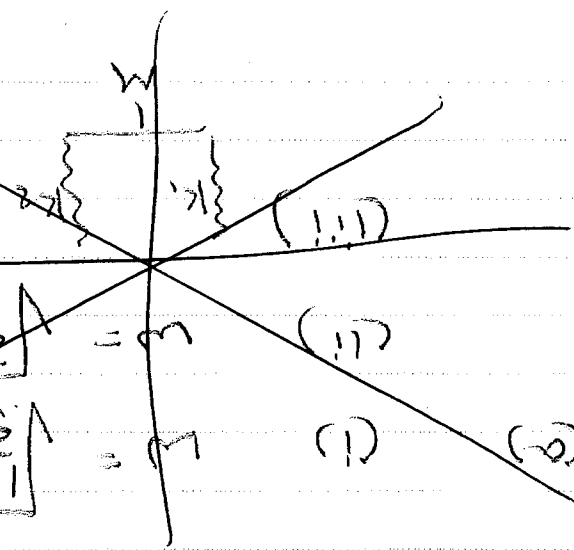
$$\omega = \sqrt{\frac{2}{5}} = \sqrt{0.4} \text{ s}^{-1}$$

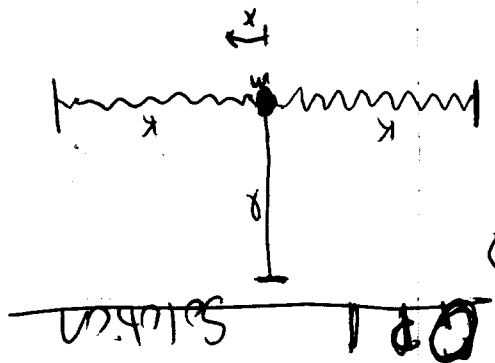
(2)

(iii)

$$m d^2 x_A = -k_1 x_A - k_2 x_A$$

$$\omega = \sqrt{\frac{5}{k_1+k_2}} = \sqrt{6} \text{ s}^{-1}$$





- Before we can write the differential equations, we need to know the forces involved.

$$F_{spring} = -kx$$

$$F_{grav} = mgsin\theta \approx -mgx$$

small angle approximation

$$\Rightarrow F_{net} = -kx - mgx = -(k+mg)x$$

$$\Rightarrow m \frac{d^2x}{dt^2} = -(k+mg)x \Rightarrow \frac{d^2x}{dt^2} = -\left(\frac{k}{m} + \frac{g}{l}\right)x$$

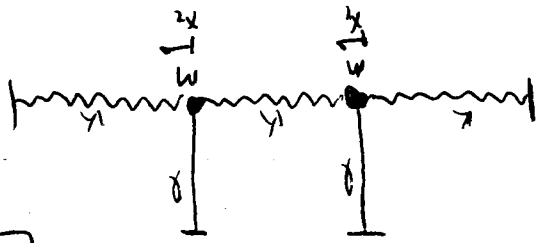
b) The student's should be able to argue directly from this differential equation, what the frequency is.

guess:  $x = A \cos(\omega t + \phi)$

$$\frac{d^2x}{dt^2} = -\omega^2 A \cos(\omega t + \phi)$$

$$\Rightarrow \omega^2 = \left(\frac{k}{m} + \frac{g}{l}\right)$$

$$\Rightarrow |\omega| = \sqrt{\left(\frac{k}{m} + \frac{g}{l}\right)}$$



- Using same reasoning as before:  $F_{spring} = -mgx$

$$F_{spring} = -kx_1 + k(x_2 - x) = -2kx_1 + kx_2$$

$$F_{spring} = kx_1 - 2kx_2$$

$$\Rightarrow \alpha = \pm i \left[ \frac{\delta}{2} + \sqrt{\frac{\delta^2}{4} + 3K} \right], \quad \mp i \left[ \frac{\delta}{2} + \sqrt{\frac{\delta^2}{4} + 3K} \right]$$

$$\Rightarrow \left( \frac{\delta}{2} + 2K \right)^2 + (\alpha)^2 + 2 \left( \frac{\delta}{2} + 2K \right) \alpha^2 - K^2 = 0$$

Find the eigenvalues:  $\det \begin{bmatrix} K_{11} & K_{12} \\ K_{21} & K_{22} \end{bmatrix} = 0$

The normal mode frequencies  $\alpha$  must be the eigenvalues of this matrix and the relative amplitudes of the normal modes,  $V$ , must be the eigenvectors.

Now we make the guess that  $X = V e^{\alpha t}$ . Let's plug this in.

$$\Rightarrow \alpha^2 V e^{\alpha t} = \begin{bmatrix} -(\delta/2 + 2K) & K_{12} \\ K_{21} & -(\delta/2 + 2K) \end{bmatrix} V e^{\alpha t} \Rightarrow \begin{bmatrix} K_{11} & -(\delta/2 + 2K) \\ -(\delta/2 + 2K) & K_{11} \end{bmatrix} V = \alpha^2 V$$

where  $X$ 's notation represents time derivative

$$\Rightarrow \ddot{X} = \begin{bmatrix} -(\delta/2 + 2K) & K_{12} \\ K_{21} & -(\delta/2 + 2K) \end{bmatrix} X$$

$$\Rightarrow \begin{bmatrix} \frac{d^2 x_1}{dt^2} \\ \frac{d^2 x_2}{dt^2} \end{bmatrix} = \begin{bmatrix} -(\delta/2 + 2K) & K_{12} \\ K_{21} & -(\delta/2 + 2K) \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

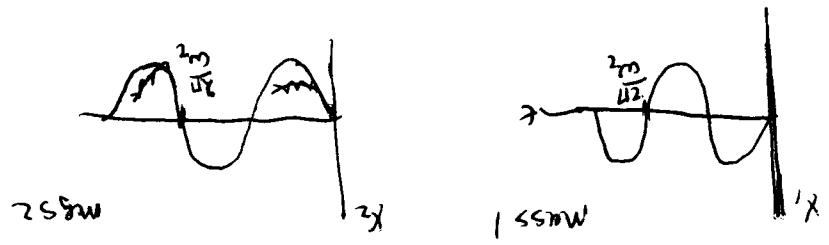
$$\Rightarrow m \frac{d^2 x_1}{dt^2} = -m \delta x_1 - 2K x_1 + K x_2$$

$$\Rightarrow m \frac{d^2 x_2}{dt^2} = -m \delta x_2 - 2K x_2 + K x_1$$

$$\Rightarrow m \frac{d^2 x_1}{dt^2} = -m \delta x_1 - 2K x_1 + K x_2$$

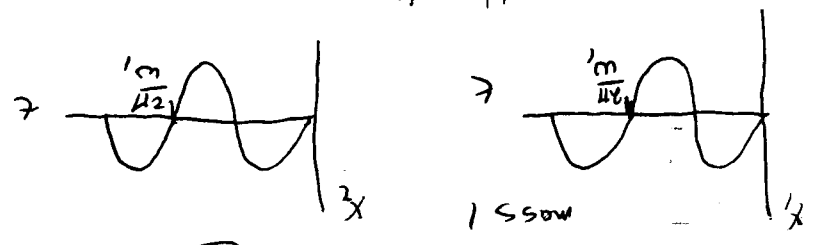
now add all the forces together and set equal to  $m a = m \ddot{x}$

- In eigenmode two the masses move with the same amplitude, and frequency but with 180° phase difference.



Sketch eigenmode 2:

- in eigenmode 1 the masses move with the same amplitude, phase, and frequency.



Sketch eigenmode 1:

$$\begin{bmatrix} A_2 \cos(\omega_2 t + \phi_2) \\ 1 \end{bmatrix}$$

eigenfunktion 2:

$$\begin{bmatrix} A_1 \cos(\omega_1 t + \phi_1) \\ 1 \end{bmatrix}$$

eigenfunktion 1:

$$\Rightarrow \begin{bmatrix} K_{1m} \\ K_{2m} \end{bmatrix} \begin{bmatrix} \frac{1}{2} \\ \frac{1}{2} \end{bmatrix} = 0 \Rightarrow \vec{v}_2 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$\begin{bmatrix} -(s/0 + 2K) - \alpha^2 & K/m \\ K/m & (-s/2 + 2K) - \alpha^2 \end{bmatrix} \begin{bmatrix} \frac{1}{2} \\ \frac{1}{2} \end{bmatrix} = 0$$

$$\Rightarrow \begin{bmatrix} -\frac{K}{m} \\ -\frac{K}{m} \end{bmatrix} \begin{bmatrix} \frac{1}{2} \\ \frac{1}{2} \end{bmatrix} = 0 \Rightarrow \vec{v}_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

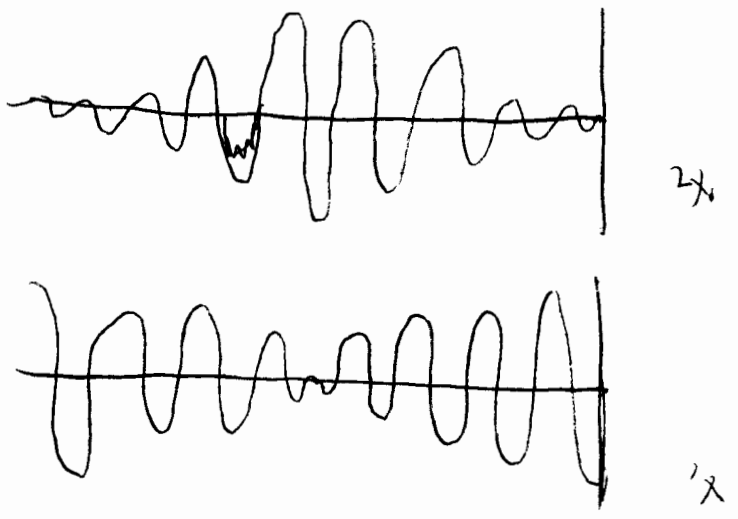
$$\begin{bmatrix} -(s/0 + 2K) - \alpha^2 & K/m \\ K/m & (-s/2 + 2K) - \alpha^2 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = 0$$

now find the eigenvectors:

- e)

$$\omega_1 = \sqrt{\frac{2}{m} + K}, \omega_2 = \sqrt{\frac{2}{m} + 3K}$$

more explicitly, the eigenfrequencies are



f)

All the students now have to do is plot this function.  
 If  $k_1 = m_1 \omega_1$  then  $\frac{\omega_1^2}{k_1} = \frac{11}{13} \Rightarrow \frac{\omega_1}{\omega_2} = \sqrt{\frac{11}{13}}$   
 Pick some value for  $\omega_1$  and do a plot. I'd be happy for something like this.

$$\vec{x} = \frac{2}{3} \cos(\omega_1 t) \begin{bmatrix} 1 \\ 1 \end{bmatrix} + \frac{2}{3} \cos(\omega_2 t) \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$\vec{x}(0) = \begin{bmatrix} x_0 \\ \dot{x}_0 \end{bmatrix} = \begin{bmatrix} A_1 + A_2 \\ A_1 - A_2 \end{bmatrix} \Rightarrow \begin{cases} A_1 = A_2 \\ A_1 = A_2 = \frac{x_0}{2} \end{cases}$$

$$\vec{x} = A_1 \cos(\omega_1 t) \begin{bmatrix} 1 \\ 1 \end{bmatrix} + A_2 \cos(\omega_2 t) \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$\Rightarrow \vec{x}(0) = 0 = -A_1 \omega_1 \sin(\phi_1) \begin{bmatrix} 1 \\ 1 \end{bmatrix} + A_2 \omega_2 \sin(\phi_2) \begin{bmatrix} 1 \\ -1 \end{bmatrix} \Rightarrow \phi_1 = \phi_2 = 0$$

Let's look at the easier initial condition first:  $\vec{x}(0) = \vec{x}_2(0) = 0$

$$\vec{x} = A_1 \cos(\omega_1 t + \phi_1) \begin{bmatrix} 1 \\ 1 \end{bmatrix} + A_2 \cos(\omega_2 t + \phi_2) \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

The general solution is the sum of two normal modes.