

Optimal scaling laws in ductile fracture

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Joint work with: S. Conti, S. Heyden
and A. Pandolfi

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Variational Models of Fracture
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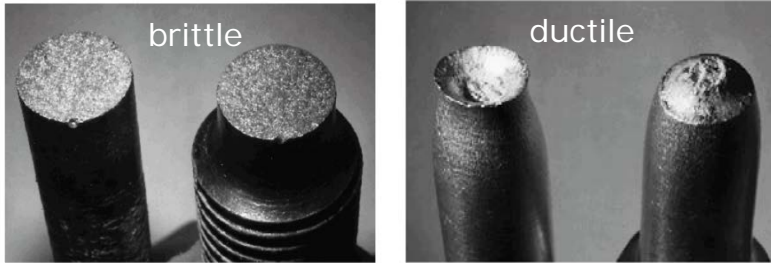
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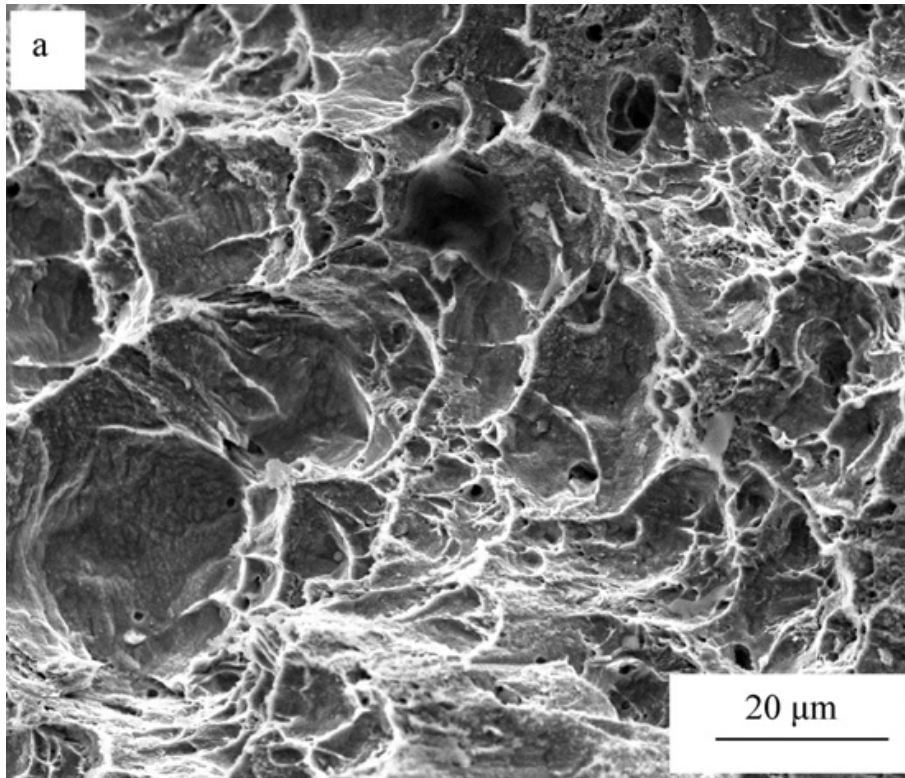
- Two mathematical results:
 - *Optimal scaling for ductile fracture of metals*
 - *Optimal scaling for ductile fracture of polymers*
- Attempts at connections with microscale:
 - *Verification of optimal scaling in atomic Ni*
 - *Nanovoid plastic cavitation*
- Attempts at connections with macroscale:
 - *Spall tests in metals*
 - *Taylor anvil impact tests for polyurea*



Background on ductile fracture



(Courtesy NSW HSC online)

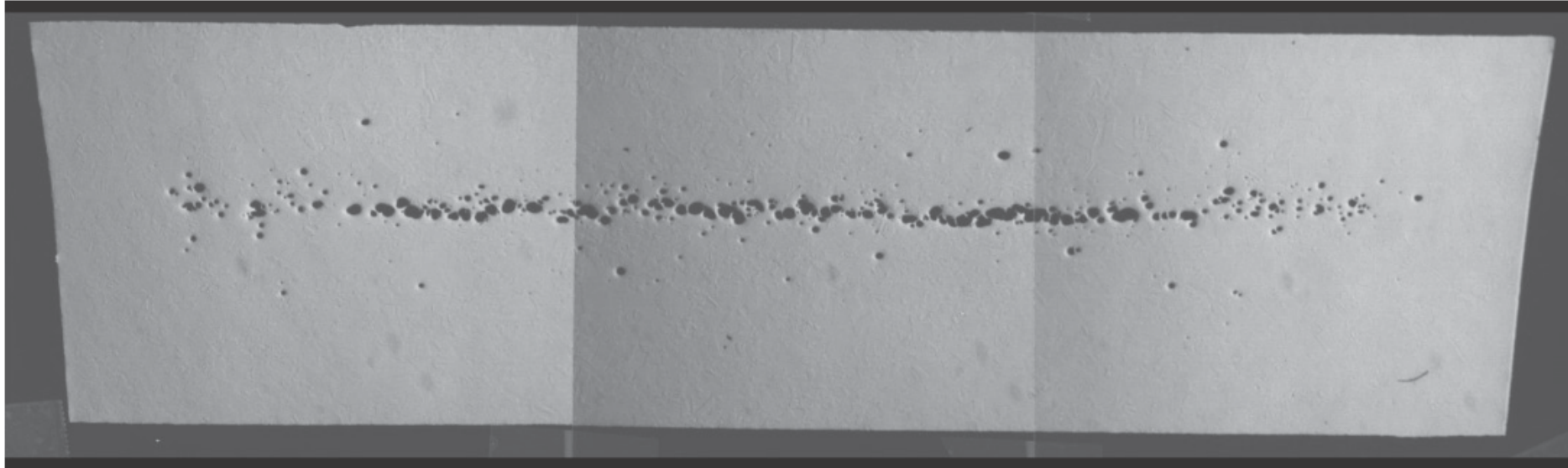


- Ductile fracture in metals occurs by *void nucleation, growth and coalescence*
- Fractography of ductile-fracture surfaces exhibits profuse *dimpling*, vestige of microvoids
- Ductile fracture entails large amounts of *plastic deformation* (vs. surface energy) and dissipation.

Fracture surface in SA333 steel, room temp., $d\epsilon/dt = 3 \times 10^{-3} s^{-1}$
(S.V. Kamata, M. Srinivasa and P.R. Rao, Mater. Sci. Engr. A, **528** (2011) 4141–4146)

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Background on ductile fracture



Photomicrograph of a copper disk tested in a gas-gun experiment showing the formation of voids and their coalescence into a fracture plane

Heller, A., How Metals Fail,
Science & Technology Review Magazine,
Lawrence Livermore National Laboratory,
pp. 13-20, July/August, 2002



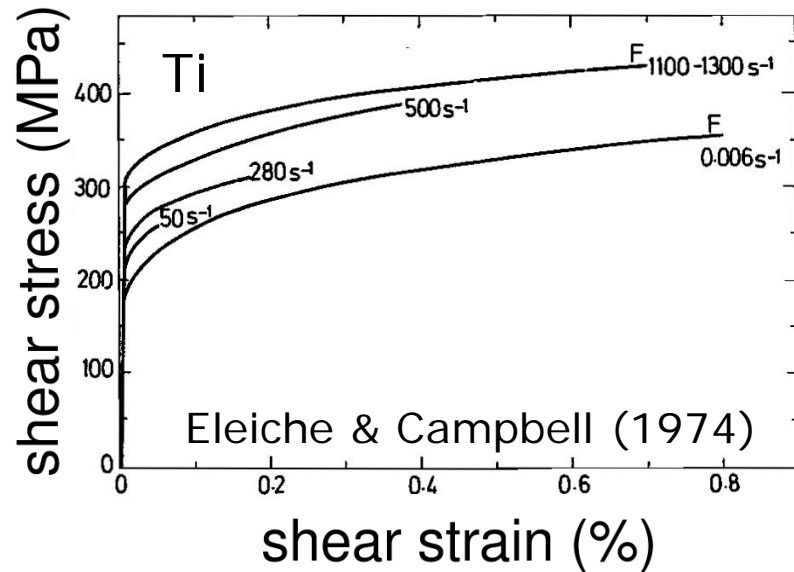
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Background on ductile fracture

- Ductile fracture is a multiscale phenomenon:
 - *Void nucleation occurs at the microscale*
 - *Void growth and coalescence occurs at the mesoscale*
 - *Fracture occurs at the macroscale*
- Challenges:
 - *Bridging of scales (micro-to-macro)*
 - *Upscaling of material properties from lower scales*
 - *Determination of macroscopic effective behavior*
- Approach:
 - *Mathematize the problem! (entry level requirement)*
 - *Micro-to-macro optimal scaling relations*
 - *Calibration of relevant properties from microscale*
 - *Application of effective laws at macroscale*



Naïve model: Local plasticity



- Deformation theory: Minimize

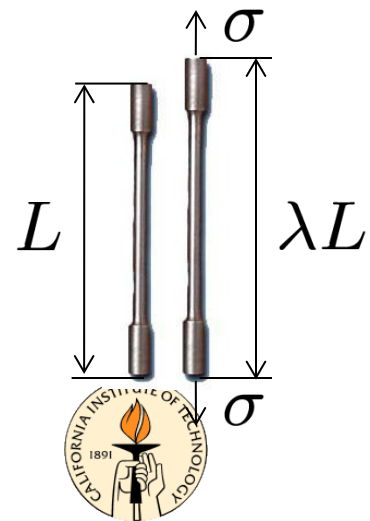
$$E(y) = \int_{\Omega} W(Dy(x)) dx$$

- Growth of $W(F)$?
- Assume power-law hardening:

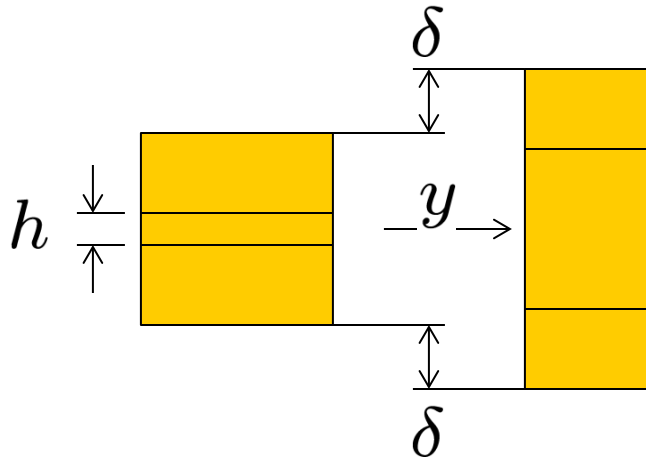
$$\sigma \sim K\epsilon^n = K(\lambda - 1)^n$$

- Nominal stress: $\partial_{\lambda} W = \sigma/\lambda = K(\lambda - 1)^n/\lambda$
- For large λ : $\partial_{\lambda} W \sim K\lambda^{n-1} \Rightarrow W \sim K\lambda^n$
- In general: $W(F) \sim |F|^p$, $p = n \in (0, 1)$

\Rightarrow Sublinear growth!



Naïve model: Local plasticity



- Example: Uniaxial extension

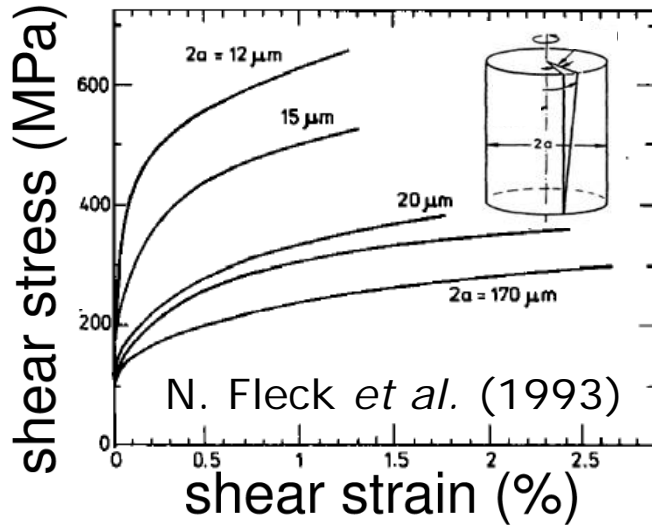
- Energy: $E_h \sim h \left(\frac{2\delta}{h} \right)^p$

- For $p < 1$: $\lim_{h \rightarrow 0} E_h = 0$

- Energies with sublinear growth relax to 0.
- For hardening exponents in the range of experimental observation, local plasticity yields no useful information regarding ductile fracture properties of materials
- Need additional physics, structure...



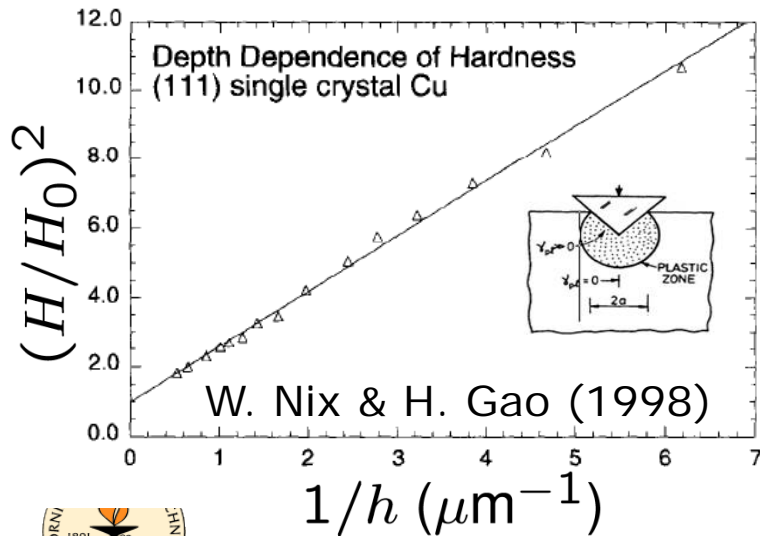
Strain-gradient plasticity



- The yield stress of metals is observed to increase in the presence of strain gradients
- Deformation theory of strain-gradient plasticity:

$$E(y) = \int_{\Omega} W(Dy(x), D^2y(x)) dx$$

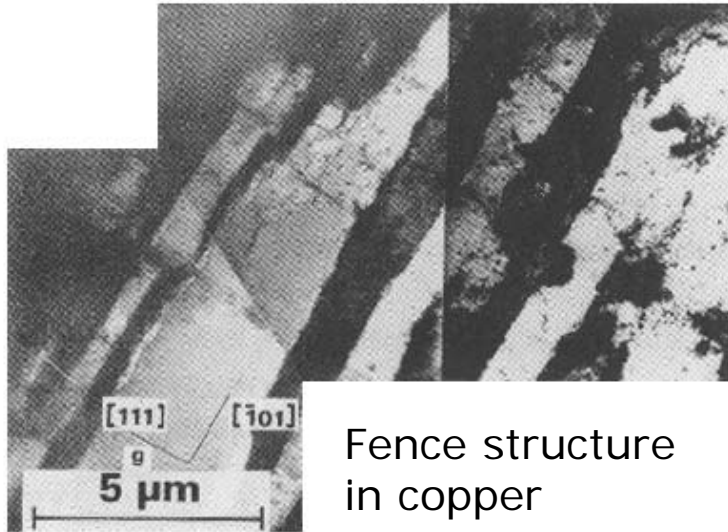
$y : \Omega \rightarrow \mathbb{R}^n$, volume preserving



- Strain-gradient effects may be expected to oppose localization
- Growth of W with respect to the second deformation gradient?

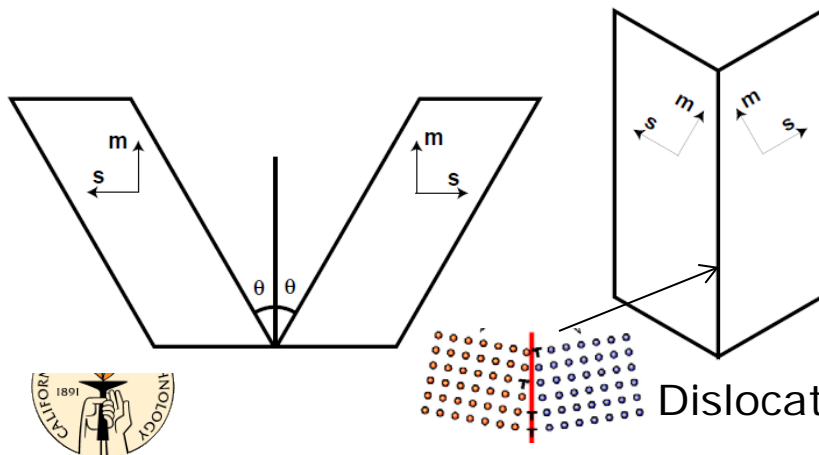


Strain-gradient plasticity



Fence structure
in copper

(J.W. Steeds, *Proc. Roy. Soc. London*,
A292, 1966, p. 343)



Dislocation wall

- Growth of $W(F, \cdot)$?

- For fence structure:

$$F^{\pm} = R^{\pm}(I \pm \tan \theta s \otimes m)$$

- Across jump planes:

$$|\llbracket F \rrbracket| = 2 \sin \theta$$

- Dislocation-wall energy:

$$E = \frac{T}{b} 2 \sin \theta = \frac{T}{b} |\llbracket F \rrbracket|$$

$\Rightarrow W(F, \cdot)$ has linear growth!



Strain-gradient plasticity

- Mathematical model: Minimize

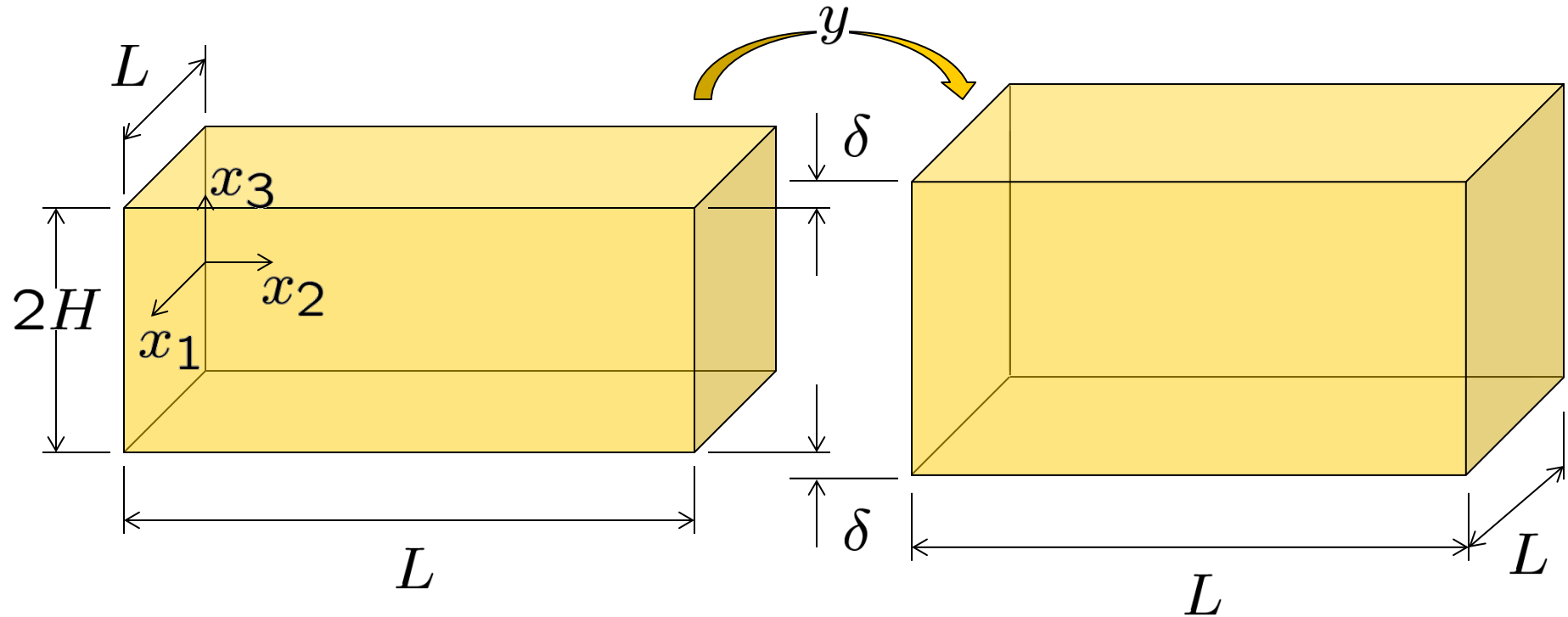
$$E(y) = \int_{\Omega} W(Dy(x), D^2y(x)) dx$$

$y : \Omega \rightarrow \mathbb{R}^n$, volume preserving

- For metals, local plasticity exhibits sub-linear growth, which favors localization of deformations
- Strain-gradient plasticity may be expected to exhibit linear growth, which opposes localization
- *Question: Can ductile fracture be understood as the result of a competition between sublinear growth and strain-gradient plasticity?*



Optimal scaling – Uniaxial extension



- Approach: Optimal scaling
- Slab: $\Omega = [0, L]^2 \times [-H, H]$, periodic
- Uniaxial extension: $y_3(x_1, x_2, \pm H) = x_3 \pm \delta$



Optimal scaling – Uniaxial extension

- $y : \Omega \rightarrow \mathbb{R}^3$, $[0, L]^2$ -periodic, volume preserving
- $y \in W^{1,1}(\Omega; \mathbb{R}^3)$, $Dy \in BV(\Omega; \mathbb{R}^{3 \times 3})$
- Growth: For $0 < K_L < K_U$, *intrinsic length* $\ell > 0$,

$$E(y) \geq K_L \left(\int_{\Omega} (|Dy|^p - 3^{p/2}) dx + \ell \int_{\Omega} |D^2 y| dx \right)$$

$$E(y) \leq K_U \left(\int_{\Omega} (|Dy|^p - 3^{p/2}) dx + \ell \int_{\Omega} |D^2 y| dx \right)$$

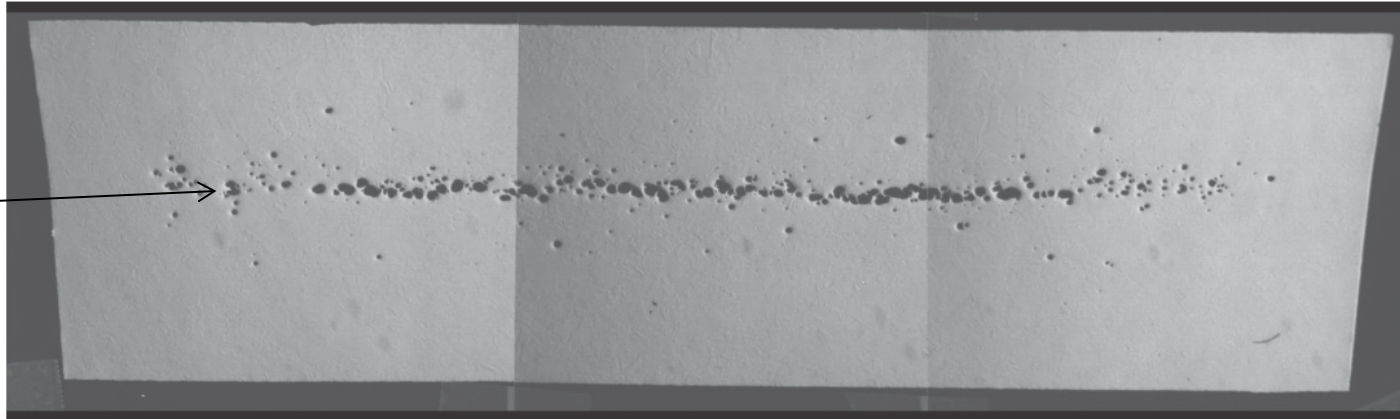
Theorem [Fokoua, Conti & MO, ARMA, 2014]. For ℓ sufficiently small, $p \in (0, 1)$, $0 < C_L(p) < C_U(p)$,

$$C_L(p) L^2 \ell^{\frac{1-p}{2-p}} \delta^{\frac{1}{2-p}} \leq \inf E \leq C_U(p) L^2 \ell^{\frac{1-p}{2-p}} \delta^{\frac{1}{2-p}}$$

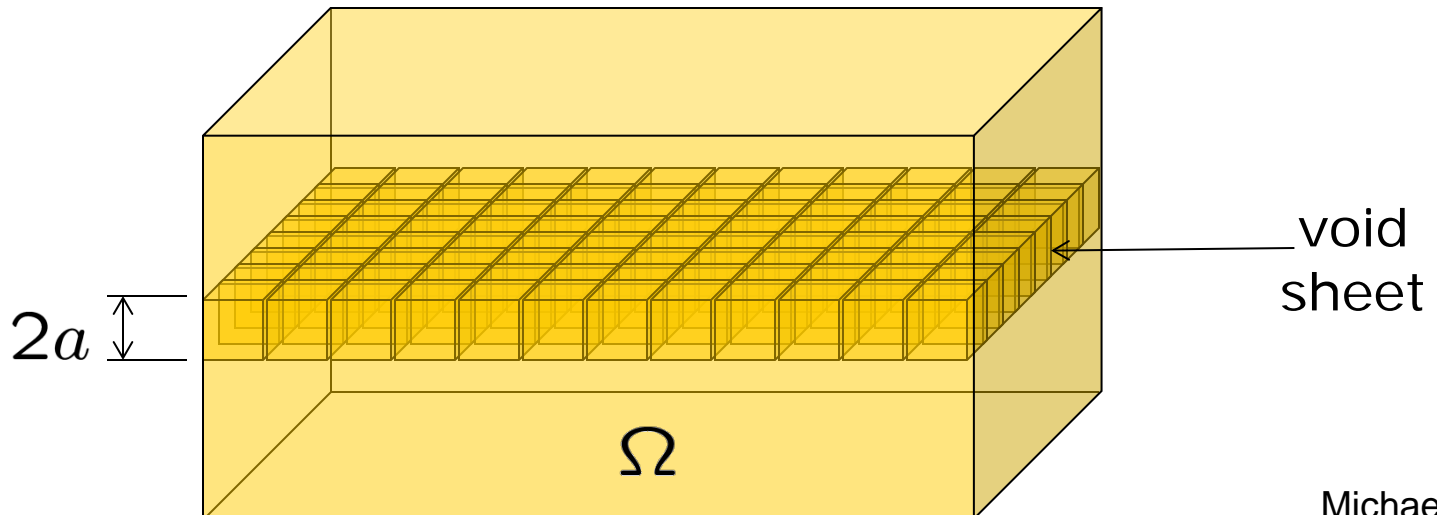


Sketch of proof – Upper bound

void
sheet



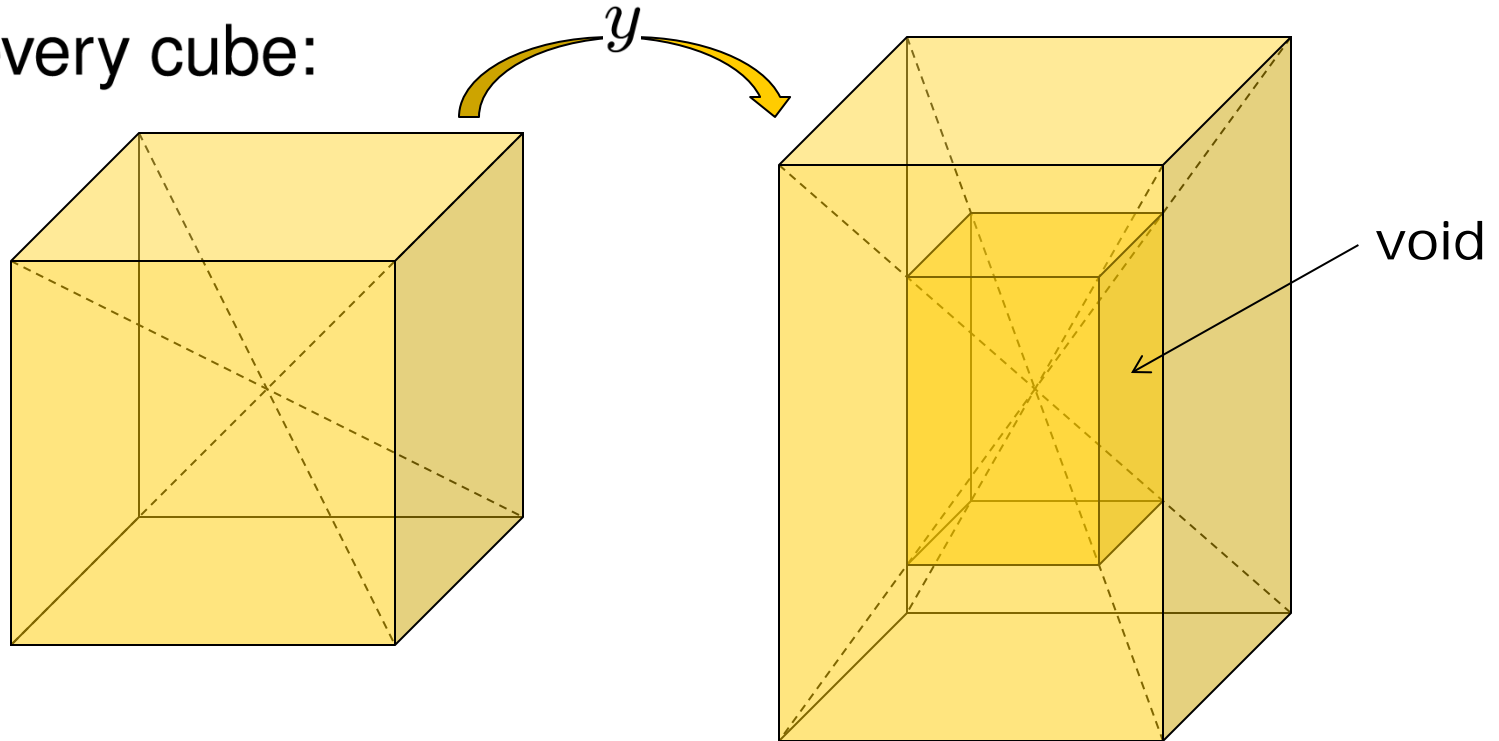
Heller, A., Science & Technology Review Magazine,
LLNL, pp. 13-20, July/August, 2002



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Sketch of proof – Upper bound

- In every cube:

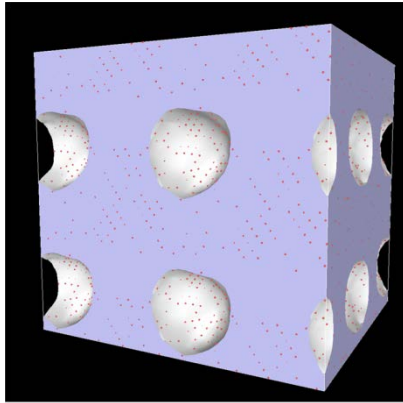


- Calculate, estimate: $E \leq CL^2 \left(a^{1-p} \delta^p + \ell \delta / a \right)$

- Optimize: $a = \left(\frac{\ell \delta^{1-p}}{1-p} \right)^{1/(2-p)} \Rightarrow E \leq C_U L^2 \ell^{\frac{1-p}{2-p}} \delta^{\frac{1}{2-p}}$

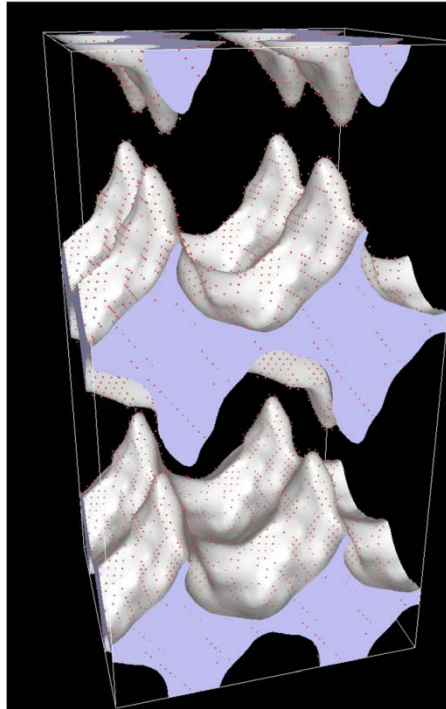


Optimal scaling – Atomic Ni

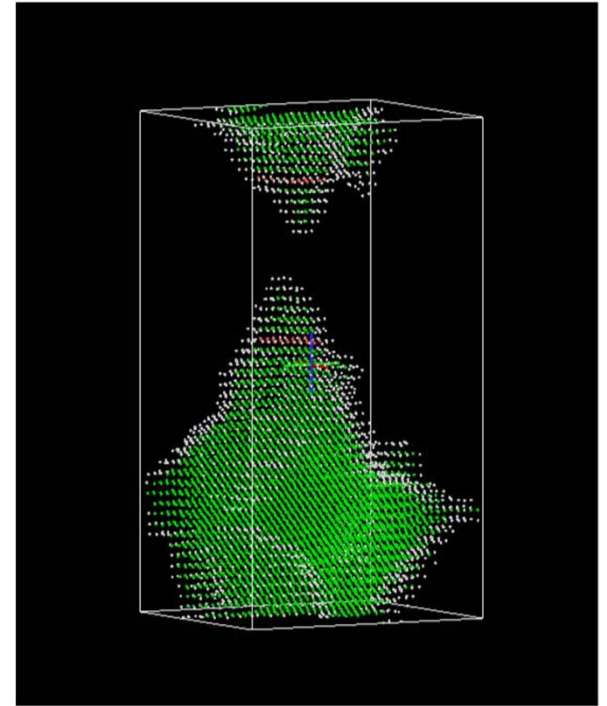


(a)

EAM Nickel,
[111] loading,
NPT 300K¹



(b)



(c)

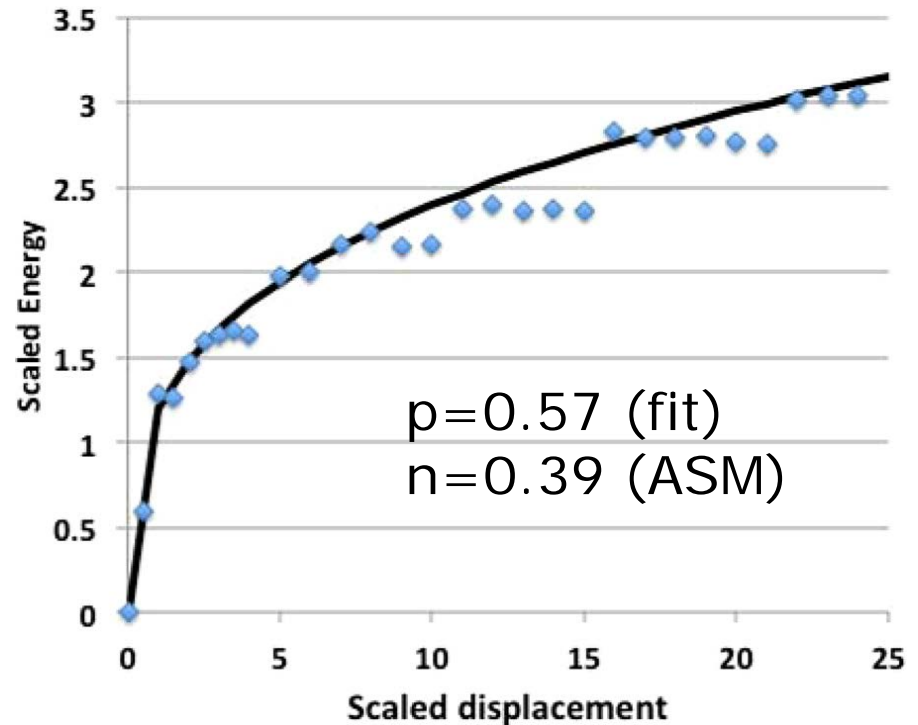
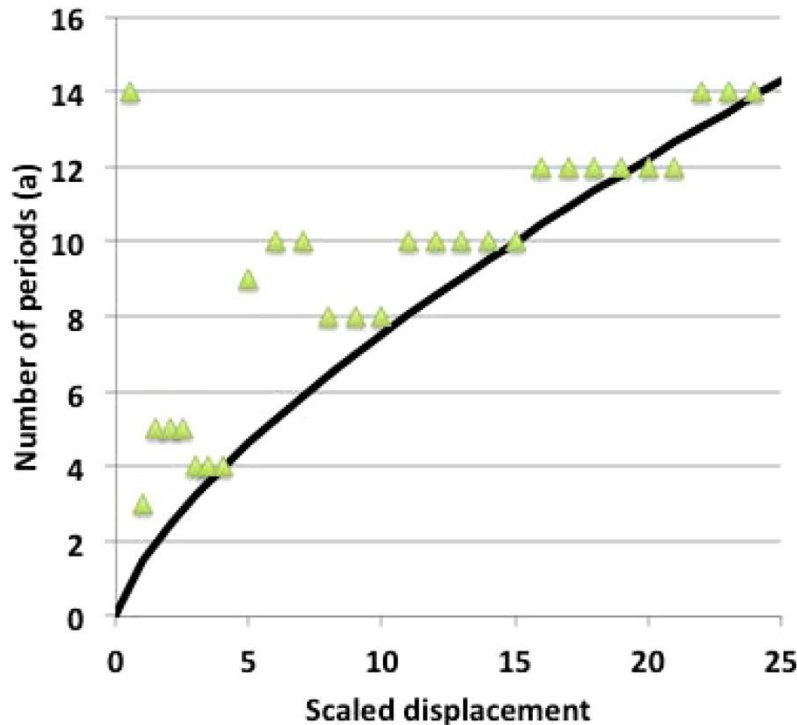
- Calculate, estimate: $E \leq CL^2 \left(a^{1-p} \delta^p + \ell \delta / a \right)$

- Optimize: $a = \left(\frac{\ell \delta^{1-p}}{1-p} \right)^{1/(2-p)} \Rightarrow E \leq C_U L^2 \ell^{\frac{1-p}{2-p}} \delta^{\frac{1}{2-p}}$



¹M.I. Baskes and M. Ortiz, *JAM*, **82**: 071003-1-071003-5, 2015

Optimal scaling – Atomic Ni



• Calculate, estimate: $E \leq CL^2 \left(a^{1-p} \delta^p + \ell \delta / a \right)$

• Optimize: $a = \left(\frac{\ell \delta^{1-p}}{1-p} \right)^{1/(2-p)} \Rightarrow E \leq C_U L^2 \ell^{\frac{1-p}{2-p}} \delta^{\frac{1}{2-p}}$



Optimal scaling – Uniaxial extension

- Optimal (matching) upper and lower bounds:

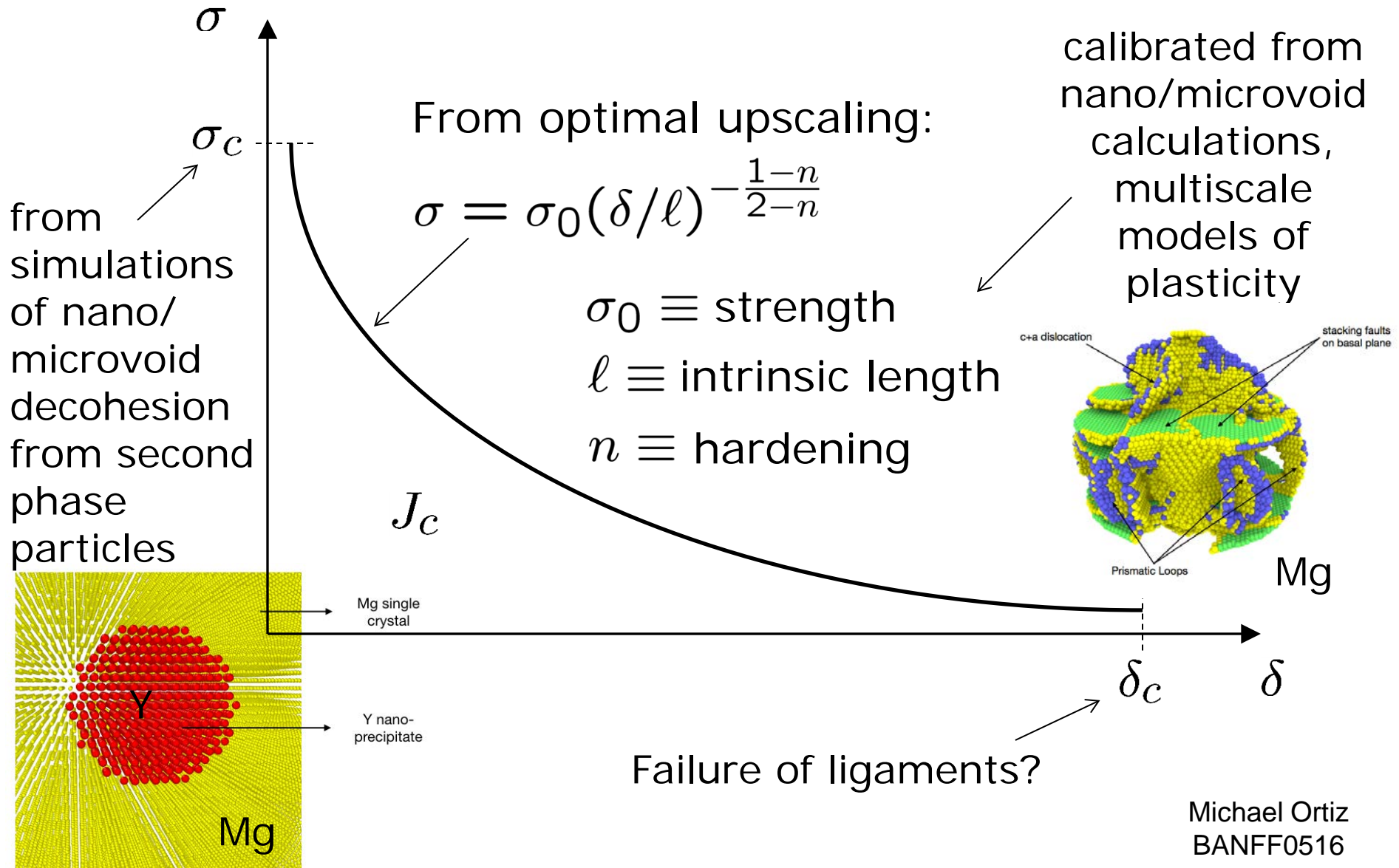
$$C_L(p)L^2\ell^{\frac{1-p}{2-p}}\delta^{\frac{1}{2-p}} \leq \inf E \leq C_U(p)L^2\ell^{\frac{1-p}{2-p}}\delta^{\frac{1}{2-p}}$$

- Bounds apply to *classes of materials* having the same growth, specific model details immaterial
- Energy scales with *area* (L^2): Fracture scaling!
- Energy scales with power of *opening displacement* (δ): Cohesive behavior!
- Lower bound degenerates to 0 when the intrinsic length (ℓ) decreases to zero...
- Bounds on cohesive energy:

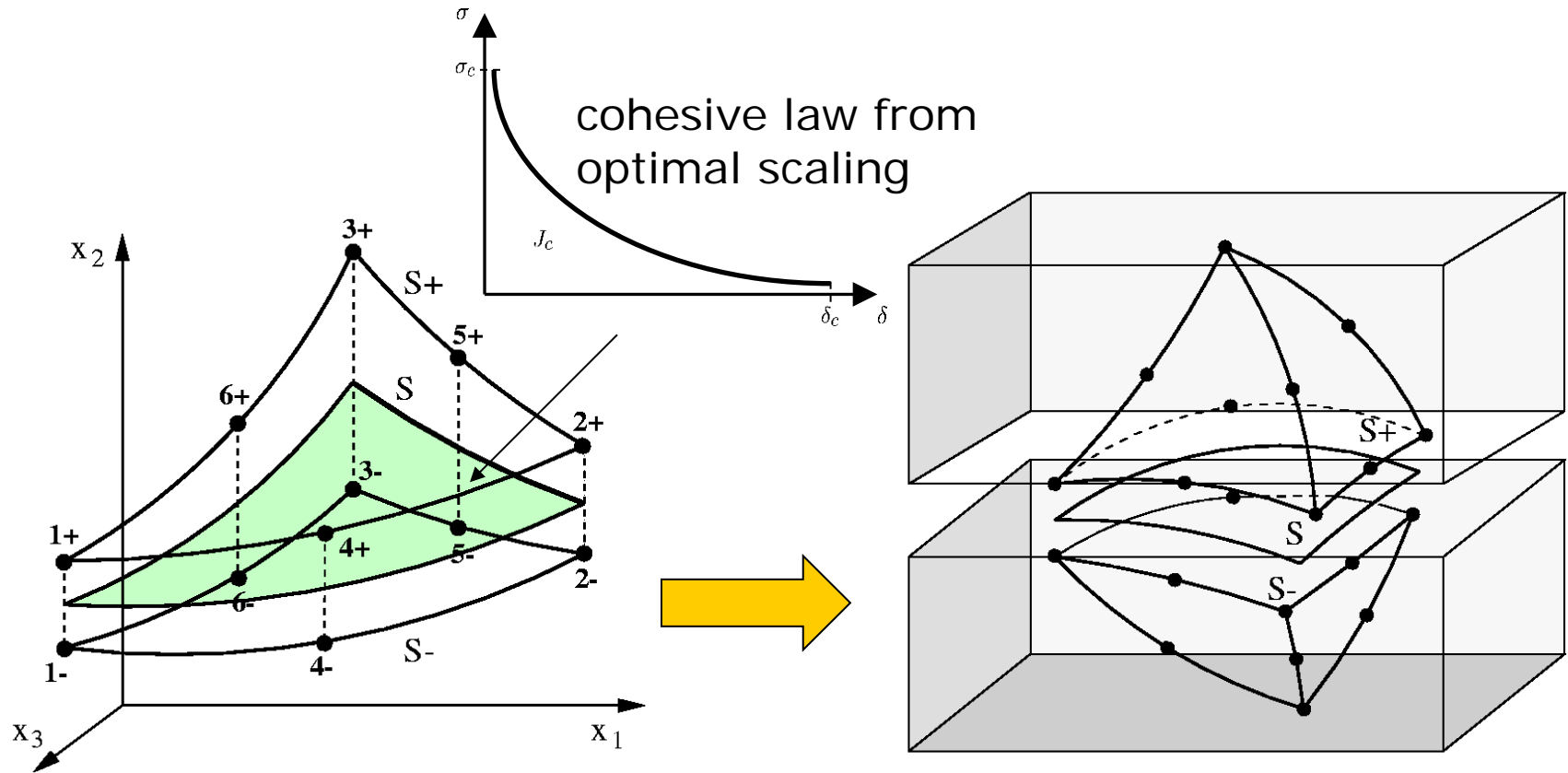
$$C_L(p)\ell^{\frac{1-p}{2-p}}\delta^{\frac{1}{2-p}} \leq \Phi(\delta) \leq C_U(p)\ell^{\frac{1-p}{2-p}}\delta^{\frac{1}{2-p}}$$



Upscaling: Effective cohesive law



Implementation: Cohesive elements

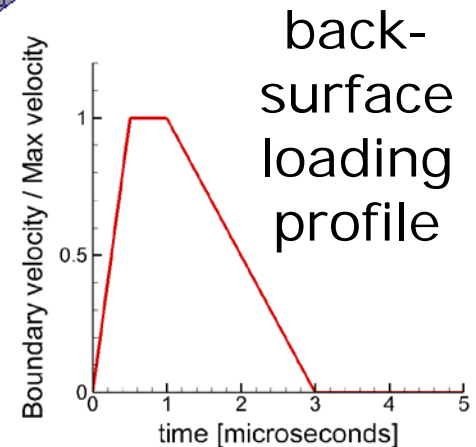
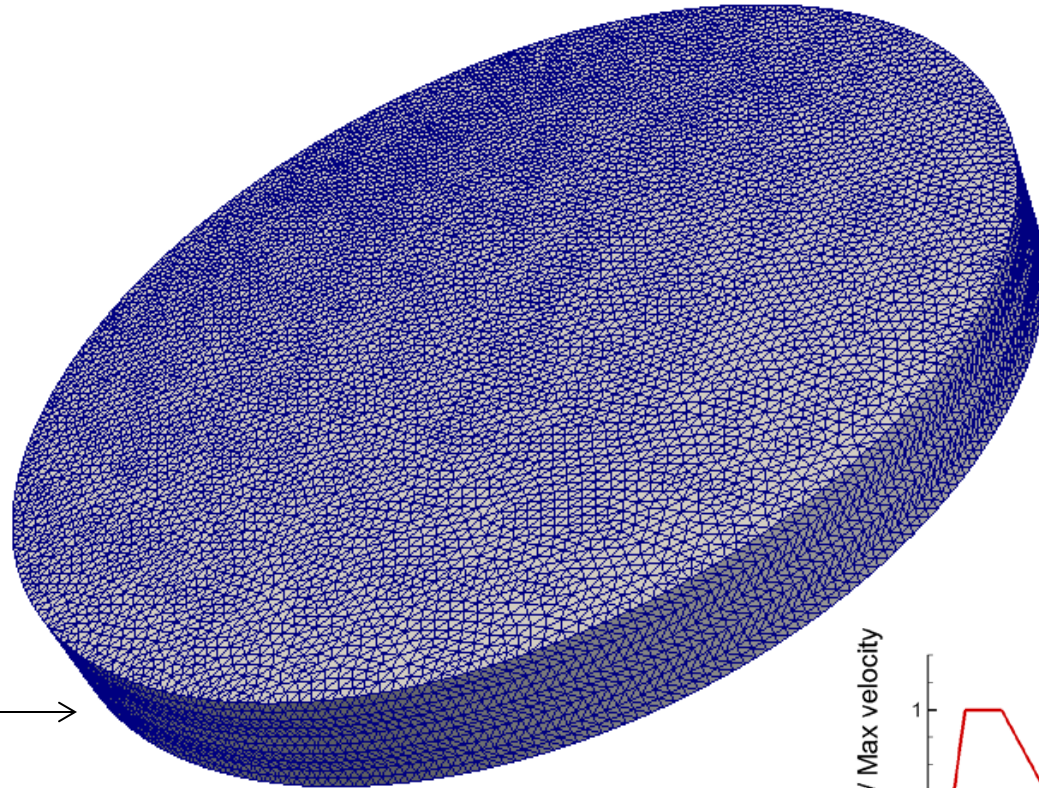
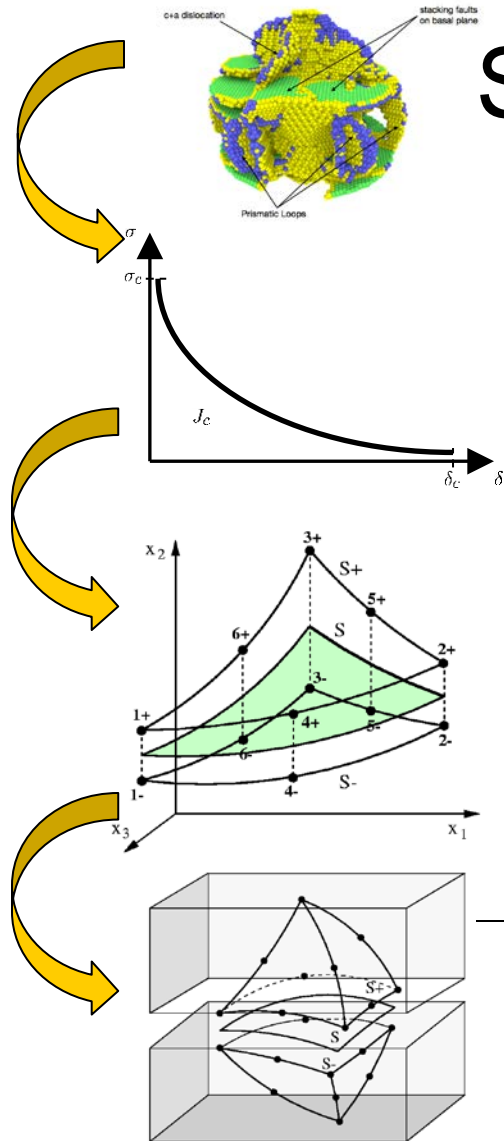


12-node quadratic
cohesive elements

Insertion of cohesive element
between two volume elements



Spall fracture simulations

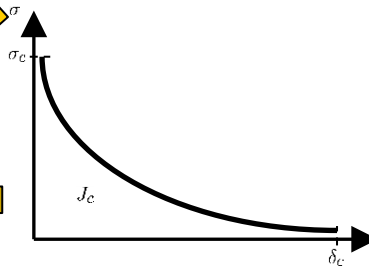
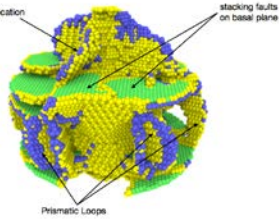


- Ni specimen, $D = 50$ mm, $t = 4.95$ mm
- J2 plasticity, power-law hardening
- $h = 0.49$ mm, 191,960 tets, 456,262 nodes

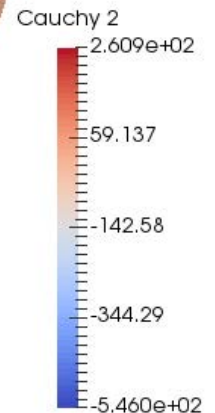
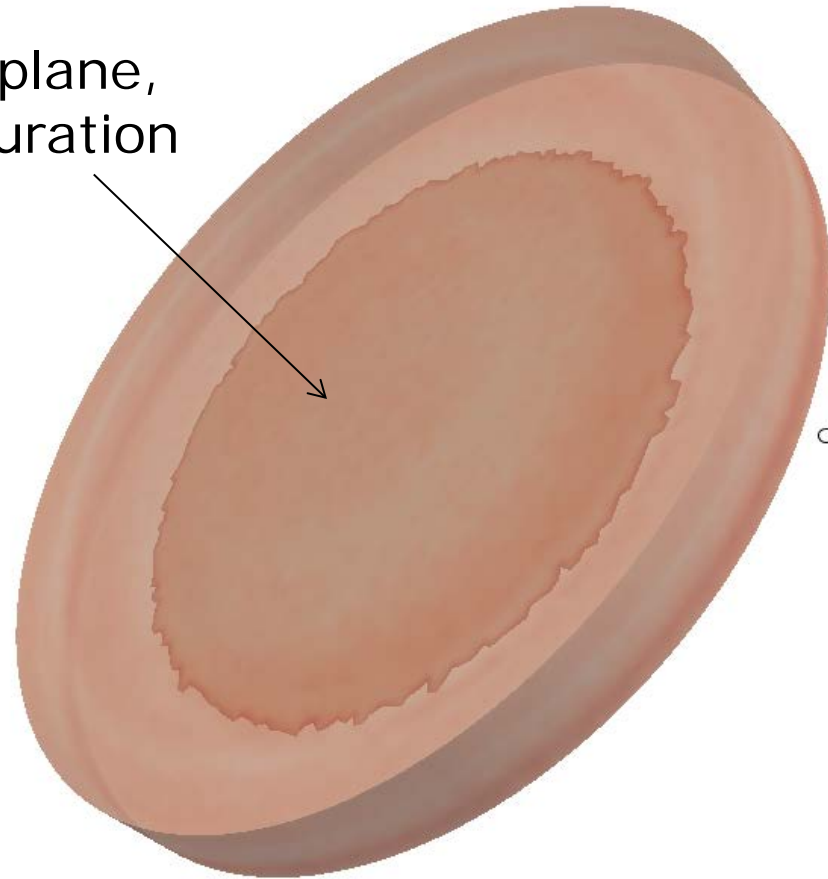
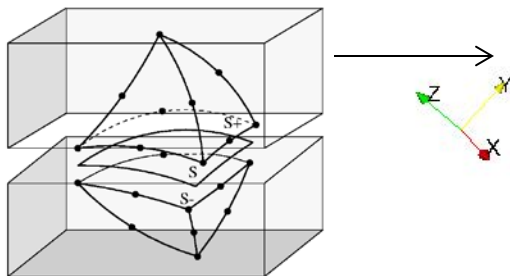
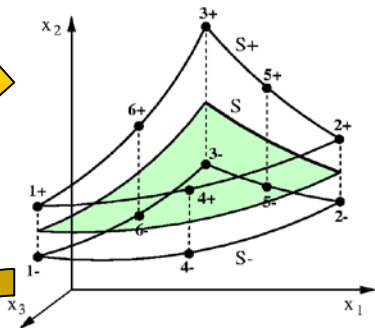


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Spall fracture simulations



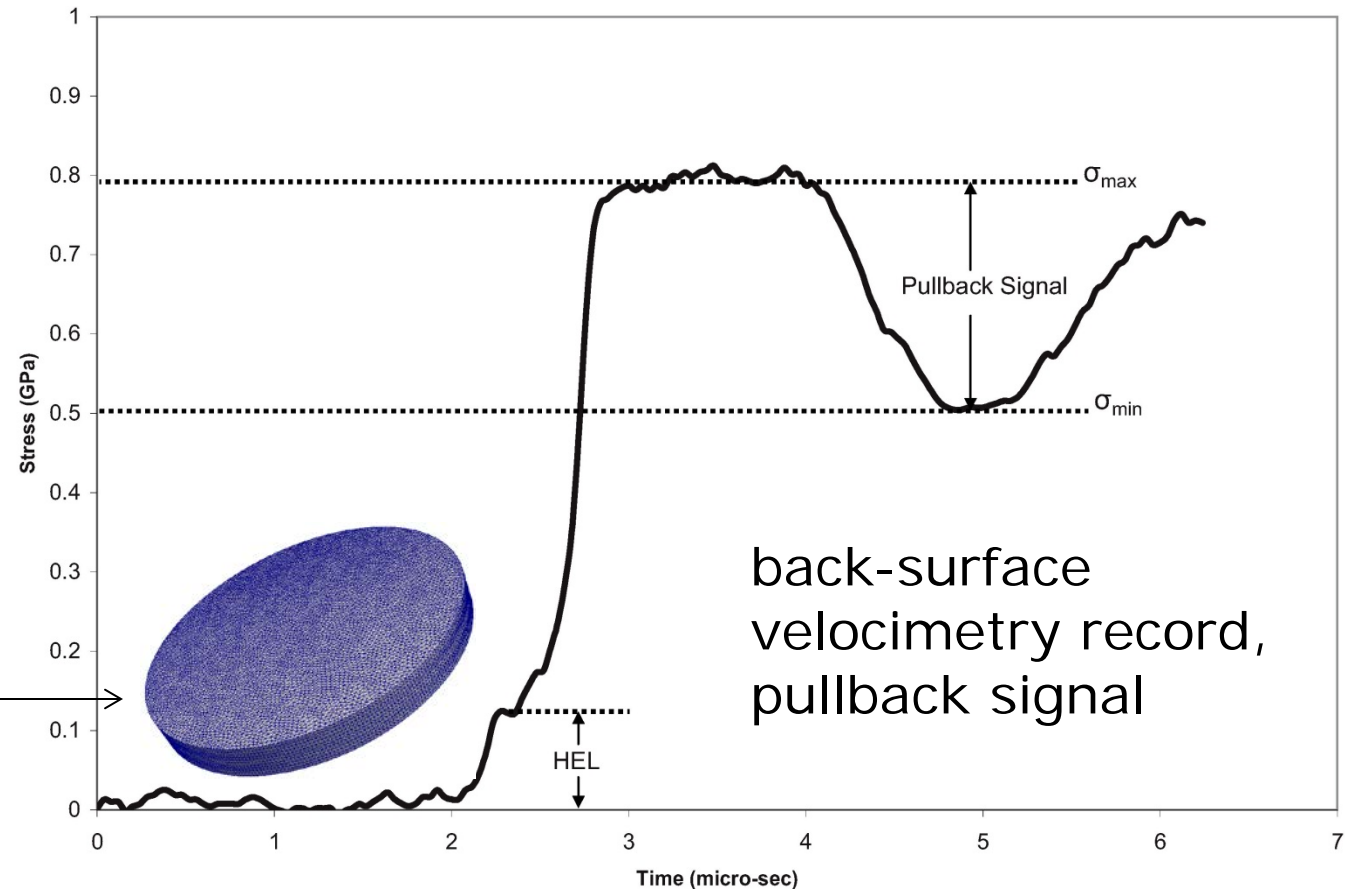
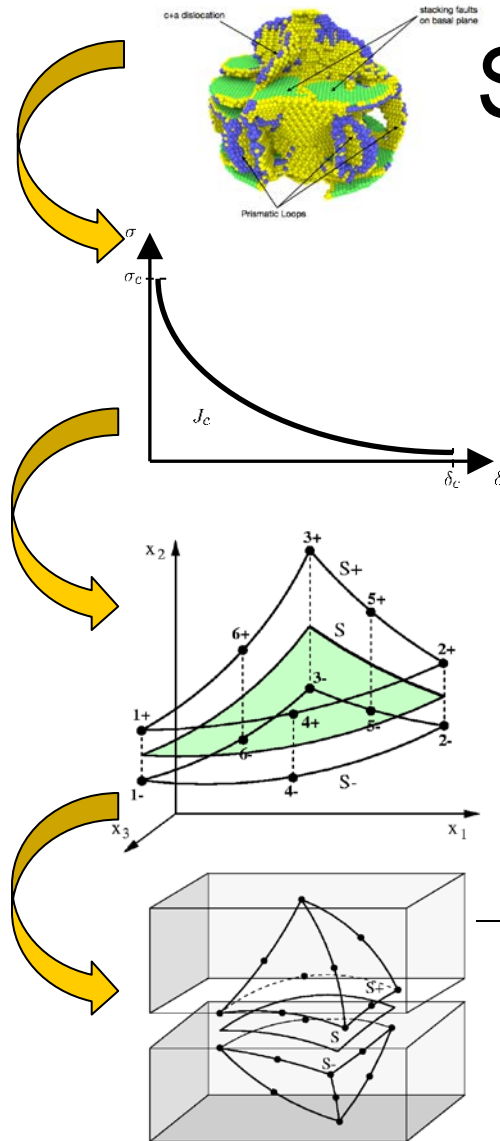
spall plane,
final configuration



- Ni specimen, $D = 50 \text{ mm}$, $t = 4.95 \text{ mm}$
- J2 plasticity, power-law hardening
- $h = 0.49 \text{ mm}$, 191,960 tets, 456,262 nodes



Spall fracture simulations



- Ni specimen, $D = 50 \text{ mm}$, $t = 4.95 \text{ mm}$
- J2 plasticity, power-law hardening
- $h = 0.49 \text{ mm}$, 191,960 tets, 456,262 nodes

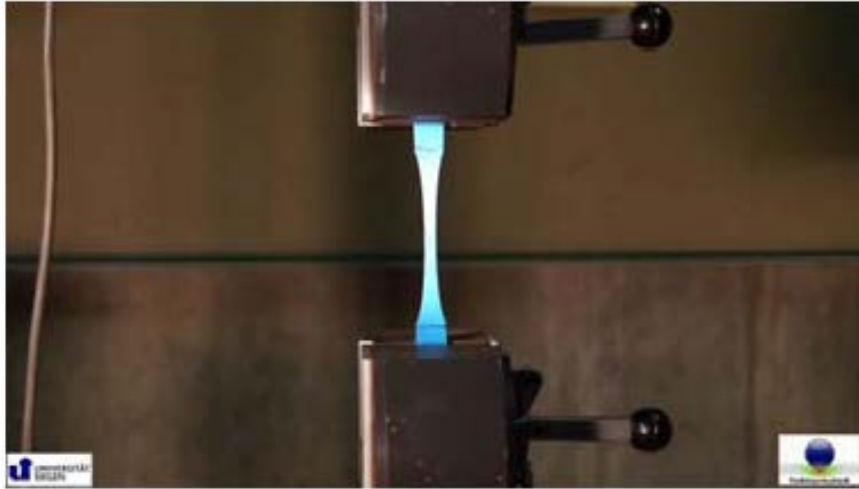




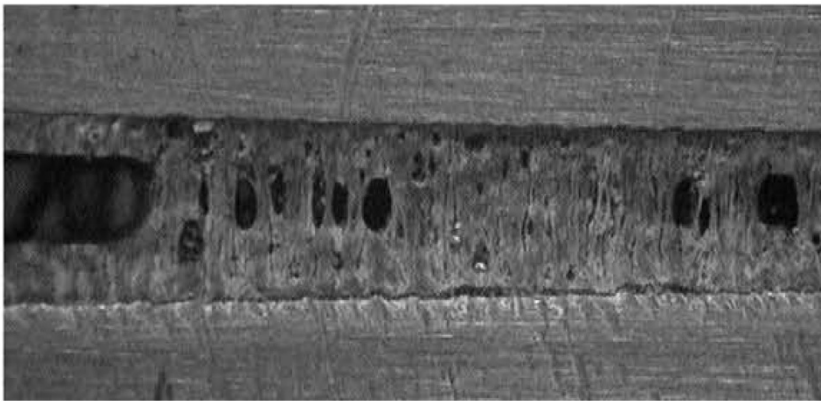
INTERMISSION



Fracture of polymers



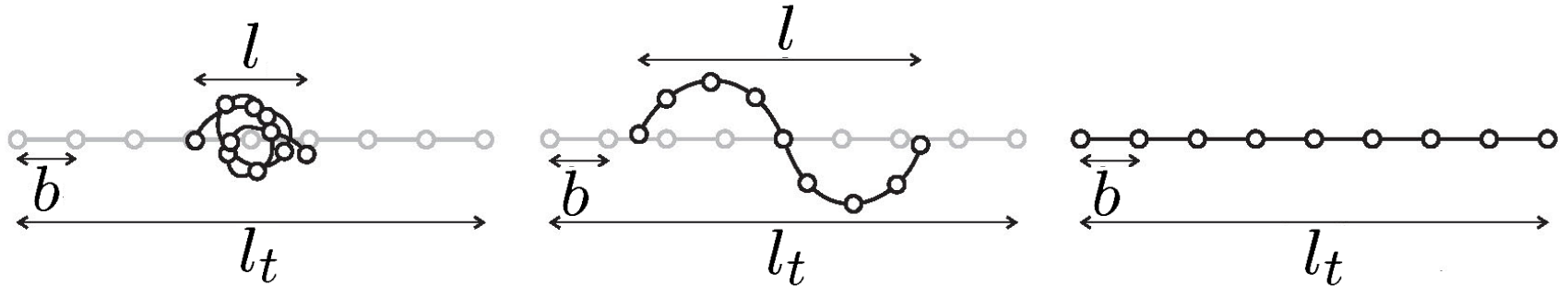
T. Reppel, T. Dally, T. and K. Weinberg,
Technische Mechanik, 33 (2012) 19-33.



Crazing in steel/polyurea/steel
sandwich specimen (Zhu *et al.*, 2008).

- Polymers undergo entropic elasticity and damage due to chain stretching and failure
- Polymers fracture by means of the crazing mechanism consisting of fibril nucleation, stretching and failure
- The free energy density of polymers saturates in tension once the majority of chains are failed: $p=0$!
- Crazing mechanism is incompatible with strain-gradient elasticity...

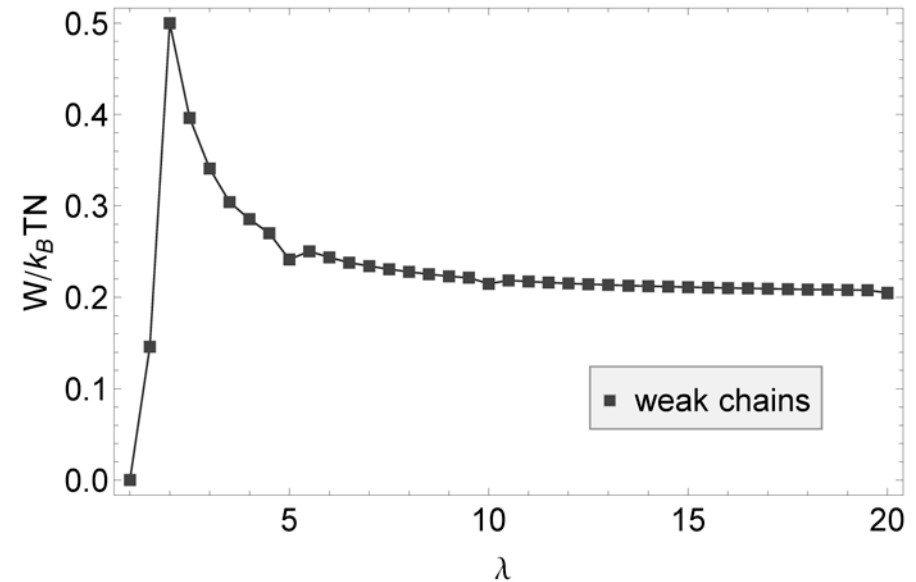
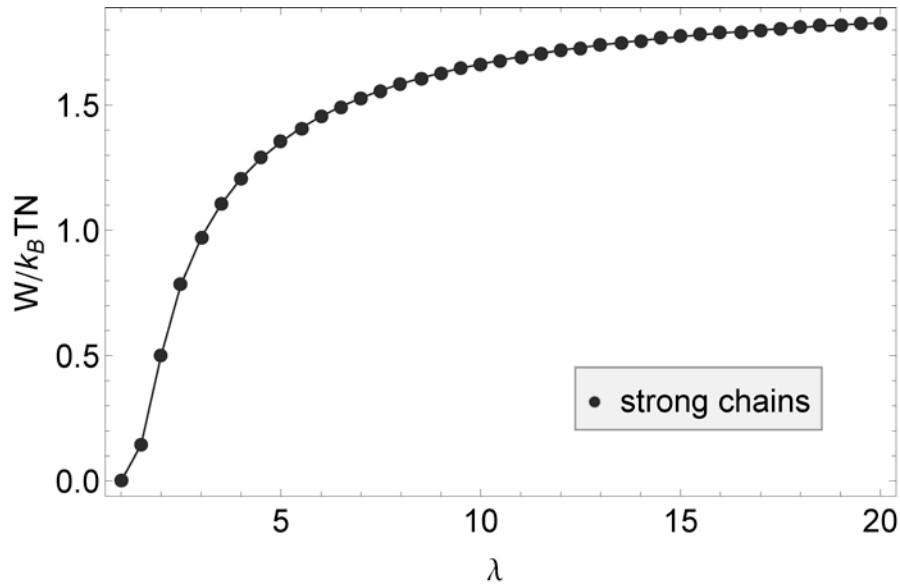
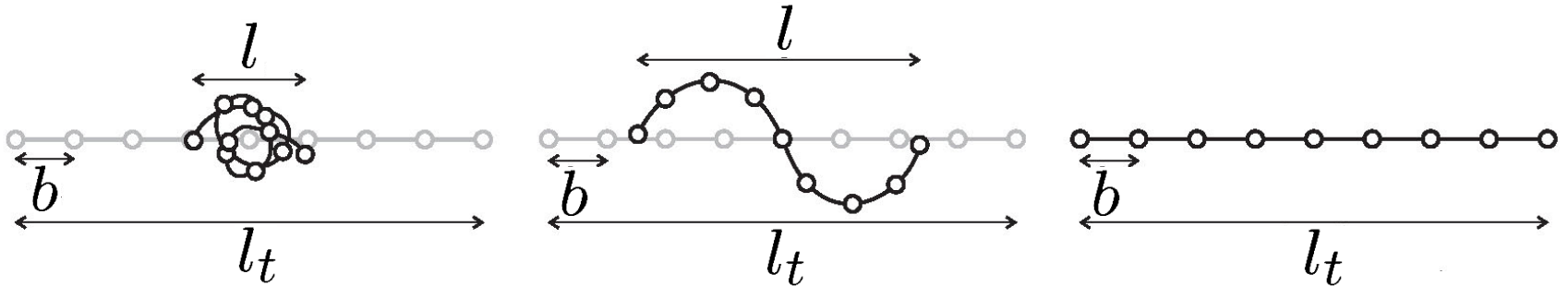
Network theory of polymer elasticity



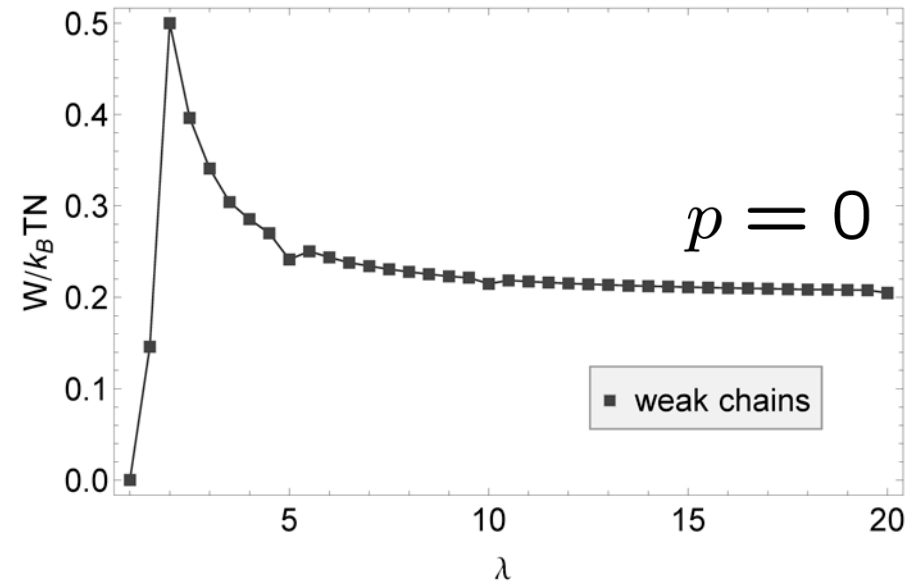
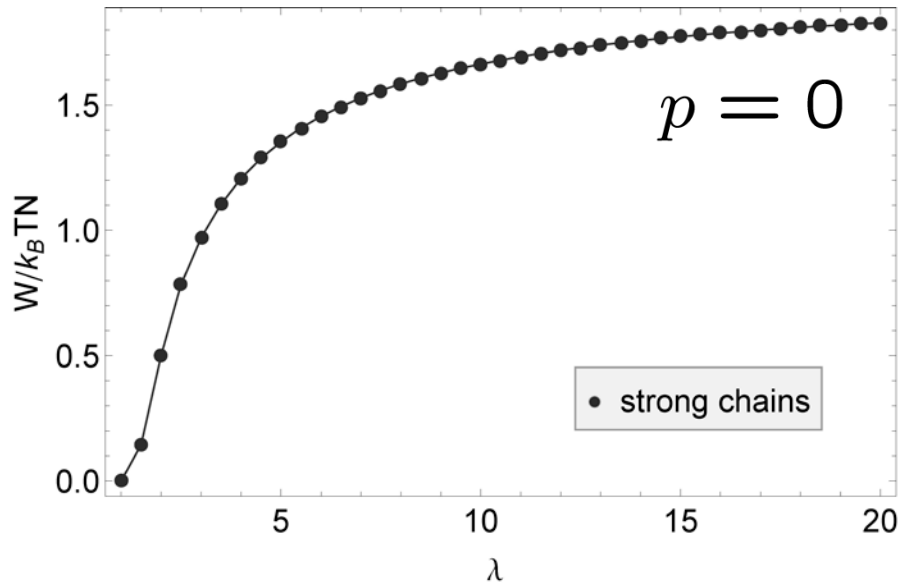
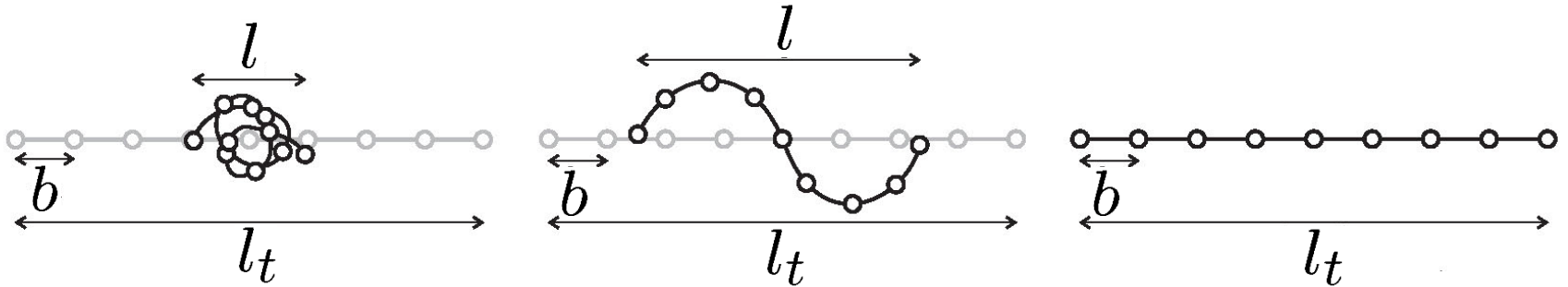
- Polymer: Cross-linked long-chain molecules
- Chains: Freely jointed, far from full extension
- Cross-linking points follow macroscopic def.
- Polymer nearly incompressible
- *Chain links break at critical elongation*



Network theory of polymers



Network theory of polymers



Energy has zero growth!

Fracture of polymers

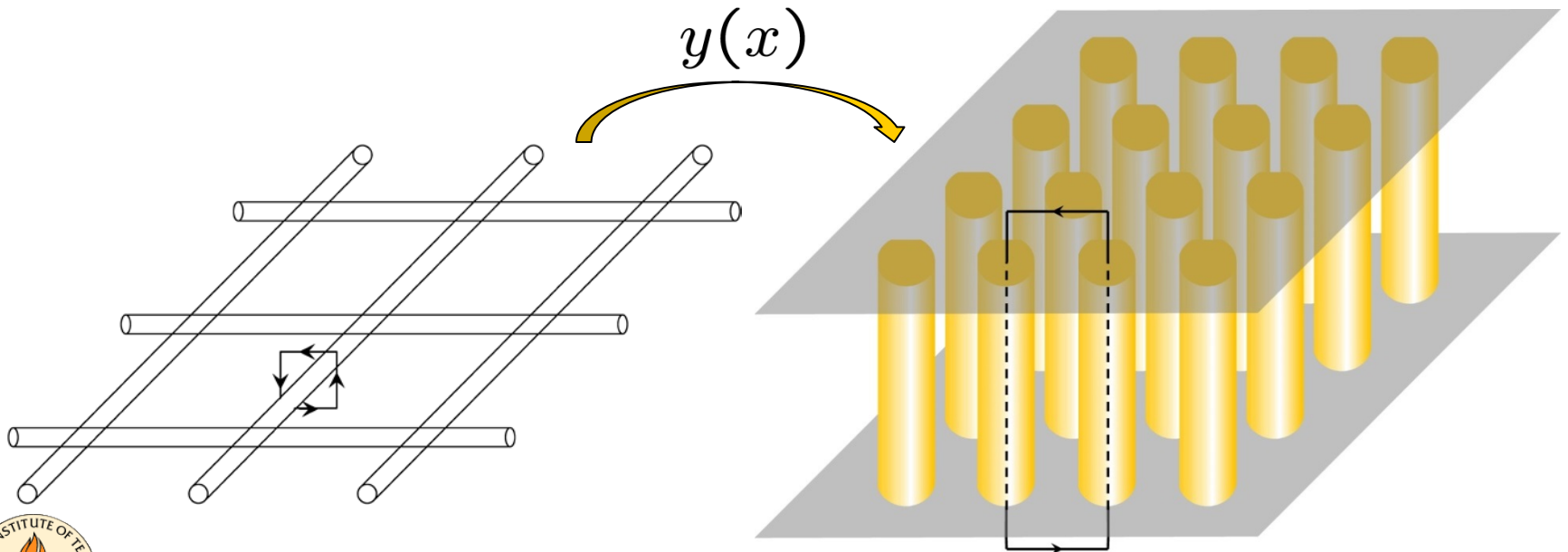
- Suppose: For $K_L > 0$, *intrinsic length* $\ell > 0$, $p \approx 0$,
$$E(y) \geq K_L \left(\int_{\Omega} (|Dy|^p - 3^{p/2}) dx + \ell \int_{\Omega} |D^2 y| dx \right)$$
- If $E(y) < +\infty$: $y \in W^{1,1}(\Omega) \Rightarrow$ No crazing!

Strain-gradient elasticity
precludes crazing!



Fracture of polymers

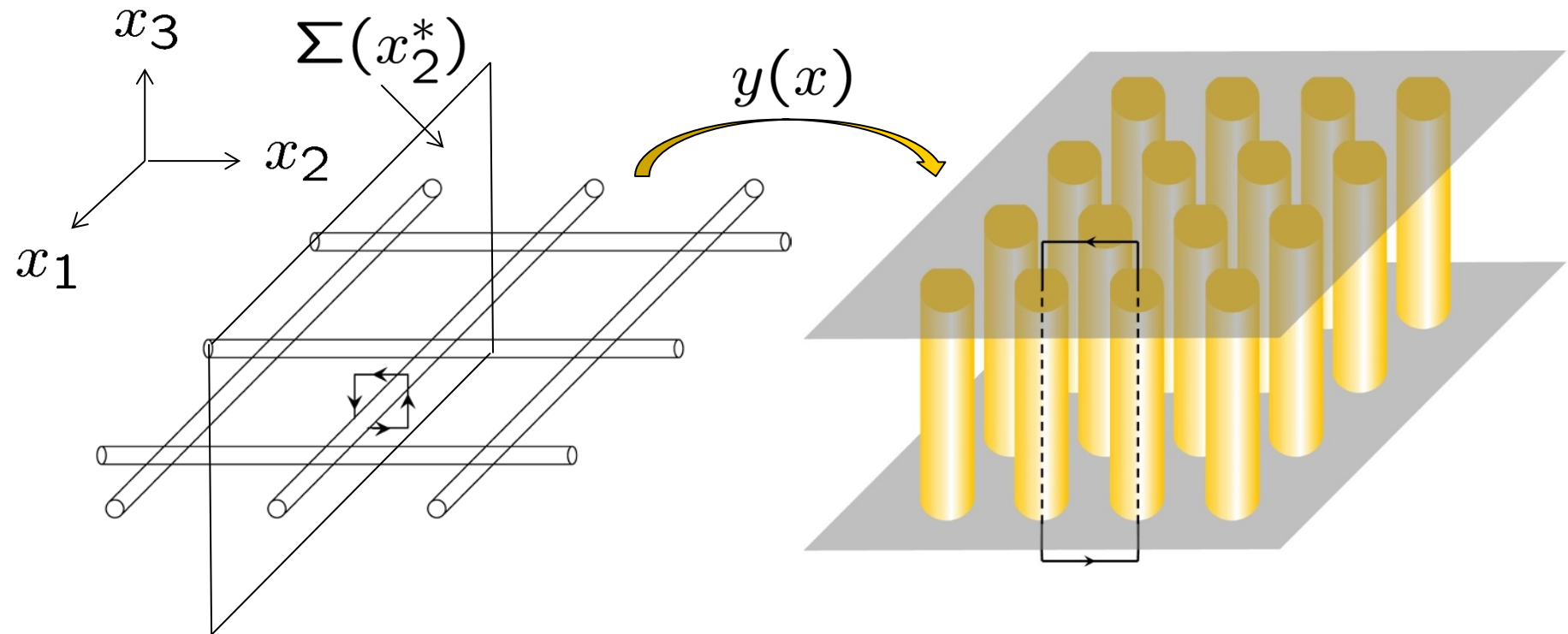
- Suppose: For $K_L > 0$, *intrinsic length* $\ell > 0$,
$$E(y) \geq K_L \left(\int_{\Omega} (|Dy|^p - 3^{p/2}) dx + \ell \int_{\Omega} |D^2 y| dx \right)$$
- If $E(y) < +\infty$: $y \in W^{1,1}(\Omega) \Rightarrow$ No crazing!



Topology of crazing



The topology of crazing



• Suppose $y \in W^{1,1}(\Omega)$, $|D^2y|(\Omega) < +\infty$.

\Rightarrow For every $x_2^* \in (0, L)$: $v(x_1, x_3) = y(x_1, x_2^*, x_3)$,

$v \in W^{1,1}$ and $|D^2v|(\Sigma(x_2^*)) < +\infty$,



$\Rightarrow v$ continuous and $v(\Sigma(x_2^*))$ simply connected!

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Fracture of polymers

- Suppose: For $K_U > 0$, *intrinsic length* $\ell > 0$,

$$E(y) \geq K_L \left(\int_{\Omega} (|Dy|^p - 3^{p/2}) dx + \ell \int_{\Omega} |D^2 y| dx \right)$$
- If $E(y) < +\infty$: $y \in W^{1,1}(\Omega) \Rightarrow$ No crazing!
- Instead suppose: For $\sigma \in (0, 1)$,

$$E(y) \leq K_U \left(\int_{\Omega} (|Dy|^p - 3^{p/2}) dx + \ell^\sigma |y|_{W^{1+\sigma,1}(\Omega)} \right)$$

 \Rightarrow *Fractional strain-gradient elasticity!*

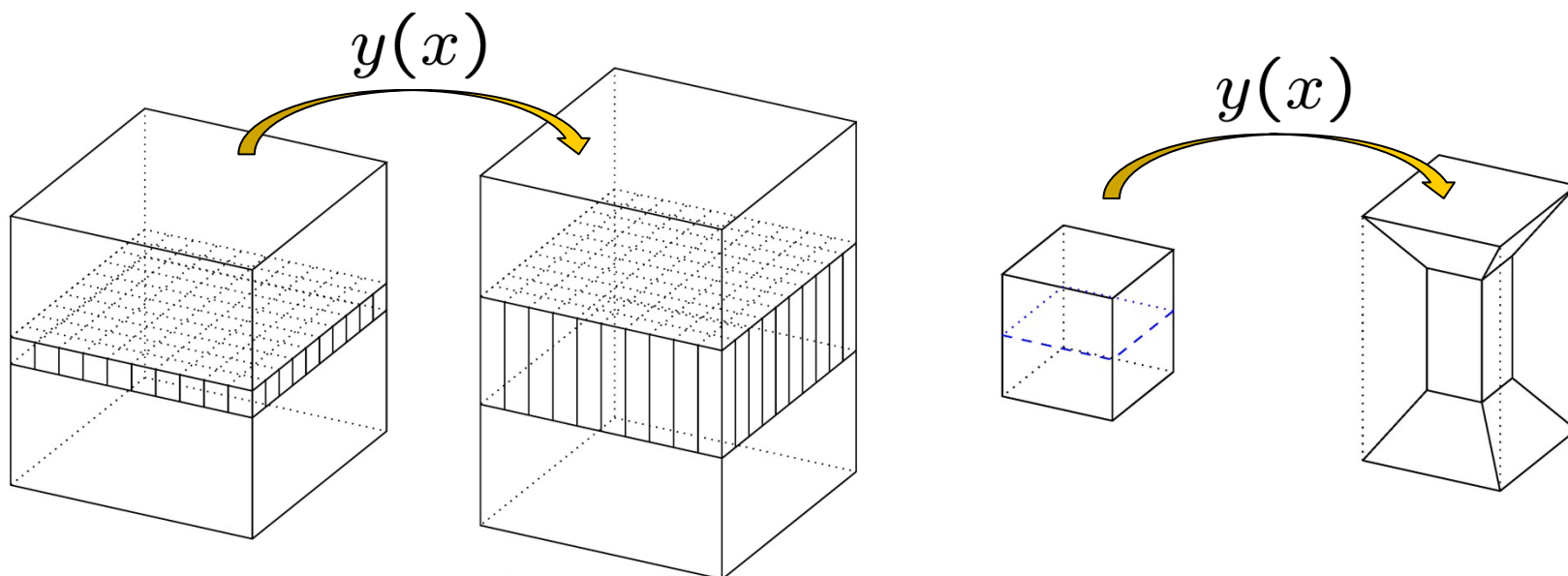
Theorem [Conti & MO, 2016]. For ℓ sufficiently small,
 $p = 0$, $\sigma \in (0, 1)$, $0 < C_L < C_U$,

$$C_L L^2 \ell^{\frac{\sigma}{1+\sigma}} \delta^{\frac{1}{1+\sigma}} \leq \inf E \leq C_U L^2 \ell^{\frac{\sigma}{1+\sigma}} \delta^{\frac{1}{1+\sigma}}$$

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Sketch of proof: Upper bound

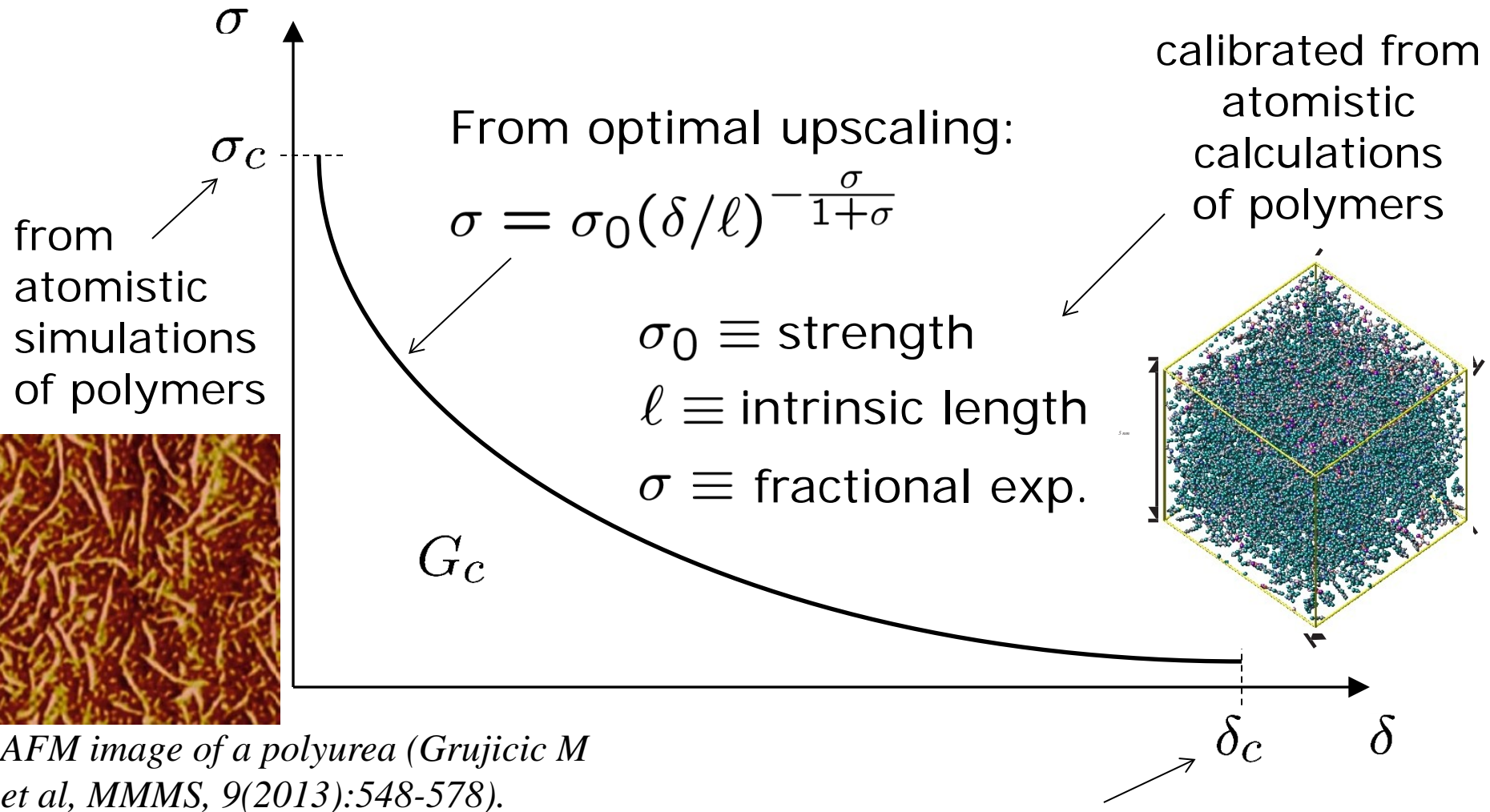


• Calculate, estimate: $E \leq CL^2 (1 + c_\sigma \ell^\sigma \delta / a^\sigma)$

• Optimize: $a = \frac{1}{2}(\delta \ell^\sigma)^{1/(1+\sigma)} \Rightarrow E \leq C_U L^2 \ell^{\frac{\sigma}{1+\sigma}} \delta^{\frac{1}{1+\sigma}}$



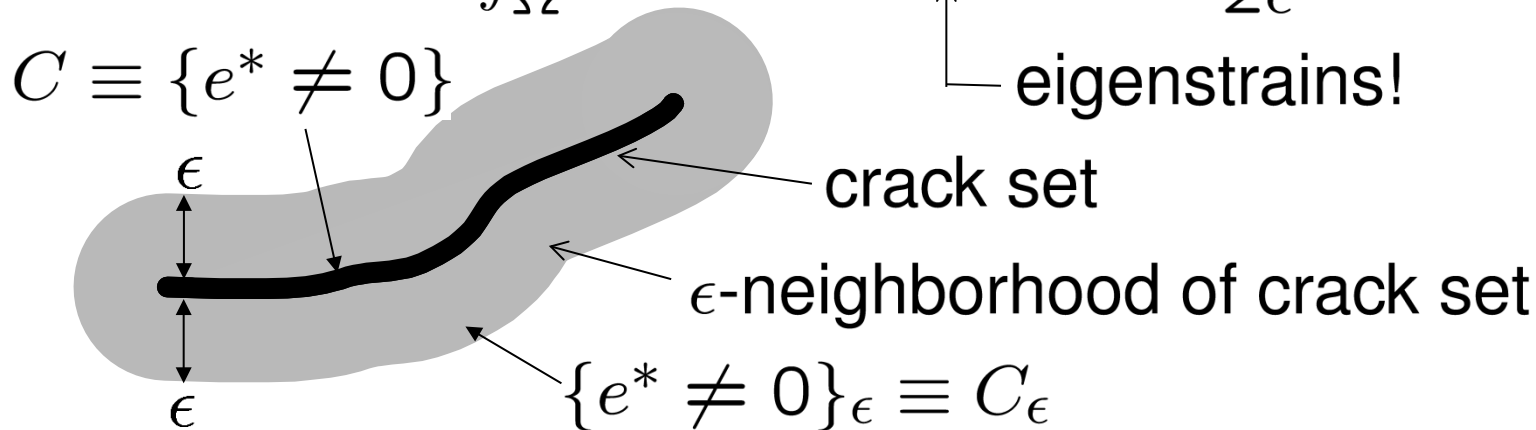
Upscaling: Effective cohesive law



Implementation: Eigenfracture

- Regard fracture as an energy-relaxation process!
- Total incremental energy¹: Elastic + fracture,

$$E_\epsilon(u, e^*) = \int_\Omega W(e(u) - \underline{e^*}) dx + \frac{G_c}{2\epsilon} |\{e^* \neq 0\}_\epsilon|$$



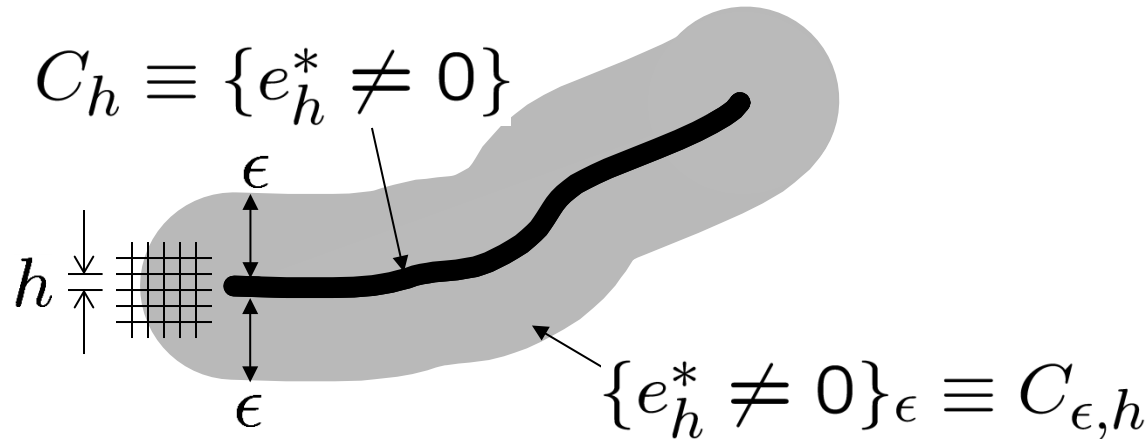
- Energy-minimizing cracks: $E_\epsilon(u, e^*) \rightarrow \inf!$
- **Theorem**¹: $\Gamma\text{-}\lim_{\epsilon \rightarrow 0} E_\epsilon = \text{Griffith energy}$



¹Schmidt, B., *et al.*, *SIAM Multi. Model.*, **7** (2009) 1237.

Implementation: Eigenfracture

- Spatial discretization:



- Discretized incremental energy:

$$E_{\epsilon,h}(u, e^*) = \begin{cases} E_\epsilon(u, e^*), & \text{if } u \in V_h, e^* \in W_h, \\ +\infty, & \text{otherwise.} \end{cases}$$

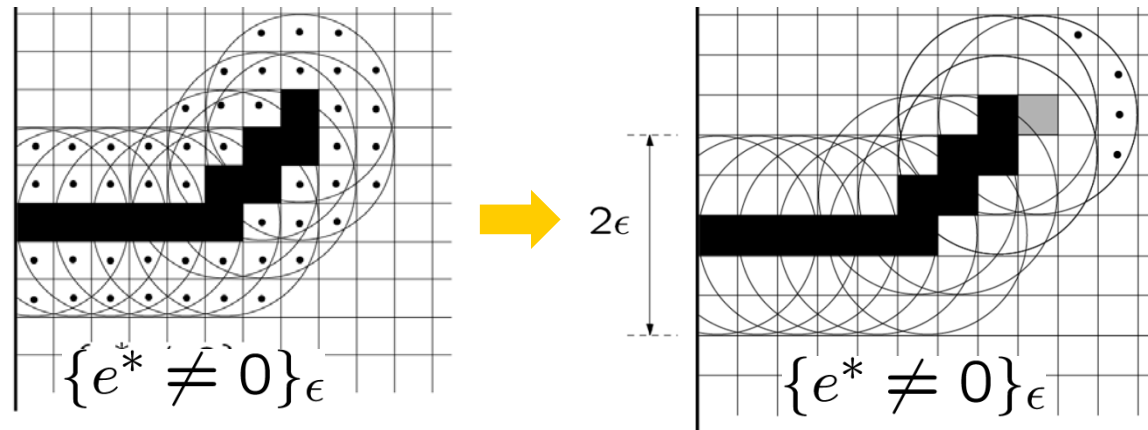
- **Theorem**¹: Suppose $\epsilon = \epsilon(h)$ and $h/\epsilon(h) \rightarrow 0$ as $h \rightarrow 0$. Then, $\Gamma\text{-}\lim_{h \rightarrow 0} E_{h,\epsilon(h)} = \text{Griffith energy}$



¹Schmidt, B., *et al.*, *SIAM Multi. Model.*, **7** (2009) 1237.

Implementation: Eigenerosion

- For every element K , choose^{1,2}
 - either: $e_K^* = e(u_K) \Rightarrow$ element erosion,
 - or: $e_K^* = 0 \Rightarrow$ intact element.
- Erosion criterion: $-\Delta E_K \geq \frac{G_c}{2\epsilon} \underbrace{|(C \subset K)_\epsilon \setminus C_\epsilon|}$



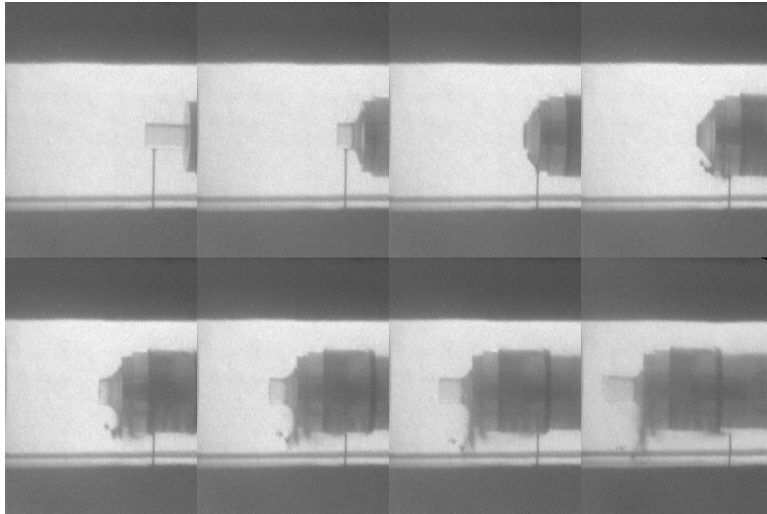
- To first order^{1,2}: $-\Delta E_K \sim$ energy in element K

¹Pandolfi, A. & Ortiz, M. , *IJNME*, **92** (2012) 694.

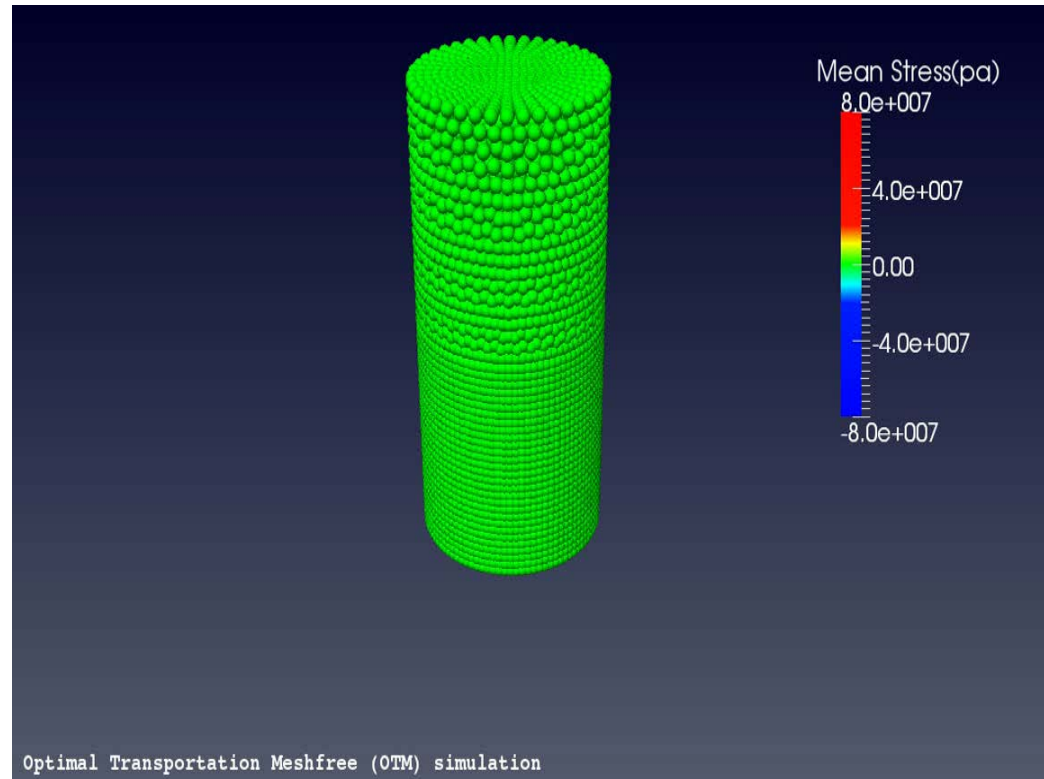
²Pandolfi, A., Li, B. & Ortiz, M. , *Int. J. Fract.*, **184** (2013) 3.



Taylor-anvil tests on polyurea



Shot #854:
 $R_0 = 6.3075 \text{ mm}$,
 $L_0 = 27.6897 \text{ mm}$,
 $v = 332 \text{ m/s}$

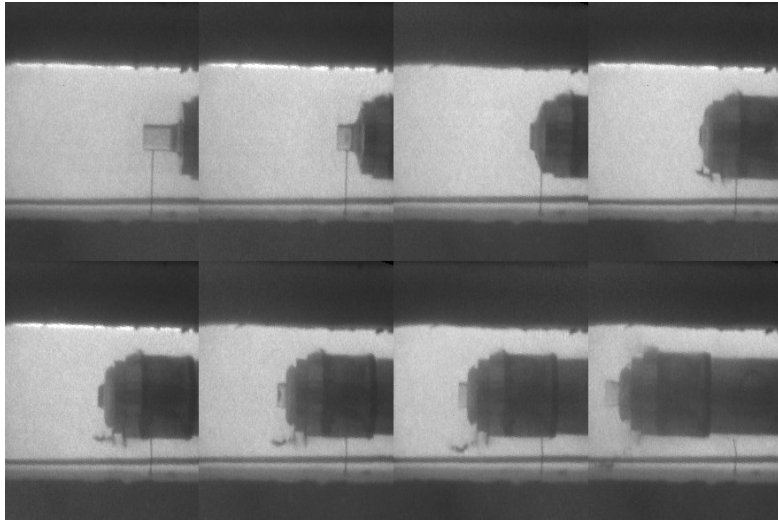


Experiments conducted by W. Mock, Jr. and J. Drotar,
at the Naval Surface Warfare Center (Dahlgren Division)
Research Gas Gun Facility, Dahlgren, VA 22448-5100, USA

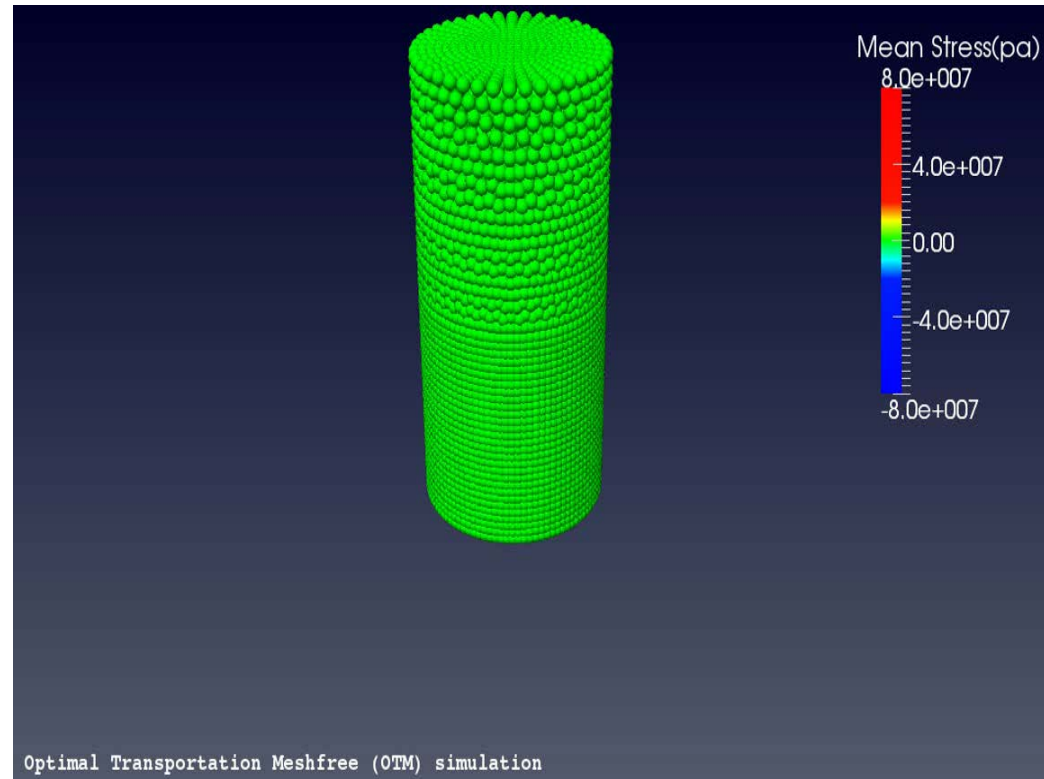


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Experiments and simulations



Shot #861:
 $R0 = 6.3039 \text{ mm}$,
 $L0 = 27.1698 \text{ mm}$,
 $v = 424 \text{ m/s}$

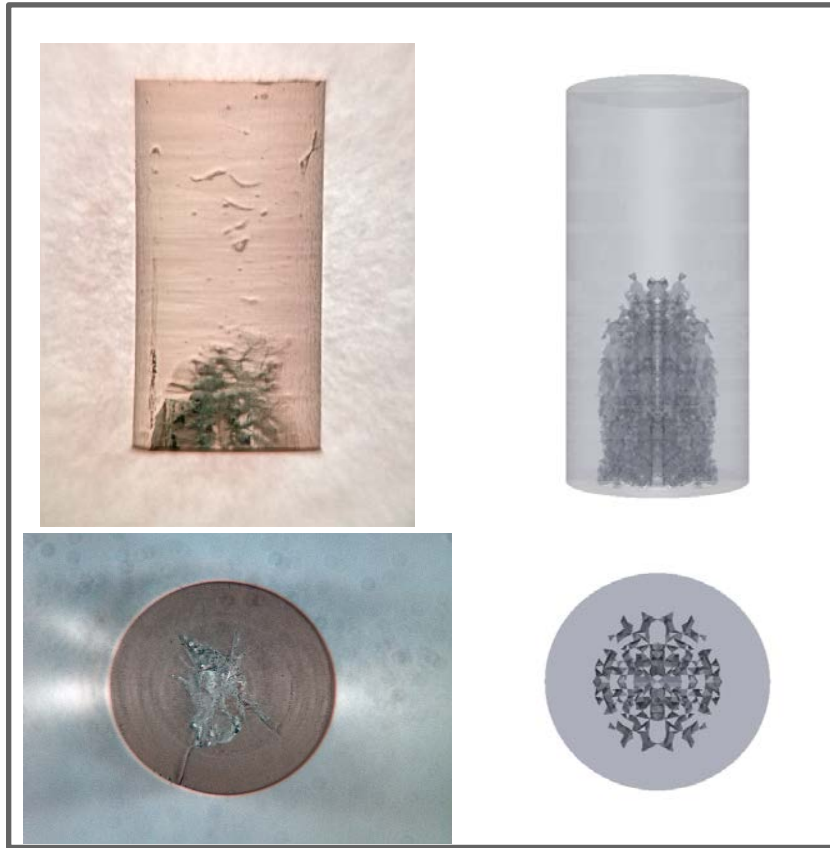


Experiments conducted by W. Mock, Jr. and J. Drotar,
at the Naval Surface Warfare Center (Dahlgren Division)
Research Gas Gun Facility, Dahlgren, VA 22448-5100, USA

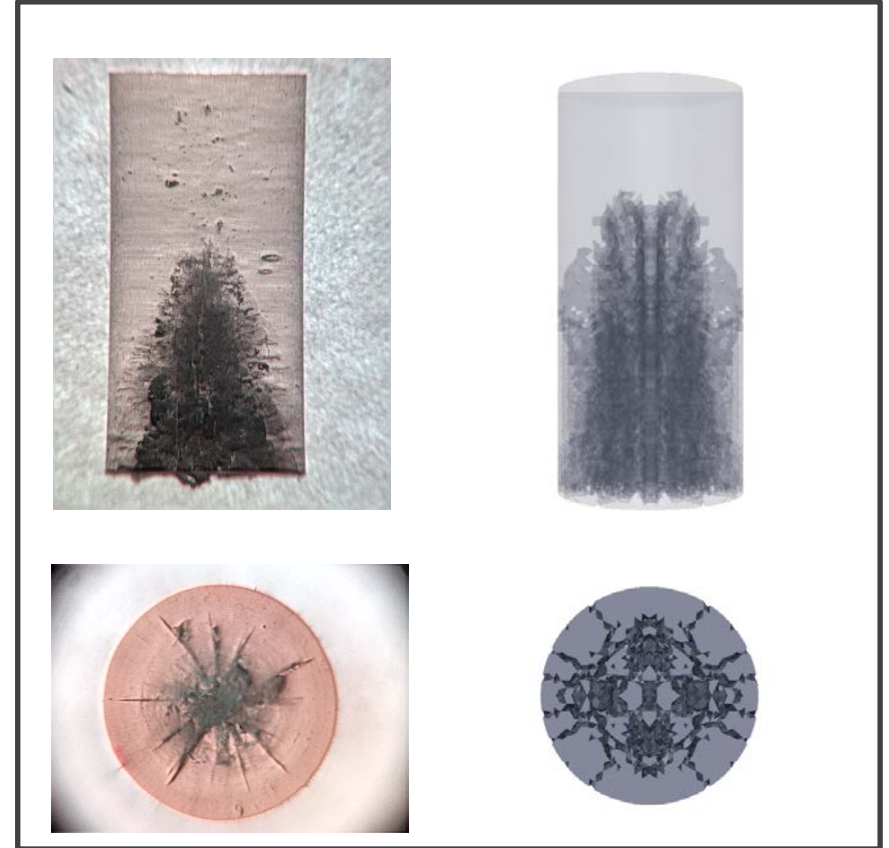


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Taylor-anvil tests on polyurea



Shot #854



Shot #861

Comparison of damage and fracture patterns
in recovered specimens and simulations



Concluding remarks

- Ductile fracture can indeed be understood as the result of the competition between sublinear growth and (possibly fractional) strain-gradient effects
- Optimal scaling laws are indicative of a well-defined specific fracture energy, cohesive behavior, and provide a (multiscale) link between macroscopic fracture properties and micromechanics (intrinsic micromechanical length scale, void-sheet and crazing mechanisms...)
- Upscaled properties can be efficiently implemented through cohesive or material-point erosion schemes
- Highly to be desired: Full Γ -limit as $\ell \rightarrow 0$, evolution...



Concluding remarks

