

Lecture 8 : Momentum

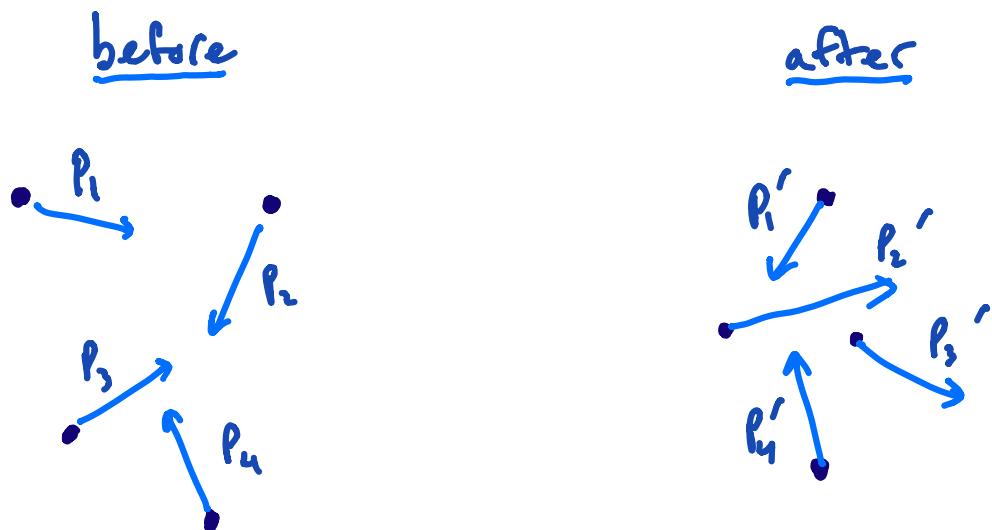
Momentum Conservation

Momentum unifies and quantifies Newton's 1st (principle of inertia) and 3rd (action/reaction) laws:

$$\overrightarrow{P} = m \overrightarrow{V}$$

momentum → velocity

all objects $\sum_i \overrightarrow{P}_i = \text{constant}$



$$\rightarrow \vec{P}_1 + \vec{P}_2 + \vec{P}_3 + \vec{P}_4 = \vec{P}'_1 + \vec{P}'_2 + \vec{P}'_3 + \vec{P}'_4$$

demo: "Newton's cradle"

1st law: special case of one object,

$$\vec{p} = m\vec{v} = \text{const}$$

3rd law: special case of two objects,

$$\vec{p}_1 + \vec{p}_2 = \text{const} = \vec{p}'_1 + \vec{p}'_2$$

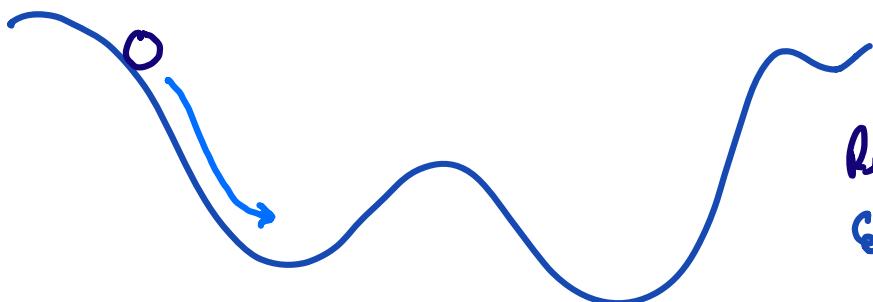
$$\rightarrow (\vec{p}_1 - \vec{p}'_1) = -(\vec{p}_2 - \vec{p}'_2)$$

$$\rightarrow -\frac{\Delta \vec{p}_1}{\Delta t} = \frac{\Delta \vec{p}_2}{\Delta t}$$

$$\rightarrow -m_1 \vec{a}_1 = m_2 \vec{a}_2$$

$$\rightarrow \boxed{-\vec{F}_{12} = \vec{F}_{21}}$$

Naively confusing: What happened to momentum = const??



Resolution: the Earth has momentum

demo: "big/small bouncy ball"

Center of Mass

\bar{X} = "C.o.M position"

= "where the mass is, on average"

= "mass-averaged position"

$$= \frac{m_1}{M} X_1 + \frac{m_2}{M} X_2$$

where $M = m_1 + m_2$

(ex 1) $m_1 = m_2$

$$\bar{x} = \frac{x_1 + x_2}{2}$$

(ex 2) $m_1 \gg m_2$

$$\bar{x} \sim x_1$$

We also define a center of mass velocity,

$$\bar{V} = \frac{d\bar{X}}{dt} = \frac{m_1}{M} V_1 + \frac{m_2}{M} V_2$$

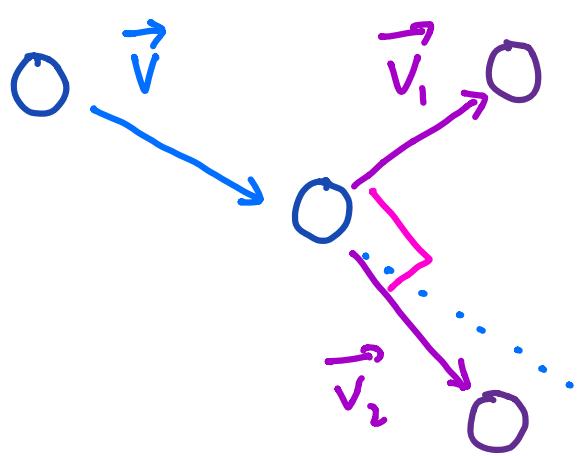
$$= \frac{P_1 + P_2}{M}$$

$$\Rightarrow \underbrace{M\bar{V}}_{\bar{P}} = P_1 + P_2 = \text{const} \quad (\text{by momentum conservation})$$

\bar{P} = "C.o.M. momentum"

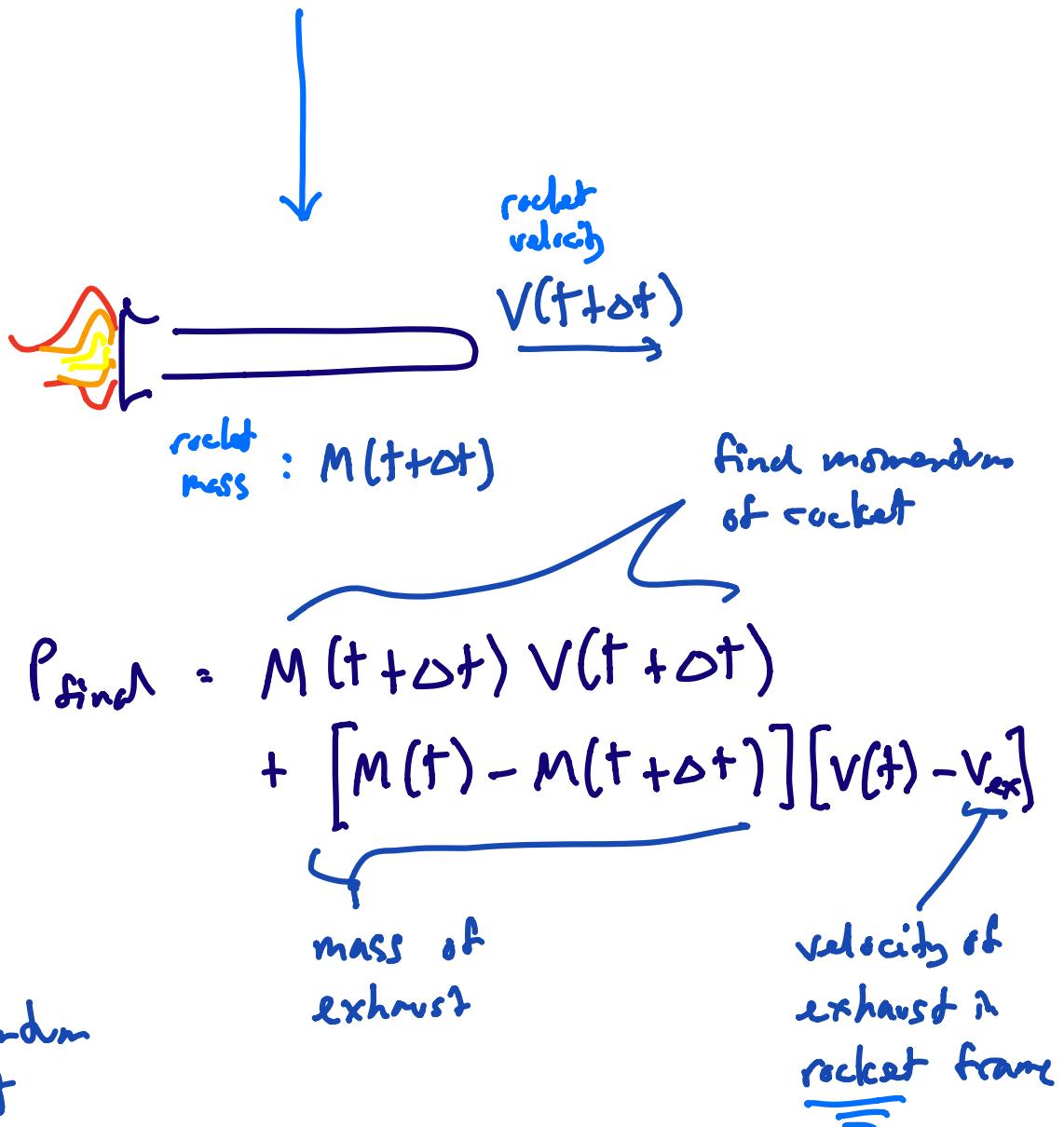
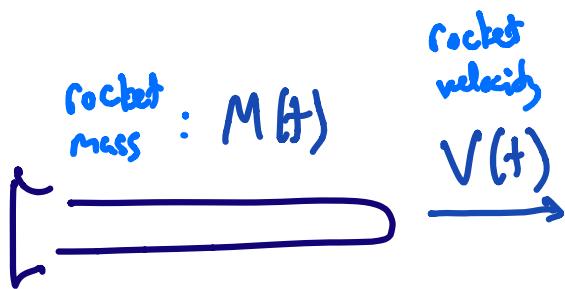
[Bottom line: C.o.M position of a closed system moves in a straight line]

demo: "airtrack billiards"



$$\begin{aligned} i) \frac{1}{2} m \vec{v}^2 &= \frac{1}{2} m (\vec{v}_1^2 + \vec{v}_2^2) \\ ii) m \vec{v} &= m (\vec{v}_1 + \vec{v}_2) \\ &\Downarrow \\ \vec{v}^2 &= \vec{v}_1^2 + 2\vec{v}_1 \cdot \vec{v}_2 + \vec{v}_2^2 \\ \Rightarrow \vec{v}_1 \cdot \vec{v}_2 &= 0 \end{aligned}$$

Rocket Science



$$P_{\text{initial}} = P_{\text{final}} = M(t + \Delta t) V(t + \Delta t)$$

$$= M(t) V(t) + [M(t) - M(t + \Delta t)] [V(t) - V_{ex}]$$

where

$$0 = M V \Big|_{t+\Delta t} - M V \Big|_t + (M \Big|_t - M \Big|_{t+\Delta t}) (V - V_{ex})$$

$$\Rightarrow \frac{d}{dt} (Mv) - \frac{dM}{dt} (v - v_{ex}) = 0$$

$$\cancel{\frac{dM}{dt} v} + M \frac{dv}{dt} - \cancel{\frac{dM}{dt} v} + \cancel{\frac{dM}{dt}} v_{ex}$$

$$\Rightarrow M \frac{dv}{dt} = - \frac{dM}{dt} v_{ex}$$

Solving the diff eq, we obtain

$$\int \frac{dv}{dt} dt = -v_{ex} \int \frac{dM/dt}{M} dt$$

$$v(t) = -v_{ex} \log M(t) + \text{const}$$

$$V(t) = V(0) + v_{ex} \log \frac{M(0)}{M(t)}$$

bottom line: you need to lose an exponentially high fraction of your rocket mass to increase your speed $\sim v_{ex}$.

\Rightarrow rocket science is hard.