



Optimal Uncertainty Quantification

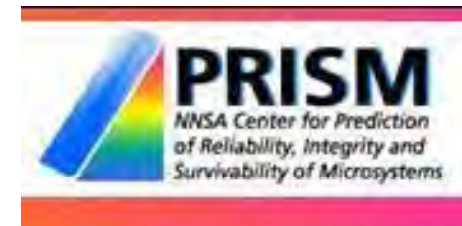
M. Ortiz

California Institute of Technology

Advanced Computational Engineering Workshop
Oberwolfach (Germany) Feb 12-18, 2012

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The Quantification of Margins and Uncertainties (QMU) Paradigm

- Aim: *Predict mean performance and **uncertainty** in the behavior of complex physical/engineered systems*
- **Paradigm shift** in experimental science, modeling and simulation, scientific computing (***predictive science***):
 - Deterministic → Non-deterministic systems
 - Mean performance → Mean performance + Uncertainty

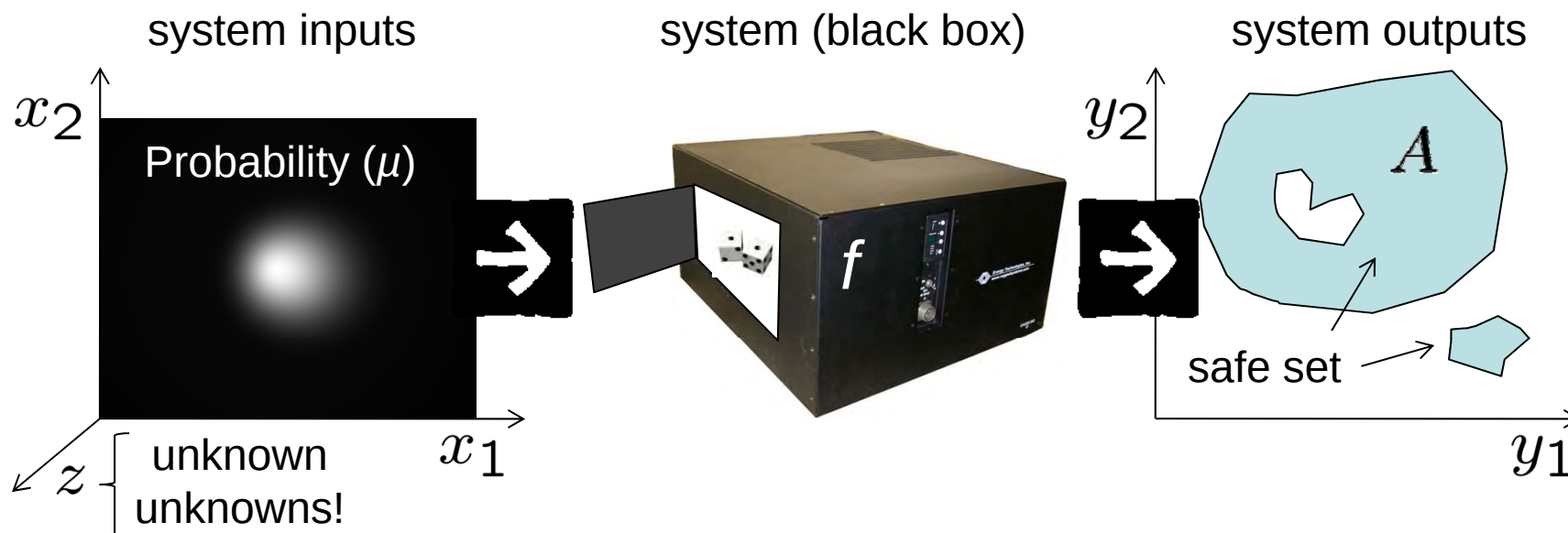


Old single-calculation paradigm



New ensemble-of-calculations
paradigm (QMU)

What is QMU?: Certification view



- Certification: PoF of the system below tolerance,

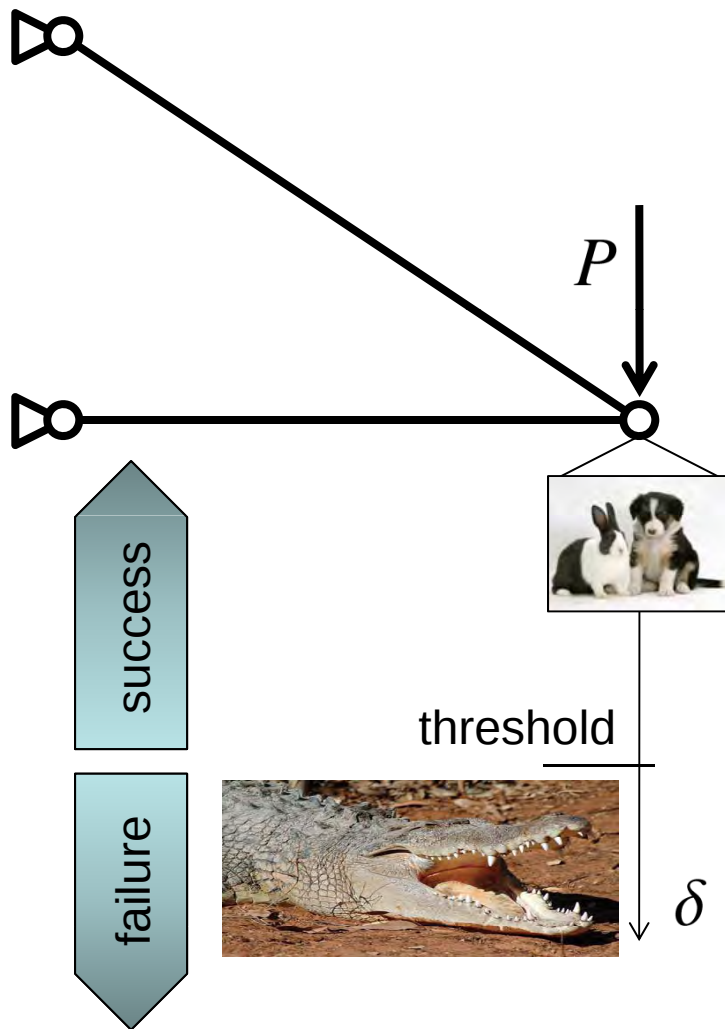
$$\mathbb{P}[\text{failure}] = \mathbb{P}[y \notin A] \leq \epsilon$$

- Exact probability of failure:

$$\mathbb{P}[\text{failure}] = \int \left\{ \begin{array}{ll} 0, & \text{if } f(x) \in A \\ 1, & \text{if } f(x) \notin A \end{array} \right\} d\mu(x)$$



QMU – A simple truss example



- System input: Applied force (P)
- System output: Tip deflection (δ)
- Response function (f): Energy minimization, static equilibrium
- Failure criterion: $\delta > \text{threshold}$
- To compute: $\mathbb{P}[\text{failure}] =$

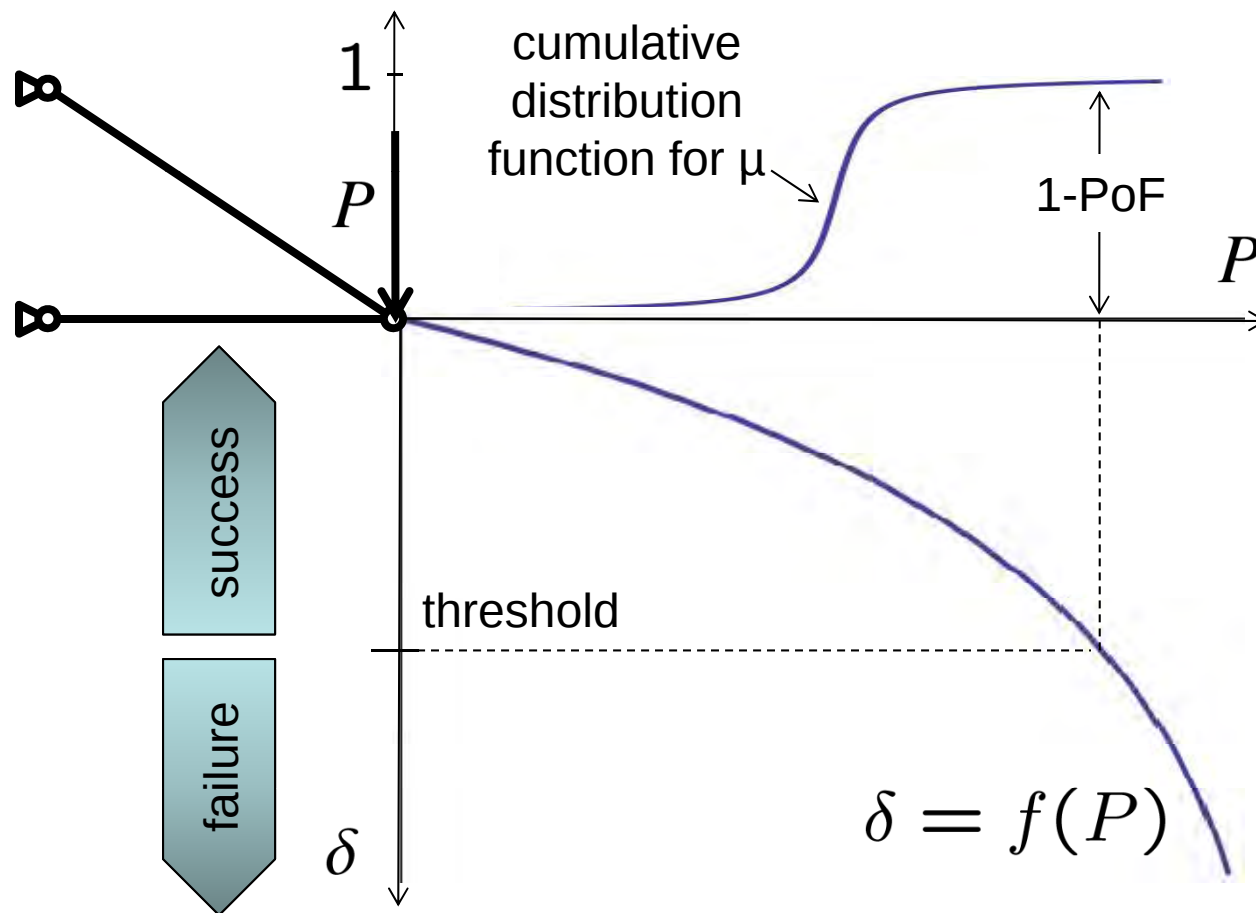
$$\int \left\{ \begin{array}{ll} 0, & \text{if } \delta < \delta_{\max} \\ 1, & \text{if } \delta \geq \delta_{\max} \end{array} \right\} d\mu(P)$$



QMU – A simple truss example



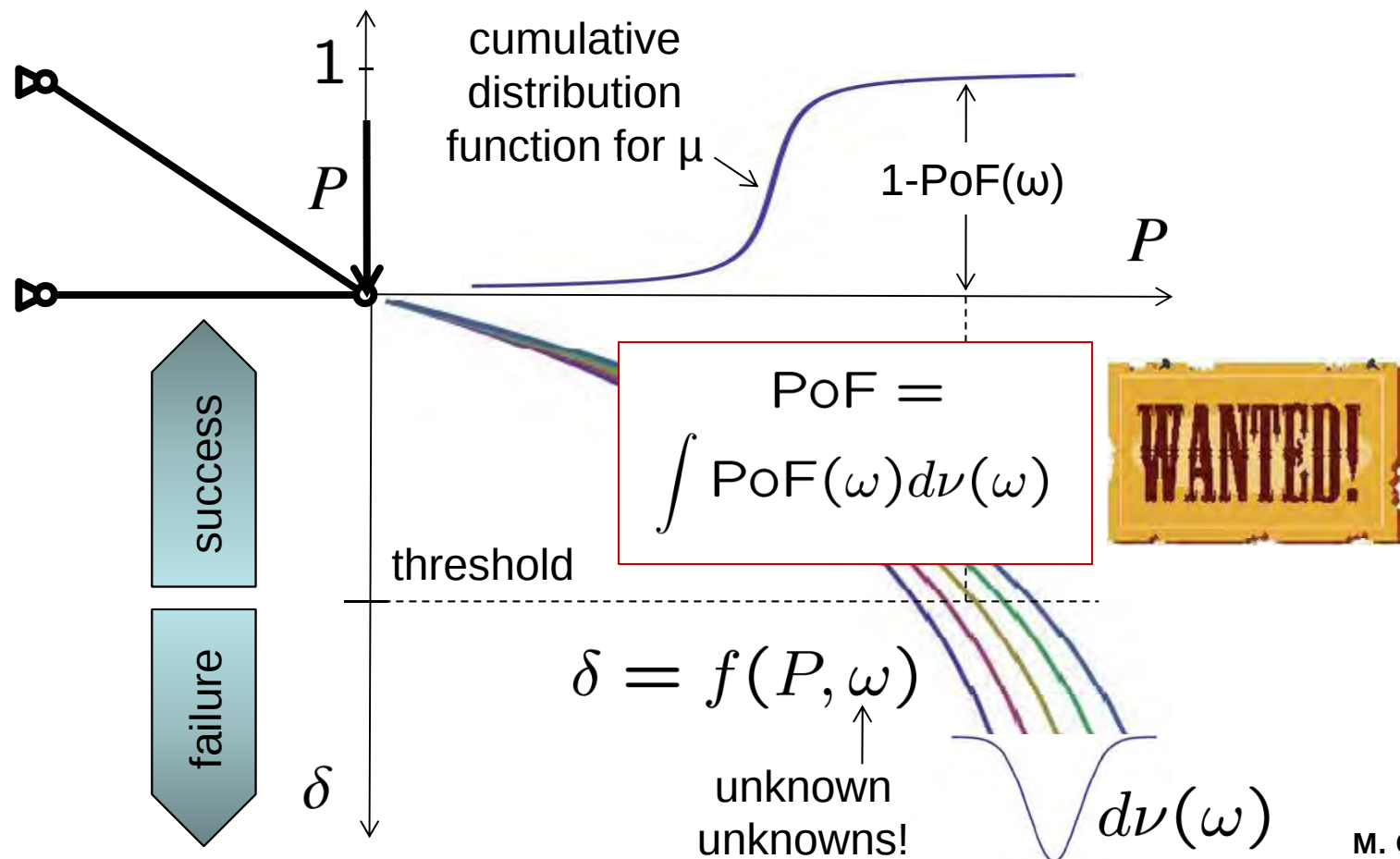
- Assume: Deterministic response, known probability distribution of inputs



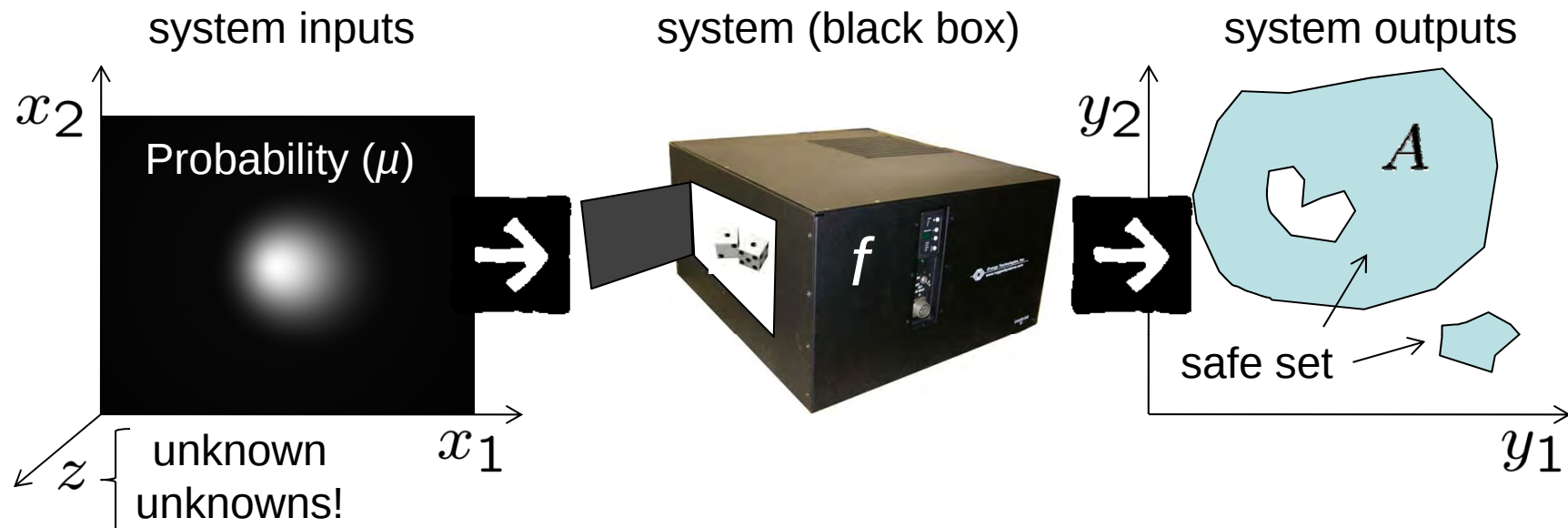
QMU – A simple truss example



- Assume: Stochastic response function, known probability distribution of inputs



QMU – Certification view



- Certification: PoF of the system below tolerance,

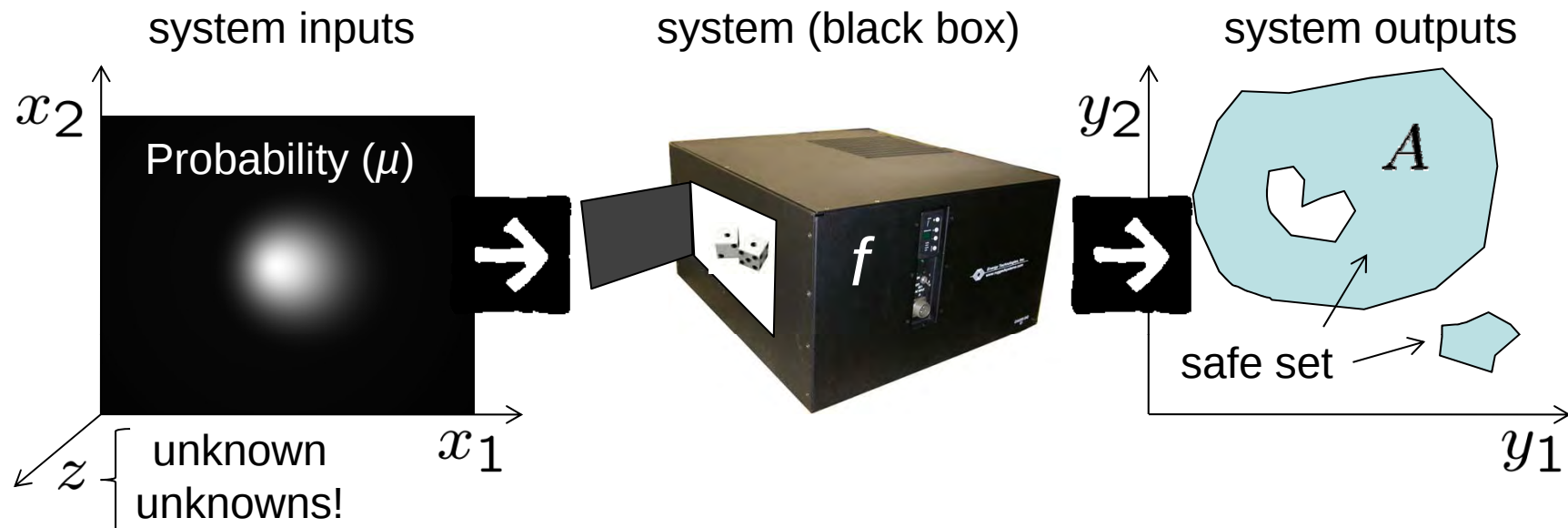
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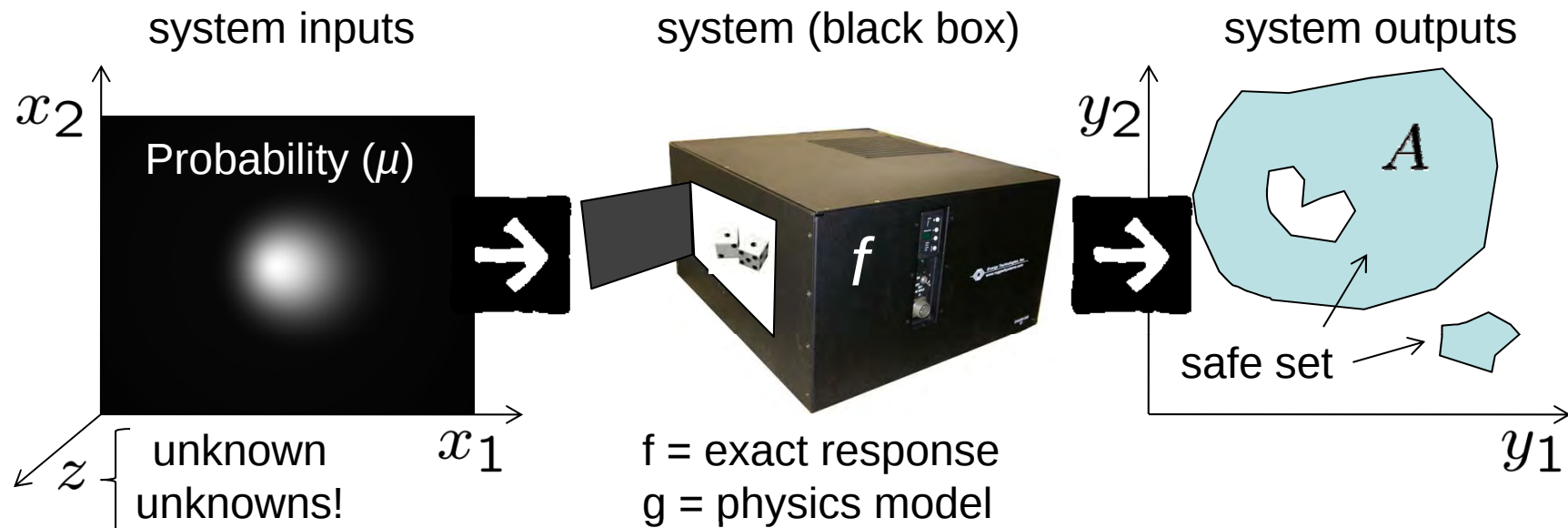
QMU – Essential difficulties



- Input space of high dimension, unknown unknowns
- Probability distribution of inputs not known in general
- System response stochastic, not known in general
- Models are inaccurate, partially verified & validated
- System performance cannot be tested on demand
- Legacy data incomplete, inconsistent, and noisy
- Failure events rare, high consequence decisions...



QMU – Conservative certification

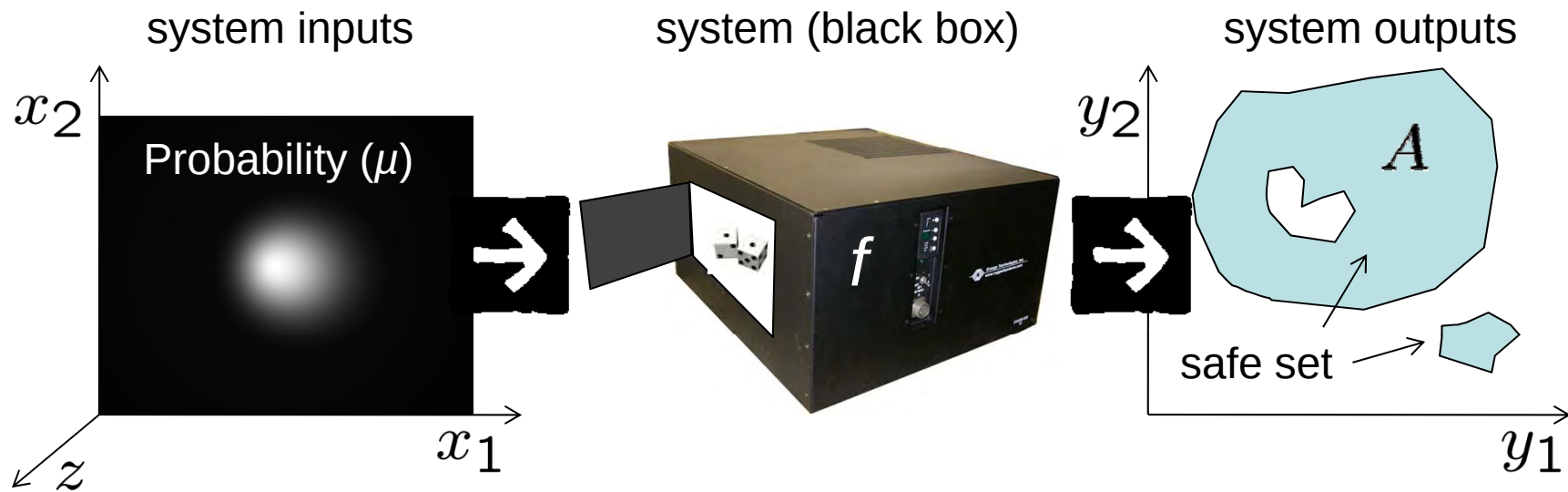


- Conservative certification: **Upper bound** on the PoF of the system below tolerance,

$$\mathbb{P}[\text{failure}] = \mathbb{P}[y \notin A] \leq \text{upper bound} \leq \epsilon$$

- **Problem:** Obtain *tight* (optimal?) *PoF upper bounds* from all information known about the system...

Optimal Uncertainty Quantification



- Wanted: $\mathbb{P}[\text{failure}] = \mathbb{E}_\mu[\{f \in A\}]$
- Assume information about (μ, f) : Data, models...
- Admissible set: $\mathcal{A} = \{(\mu, f) \text{ compatible with info}\}$
- Optimal PoF bounds given $\mathcal{A}$:

$$\inf_{(\mu, f) \in \mathcal{A}} \mathbb{E}_\mu[\{f \in A\}] \leq \text{PoF} \leq \sup_{(\mu, f) \in \mathcal{A}} \mathbb{E}_\mu[\{f \in A\}]$$

OUQ – The Reduction Theorem



Theorem [Owhadi *et al.* (2011)] Suppose that

$$\mathcal{A} = \left\{ (\mu, f) \mid \begin{array}{l} \langle \text{some conditions on } f \text{ alone} \rangle \\ \mathbb{E}_\mu[\varphi_1] \leq 0, \dots, \mathbb{E}_\mu[\varphi_n] \leq 0 \end{array} \right\}. \text{ Let:}$$

$$\mathcal{A}_{\text{red}} = \left\{ (\mu, f) \in \mathcal{A} \mid \mu = \sum_{i=1}^n \alpha_i \delta_{x_i}, \alpha_i \geq 0, \sum_{i=1}^n \alpha_i = 1 \right\}$$

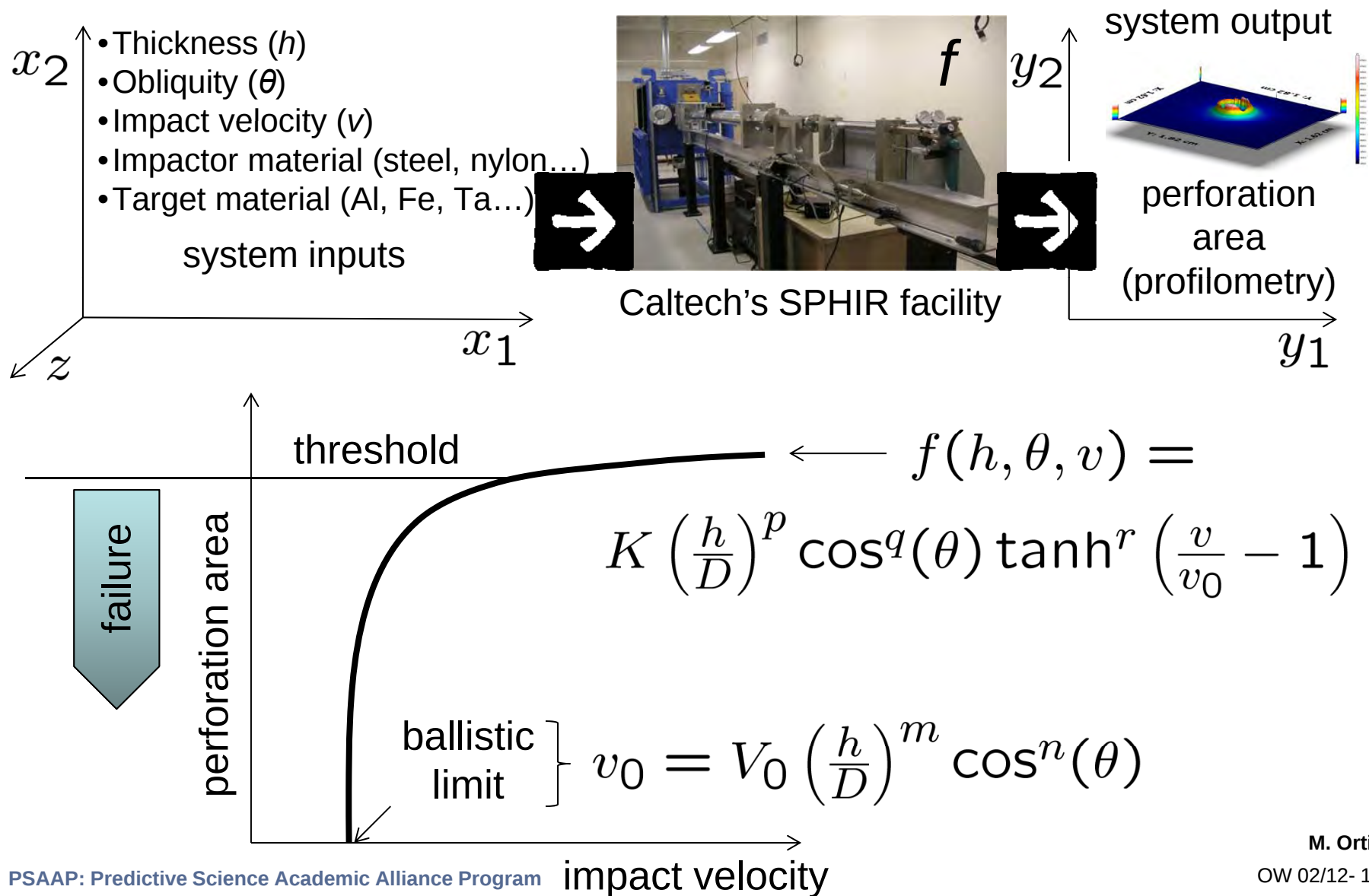
$$\text{Then: } \inf_{(\mu, f) \in \mathcal{A}} \mathbb{E}_\mu[\{f \in A\}] = \inf_{(\mu, f) \in \mathcal{A}_{\text{red}}} \mathbb{E}_\mu[\{f \in A\}]$$

$$\sup_{(\mu, f) \in \mathcal{A}} \mathbb{E}_\mu[\{f \in A\}] = \sup_{(\mu, f) \in \mathcal{A}_{\text{red}}} \mathbb{E}_\mu[\{f \in A\}]$$

- OUQ problem is reduced to optimization over finite-dimensional space of measures: Program feasible!

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Example – Certifying lethality in terminal ballistics



Example – Certifying lethality



Caltech's SPHIR facility

$$(h, \theta, v) \in \mathcal{X} \equiv \mathcal{X}_1 \times \mathcal{X}_2 \times \mathcal{X}_3$$

$$h \in \mathcal{X}_1 \equiv [1.524, 2.667] \text{ mm}$$

$$\theta \in \mathcal{X}_2 \equiv [0, \frac{\pi}{6}]$$

$$v \in \mathcal{X}_3 \equiv [2.1, 2.8] \text{ km s}^{-1}$$

- **Admissible set:**

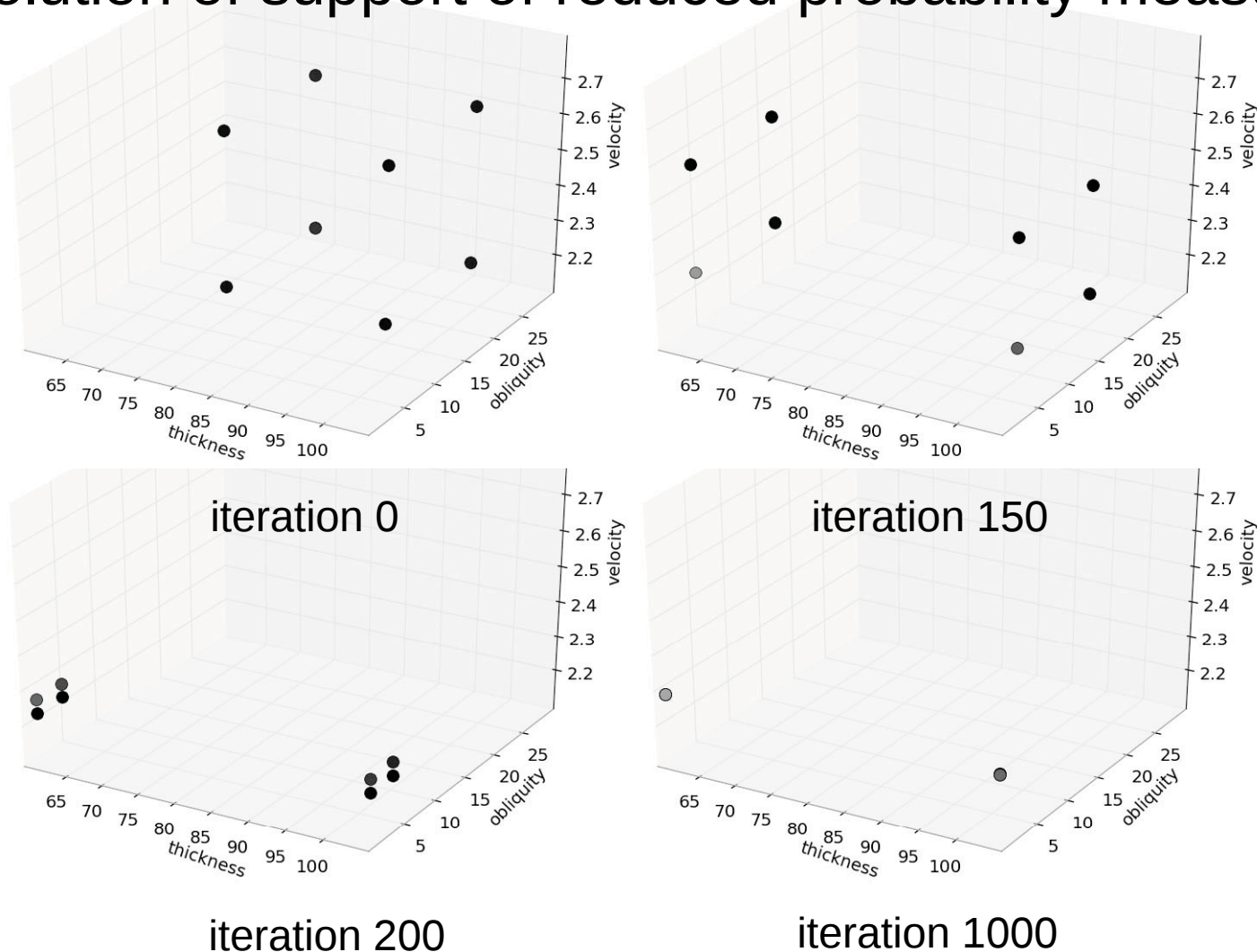
$$\mathcal{A} \equiv \left\{ (f, \mu) \left| \begin{array}{l} f \text{ known exactly,} \\ \mu = \mu_1 \otimes \mu_2 \otimes \mu_3, \\ 5.5\text{mm}^2 \leq \mathbb{E}_\mu[f] \leq 7.5\text{mm}^2 \end{array} \right. \right\}$$

- **Reduced admissible set:**

$$\mathcal{A}_{\text{red}} \equiv \left\{ (f, \mu) \left| \begin{array}{l} f \text{ known exactly,} \\ \mu = \mu_1 \otimes \mu_2 \otimes \mu_3, \\ \mu_i = \alpha_i \delta_{a_i} + (1 - \alpha_i) \delta_{b_i}, \quad i = 1, 2, 3, \\ 5.5\text{mm}^2 \leq \mathbb{E}_\mu[f] \leq 7.5\text{mm}^2 \end{array} \right. \right\}$$

Example – Certifying lethality

- Evolution of support of reduced probability measure:



Example – Certifying lethality



Caltech's SPHIR facility

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- Optimal PoF upper bound:

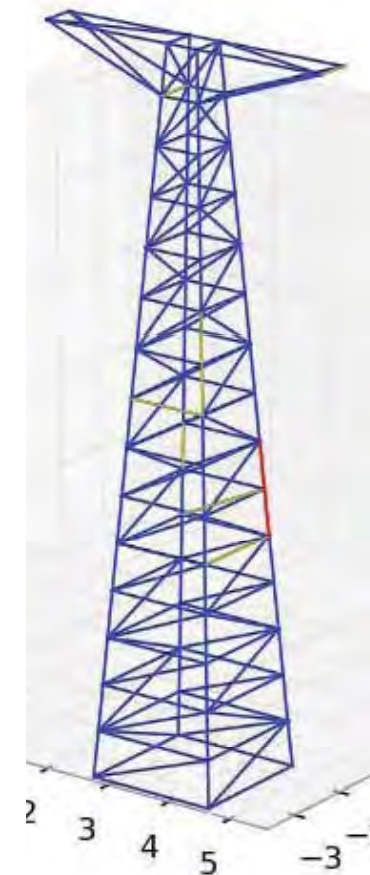
$$\sup_{(\mu, f) \in \mathcal{A}} \mathbb{E}_{\mu}[\{f = 0\}] = \sup_{(\mu, f) \in \mathcal{A}_{\text{red}}} \mathbb{E}_{\mu}[\{f = 0\}] = \underline{37.9\%}$$

Example – Seismic risk assessment

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Simulation of seismic waves from rupture initiating at Parkfield, central California, and propagating over Los Angeles basin (<http://krishnan.caltech.edu/krishnan/res.html>)



3D truss structure of power-line tower

Example – Seismic risk assessment



- Ground motion acceleration:

$$\ddot{u}_0(t) = (\psi * s)(t)$$

where: $s(t) \equiv$ Source activity

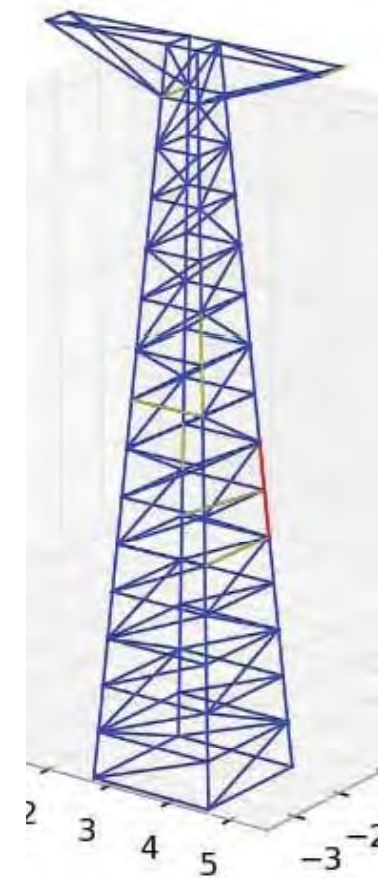
$\psi(t) \equiv$ Transfer function

- Structural response:

$$M\ddot{u} + C\dot{u} + Ku = -MT\ddot{u}_0(t)$$

- Failure criterion: $f \leq 0$, where

$$f = \min_{i \in \text{members}} \left\{ \sigma_y - \max_{t \geq 0} |\sigma_i(t)| \right\}$$

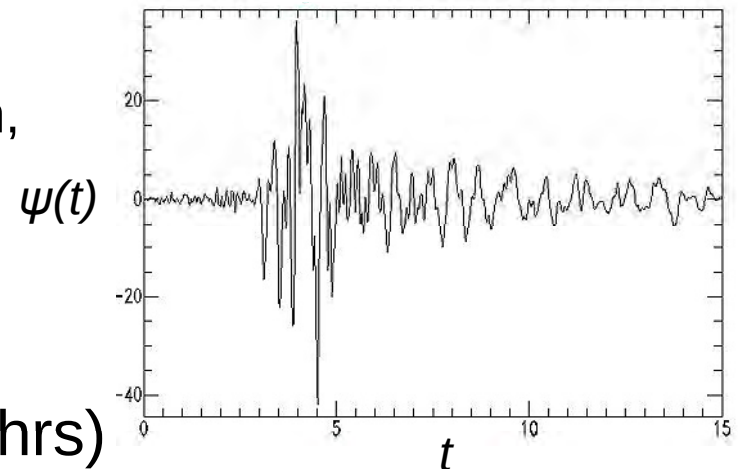
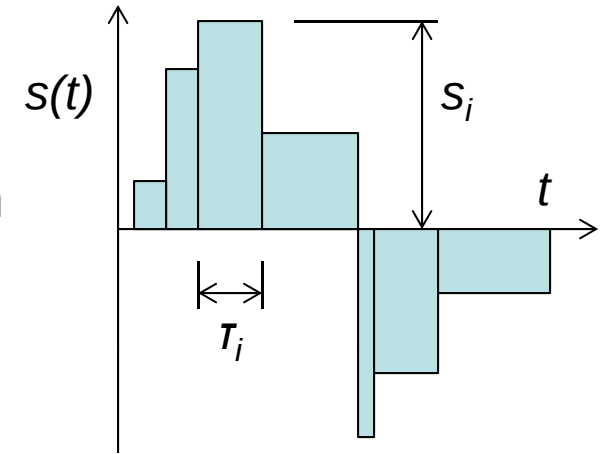


3D truss structure
of power-line tower

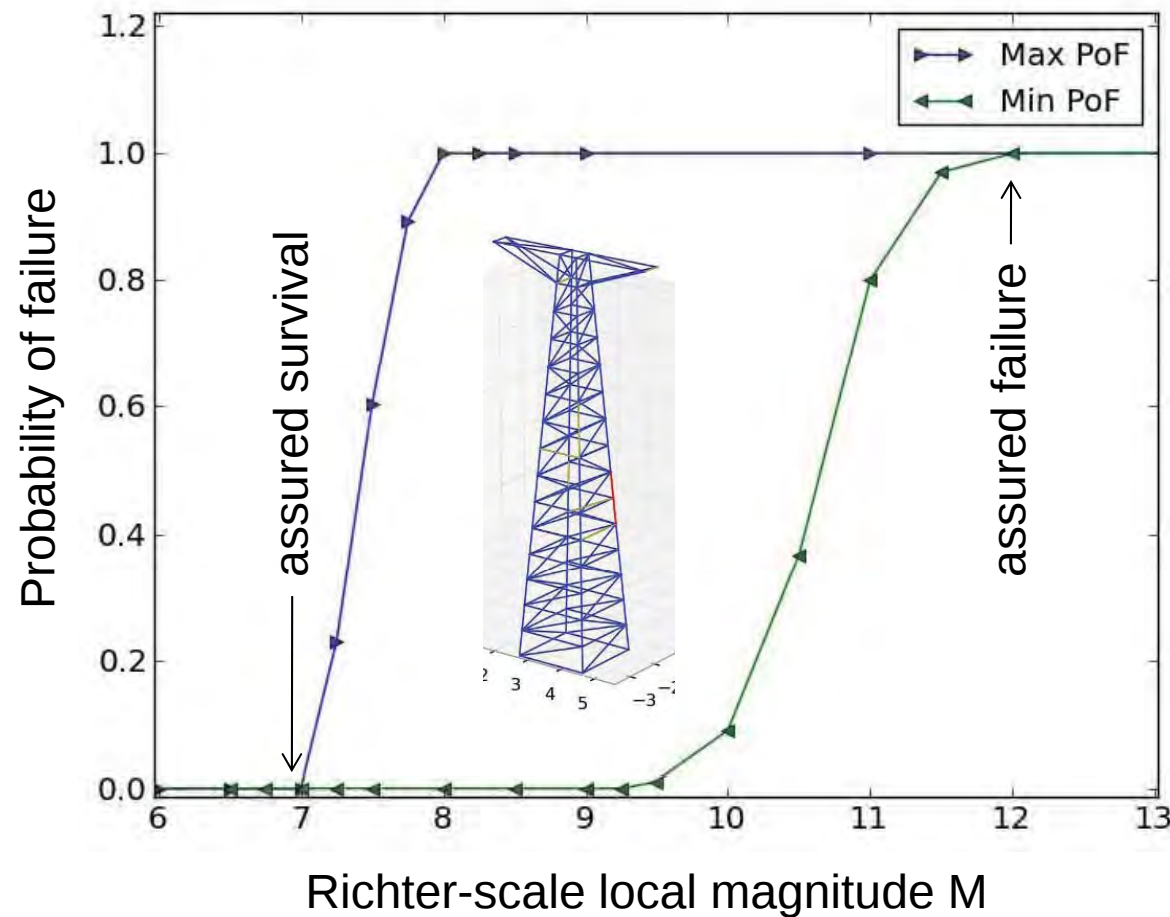
Example – Seismic risk assessment



- Assumptions on source term $s(t)$:
 - Piecewise constant (boxcar) in time
 - Random amplitudes in $[-a_{\max}, a_{\max}]$ (given by Richter magnitude M) with zero mean
 - Random time interval durations with bounded mean
- Assumptions on transfer function $\psi(t)$:
 - Piecewise linear in time
 - Random amplitudes with zero mean, bounded L^2 norm
- Reduced OUQ problem: Global optimization in 179 dimensions
- One PoF calculation takes $O(24 \text{ hrs})$ on $O(1000)$ AMD opteron cluster



Example – Seismic risk assessment



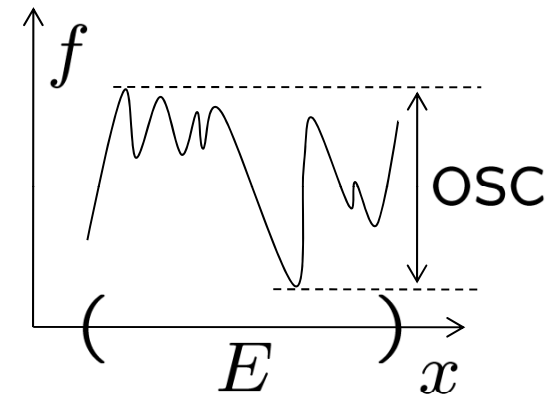
Optimal PoF upper and lower bounds for steel tower
vs. Richter scale magnitude M at hypocentral distance $R=25$ km,
($a_{\max}$ given by Esteva's semi-empirical expression as a function of M)

OUQ with diameter data

- Question: How is $\mathcal{A}$ to be defined? What type of data on system response leads to effective UQ?

- Oscillation of a function of one variable:

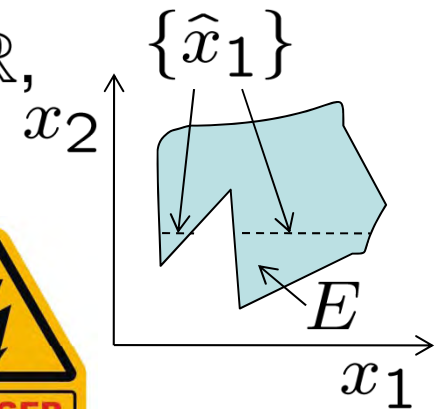
$$\begin{aligned}\text{osc}(f, E) &= \sup_{x \in E} f(x) - \inf_{x \in E} f(x) \\ &= \sup_{x, x' \in E} |f(x) - f(x')|\end{aligned}$$



- Function subdiameters: $f : E \subset \mathbb{R}^N \rightarrow \mathbb{R}$,

$$D_i(f, E) = \sup_{\hat{x}_i \in \mathbb{R}^{N-1}} \text{osc}(f, E \cap \{\hat{x}_i\}),$$

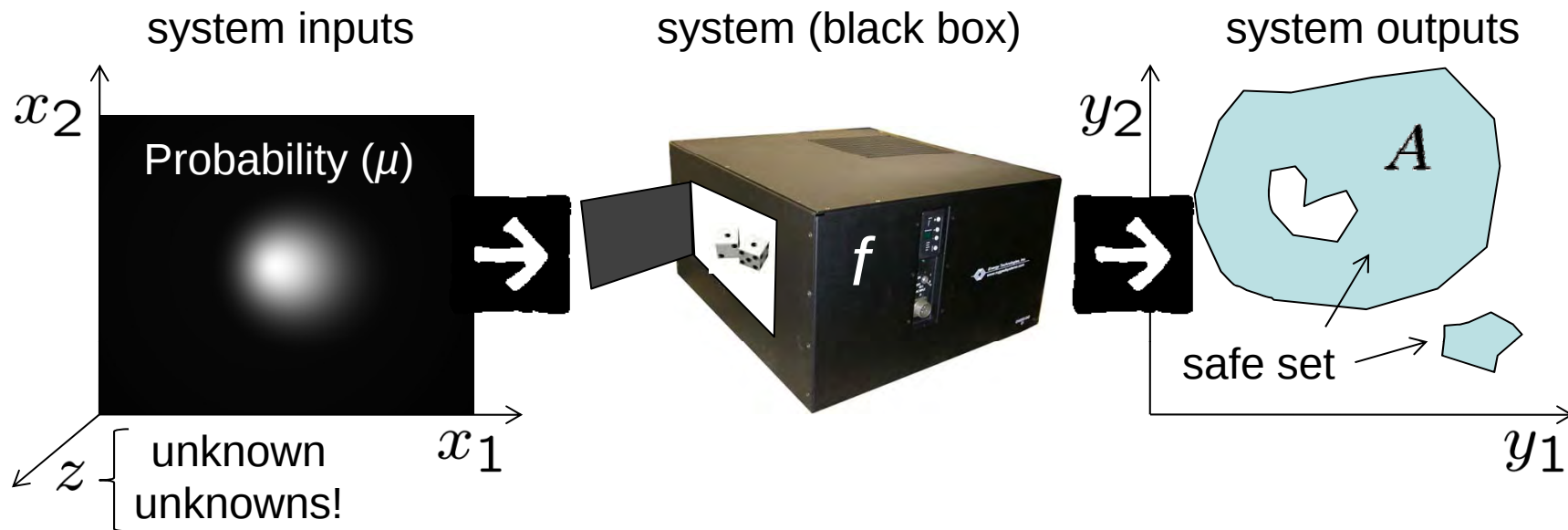
$$\hat{x}_i = \{x_1, \dots, x_{i-1}, x_{i+1}, \dots, x_N\}$$



possibly unknown unknowns!

global optimization!

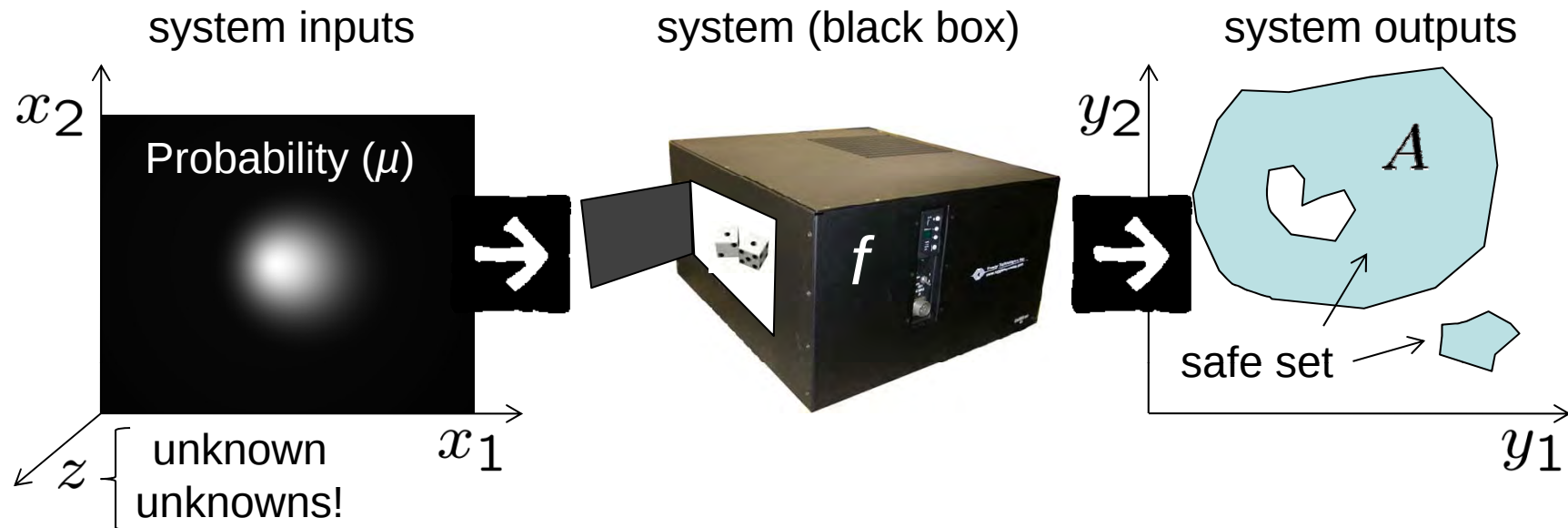
OUQ with diameter data



- Admissible set for diameter data with scatter:

$$\mathcal{A} \equiv \left\{ (f, \mu) \left| \begin{array}{l} D_i(f, \mathcal{X}) \leq D_i, \quad i = 1, \dots, n \\ \mu = \mu_1 \otimes \dots \otimes \mu_n, \\ m_1 \leq \mathbb{E}_\mu[f] \leq m_2 \\ D_z \leq D_i(f, \mathcal{X}) - \mathbb{E}_\mu[f], \quad i = 1, \dots, n \end{array} \right. \right\}$$

OUQ with diameter data

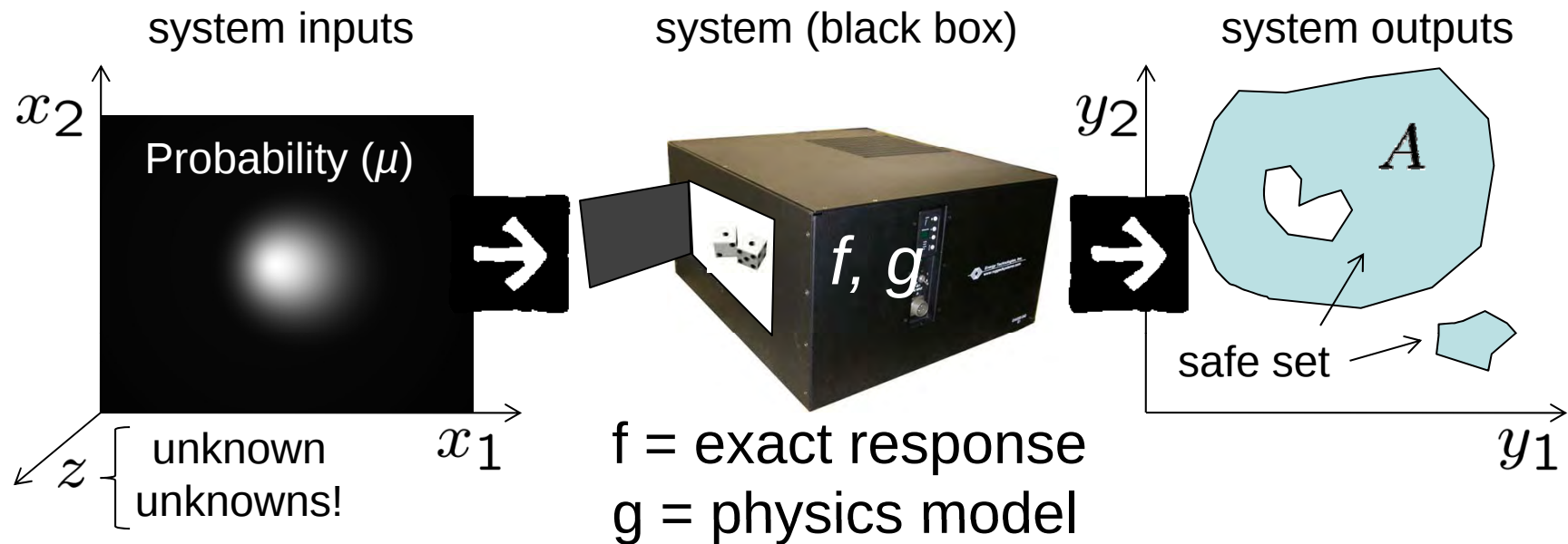


- OUQ problem explicitly solvable in low dimension!

- For $n = 2$: $\sup_{(\mu, f) \in \mathcal{A}} \mathbb{E}_\mu[\{f \leq 0\}] =$

$$\begin{cases} 0, & \text{if } D_1 + D_2 \leq \mathbb{E}_\mu[f] \\ \frac{(D_1 + D_2 - \mathbb{E}_\mu[f])^2}{4D_1D_2}, & \text{if } |D_1 - D_2| \leq \mathbb{E}_\mu[f] \leq D_1 + D_2 \\ 1 - \frac{\mathbb{E}_\mu[f]}{\max(D_1, D_2)}, & \text{if } 0 \leq \mathbb{E}_\mu[f] \leq |D_1 - D_2| \end{cases}$$

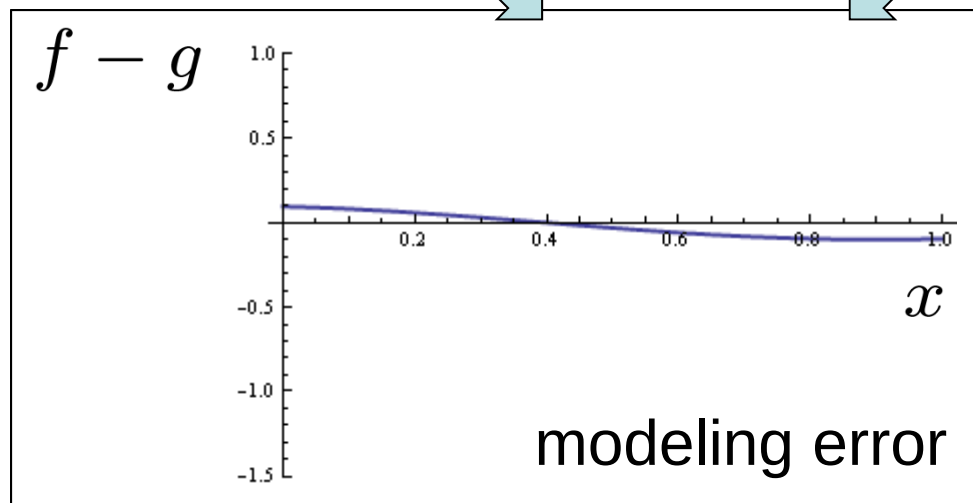
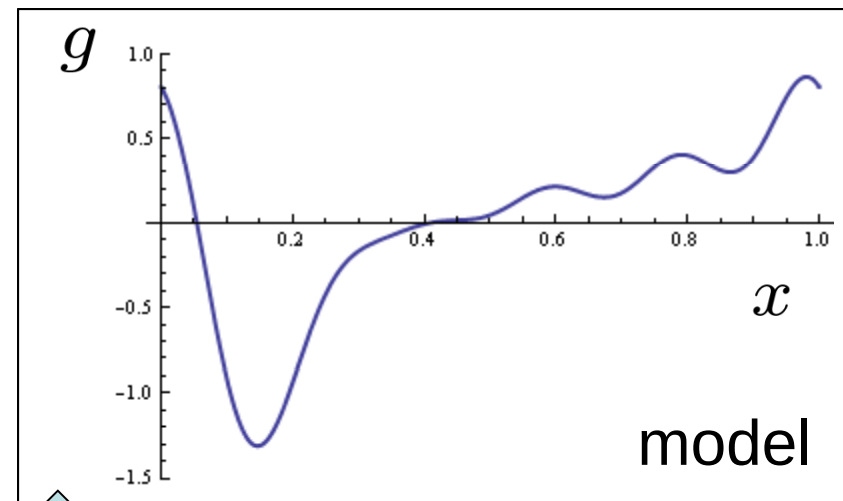
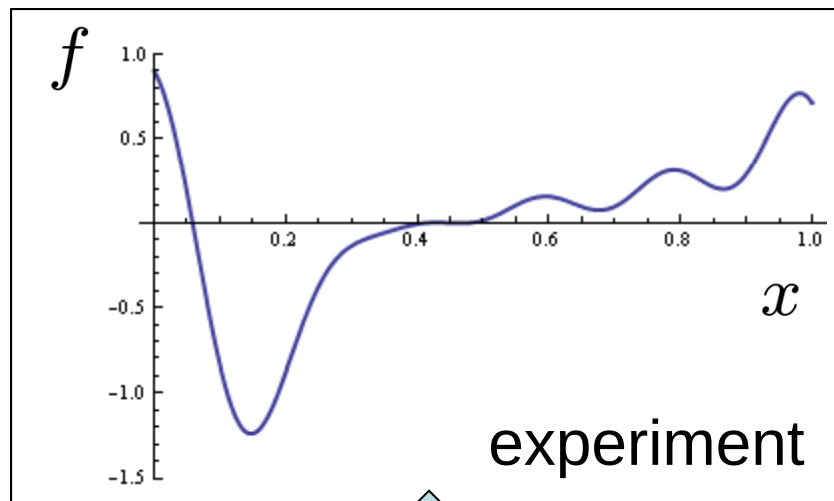
Model-based OUQ with diameter data



- Diameters $D_i(f)$ define seminorms of f .
- From the triangular inequality,

$$D_i(f) \leq \underbrace{D_i(g)}_{\text{model diameter}} + \underbrace{D_i(f - g)}_{\text{modeling error}}$$

Model-based QMU – McDiarmid



- Working assumptions:
 - $f-g$ far more regular than f or g alone
 - Global optimization for $D(f-g)$ converges fast
 - Evaluation of $D(f-g)$ requires few experiments

Model-based QMU – McDiarmid

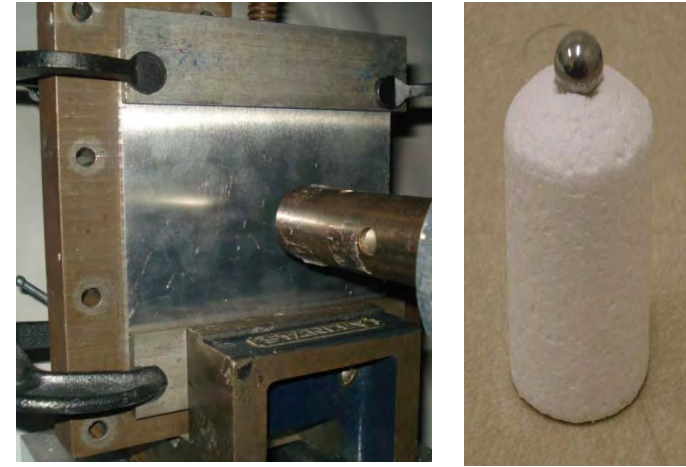
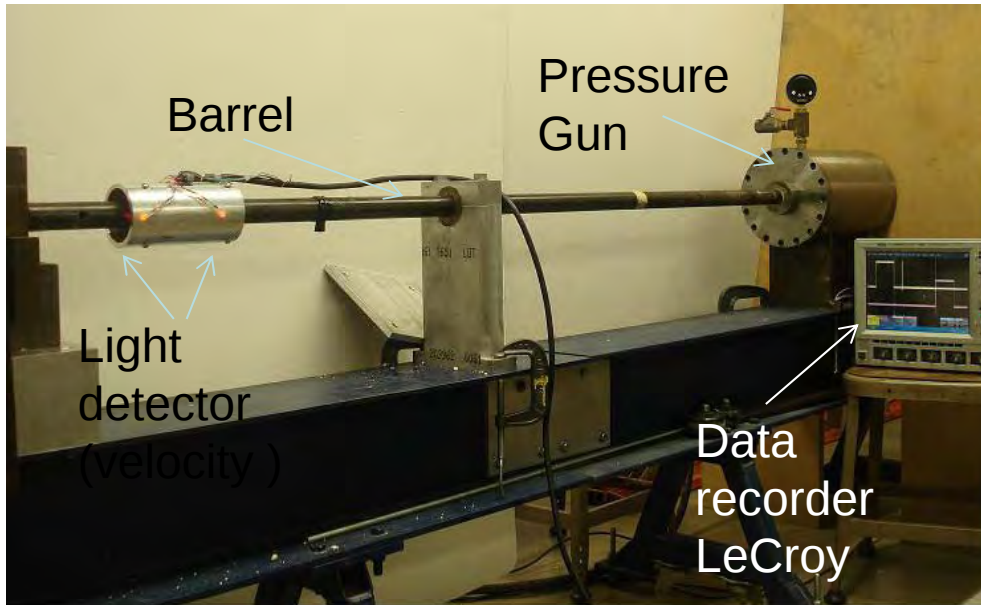


- Calculation of $D(f)$ requires exercising model only
- Uncertainty Quantification burden mostly shifted to modeling and simulation!



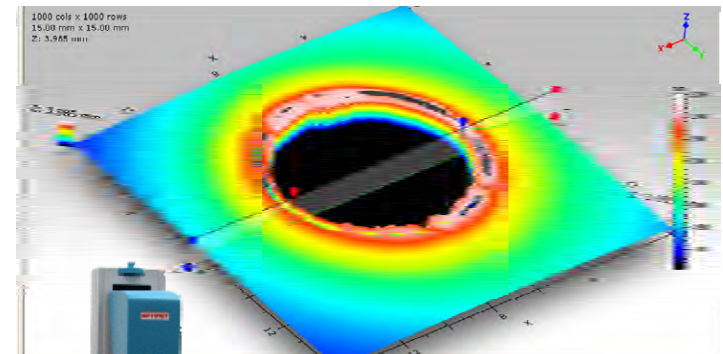
- Evaluation of $D(f-g)$ requires few experiments
- Rigorous certification not achievable by modeling and simulation alone!

Case Study – Steel/Al ballistics



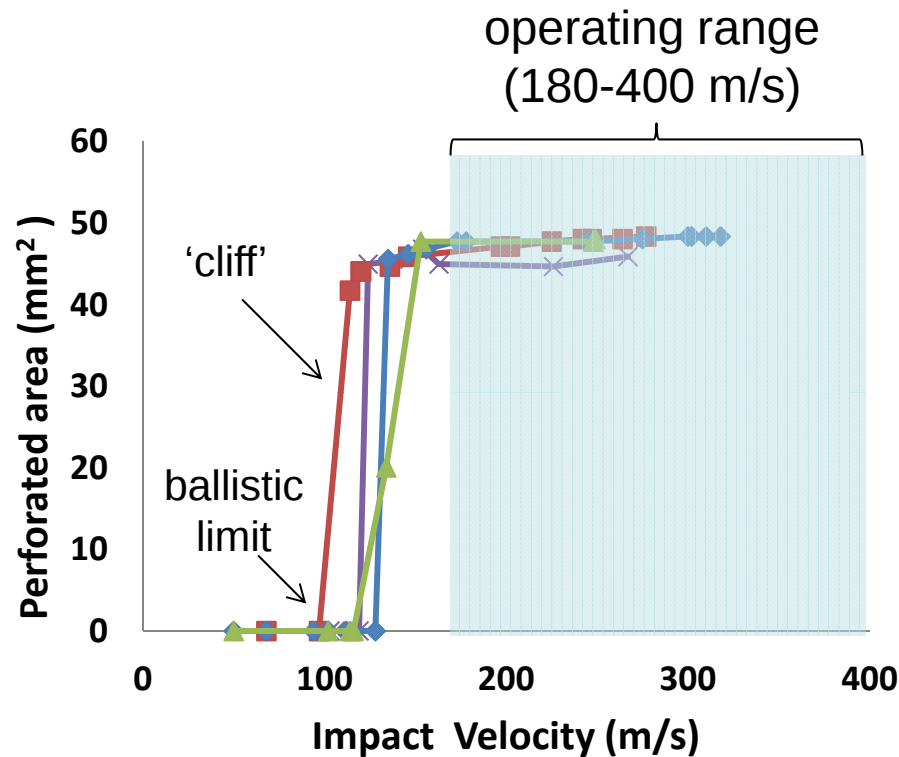
Target and projectile

- Target/projectile materials:
 - Target: Al 6061-T6 plates (6"x 6")
 - Projectile: S2 Tool steel balls (5/16")
- Model input parameters (x):
 - Plate thickness (0.032"-0.063")
 - Impact velocity (200-400 m/s)

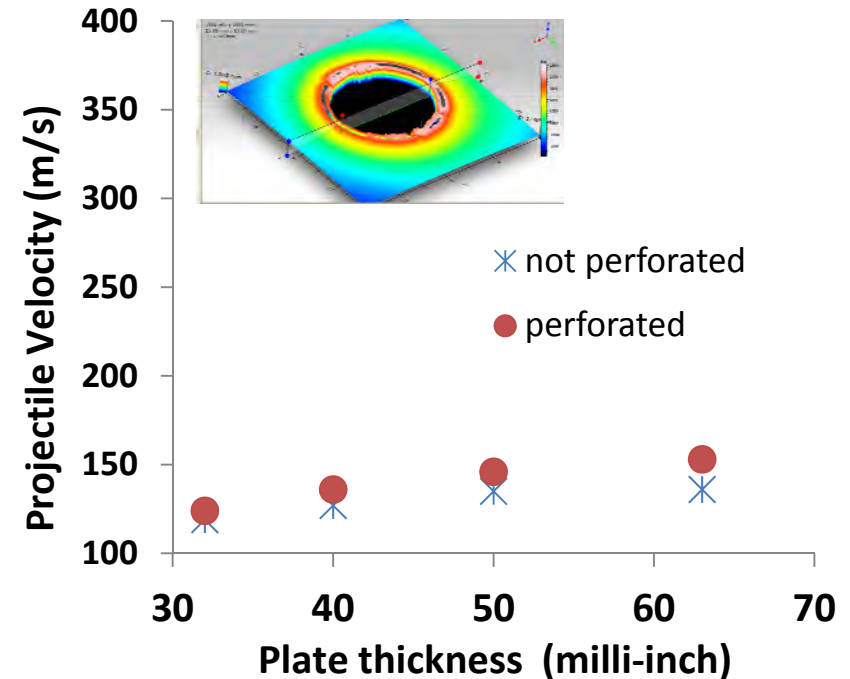


Optimet
MiniConoscan
3000

Case Study – Steel/Al ballistics



Perforation area vs. impact velocity
(note small data scatter!)



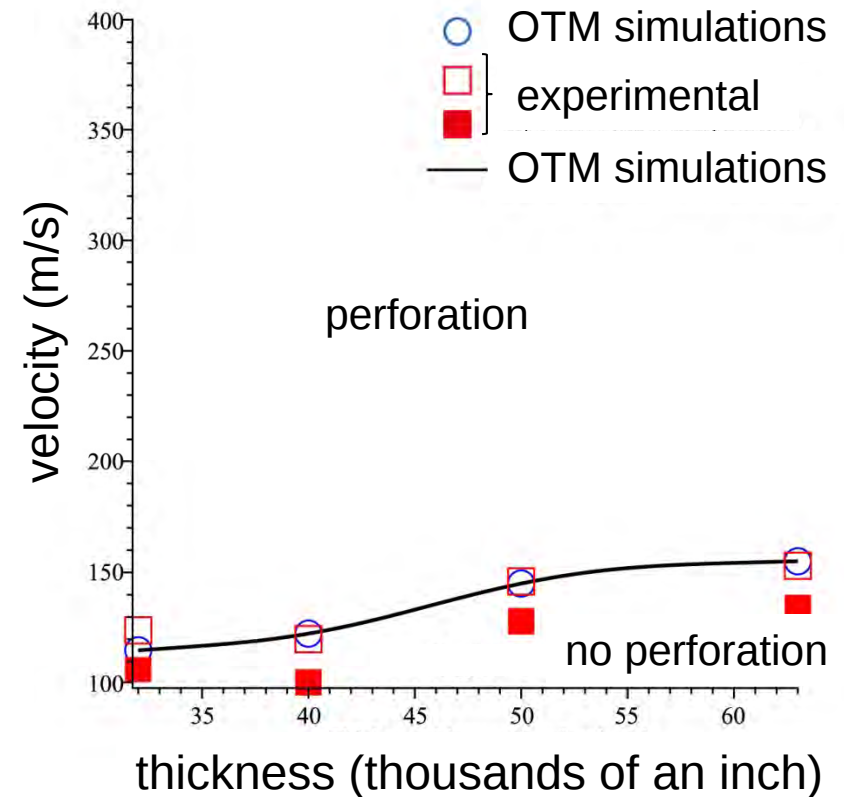
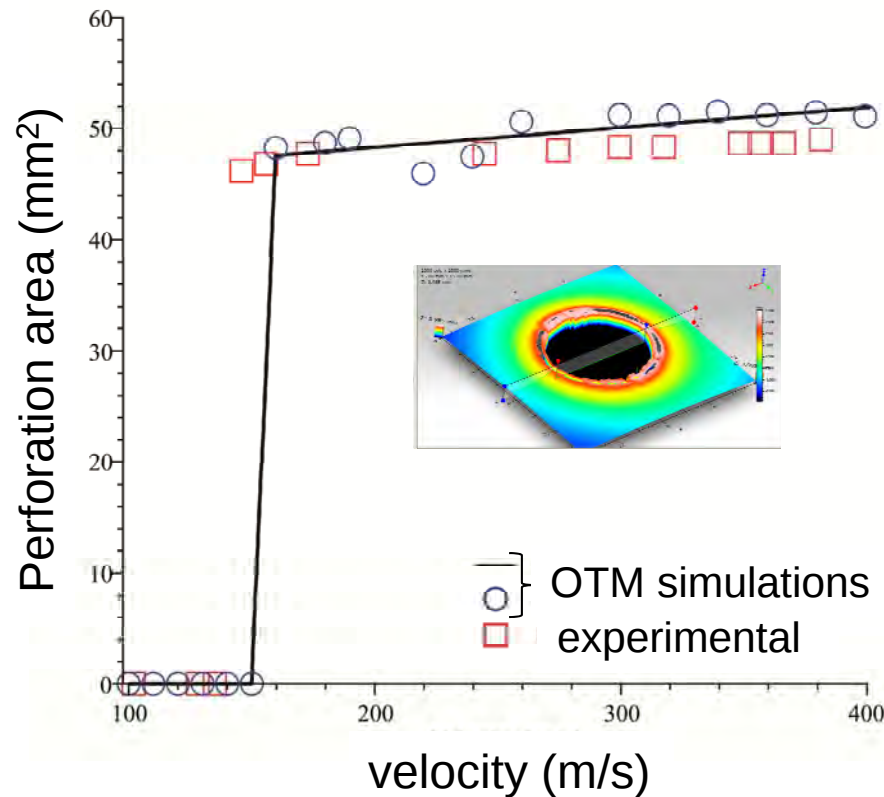
Perforation/non-perforation
boundary

- System output (y): **Perforation area!**
- Certification criterion: $y > 0$ (lethality)

Lagrangian solver: Optimal-Transportation Meshfree (OTM)

- Time integration (OT):
 - Optimal transportation methods:
 - Geometrically exact, discrete Lagrangians
 - Discrete mechanics, variational time integrators:
 - Symplecticity, exact conservation properties
 - Variational material updates, inelasticity:
 - Incremental variational structure
- Spatial discretization (M):
 - Max-ent meshfree nodal interpolation:
 - Kronecker-delta property at boundary
 - Material-point sampling:
 - Numerical quadrature, material history
 - Dynamic reconnection, ‘on-the-fly’ adaptivity

Case Study – OTM modeling error

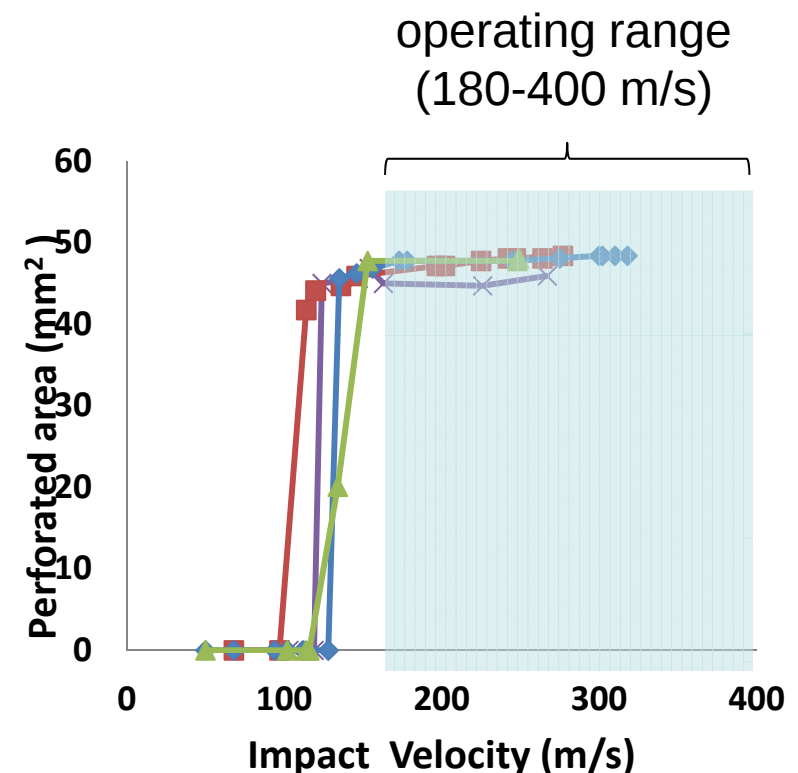


Measured vs. computed perforation area

Case study – Terminal ballistics



Model diameter $D(g)$	thickness	4.33 mm ²
	velocity	4.49 mm ²
	RMS	6.24 mm ²
Modeling error $D(f-g)$	thickness	4.96 mm ²
	velocity	2.16 mm ²
	RMS	5.41 mm ²
Uncertainty $D(g) + D(f-g)$		11.65 mm ²
Empirical mean $E[f]$		47.77 mm ²



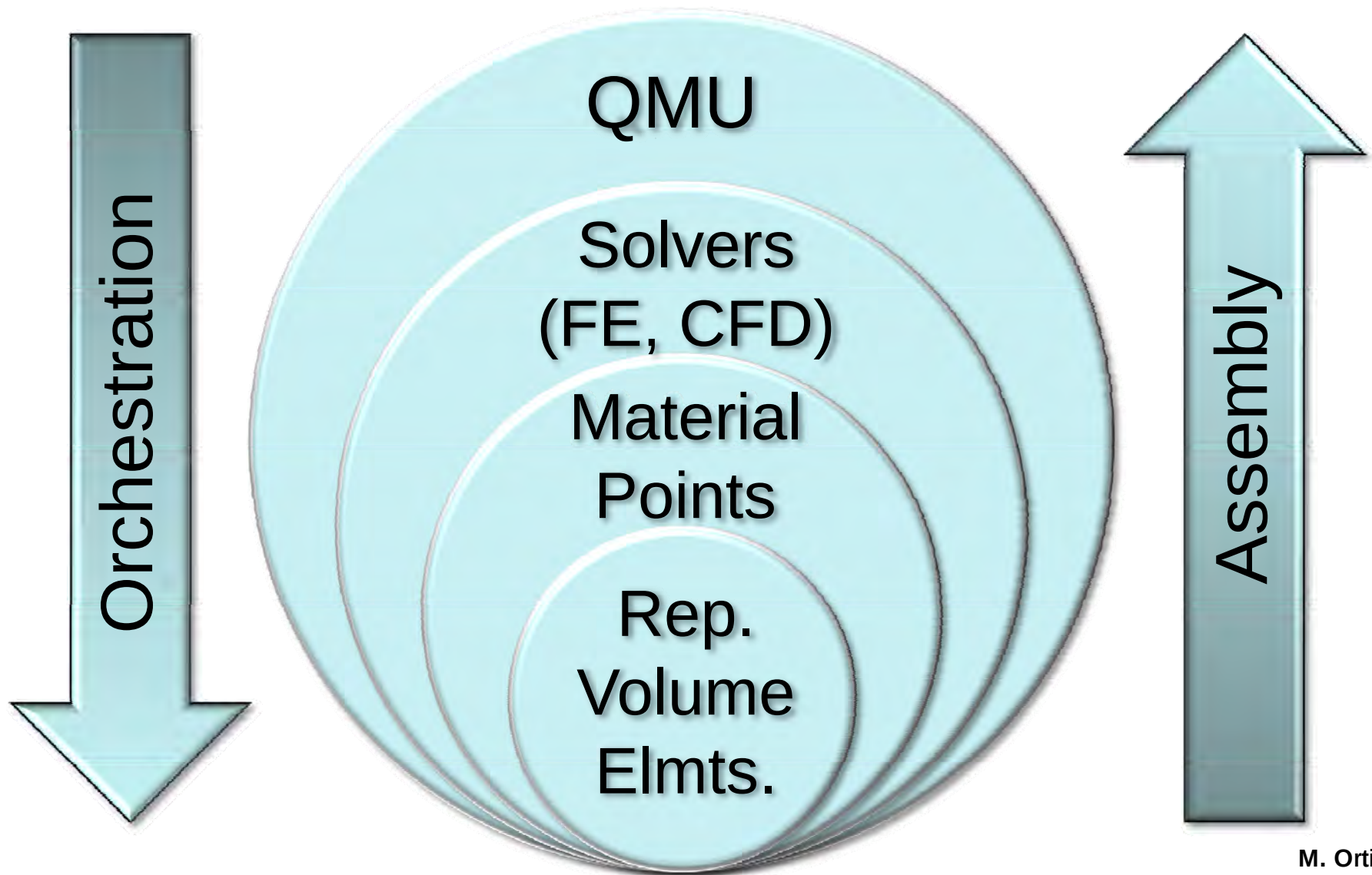
- Perforation can be certified with 99.9% confidence!
- Total number of experiments ~ 50 → Approach feasible!

Concluding remarks...

- Rigorous and conservative certification can be achieved by means of PoF upper bounds!
- PoF bounds ‘fold in’ all information available on the system (experimental data, V&V’d physics models...)
- PoF bounds are similar in spirit to bounds on effective moduli of elastic composites (which cannot be obtained exactly in general from existing data on the composite)
- However: Bounds can be suboptimal (e.g., Voigt, Reuss...) and result in excessive conservatism
- It possible to compute optimal PoF bounds (for given information about the system): **Optimal Uncertainty Quantification!** (OUQ)

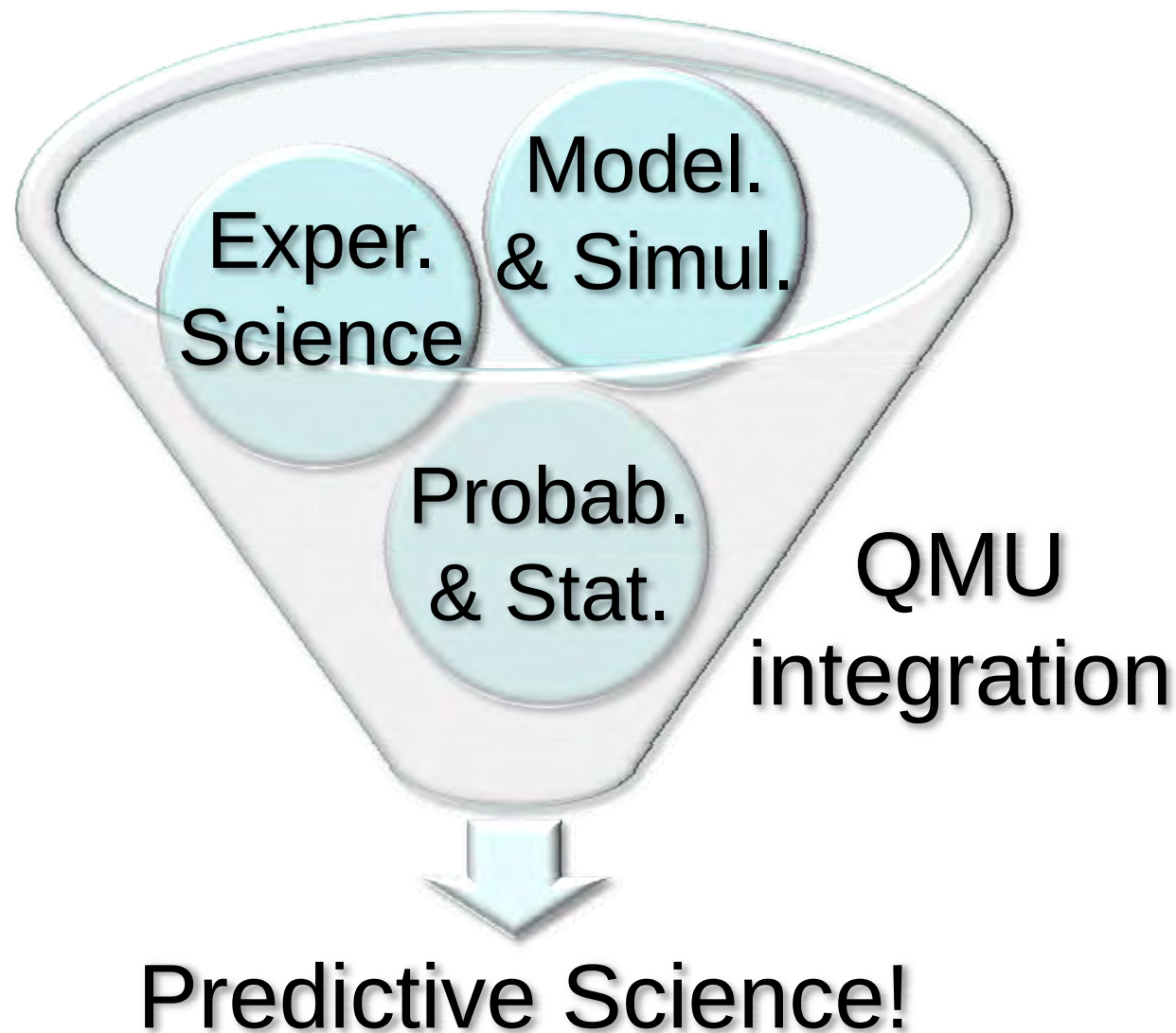
Concluding remarks – Systems view of Computational Mechanics...

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Concluding remarks – Disciplinary view of QMU and Predictive Science

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Concluding remarks...



Thank you!