

Optimal-Transportation Meshfree Approximation Schemes for Fluid and Plastic Flows

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UCLA, February 23, 2010

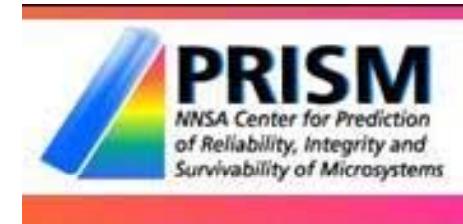


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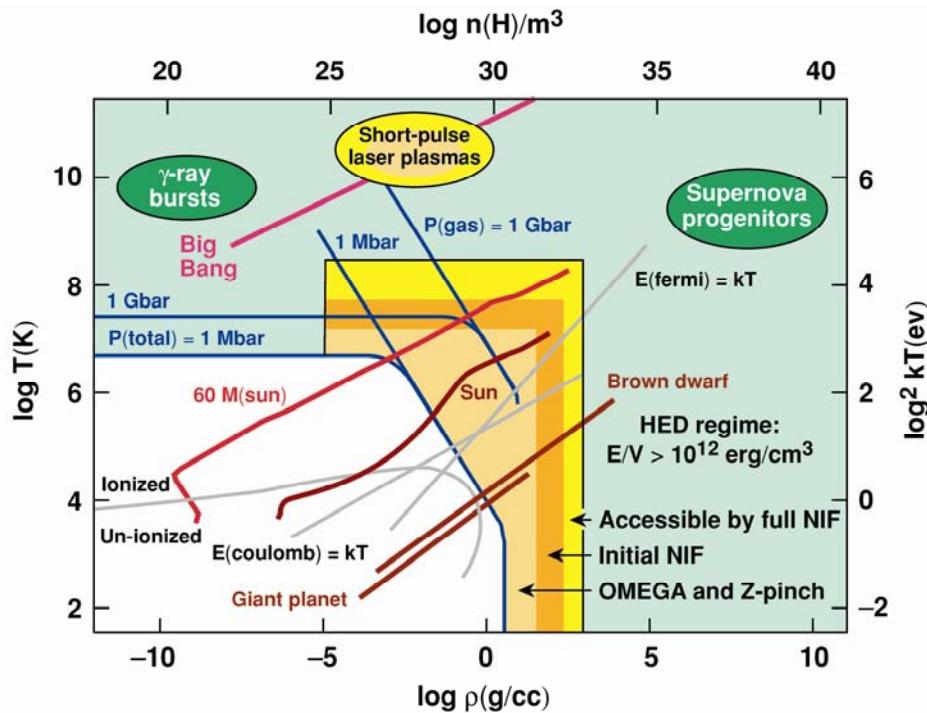


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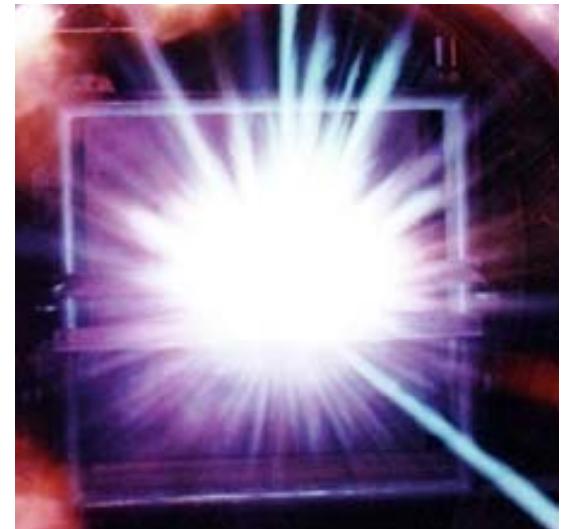
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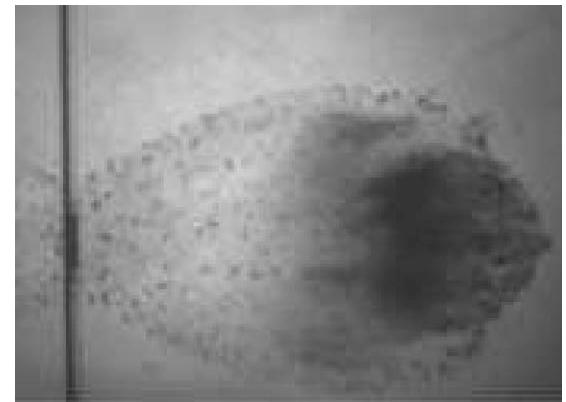
Objective: Predict *hypervelocity impact* phenomena with *quantified margins and uncertainties*



Hypervelocity impact test bumper shield
(Ernst-Mach Institut, Freiburg Germany)



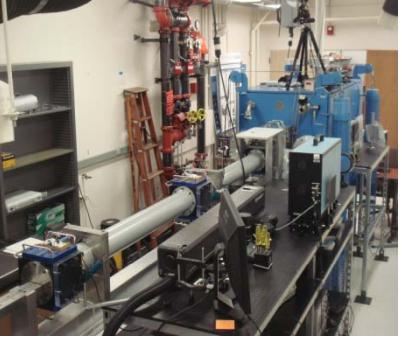
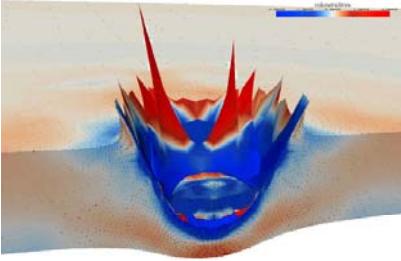
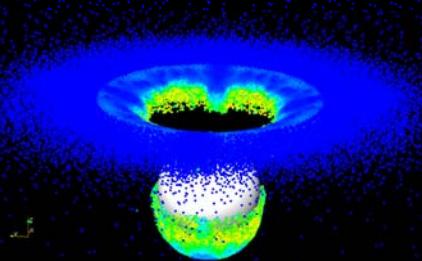
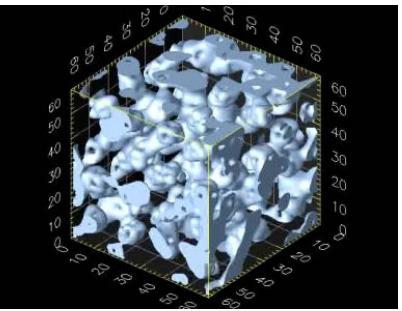
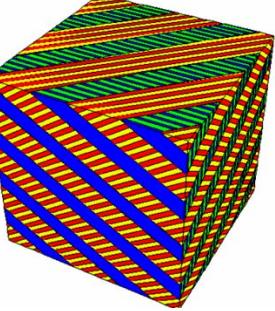
NASA Ames Research Center
Energy flash from hypervelocity
test at 7.9 Km/s



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QMU – Center's assets

Experimental Science	Simulation codes		
 A photograph of the SPHIR (Shock Physics High-Resolution Imaging) facility, showing a large vacuum chamber with various ports and equipment.	 A photograph of the HSRT (High-Speed Response Test) apparatus, which consists of a long blue metal frame with various attachments and sensors.	 A 3D simulation visualization of a VTF (Variable Temperature Furnace) experiment, showing a central cavity with a complex internal structure and a color scale indicating temperature or density.	 A 3D simulation visualization of an OTM (Optical Tomography Method) experiment, showing a spherical object with internal structures and a color scale.
SPHIR	HSRT	VTF	OTM
Physics models	UQ tools		
 A 3D visualization of plasma or material particles within a cubic volume, showing a dense cluster of blue spheres.	 A 3D visualization of a cube with internal diagonal planes colored in red, green, and blue, representing a fracture or strength model.	 Two white six-sided dice with black pips, representing probability or combinatorial methods.	 A photograph of a complex network of black pipes and fittings, representing a UQ pipeline infrastructure.
Plasma/EoS	Strength/Fracture	Probability/CoM	UQ pipeline



Simulation requirements

- Hypervelocity impact: Grand challenge in scientific computing
- Main simulation requirements:
 - *Hypersonic dynamics, high-energy density (HED)*
 - *Multiphase flows (solid, fluid, gas, plasma)*
 - *Free boundaries + contact*
 - *Fracture, fragmentation, perforation*
 - *Complex material phenomena:*
 - *HED/extreme conditions*
 - *Ionization, excited states, plasma*
 - *Multiphase equation of state, transport*
 - *Viscoplasticity, thermomechanical coupling*
 - *Brittle/ductile fracture, fragmentation...*

Optimal-Transportation Meshfree (OTM)

- Time integration (OT):
 - *Optimal transportation methods:*
 - Geometrically exact, discrete Lagrangians
 - *Discrete mechanics, variational time integrators:*
 - Symplecticity, exact conservation properties
 - *Variational material updates, inelasticity:*
 - Incremental variational structure
- Spatial discretization (M):
 - *Max-ent meshfree nodal interpolation:*
 - Kronecker-delta property at boundary
 - *Material-point sampling:*
 - Numerical quadrature, material history
 - *Dynamic reconnection, 'on-the-fly' adaptivity*

Optimal transportation theory



Gaspard Monge
Beaune (1746), Paris (1818)
"Sur la théorie des déblais et des remblais" (Mém. de l'acad. de Paris, 1781)



Leonid V. Kantorovich
Saint Petersbourg (1912)
Moscow (1986)
Nobel Prize in
Economics (1975)

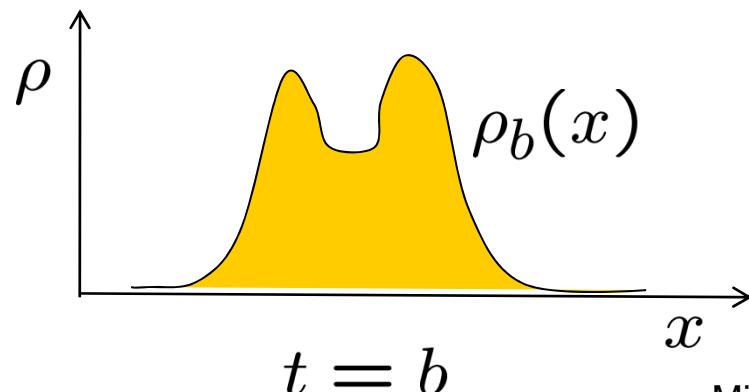
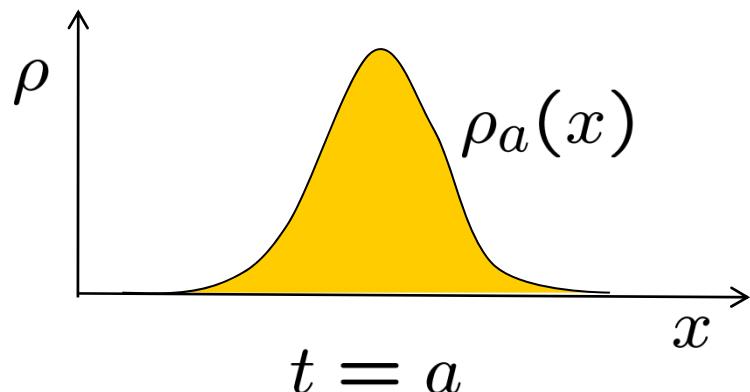
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Mass flows – Optimal transportation

- Flow of non-interacting particles in \mathbb{R}^n

$$\left. \begin{aligned} \frac{\partial \rho}{\partial t} + \nabla \cdot (\rho v) &= 0 \\ \frac{\partial(\rho v)}{\partial t} + \nabla \cdot (\rho v \otimes v) &= 0 \end{aligned} \right\} t \in [a, b]$$

- Initial and final conditions: $\begin{cases} \rho(x, a) = \rho_a(x) \\ \rho(x, b) = \rho_b(x) \end{cases}$



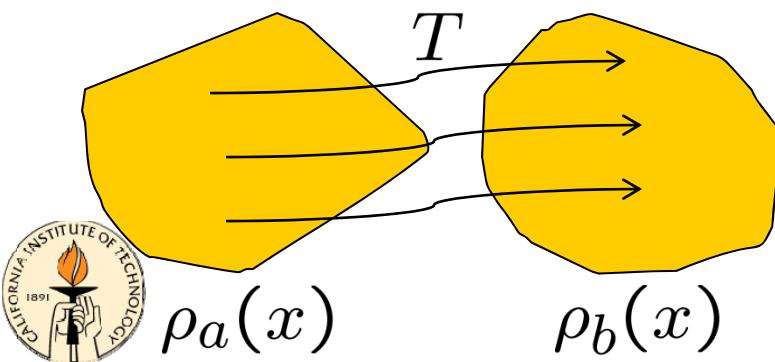
Mass flows – Optimal transportation

- *Benamou & Brenier* minimum principle:

$$\left. \begin{array}{l} \text{minimize: } A(\rho, v) = \int_a^b \int \frac{\rho}{2} |v|^2 dx dt \\ \text{subject to: } \frac{\partial \rho}{\partial t} + \nabla \cdot (\rho v) = 0 \end{array} \right\} \Rightarrow (\rho, v)$$

- Reformulation as optimal transportation problem:

$$\inf A = \inf_T \int |T(x) - x|^2 \rho_a(x) dx \equiv d_W^2(\rho_a, \rho_b)$$



- McCann's interpolation:

$$\varphi(x, t) = \frac{b-t}{b-a} x + \frac{t-a}{b-a} T(x)$$
$$\Rightarrow (\rho, v)$$

Euler flows – Optimal transportation

- Semidiscrete action: $A_d(\rho_1, \dots, \rho_{N-1}) =$

$$\sum_{k=0}^{N-1} \left\{ \underbrace{\frac{1}{2} \frac{d_W^2(\rho_k, \rho_{k+1})}{(t_{k+1} - t_k)^2}}_{\text{inertia}} - \underbrace{\frac{1}{2} [U(\rho_k) + U(\rho_{k+1})]}_{\text{internal energy}} \right\} (t_{k+1} - t_k)$$

- Discrete Euler-Lagrange equations: $\delta A_d = 0 \Rightarrow$

$$\frac{2\rho_k}{t_{k+1} - t_{k-1}} \left(\frac{\varphi_{k \rightarrow k+1} - \text{id}}{t_{k+1} - t_k} + \frac{\varphi_{k \rightarrow k-1} - \text{id}}{t_k - t_{k-1}} \right) = \nabla p_k + \rho_k b_k$$

$$\rho_{k+1} \circ \varphi_{k \rightarrow k+1} = \rho_k / \det(\nabla \varphi_{k \rightarrow k+1})$$

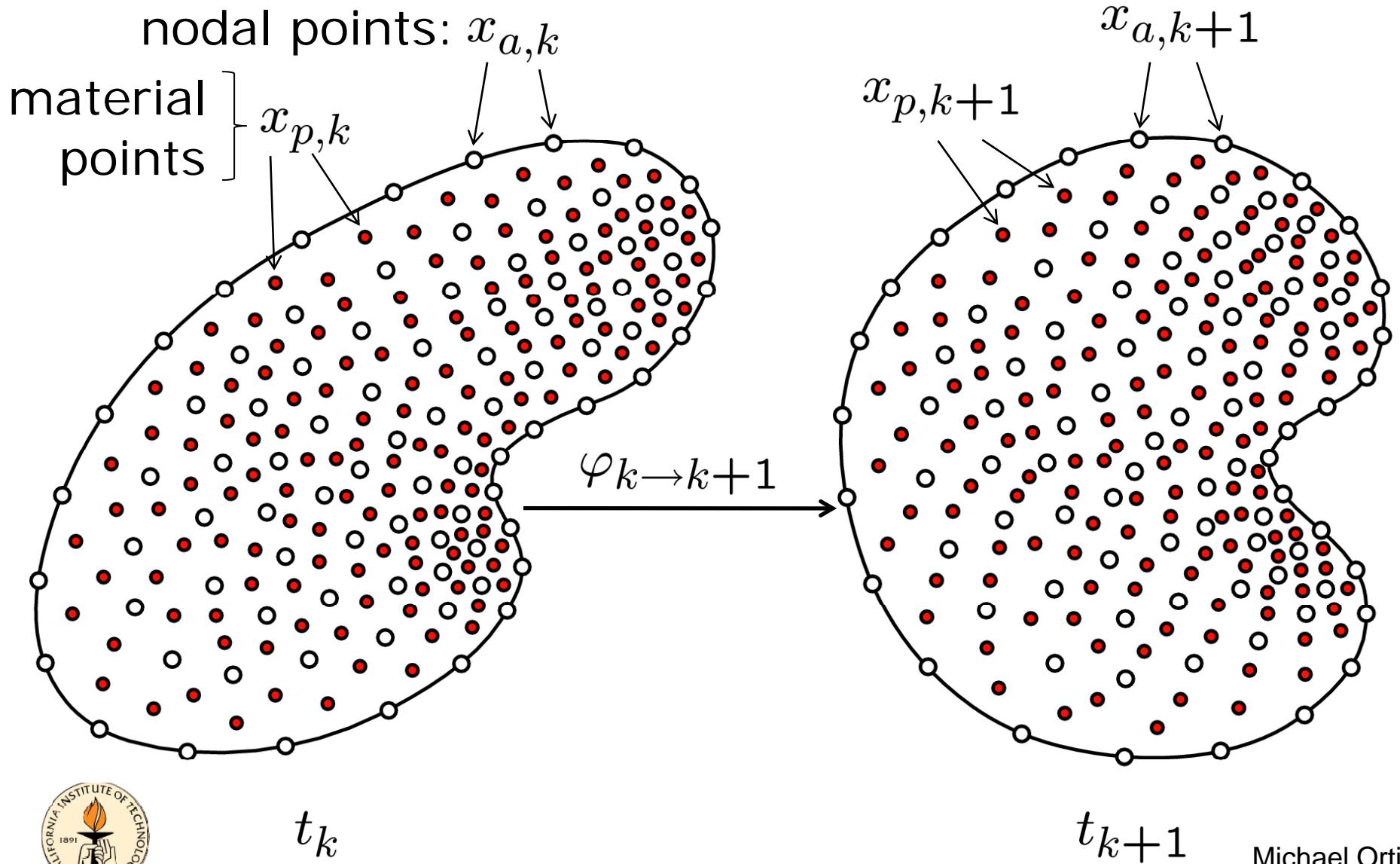
geometrically exact mass conservation!



Optimal-Transportation Meshfree (OTM)

- Optimal transportation theory is a useful tool for generating geometrically-exact discrete Lagrangians for flow problems
- Inertial part of discrete Lagrangian measures distance between consecutive mass densities (in sense of Wasserstein)
- Discrete Hamilton principle of stationary action: Variational time integration scheme:
 - *Symplectic, time reversible*
 - *Exact conservation properties (linear and angular momenta, energy)*
 - *Strong variational convergence in the sense of Γ -convergence (B. Schmidt)*

OTM – Spatial discretization

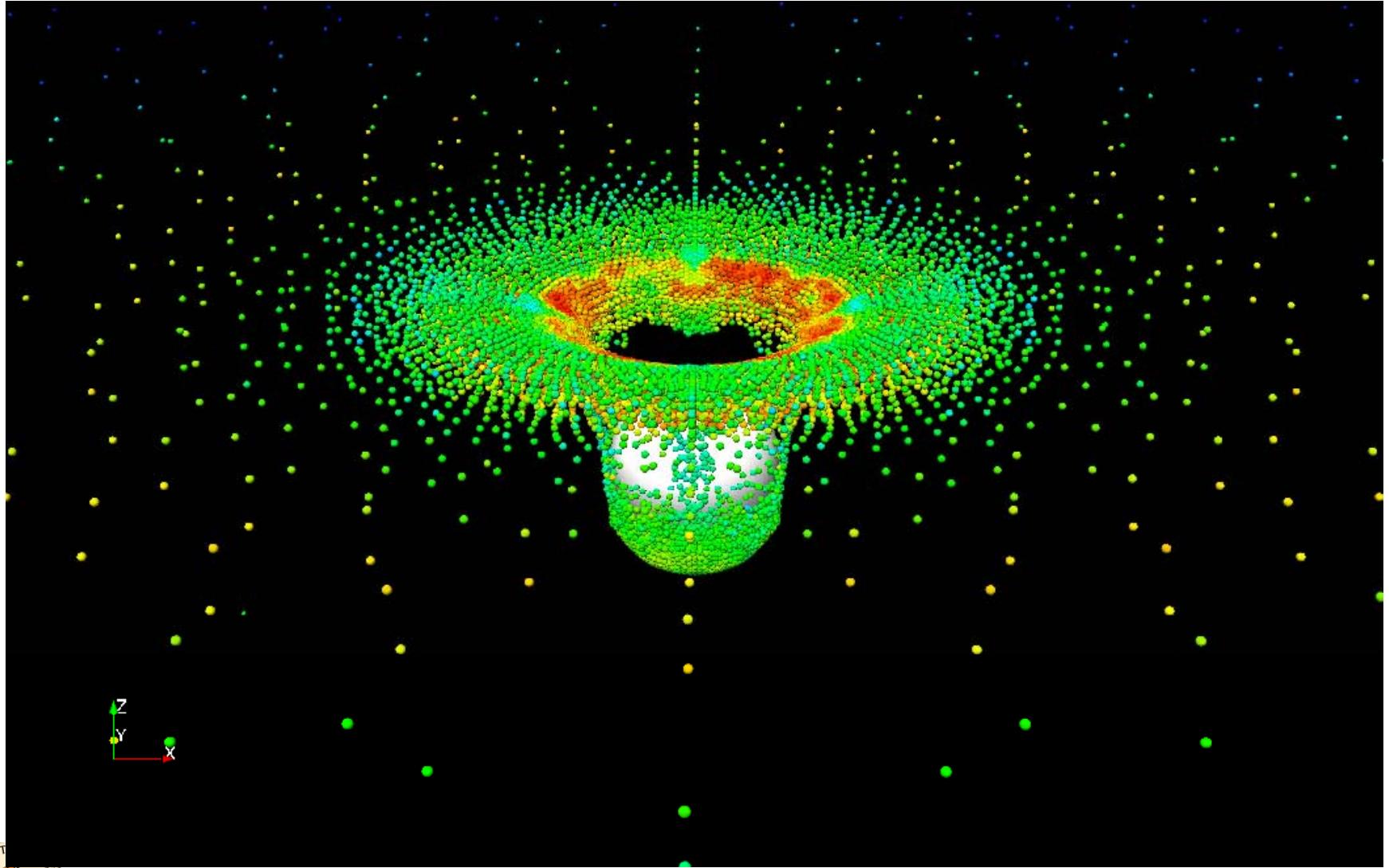


t_k

t_{k+1}

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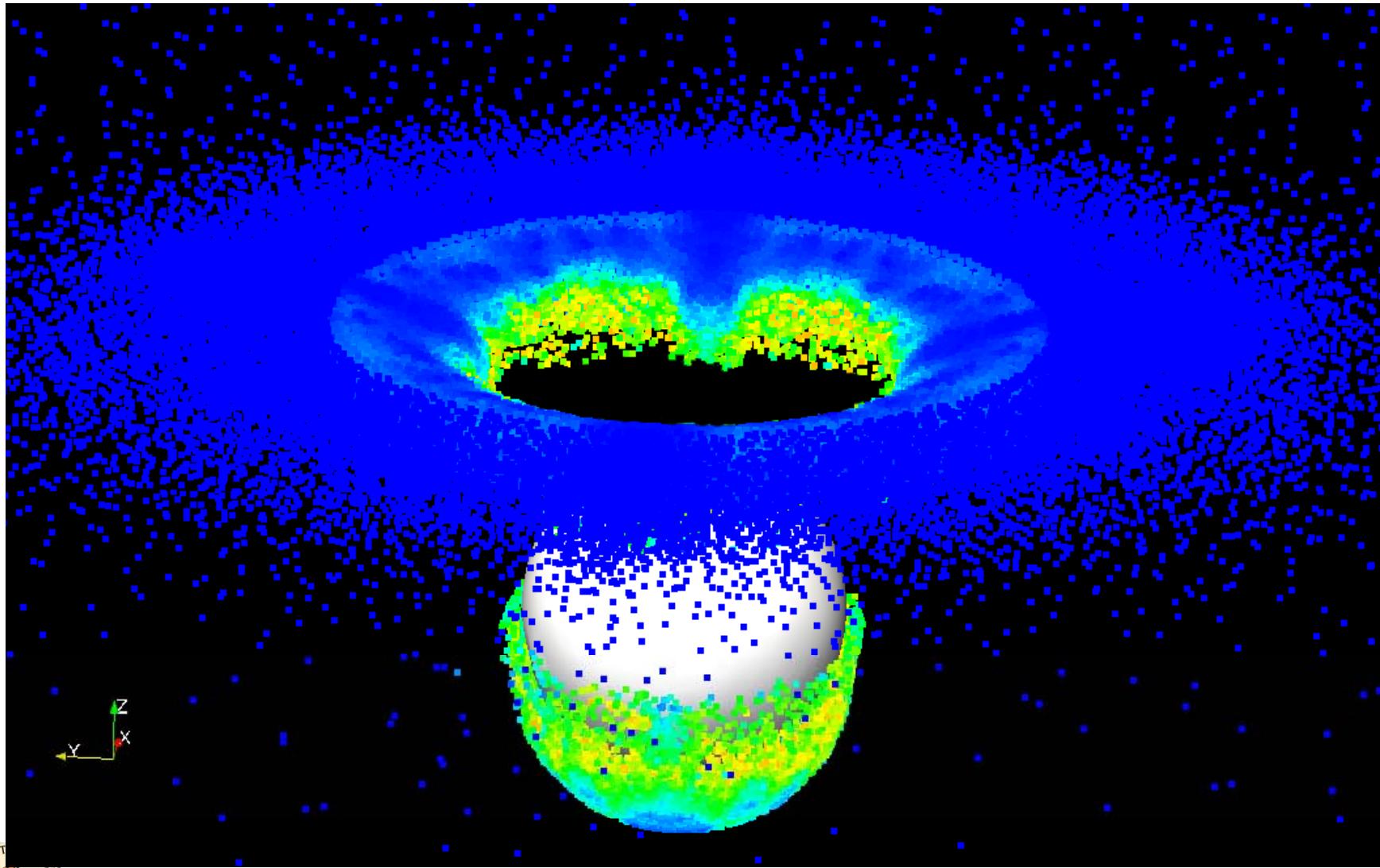
OTM – Spatial discretization



Steel projectile/aluminum plate: Nodal set

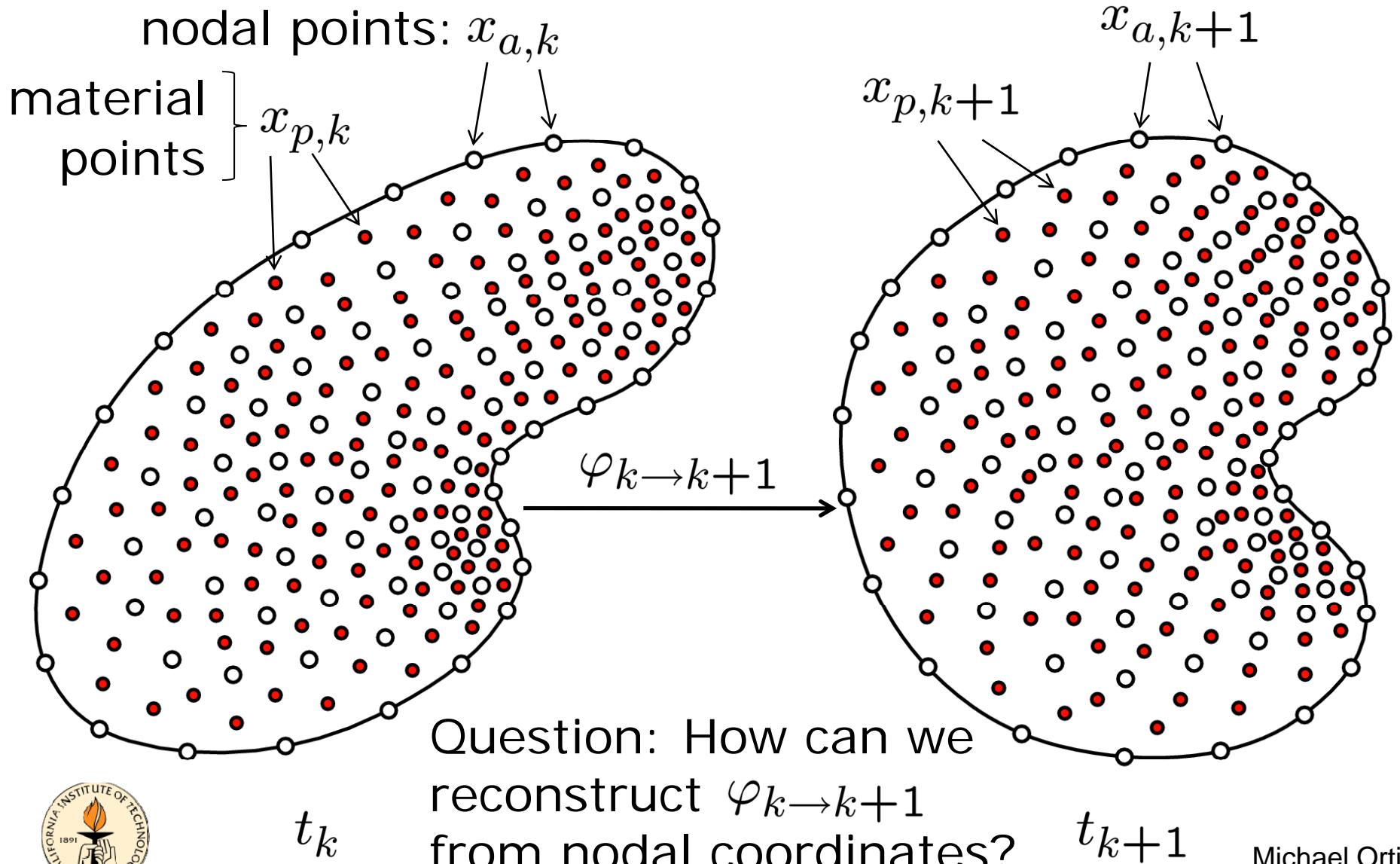
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OTM – Spatial discretization



Steel projectile/aluminum plate: Material point set Michael Ortiz
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OTM – Spatial discretization



OTM – Max-ent interpolation

- Problem: Reconstruct function $u(x)$ from nodal sample $\{u(x_a), a = 1, \dots, N\}$ so that:
 - Reconstruction is *least biased*
 - Reconstruction is *most local*
- Optimal shape functions (Arroyo & MO, *IJNME*, 2006):

$$\text{Minimize: } \sum_{a=1}^N |x-x_a|^2 N_a(x) + \beta \sum_{a=1}^N N_a(x) \log N_a(x)$$

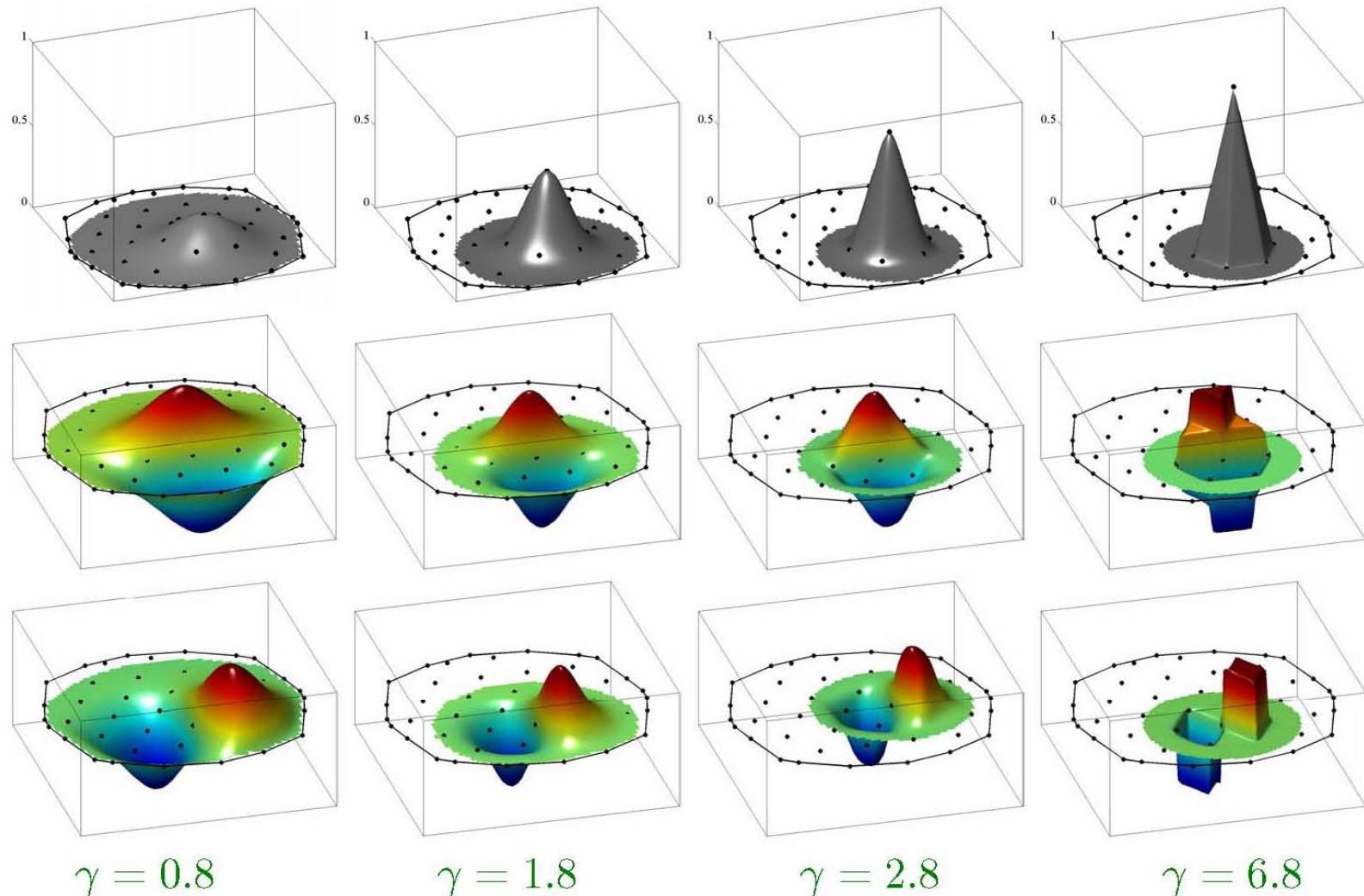
 

shape function width information entropy

$$\text{Subject to: } \sum_{a=1}^N N_a(x) = 1, \quad \sum_{a=1}^N x_a N_a(x) = x.$$



OTM – Max-ent interpolation



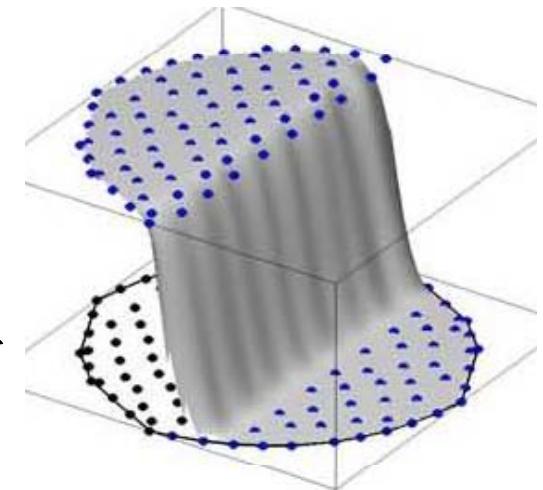
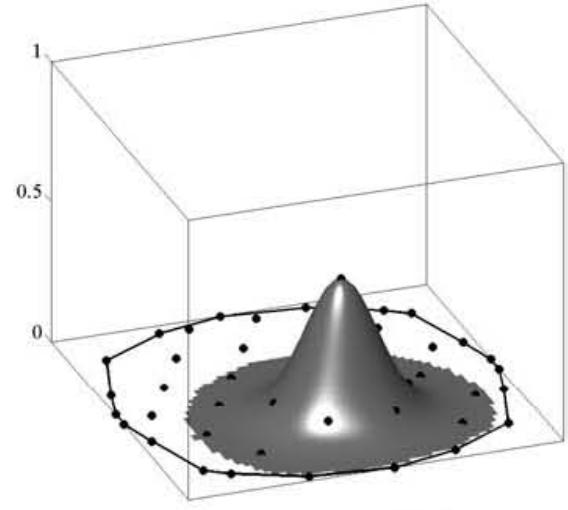
Max-ent shape functions, $\gamma = \beta h^2$



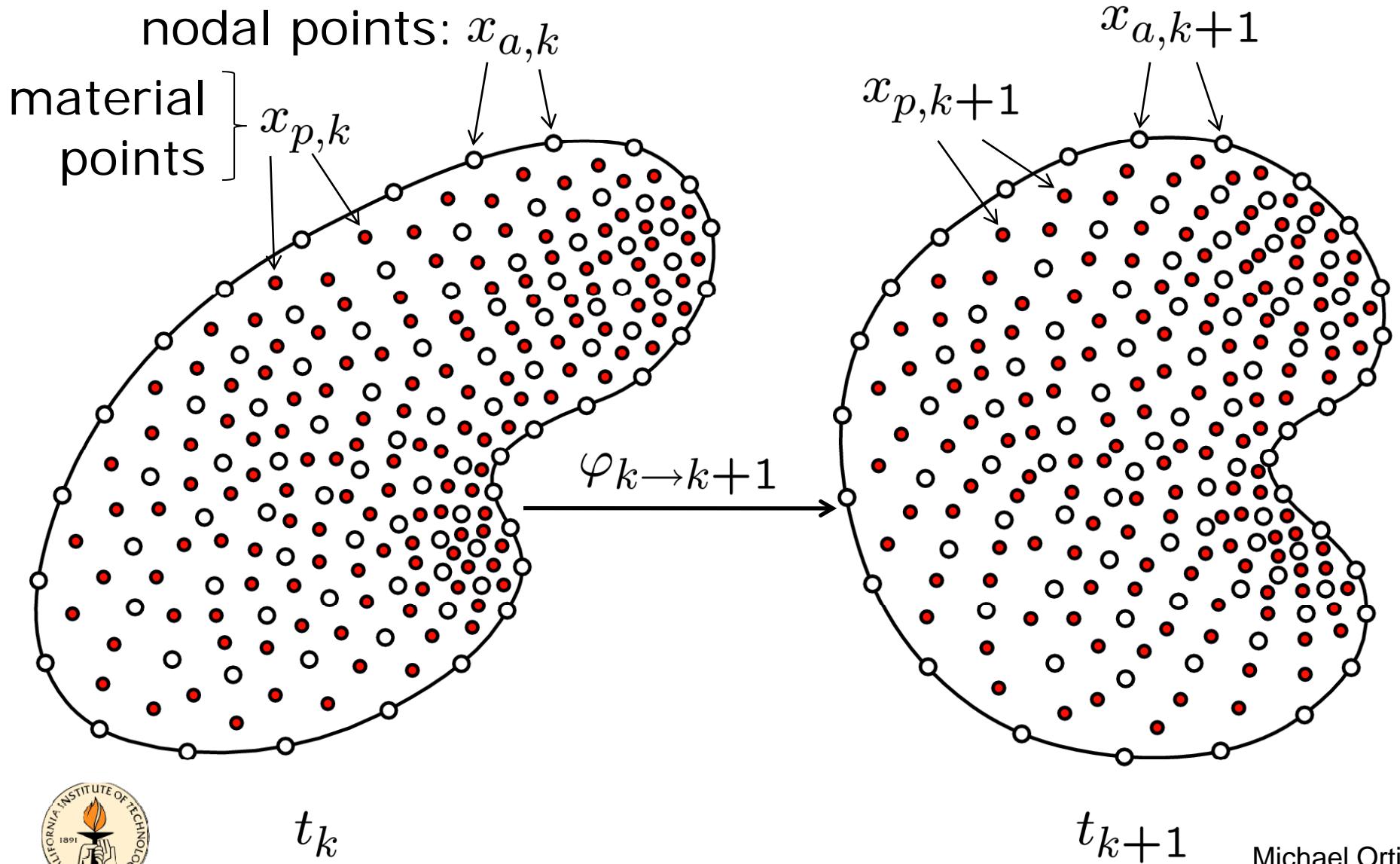
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OTM – Max-ent interpolation

- Max-ent interpolation is smooth, meshfree
- Finite-element interpolation is recovered in the limit of $\beta \rightarrow \infty$
- Rapid decay, short range
- Monotonicity, maximum principle
- Good mass lumping properties
- Kronecker-delta property at the boundary:
 - *Displacement boundary conditions*
 - *Compatibility with finite elements*



OTM – Spatial discretization

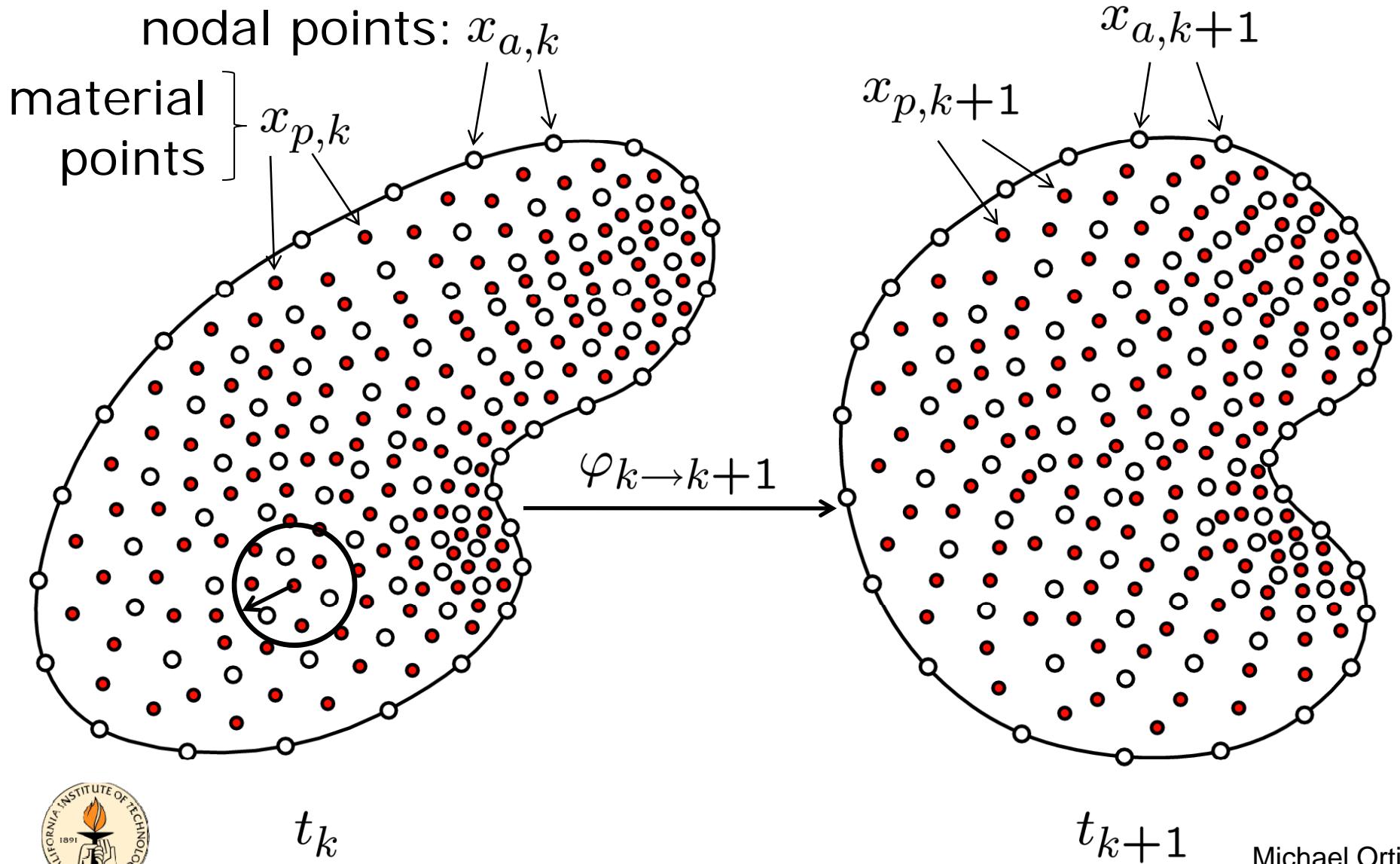


t_k

t_{k+1}

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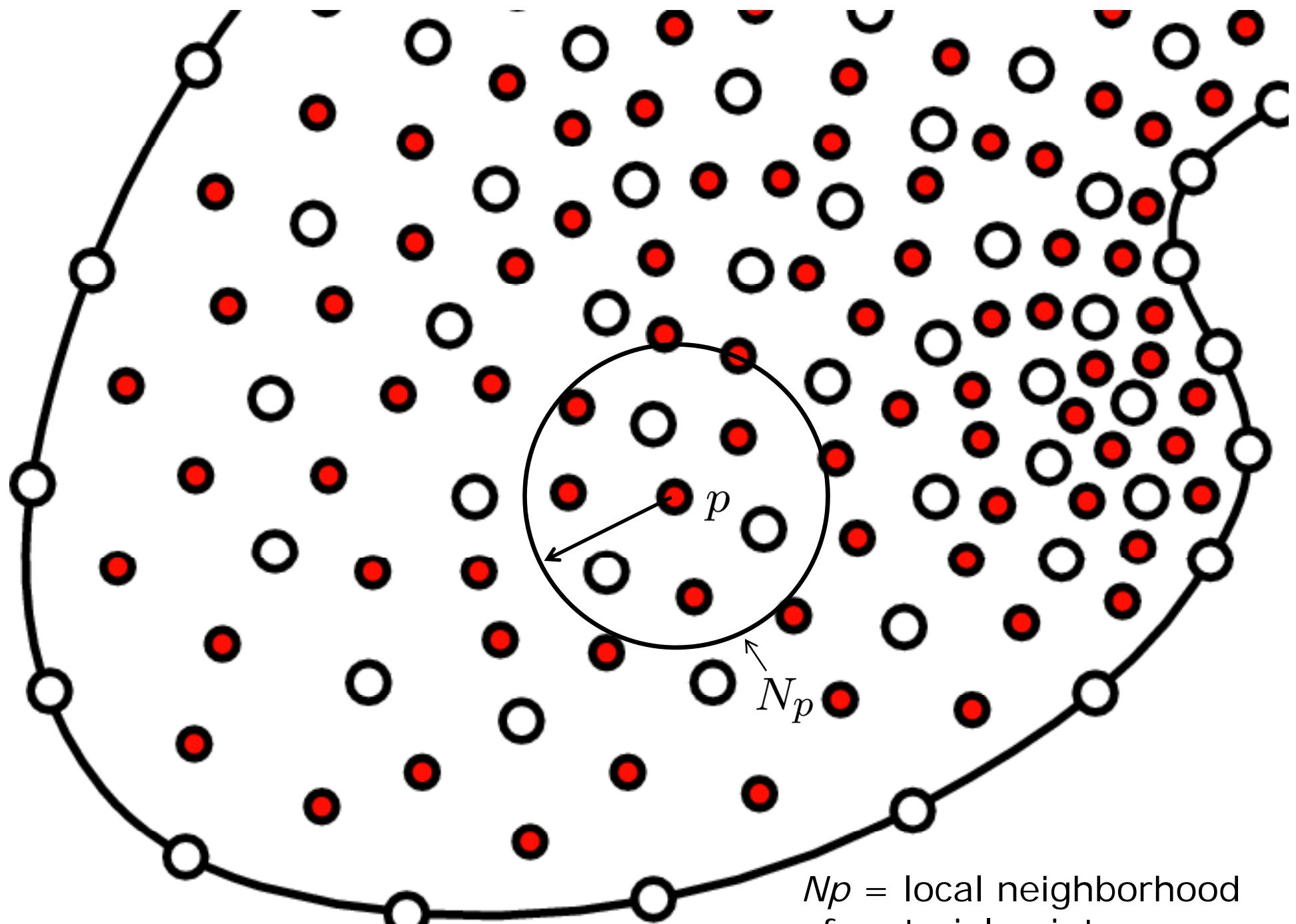
OTM – Spatial discretization



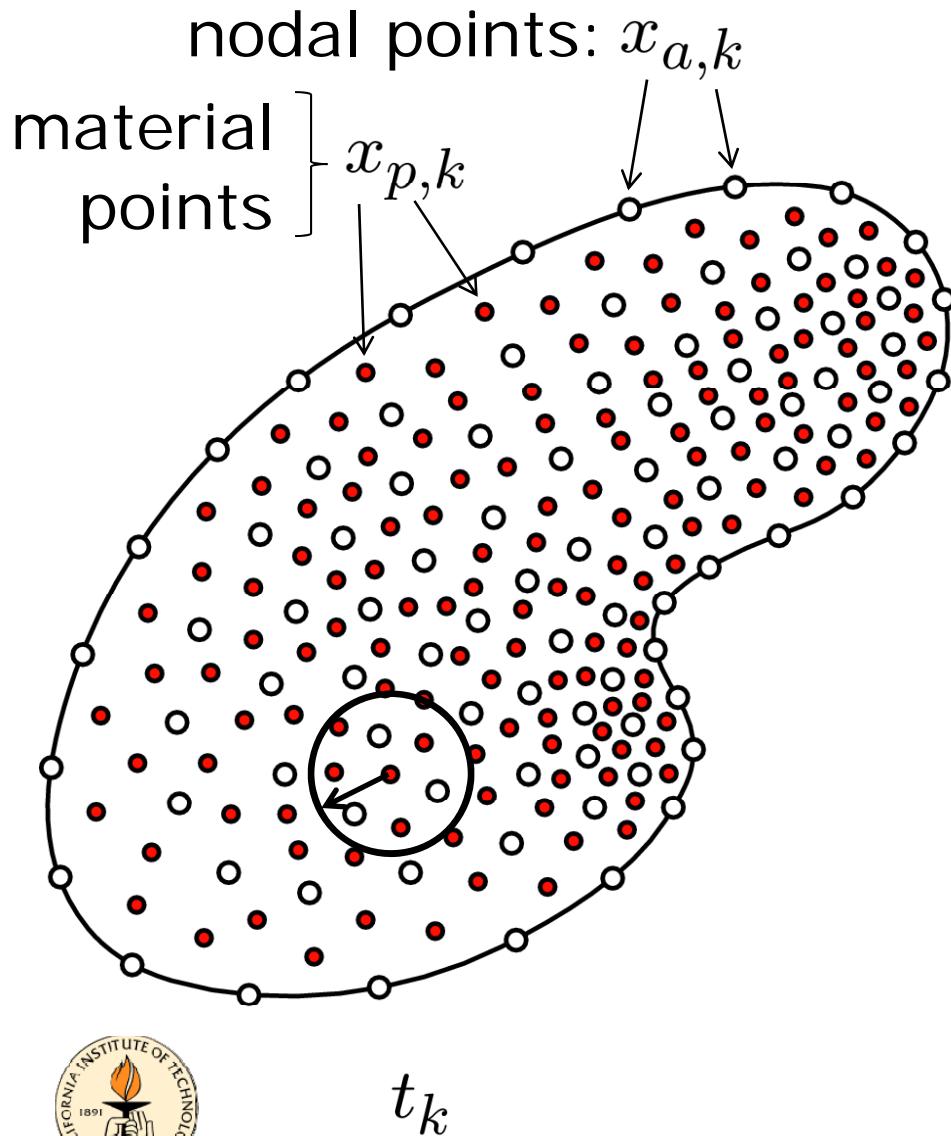
t_k

t_{k+1}

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OTM – Spatial discretization



- Max-ent interpolation at material point p determined by nodes in its local environment N_p
- Local environments determined 'on-the-fly' by range searches
- Local environments evolve continuously during flow (dynamic reconnection)
- Dynamic reconnection requires no remapping of history variables!



OTM – Flow chart

(i) Explicit nodal coordinate update:

$$x_{k+1} = x_k + (t_{k+1} - t_k)(v_k + \frac{t_{k+1} - t_{k-1}}{2} M_k^{-1} f_k)$$

(ii) Material point update:

position: $x_{p,k+1} = \varphi_{k \rightarrow k+1}(x_{p,k})$

deformation: $F_{p,k+1} = \nabla \varphi_{k \rightarrow k+1}(x_{p,k}) F_{p,k}$

volume: $V_{p,k+1} = \det \nabla \varphi_{k \rightarrow k+1}(x_{p,k}) V_{p,k}$

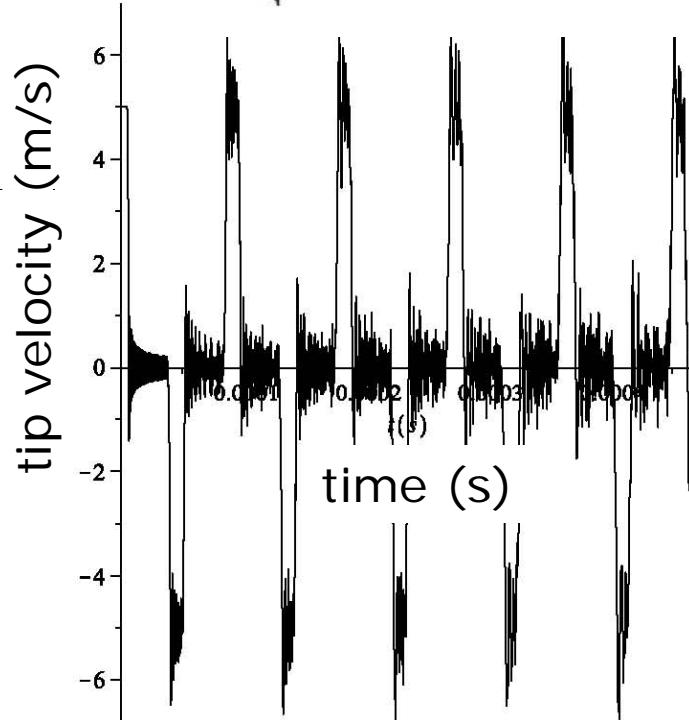
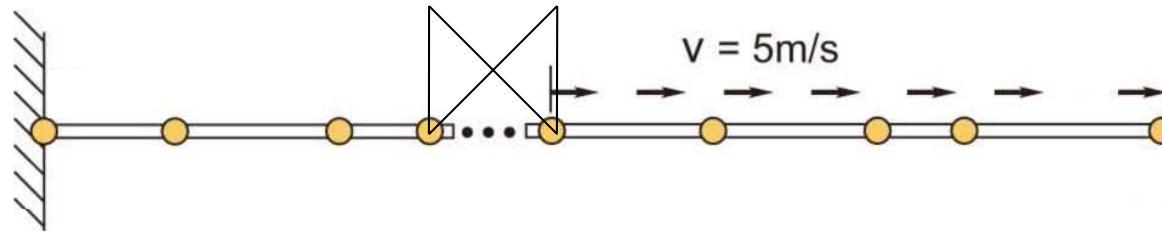
density: $\rho_{p,k+1} = m_p / V_{p,k+1}$

(iii) Constitutive update at material points

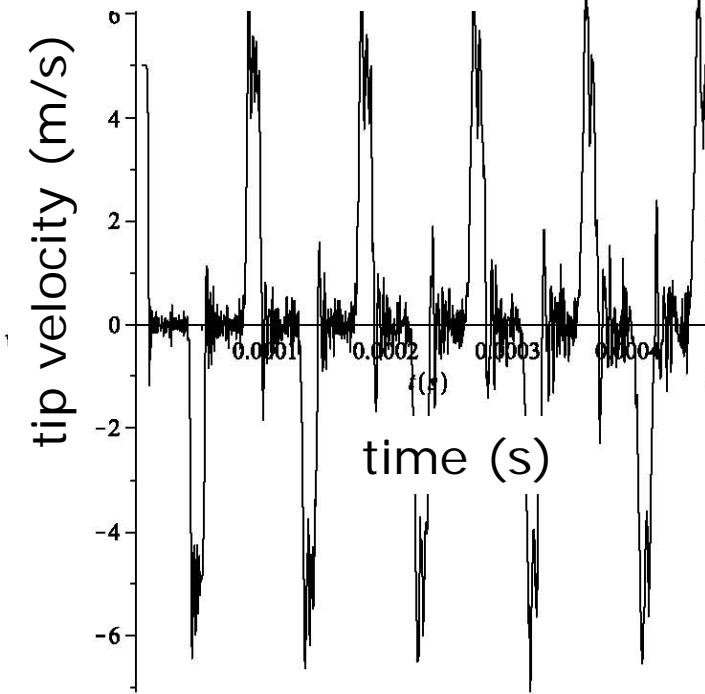
(iv) Reconnect nodal and material points (range searches), recompute max-ext shape functions



OTM – Tensile stability



Finite elements

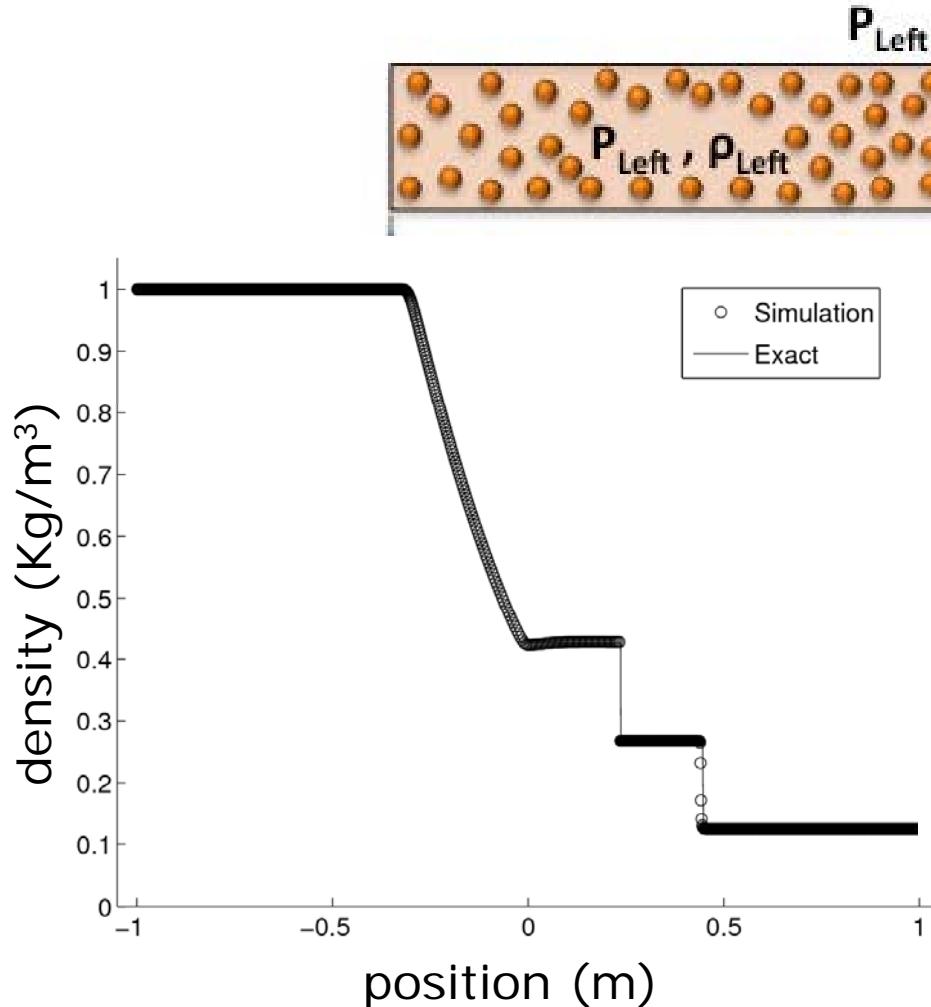


OTM

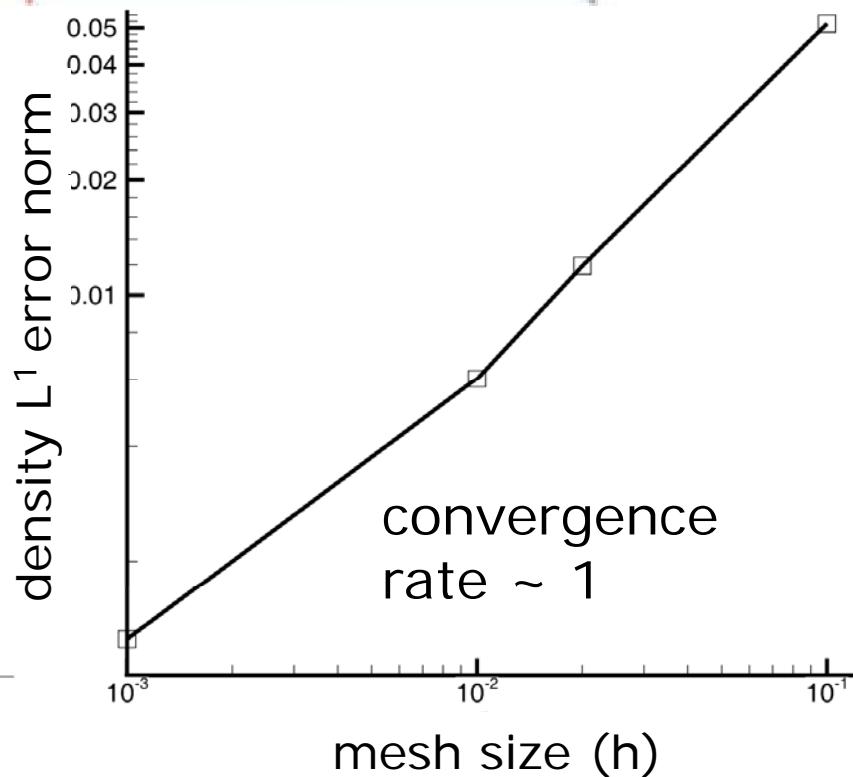
OTM is free from tensile instabilities!



OTM – Riemann problem



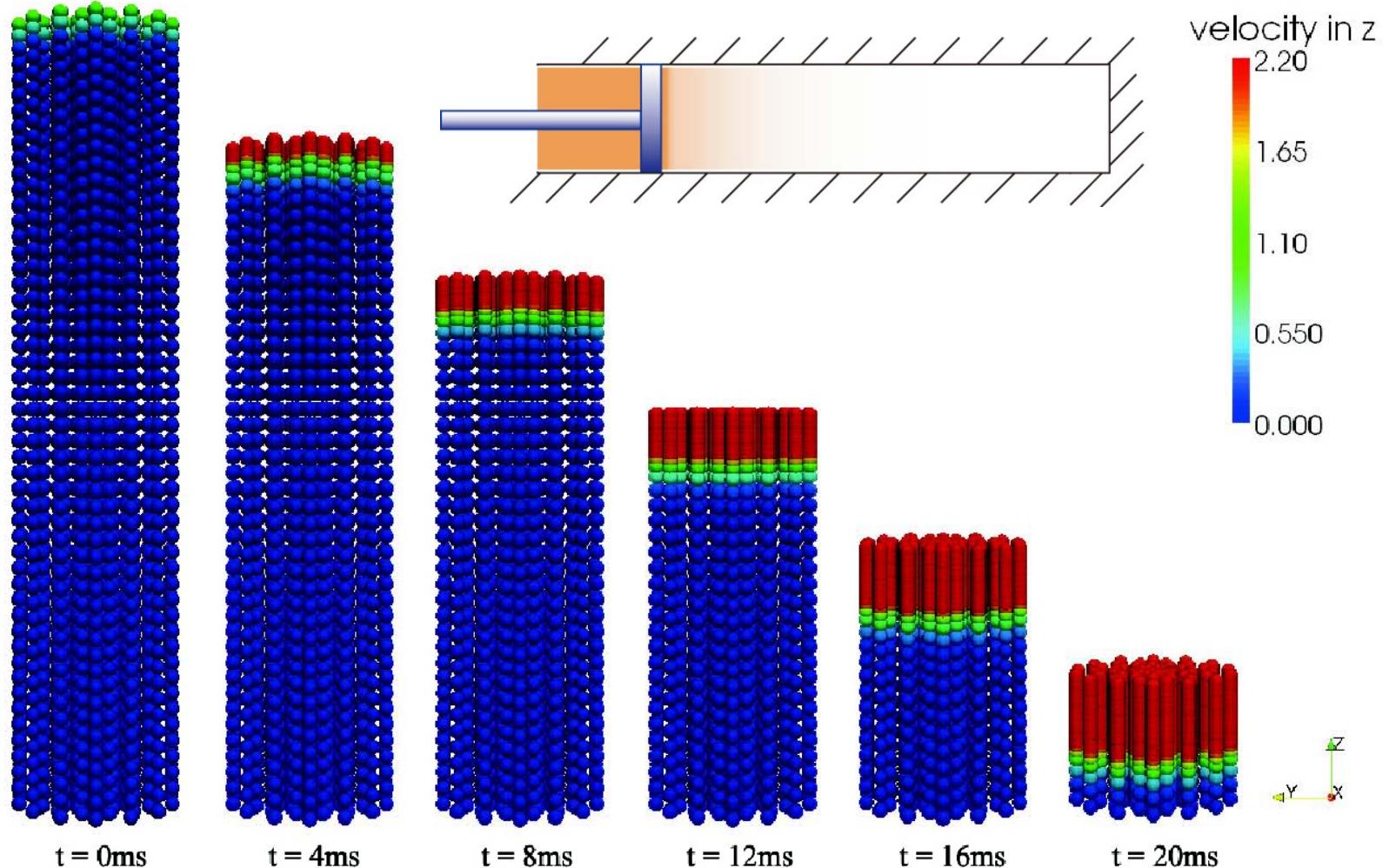
computed vs. exact
wave structure



density convergence
(L^1 norm)

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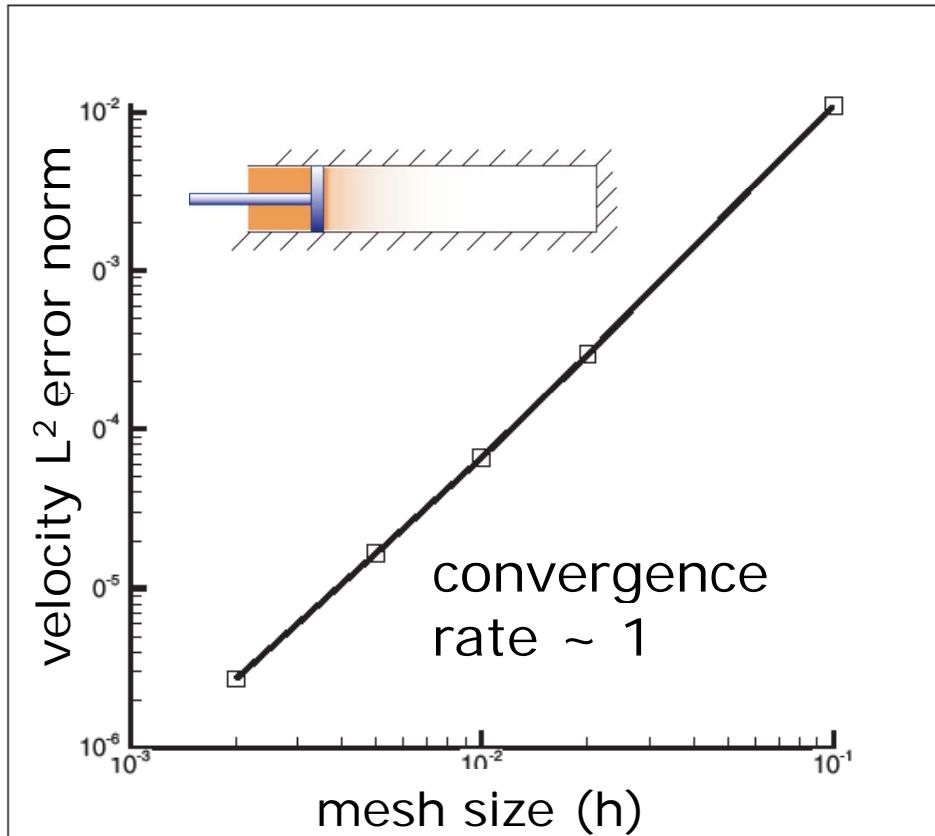
OTM – Shock tube problem



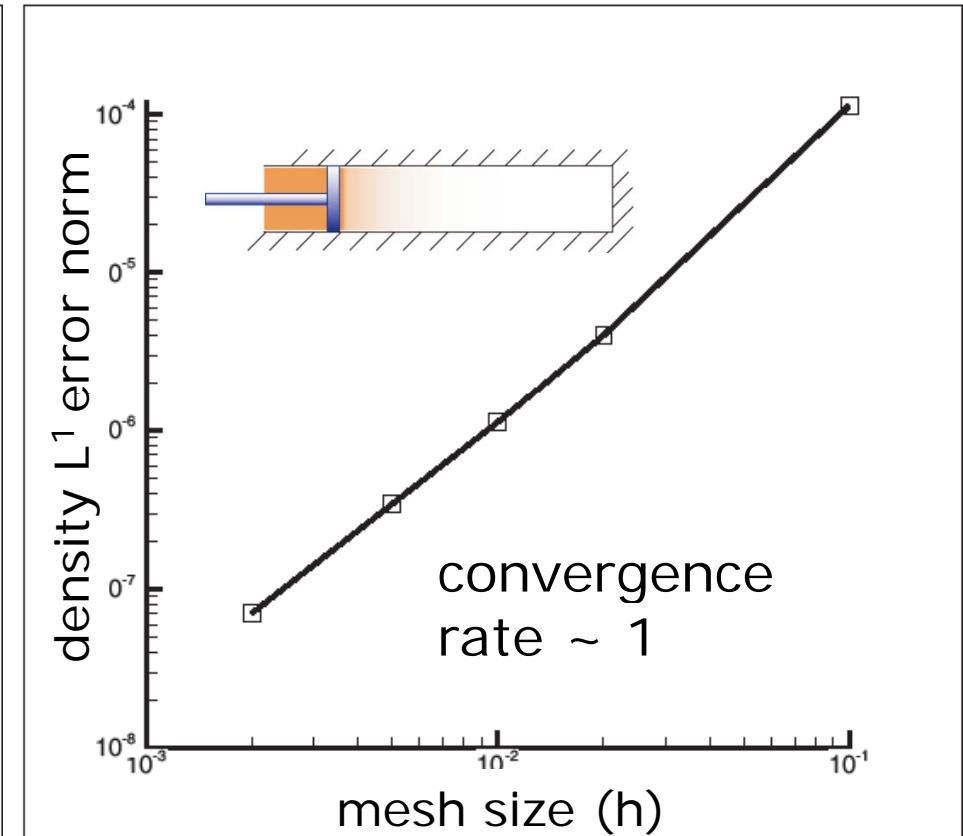
Shock tube problem – velocity snapshots

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OTM – Shock tube problem



velocity convergence
(L^2 norm)



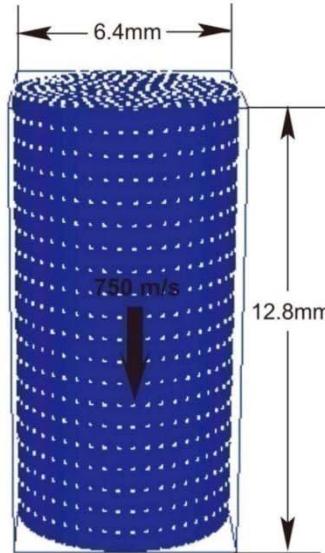
density convergence
(L^1 norm)



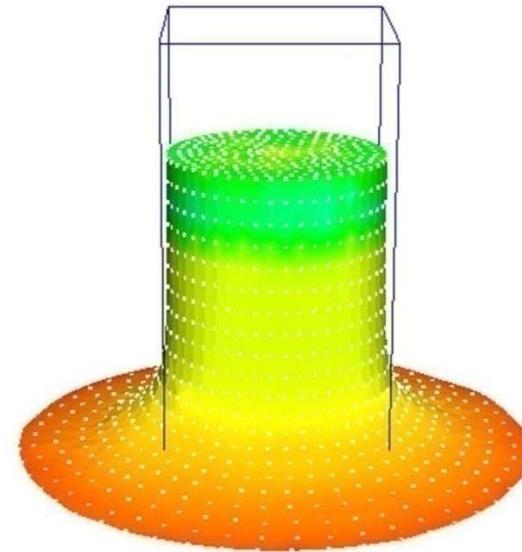
Shock tube problem – convergence plots

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OTM – Taylor anvil test

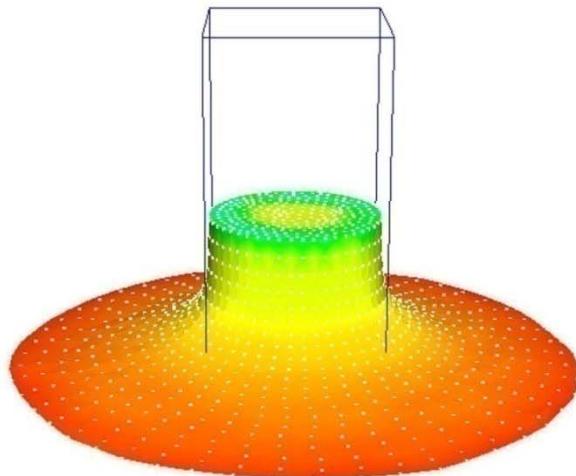


$t = 0$

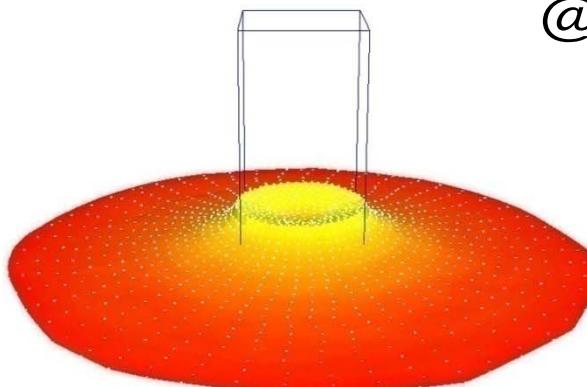


$t = 7.5 \mu s$

copper rod
@ 750 m/s



$t = 15 \mu s$

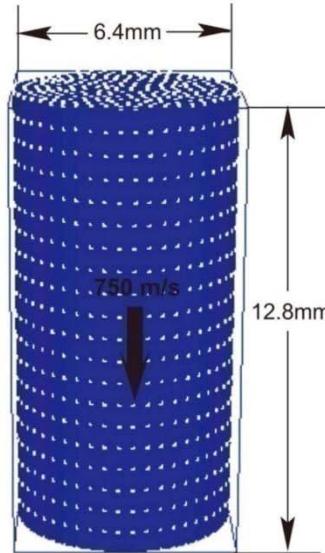


$t = 28 \mu s$

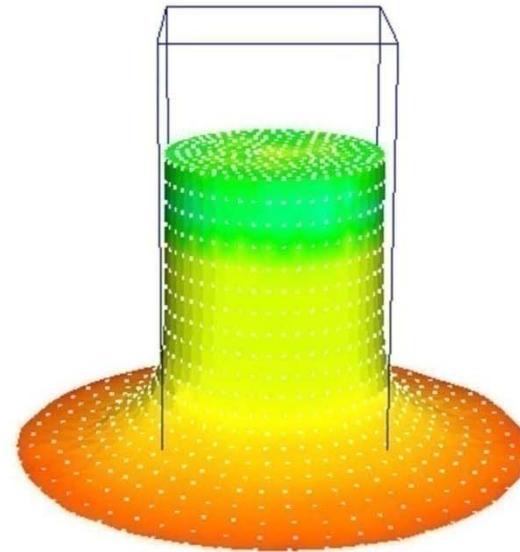


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OTM – Taylor anvil test

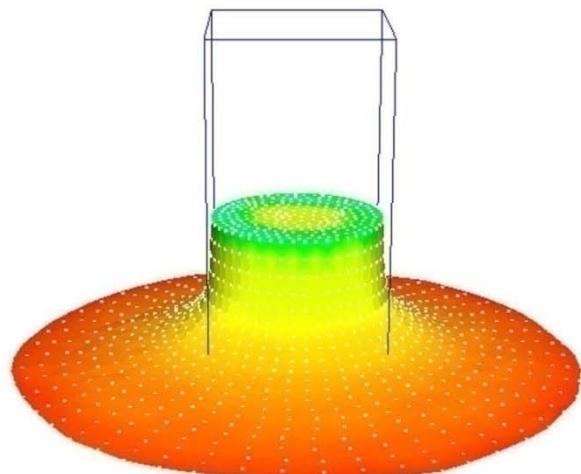


$t = 0$

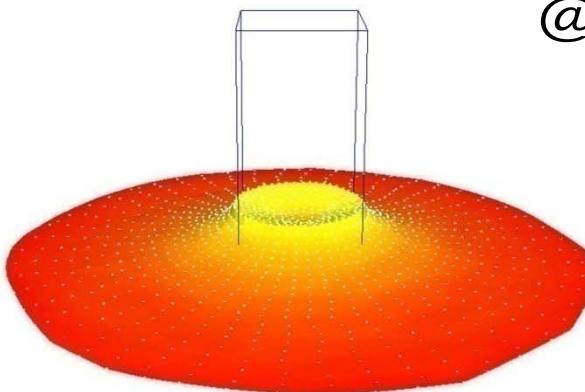


$t = 7.5 \mu s$

copper rod
@ 750 m/s



$t = 15 \mu s$

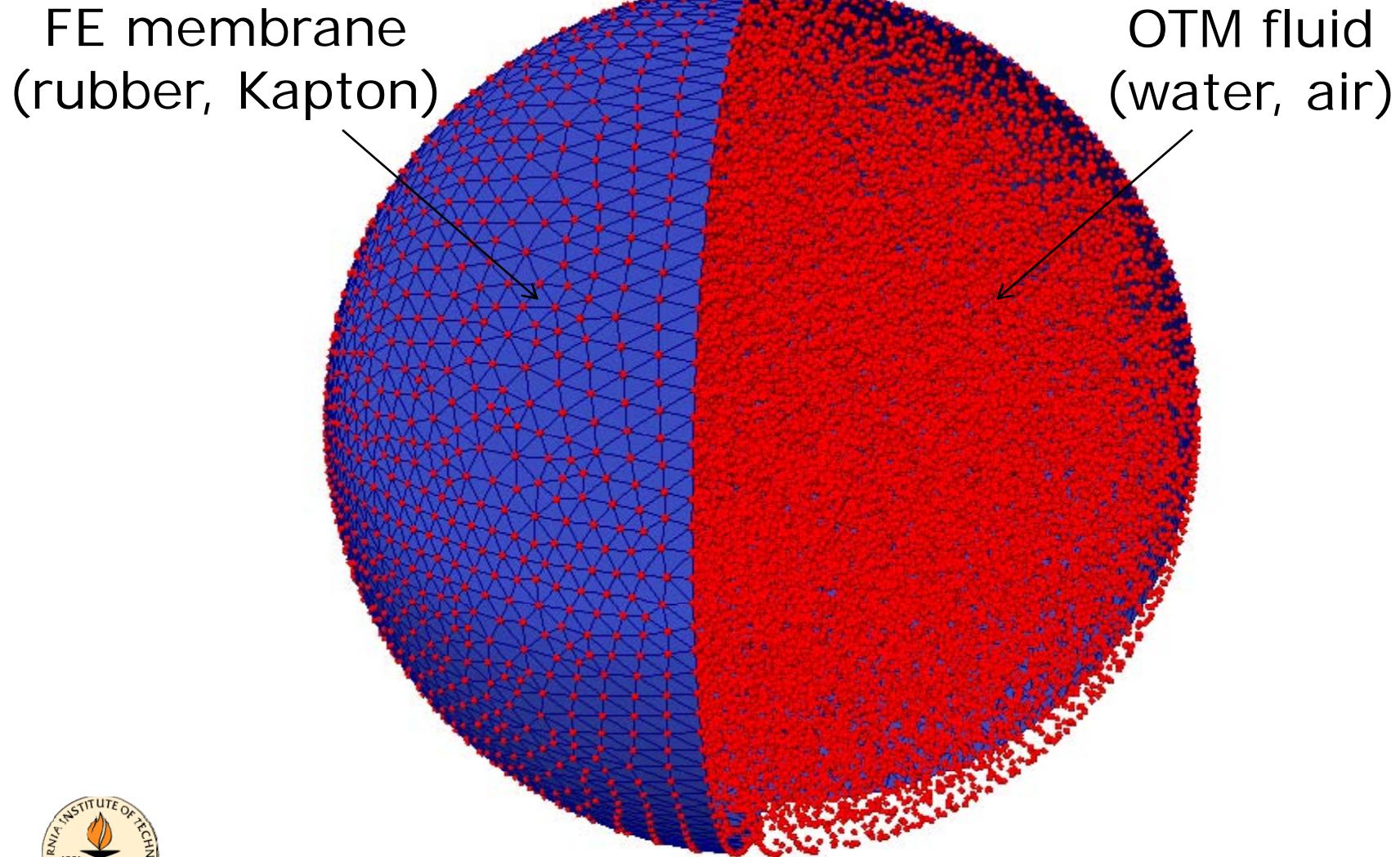


$t = 28 \mu s$

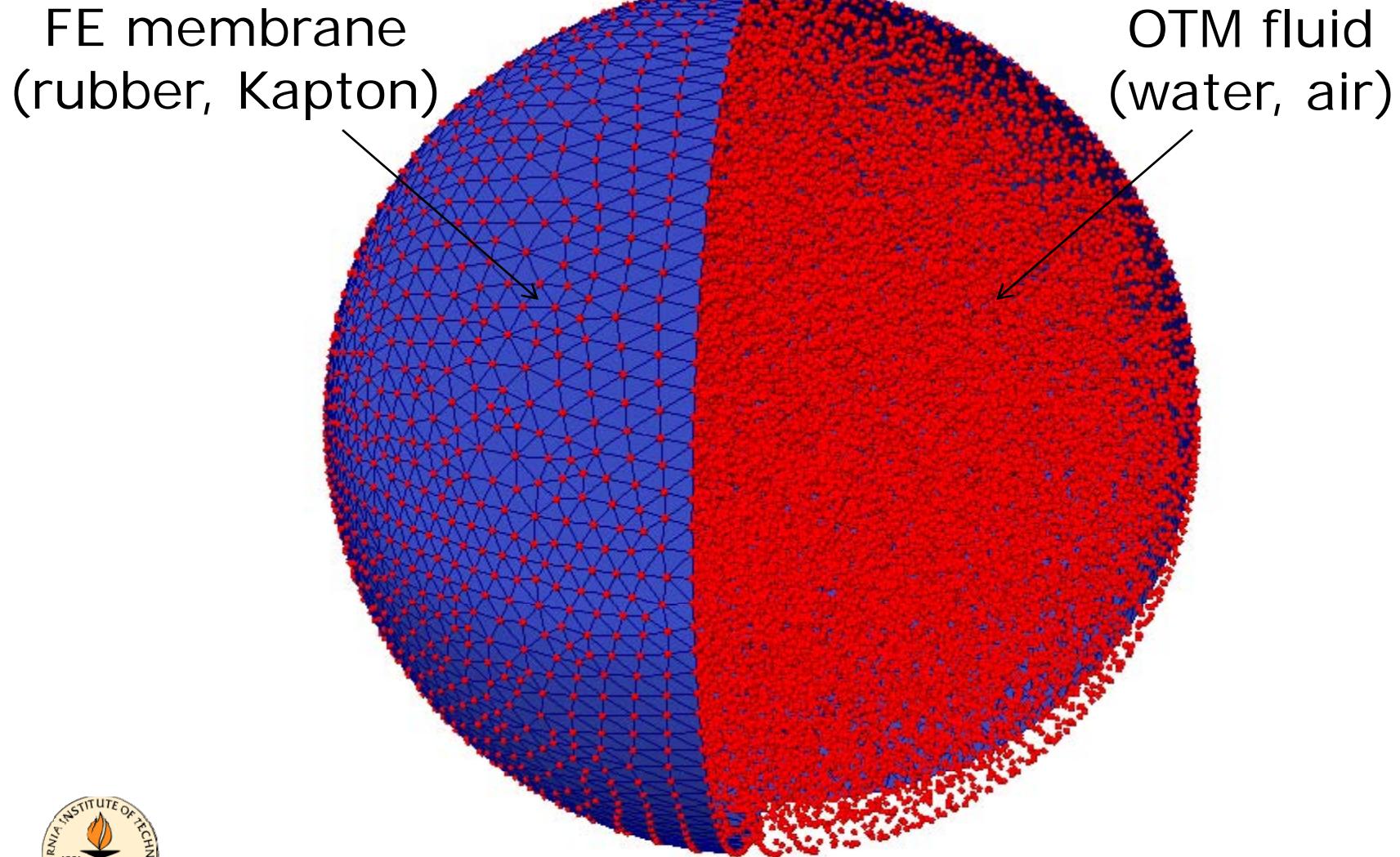


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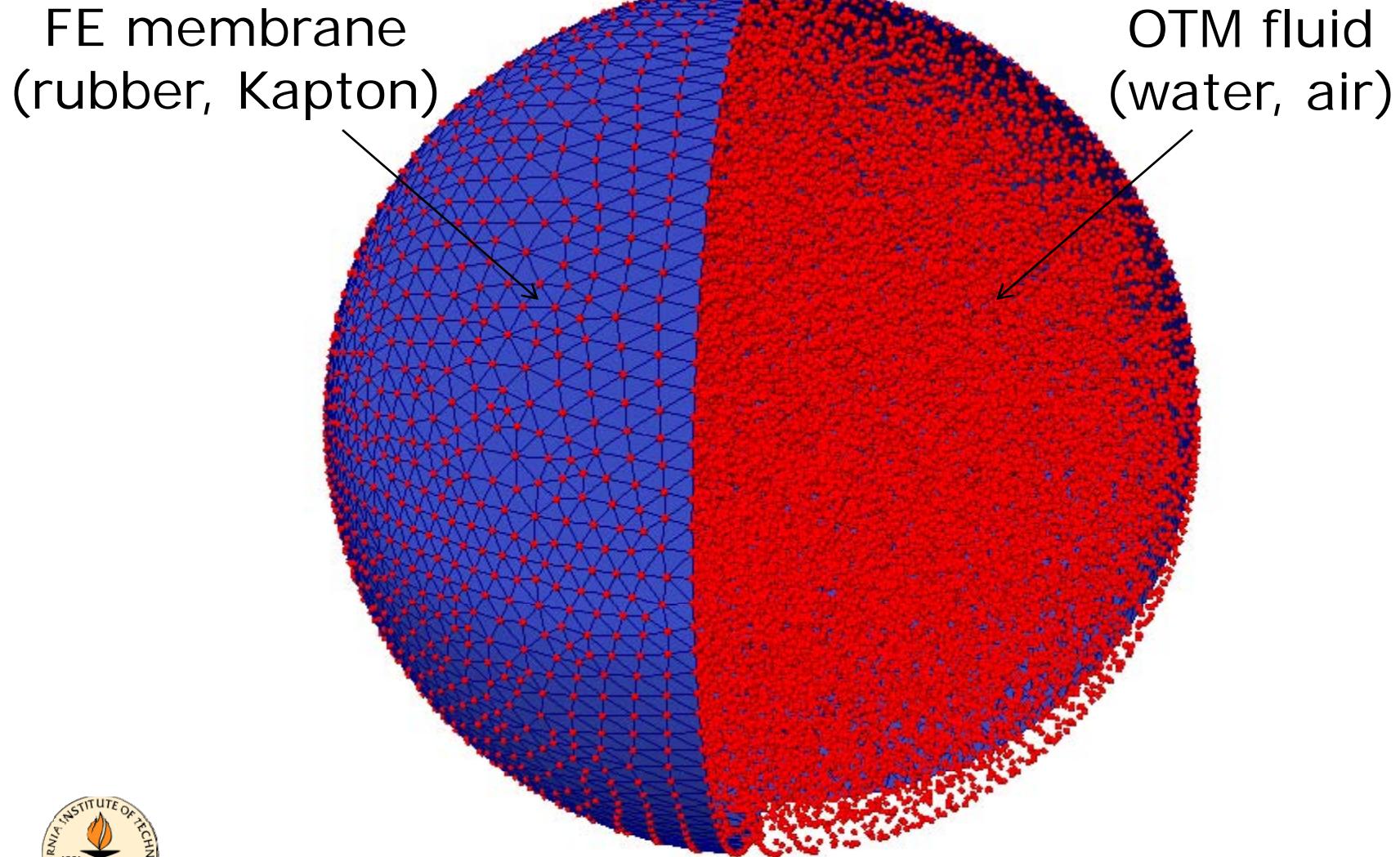
OTM – Bouncing balloons



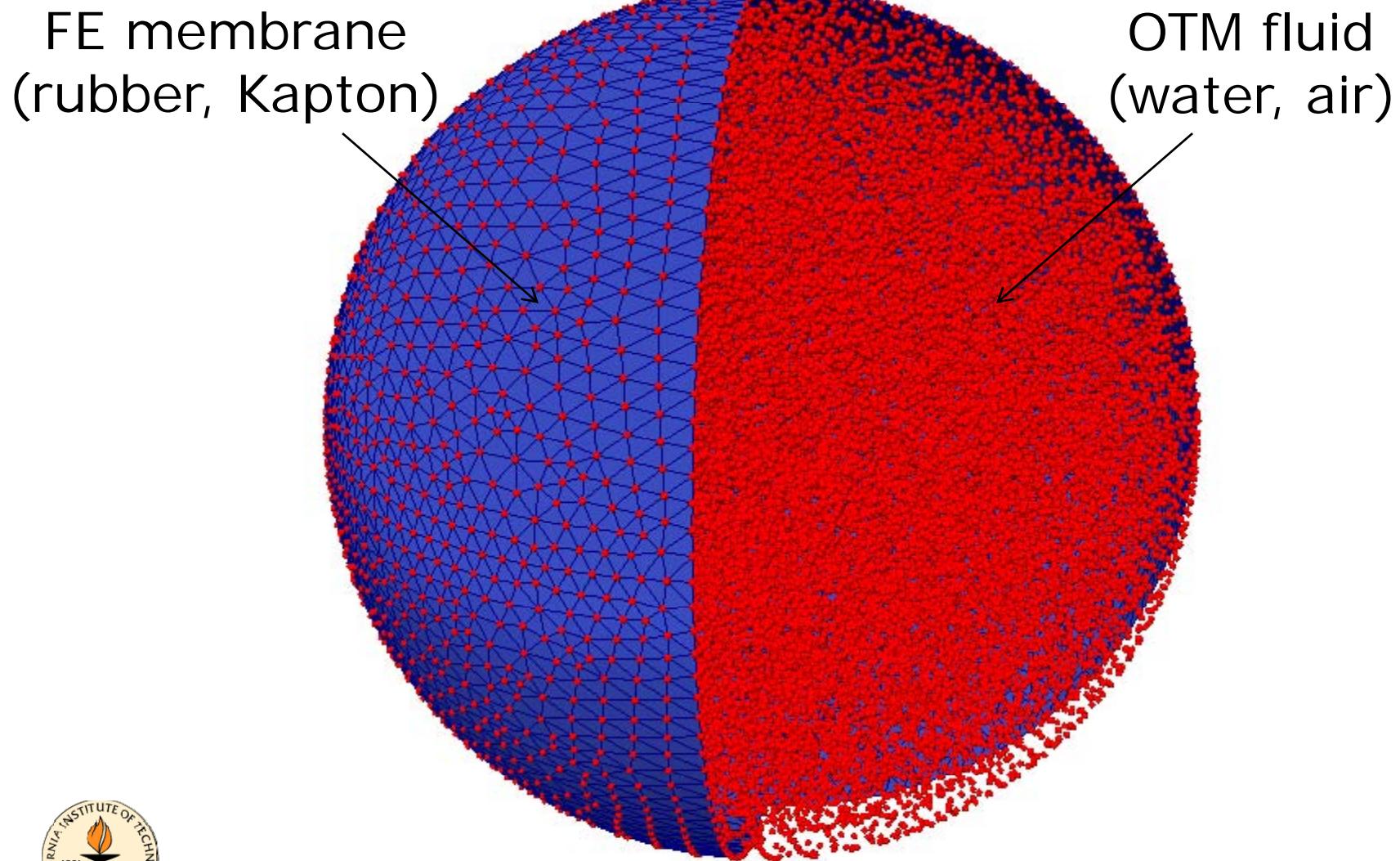
OTM – Bouncing balloons



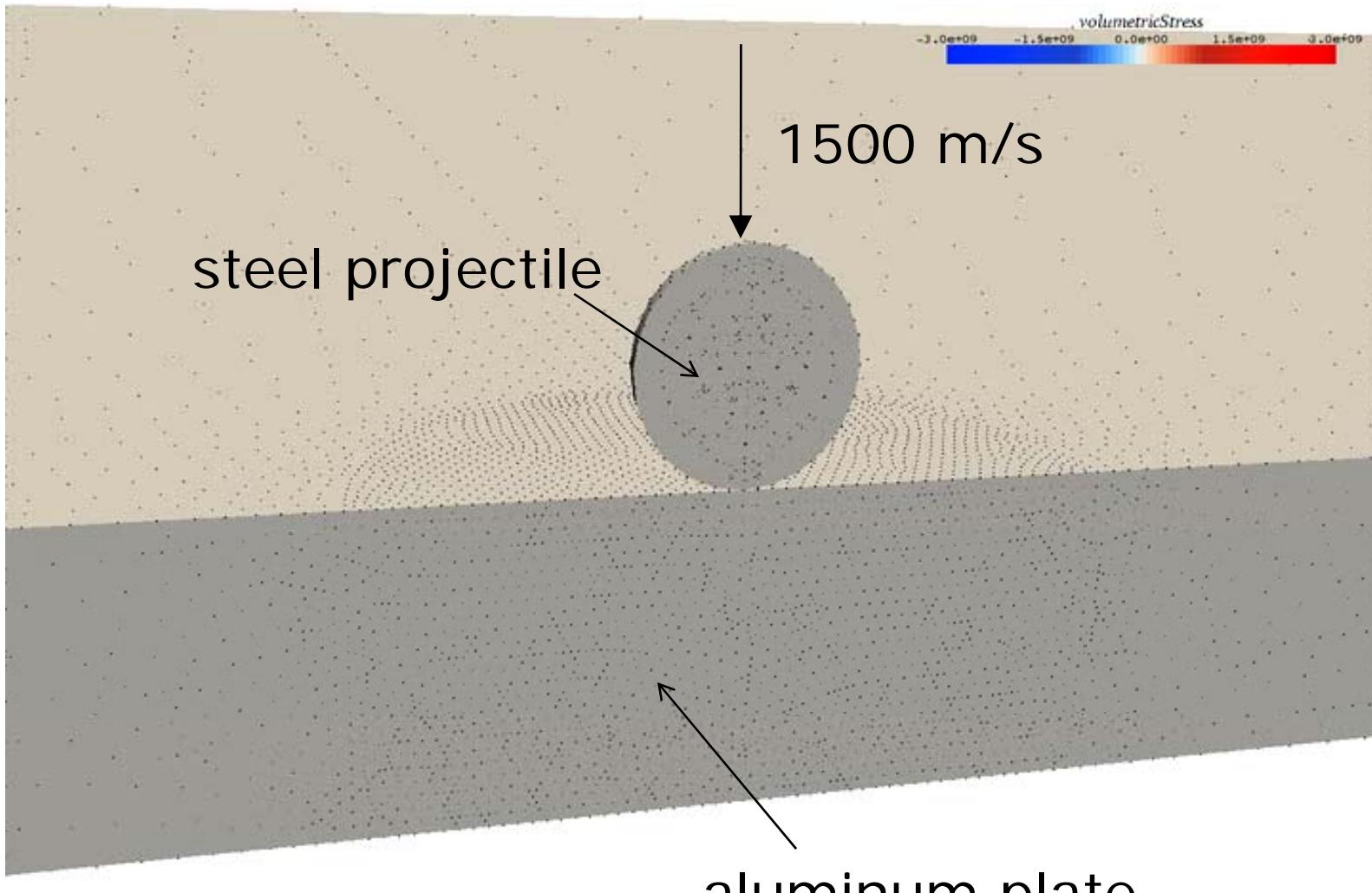
OTM – Bouncing balloons



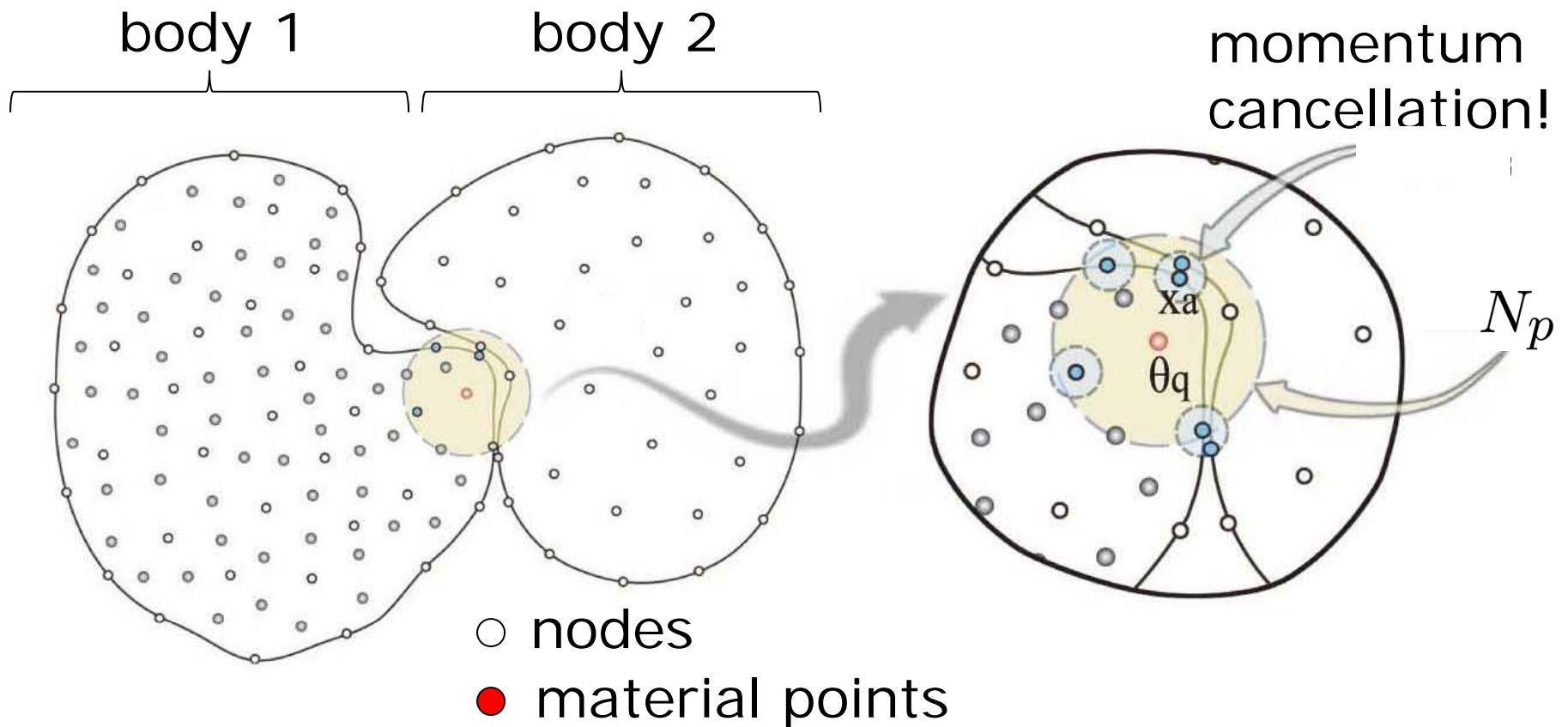
OTM – Bouncing balloons



OTM – Terminal ballistics



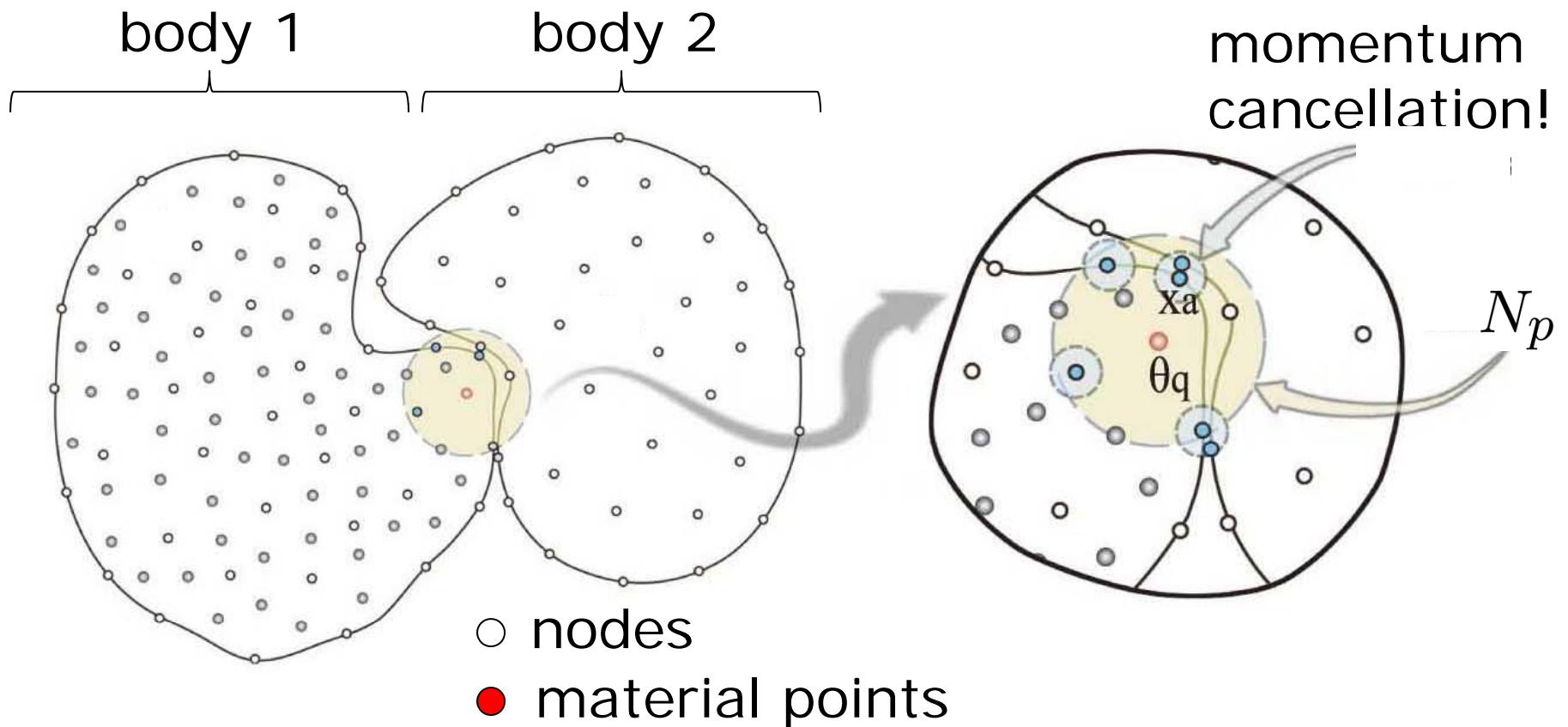
OTM – Seizing contact



Seizing contact (infinite friction)
is obtained for free in OTM!
(as in other material point methods)



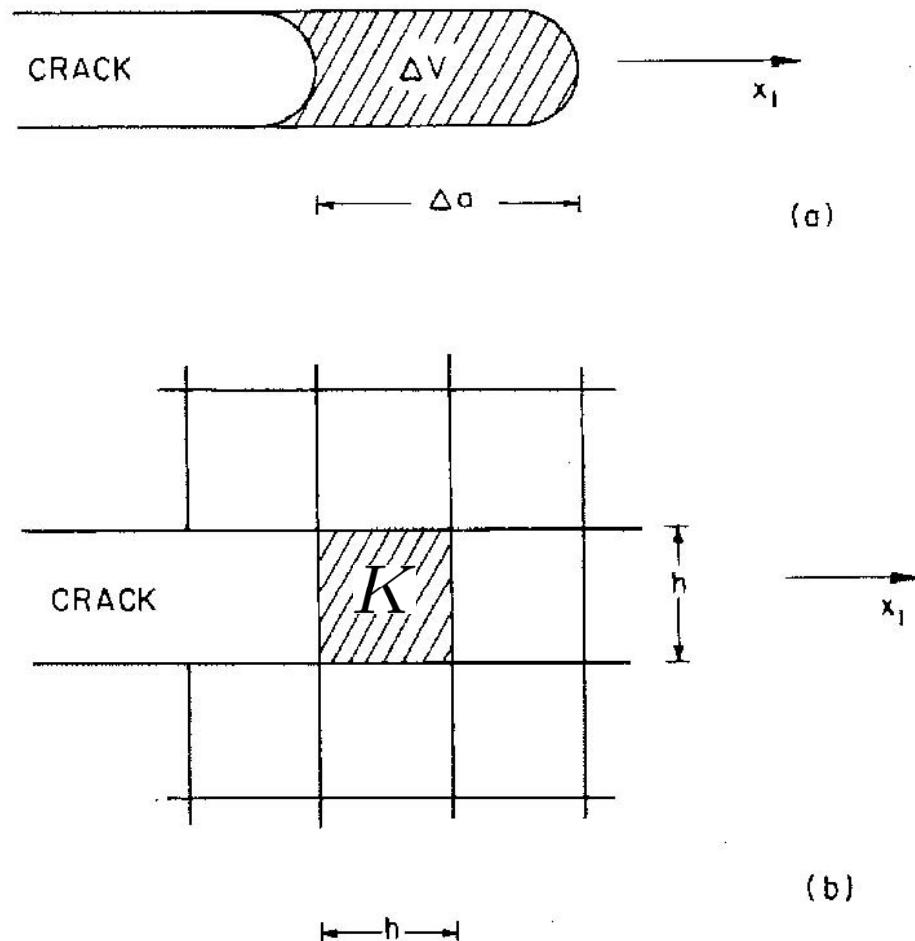
OTM – Seizing contact



Seizing contact (infinite friction)
is obtained for free in OTM!
(as in other material point methods)



Variational Fracture & fragmentation



- Energy-release rate:

$$G \sim \frac{1}{h} \int_K W(\nabla u) dx$$

- Erosion criterion:

$$G \geq G_c$$

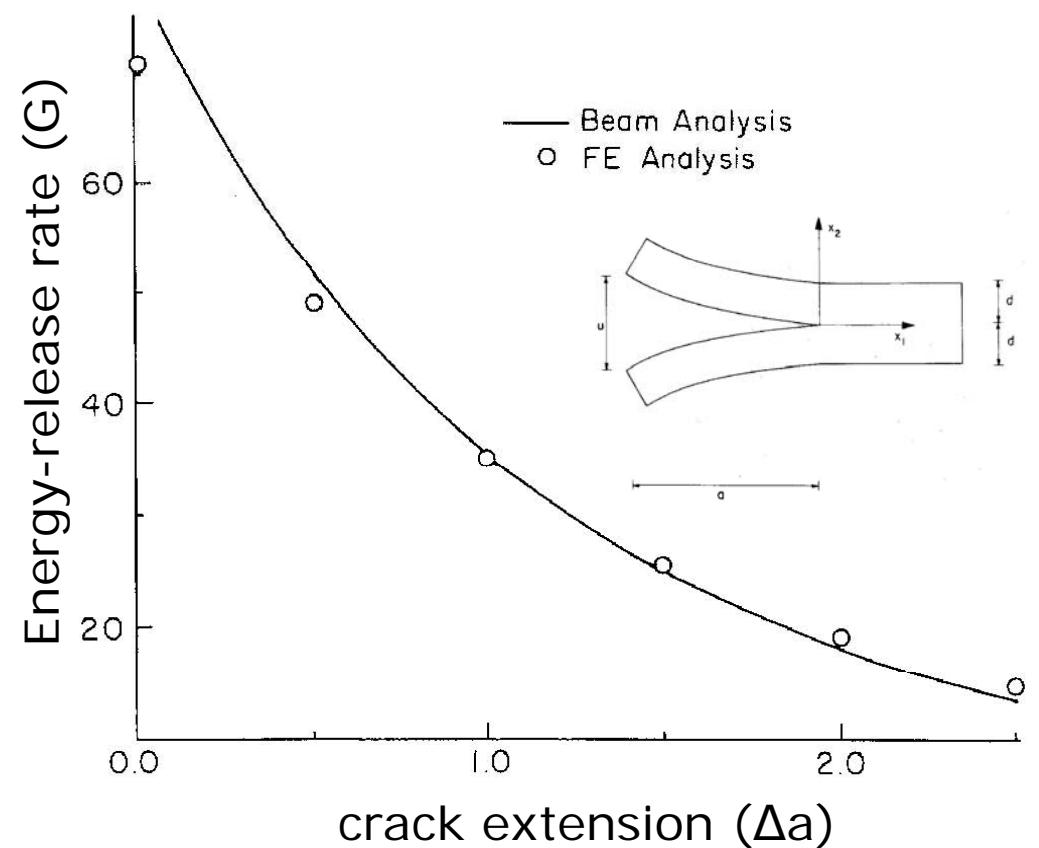
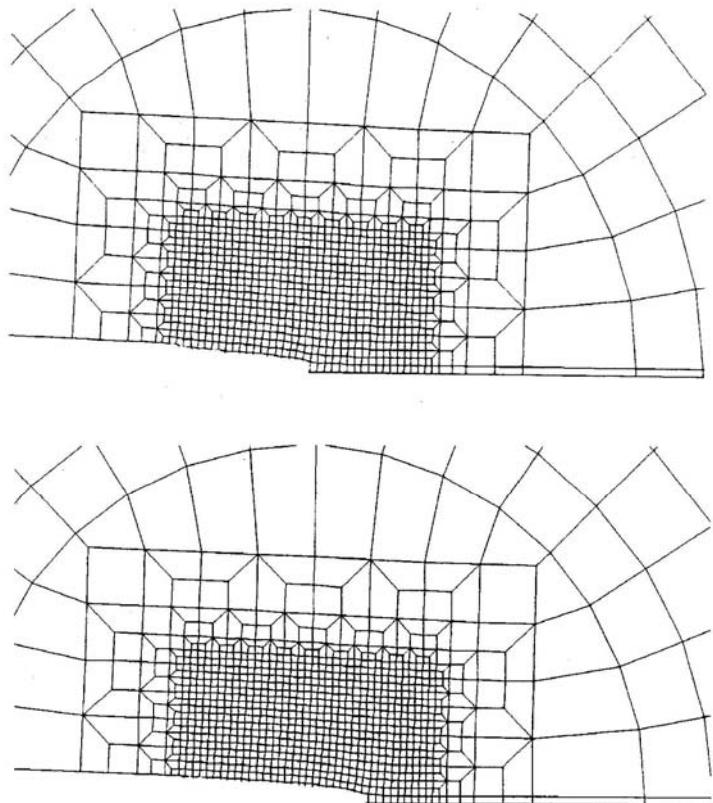
- Implementation:

- i) Order elements by G
- ii) Pop top element

M. Ortiz and A.E. Giannakopoulos,
Int. J. Fracture, **44** (1990) 233-258.



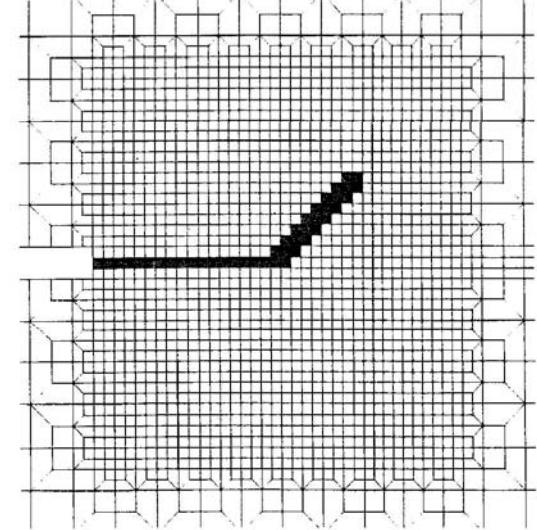
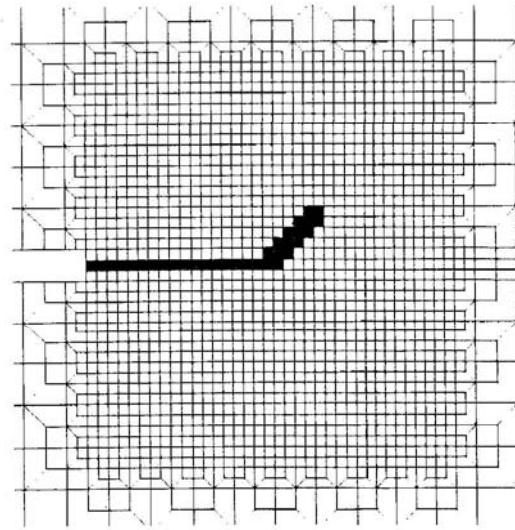
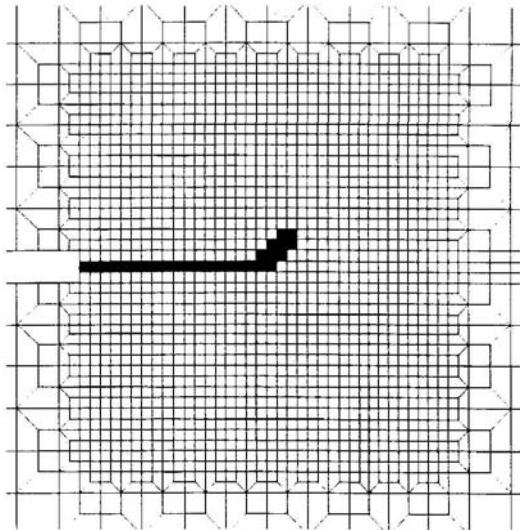
Variational Fracture & fragmentation



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OTM – Fracture & fragmentation



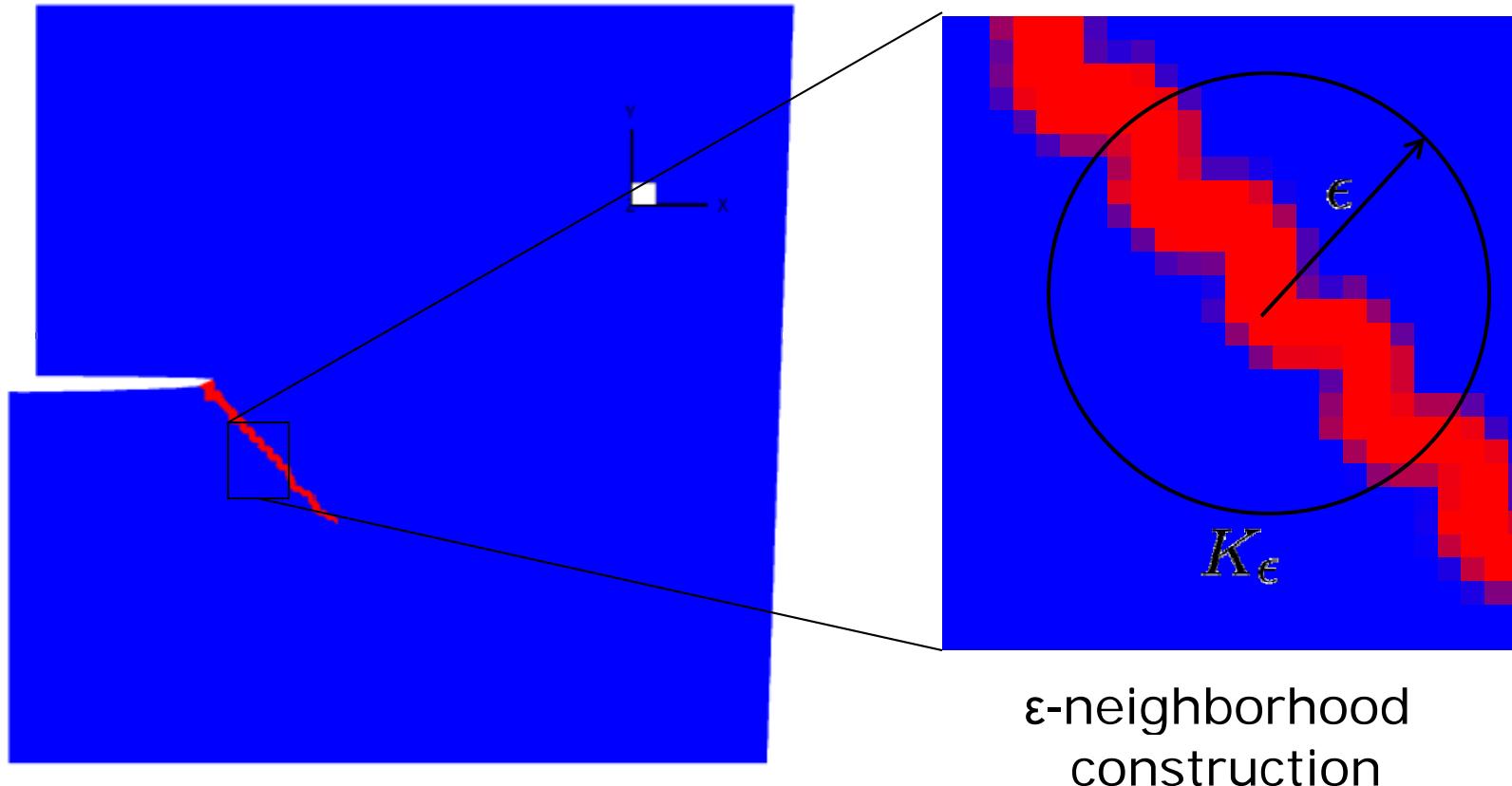
Crack growth in mixed mode

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Int. J. Fracture, **44** (1990) 233-258.

- Fracture energy over-estimated as $h \rightarrow 0!$
- Non-convergence for general paths, meshes!



OTM – Fracture & fragmentation

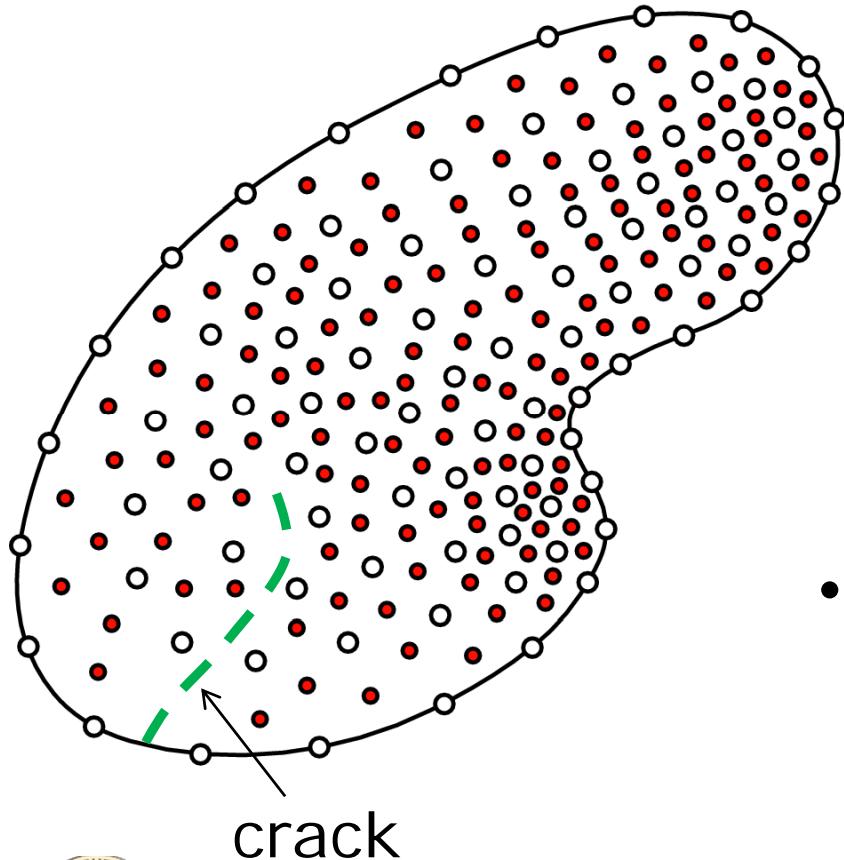


- Energy-release rate due to element erosion:

$$G_\epsilon \sim \frac{h^2}{|K_\epsilon|} \int_{K_\epsilon} W(\nabla u) dx$$



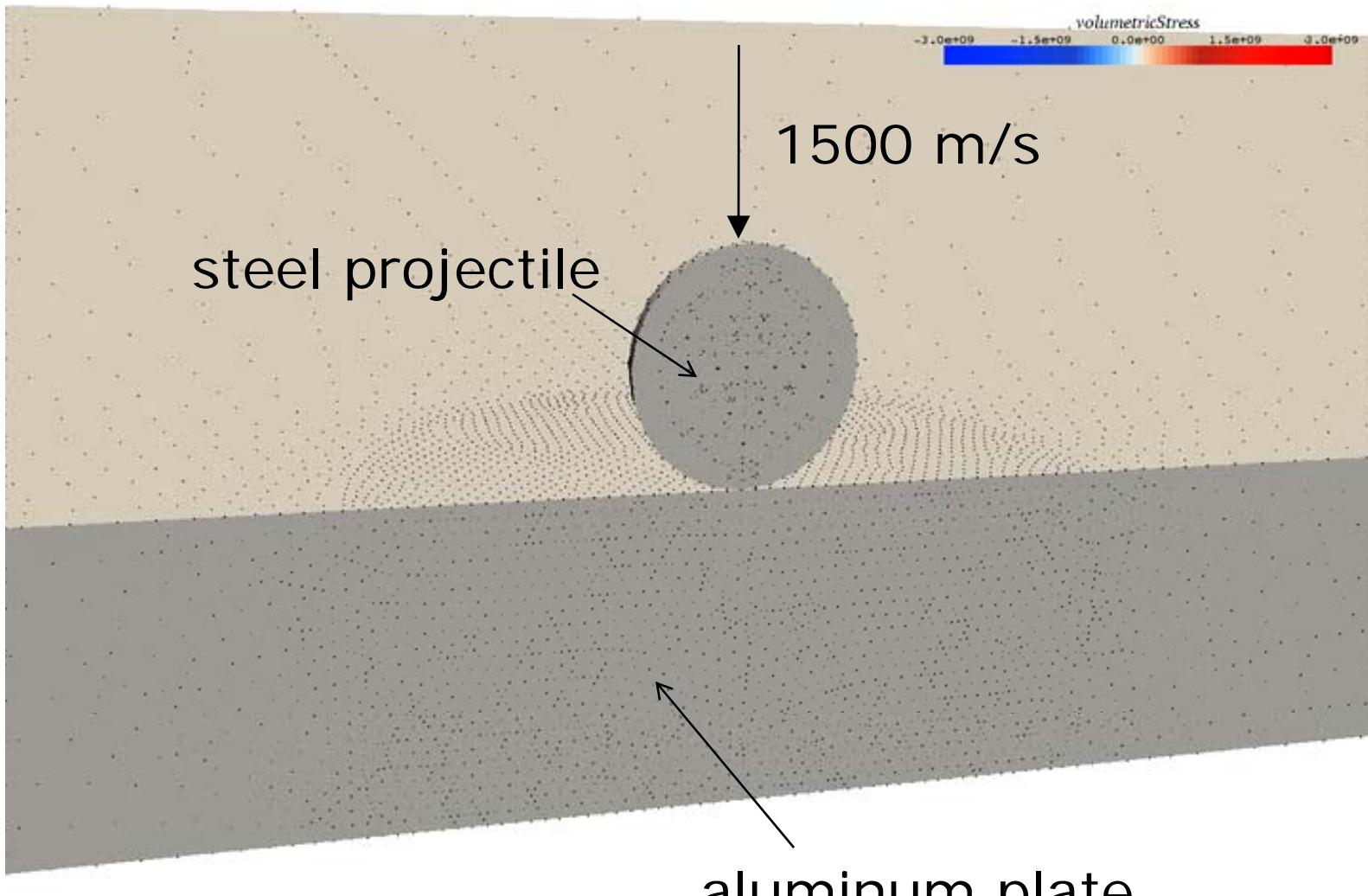
Variational Fracture & fragmentation



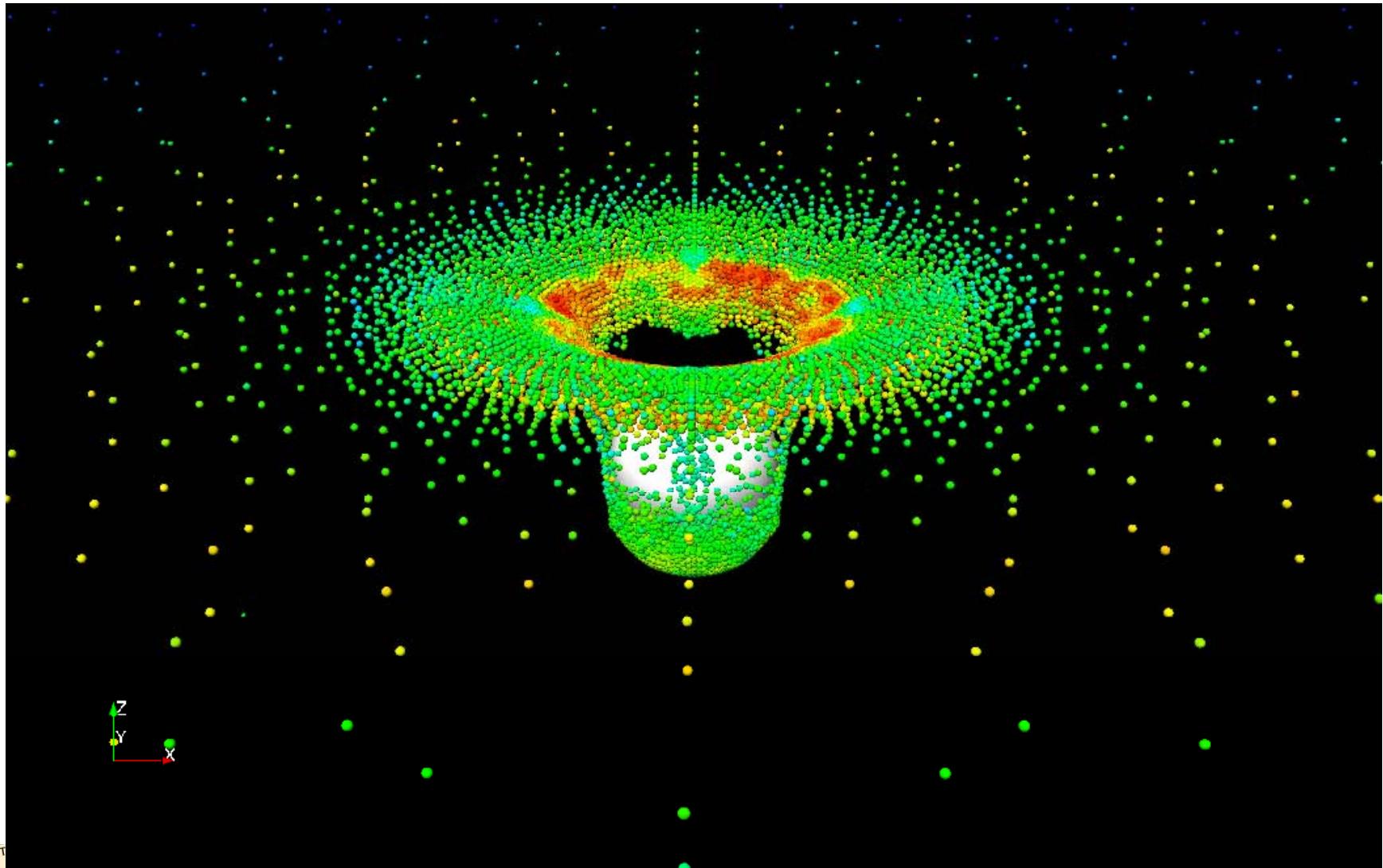
- Proof of convergence of variational element erosion to Griffith fracture:
 - Schmidt, B., Fraternali, F. and Ortiz, M. "Eigenfracture: An eigendeformation approach to variational fracture," *SIAM J. Multiscale Model. Simul.*, 7(3) (2009) 1237-1366.
- OTM implementation: Variational erosion of material points (by ϵ -neighborhood construction)



OTM – Back to terminal ballistics

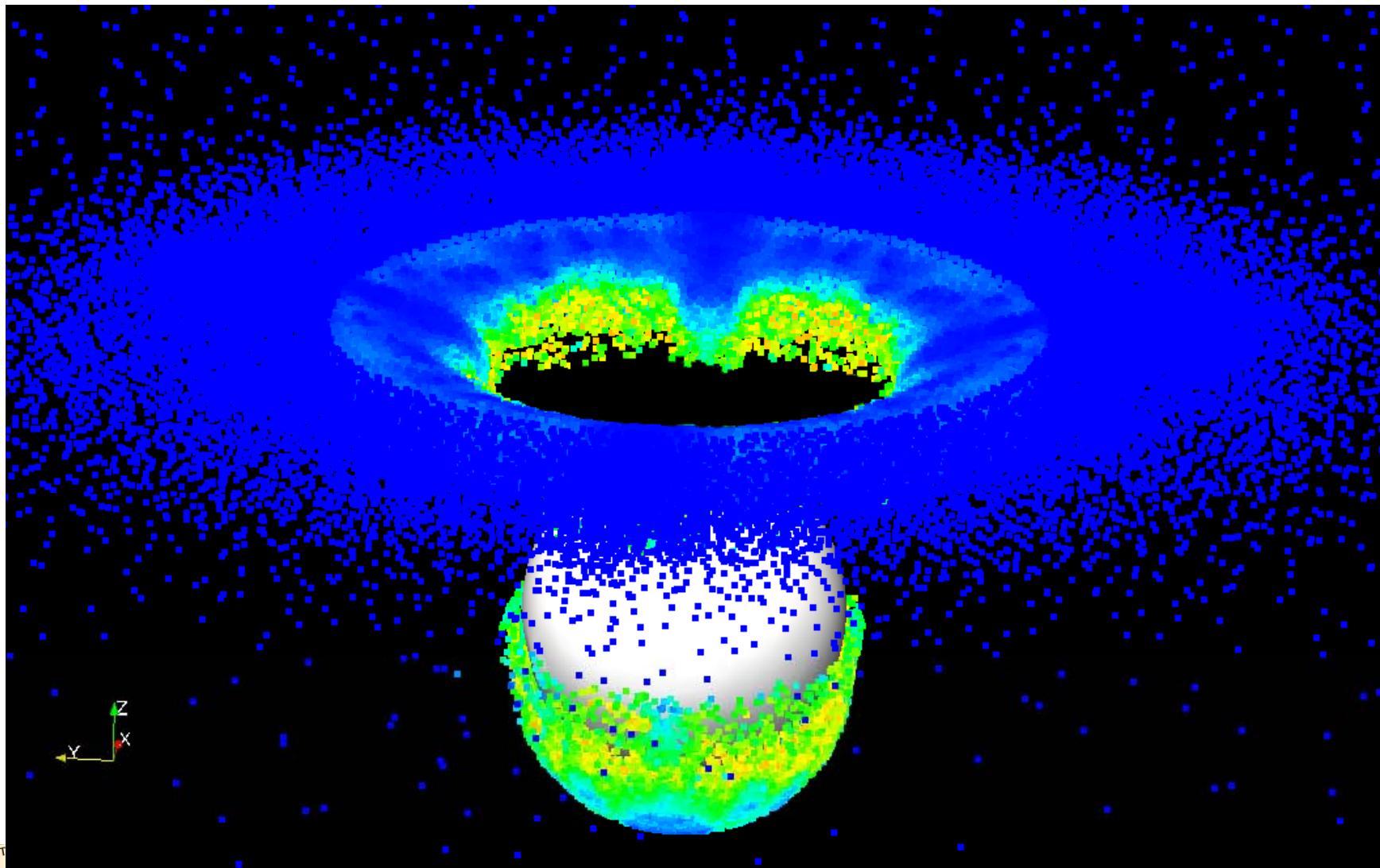


QMU – Simulation codes – OTM



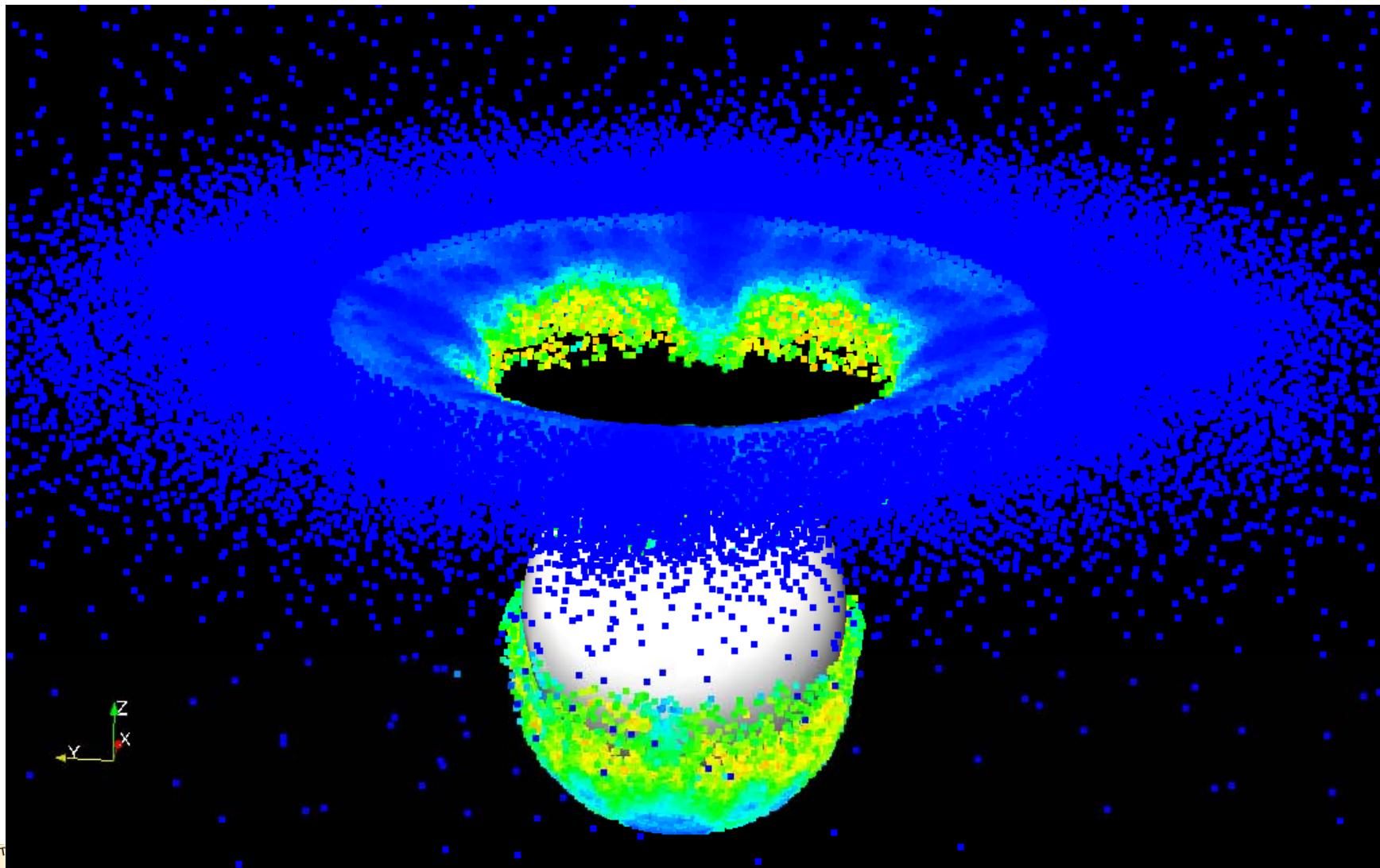
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QMU – Simulation codes – OTM



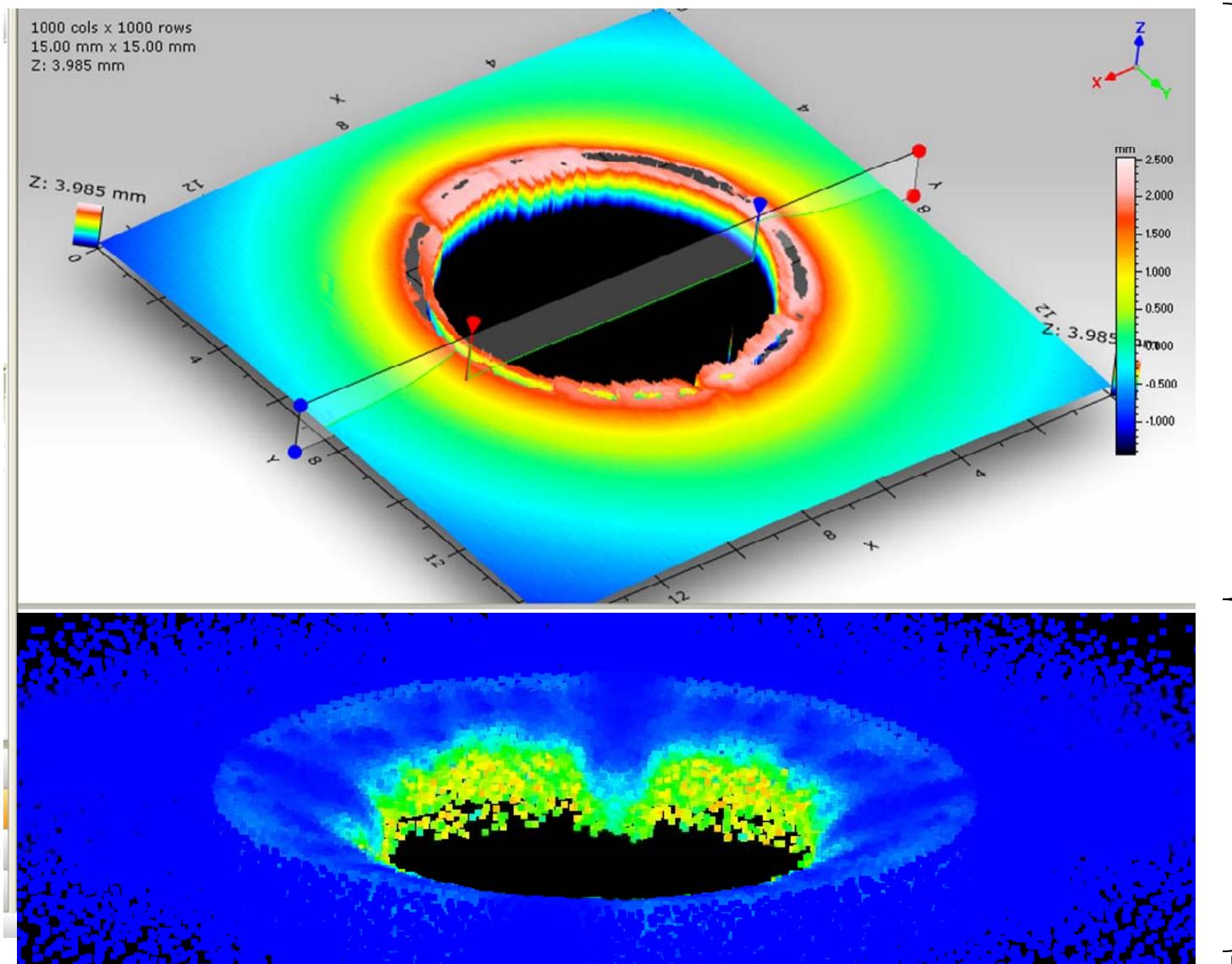
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QMU – Simulation codes – OTM



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QMU – Simulation codes – OTM



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OTM – Summary and outlook

- Optimum-Transportation-Meshfree method:
 - *OT is a useful tool for generating geometrically-exact discrete Lagrangians for flow problems*
 - *Max-ent approach supplies an efficient meshfree, continuously adaptive, remapping-free, FE-compatible, interpolation scheme*
 - *Material-point sampling effectively addresses the issues of numerical quadrature, history variables*
- Extensions include:
 - *Contact (seizing contact for free!)*
 - *Fracture and fragmentation (provably convergent)*
- Outlook: Parallel implementation, UQ...

OTM – Summary and outlook



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