#### Cohesive Models of Fracture

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Solid Mechanics at the turn of the Millennium Providence, RI, June 16, 2000



#### Introduction

- Cohesive theories of fracture are phenomenological continuum theories characterized by two independent constitutive descriptions:
  - A constitutive law governing the deformation in the bulk.
  - A cohesive law governing separation across cohesive surfaces.
- The cohesive constitutive law embodies a description of the mechanical effects of the separation processes and the dissipation associated with them.
- Origins in work of Dugdale (1960) and Barrenblatt (1962). Equivalence to Griffith's criterion shown by Willis (1967) and Rice (1968).



#### Introduction (cont'd)

- Cohesive theories of fracture provide a means of addressing certain issues that are difficult to address within classical fracture mechanics, including:
  - Nucleation in solids with no discernable initial flaws
  - Tracking of tortuous crack paths
  - Profuse branching, fragmentation
  - Small cracks, fully yielded configurations
  - Effect of free surfaces, inhomogeneities, interfaces
  - Dynamic effects, crack-tip velocity
  - Arbitrary loading paths, unloading, overloads

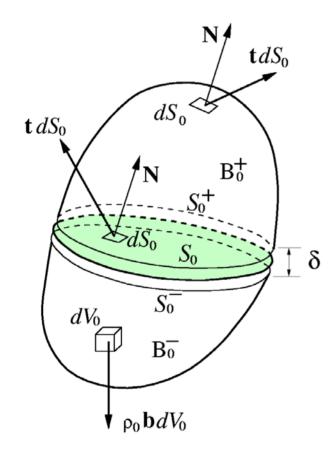


#### Introduction (cont'd)

- Cohesive theories of fracture provide a simple means of incorporating additional physics into the description of separation processes, including:
  - Dislocation emission, interplanar potentials (Needleman, 1990; Beltz and Rice, 1991; Rice, 1992)
  - Friction after debonding (Tvergaard, 1990)
  - Chemistry, corrosion (Rice et al. 1976; Wang and Rice, 1989)
  - Closure (Hutchinson and Budiansky, 1978), hysteresis.
- Cohesive theories of fracture enable the numerical simulation of processes and phenomena which are difficult to simulate within the framework of classical fracture mechanics (Hillerborg, 1976; Needleman, 1987)



#### Cohesive behavior



Schematic of body containing cohesive surface.
(Ortiz and Pandolfi, 1999)



$$P^D = \dot{W} - \dot{K} = \sum_{\pm} \int_{B_0^{\pm}} \mathbf{P} \cdot \dot{\mathbf{F}} dV_0 + \int_{S_0} \mathbf{t} \cdot \dot{\boldsymbol{\delta}} dS_0$$

• Free energy/unit surface:

$$\phi(\mathbf{F}_p, \boldsymbol{\delta}, \theta, \mathbf{q}) = \epsilon A((\mathbf{F}_p | \boldsymbol{\delta}/\epsilon), \theta, \mathbf{q})$$

Coleman's relations:

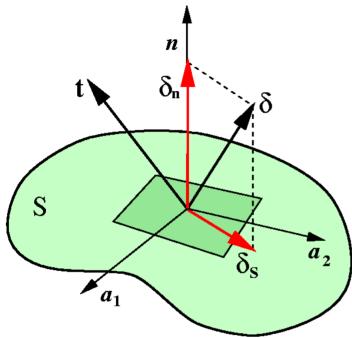
$$\mathbf{t} = rac{\partial \phi}{\partial oldsymbol{\delta}} (\mathbf{F}_p, oldsymbol{\delta}, heta, \mathbf{q})$$

Kinetic relations:

$$\dot{\mathbf{q}} = \mathbf{f}(\mathbf{F}_p, \boldsymbol{\delta}, \theta, \mathbf{q})$$



#### Cohesive behavior



Local reference frame

Material frame indifference:

$$\phi = \phi(\mathbf{C}_p, \boldsymbol{\delta} \cdot \mathbf{F}_p, \delta_n, \theta, \mathbf{q})$$



Uncoupled stretching and opening:

$$\phi = \phi(\boldsymbol{\delta} \cdot \mathbf{F}_p, \delta_n, \theta, \mathbf{q})$$

Isotropy:

$$\phi = \phi(\delta_s, \delta_n, \theta, \mathbf{q})$$

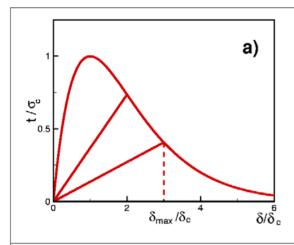
$$= \phi(\mathbf{n}, \boldsymbol{\delta}, \theta, \mathbf{q})$$

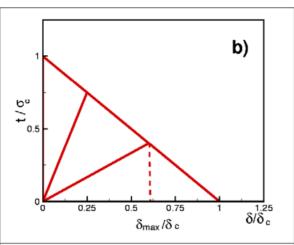
• Effective opening displacement (Tvergaard, 1990; Camacho and Ortiz, 1996):

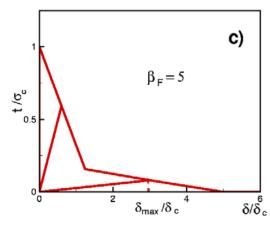
$$\delta = \sqrt{\beta^2 \delta_s^2 + \delta_n^2}$$
$$\phi = \phi(\delta, \theta, \mathbf{q})$$

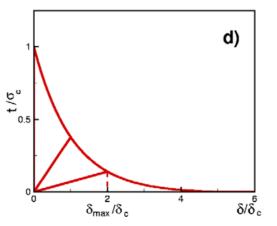


#### Cohesive behavior





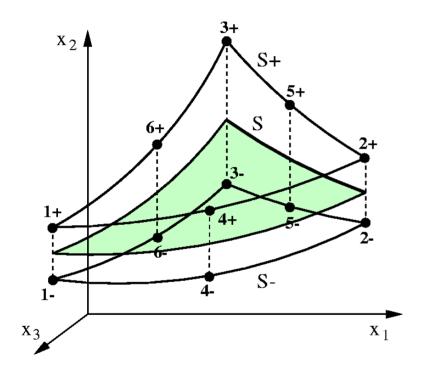


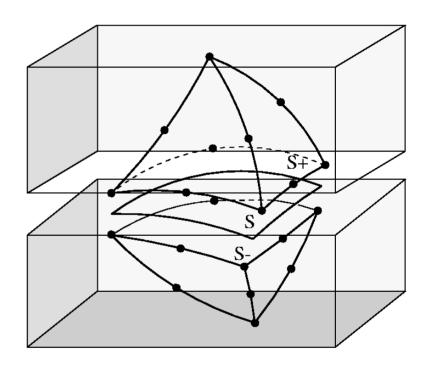


- Loading envelop:
  - a) Rose-Ferrante
  - b) Linear
  - c) Bilinear
  - d) Exponential (Planas and Elices, 1990)
- Loading/unloading irreversibility:
  - Linear unloading to origin (Camacho and Ortiz, 1996)



#### Cohesive elements - 3D

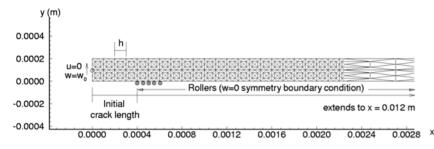




12-node quadratic cohesive elements (Ortiz and Pandolfi, 1999)



#### Cohesive elements - Convergence



Double cantilever specimen

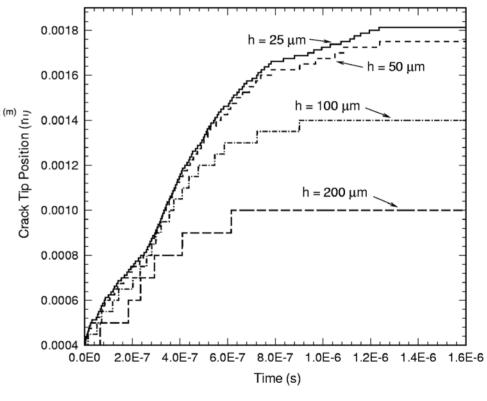
Characteristic size:

$$l_c = \frac{\pi}{8} \frac{E}{1 - \nu^2} \frac{G_c}{\sigma_c^2}$$

Characteristic time:

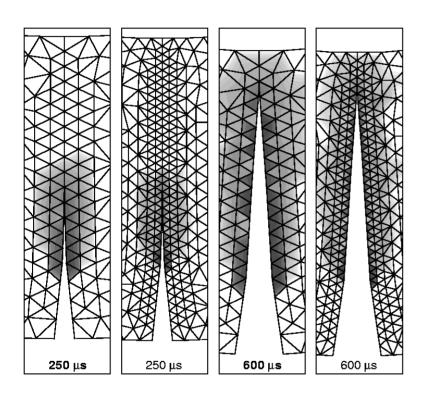
$$t_c = rac{l_c}{c_R}$$

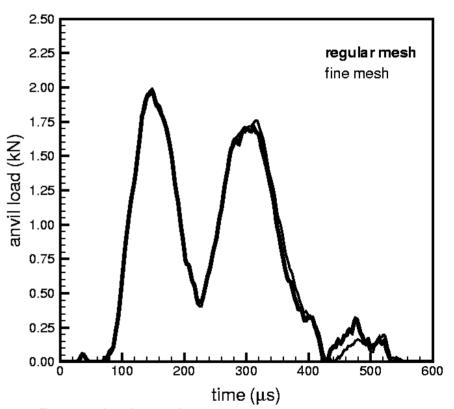




Crack-tip trajectory as a function of element size (Camacho and Ortiz, 1996)

#### Cohesive elements - Convergence

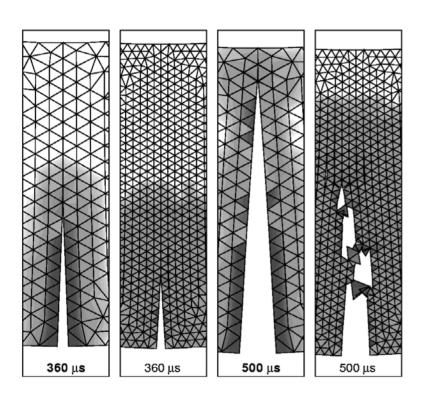


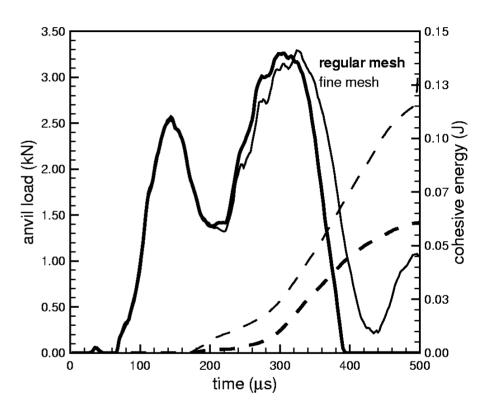


Dynamic three-point bend test - Prenotched specimen Crack-tip trajectory and contours of damage for coarse and fine meshes (Ruiz, Pandolfi and Ortiz, 2000)



#### Cohesive elements - Convergence

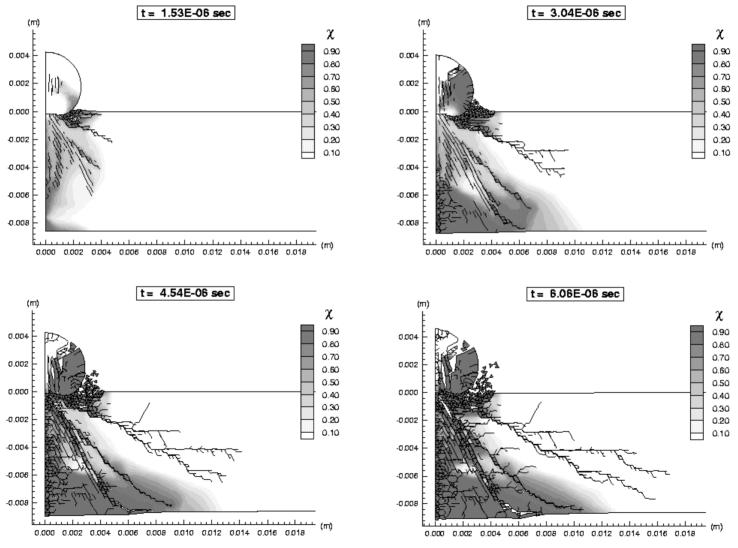




Dynamic three-point bend test - Nucleation Crack-tip trajectory and contours of damage for coarse and fine meshes (Ruiz, Pandolfi and Ortiz, 2000)



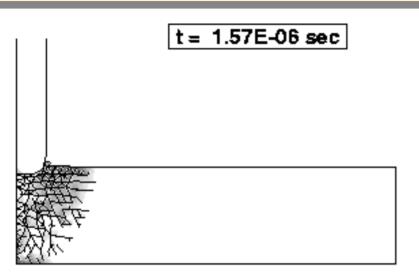
#### Steel pellet vs. alumina plate

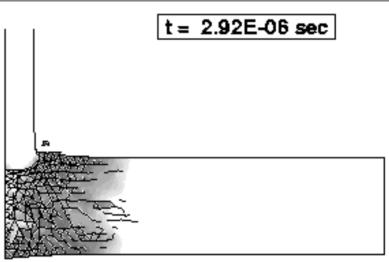


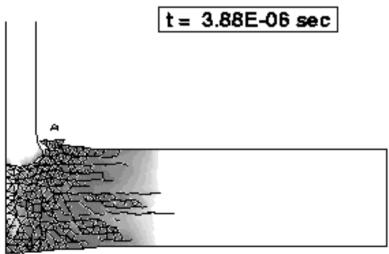


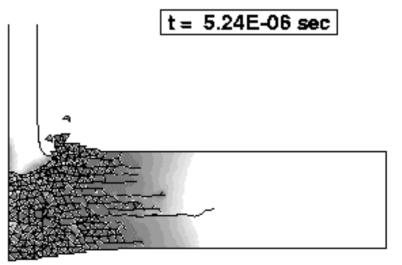
(Camacho and Ortiz, 1996; Field, 1988)

#### WHA long rod vs. alumina plate

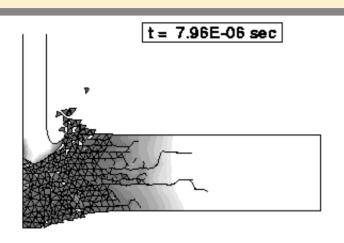


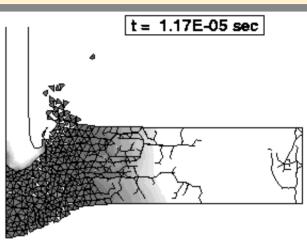


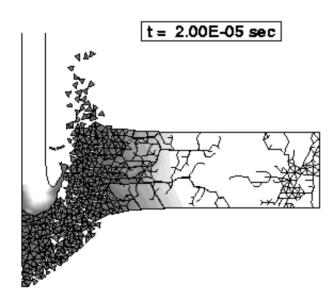


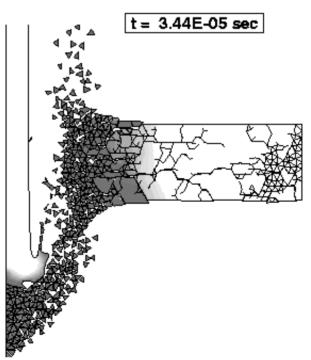


#### WHA long rod vs. alumina plate





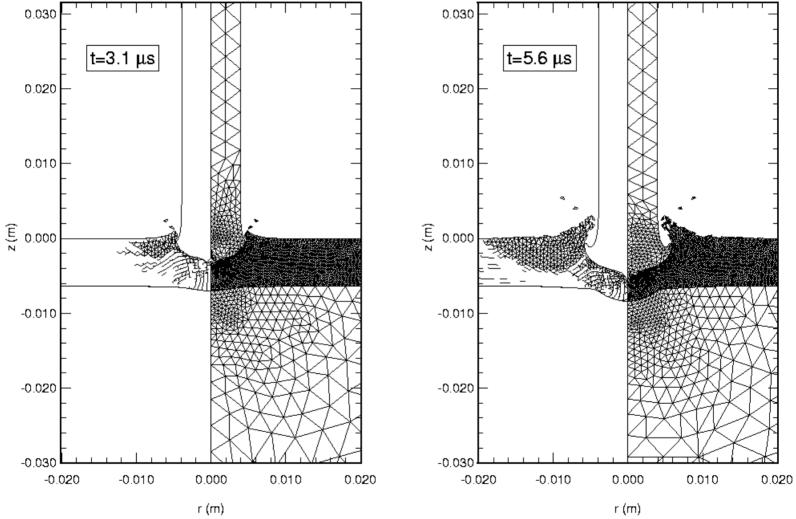






(Camacho and Ortiz, 1996) (Woodward, 1994)

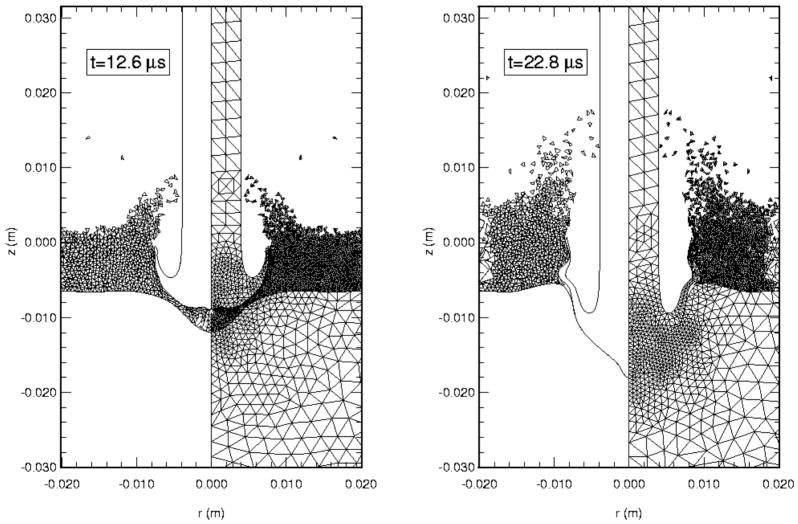
#### WHA long rod vs. confined ceramic plate





(Camacho and Ortiz, 1996; Grace and Rupert, 1994)

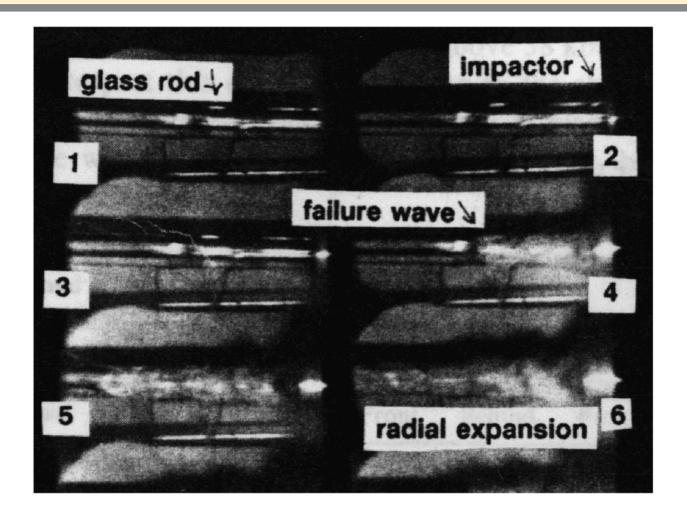
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(Camacho and Ortiz, 1996; Grace and Rupert, 1994)

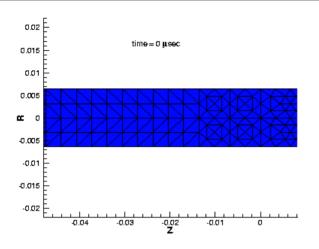
#### Failure waves in glass rods

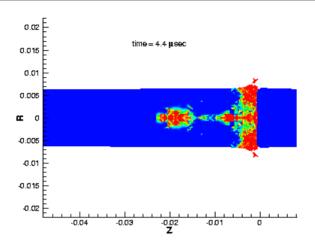


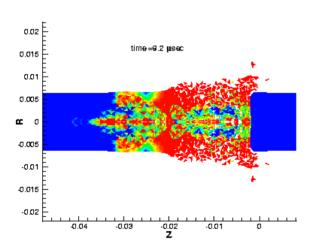


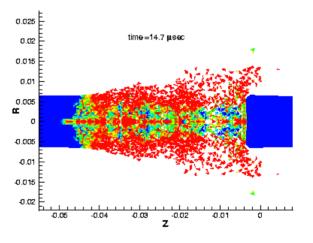
(Brar, Bless and Rosenberg, 1991) (Repetto, Radovitzky and Ortiz, 2000)

#### Failure waves in glass rods





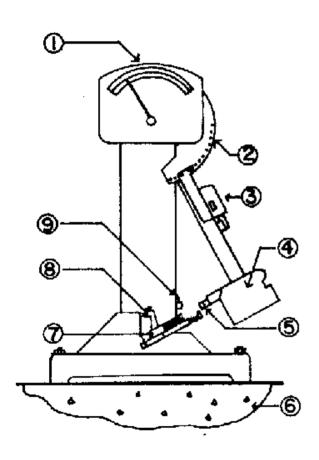




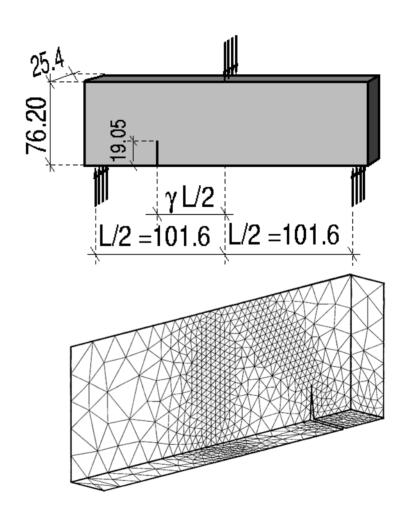


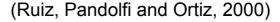
(Repetto, Radovitzky and Ortiz, 2000) (Brar, Bless and Rosenberg, 1991)

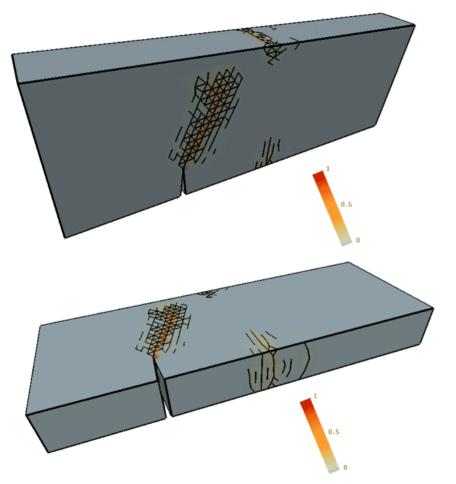


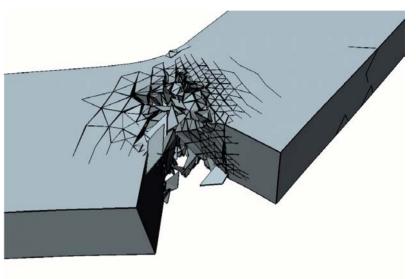


(John and Shah, 1990) (Guo et al., 1995)





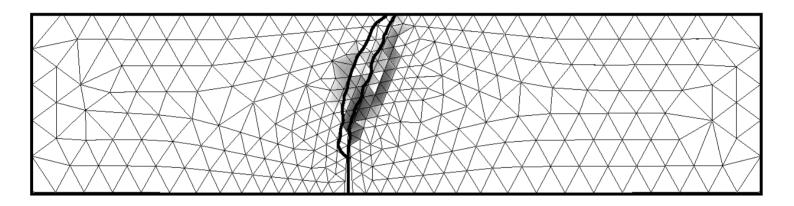




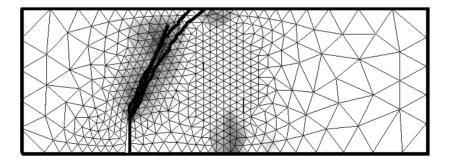
(Ruiz, Pandolfi and Ortiz, 2000)



(a)

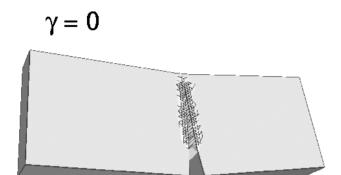


(b)

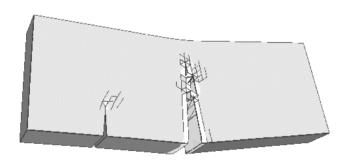




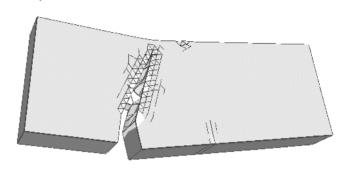
Computed and experimental crack paths.
a) Guo et al., 1995; b) John and Sha, 1990.
(Ruiz, Pandolfi and Ortiz, 2000)



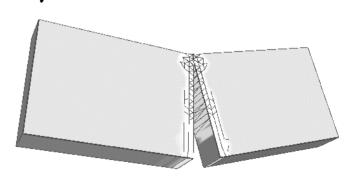
$$\gamma = 0.6$$



$$\gamma = 0.5$$



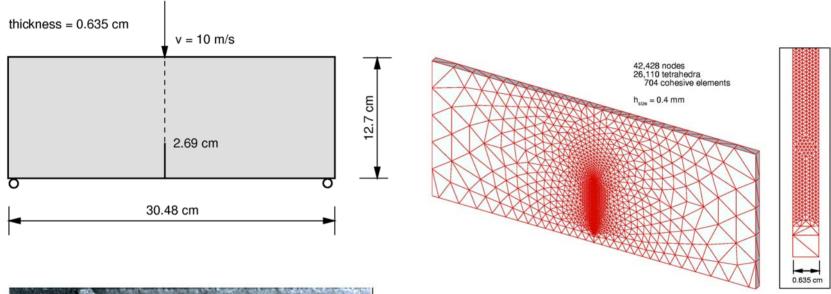
$$\gamma = 1$$





Influence of crack offset on crack pattern (Ruiz, Pandolfi and Ortiz, 2000)

## Drop-weight test - C300 steel

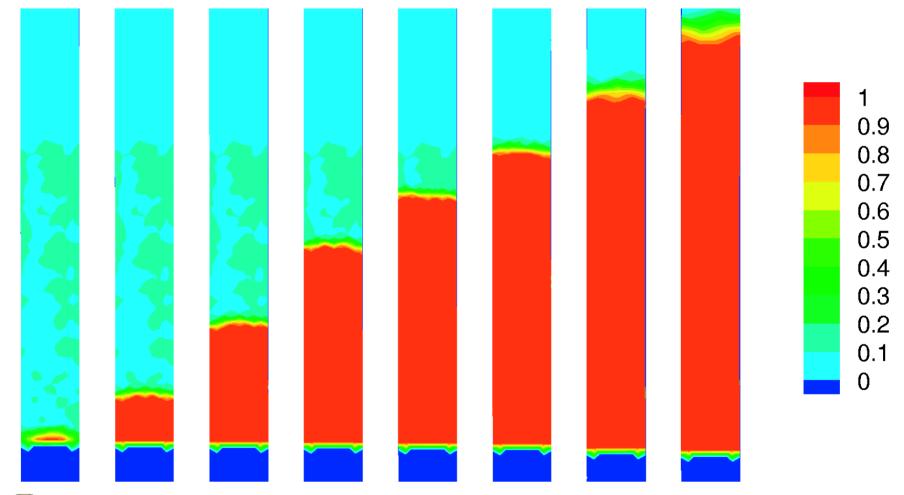




(Pandolfi, Guduru, Ortiz and Rosakis, 2000)



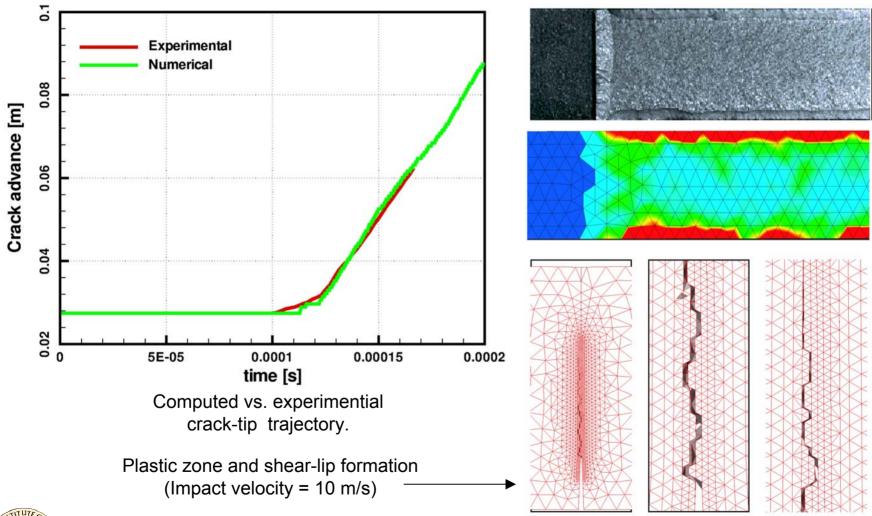
## Drop-weight test - C300 steel



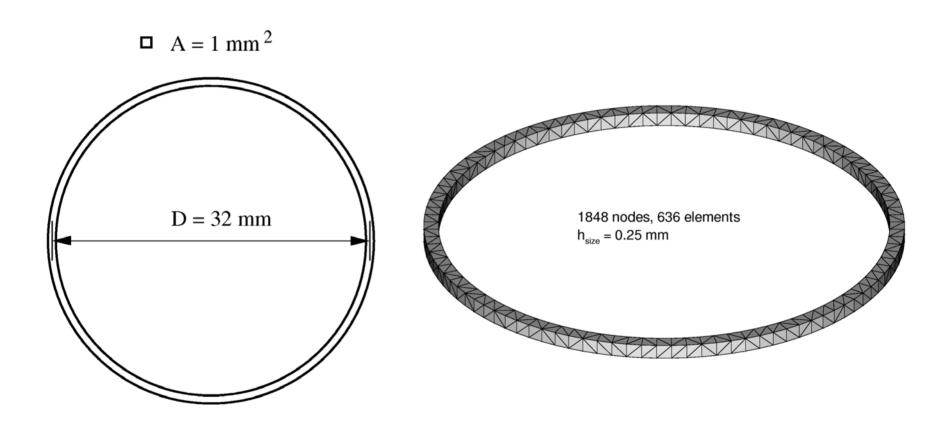


Crack geometry as a function of time (Pandolfi, Guduru, Ortiz and Rosakis, 2000)

#### Drop-weight test - C300 steel

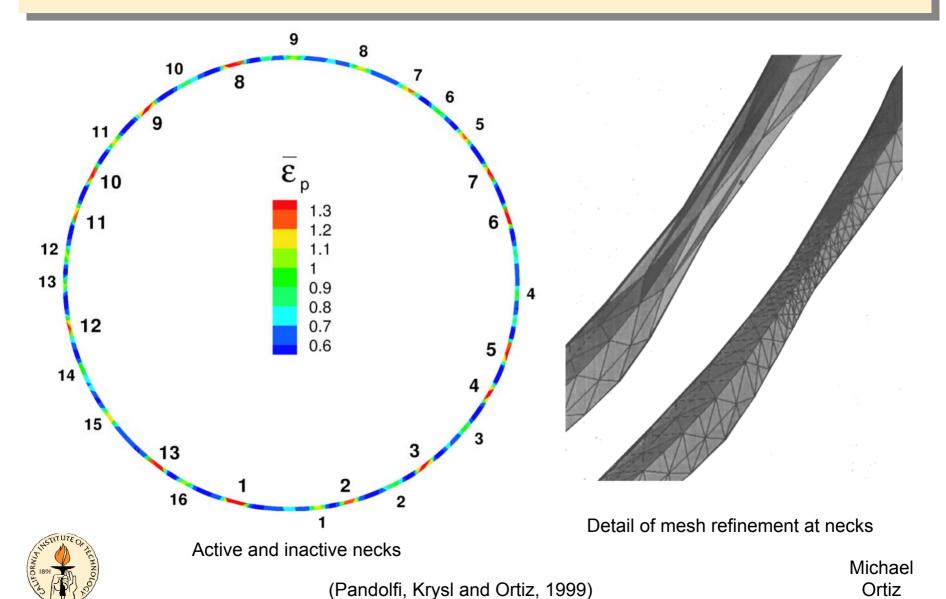


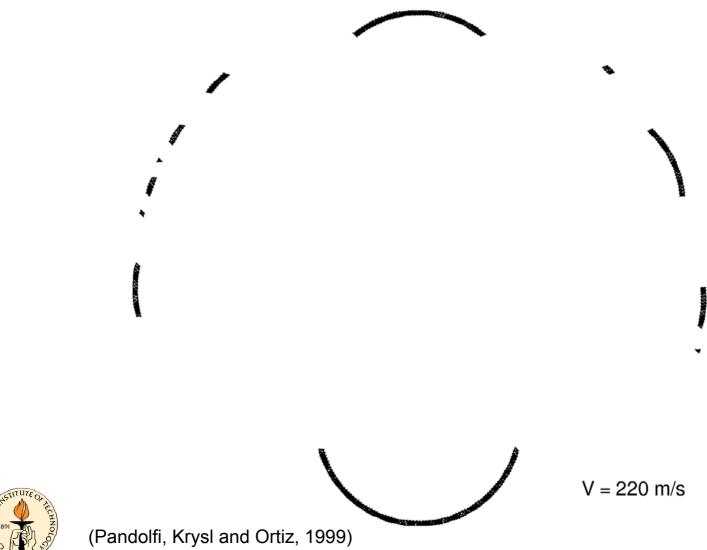




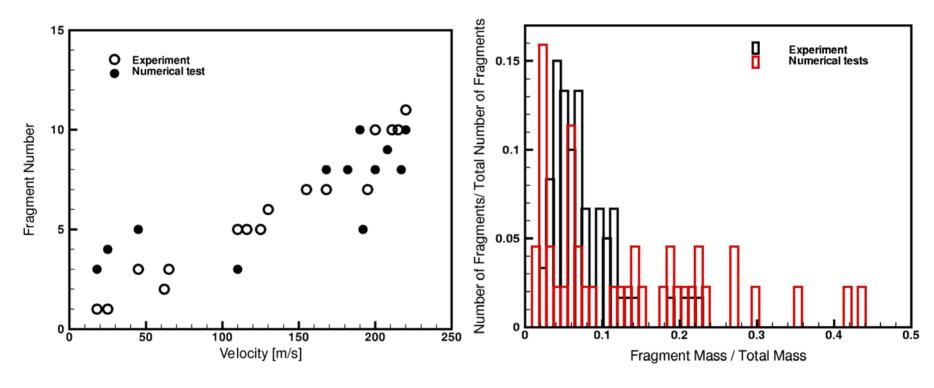


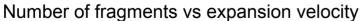
(Grady and Benson, 1983) (Pandolfi, Krysl and Ortiz, 1999)









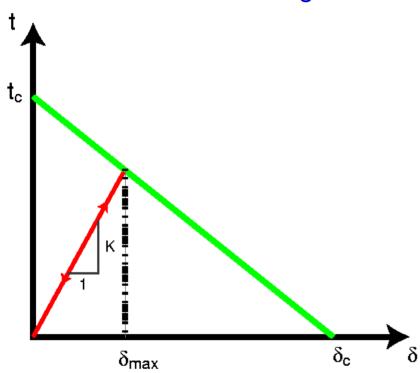


Fragment mass frequency distribution

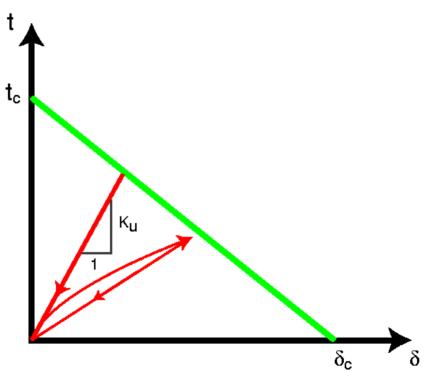


#### Fatigue crack growth - Cohesive models

Reversible unloading:



Loading-reloading hysteresis:

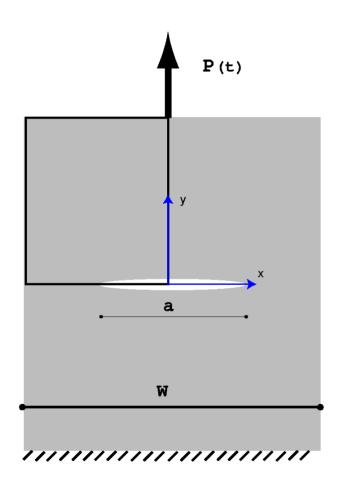


Crack shakes down under cyclic loading.

 Crack propagates under cyclic loading.



#### Case study: Al center-crack panel

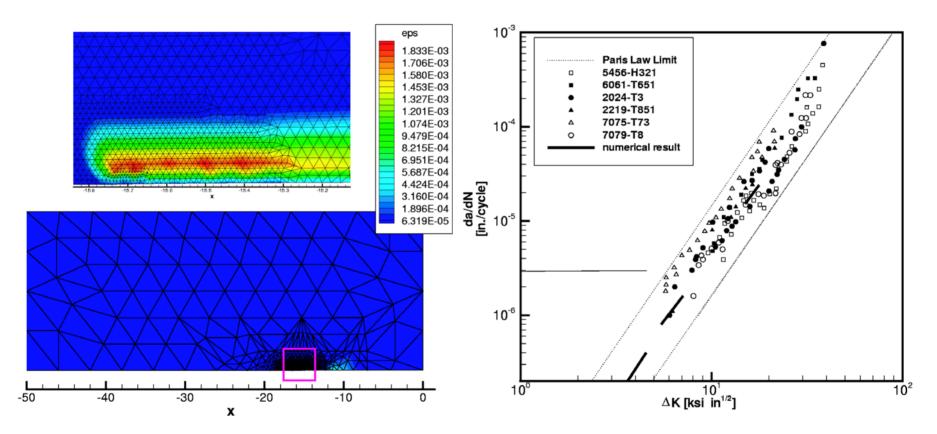


#### Parameters (Al 2024-T351):

Young's modulus E	70 GPa
Poisson's ratio $\nu$	0.3
Initial yield stress $\sigma_0$	325 MPa
Hardening exponent $n$	8
Reference plastic strain $\varepsilon_0^p$	0.0002
Specific cohesive energy $G_c$	$13.8 \; {\rm KJ/m^2}$
Cohesive strength $\sigma_c$	800 MPa
Decay displacement $\delta_f$	4 mm
Initial half-crack size $a_0$	10 mm
Applied stress amplitude $\sigma_{\infty}$	85 MPa



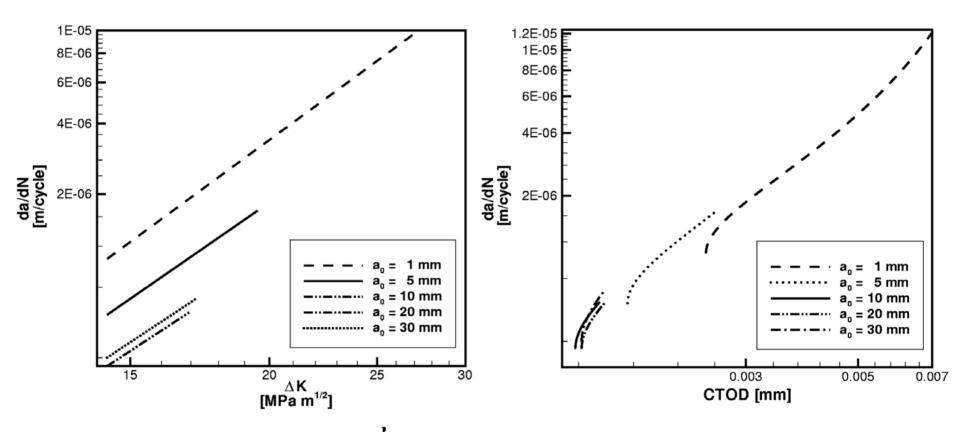
#### Fatigue crack growth - Long cracks



Contours of effective plastic strain. Initial crack length: a = 15.72 mm Comparison of computed and experimental growth rates. Initial crack lengths = 10, 20 and 30 mm (Data from ASTM Standards, Vol. 3.2, 1991)



#### Fatigue crack growth - Short cracks



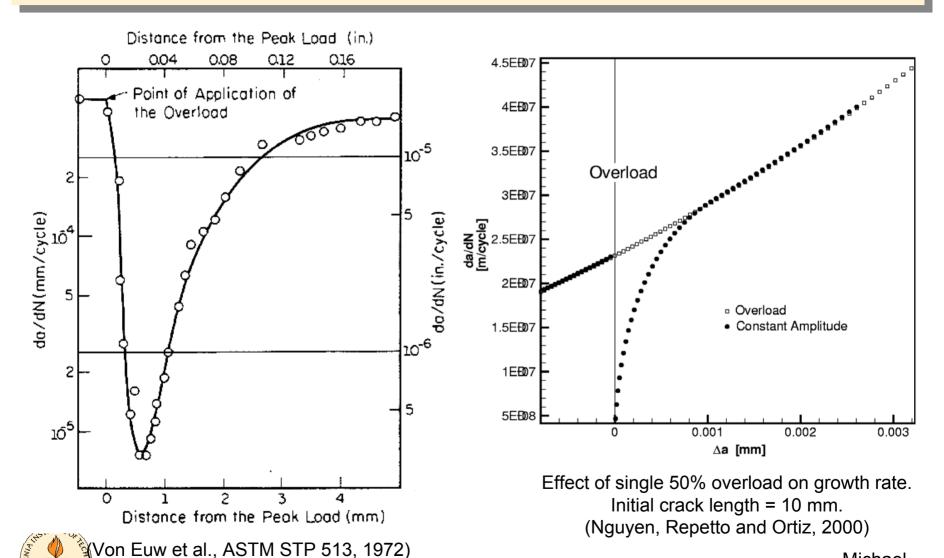
**Modified Paris law:** 

$$\frac{da}{dN} = C(\Delta\delta)^n = C'(\Delta J)^n$$



(Dowling, 1977; Kanninen et al., 1981)

#### Fatigue crack growth - Overload effect

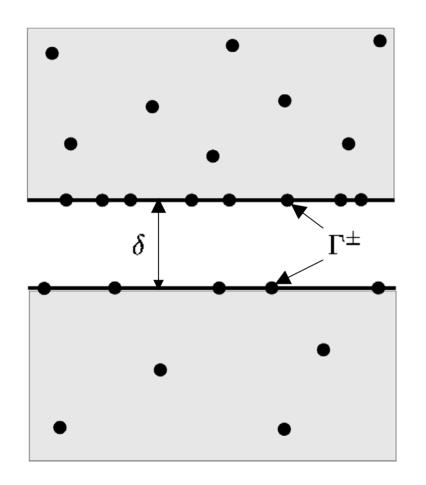


#### Issues for further study

- Crack nucleation
- Crack patterns in the presence of profuse branching, fragmentation:
  - Geometry of crack ensemble (fractal dimension?)
  - Energy balance, dissipation
  - Convergence of finite-element solutions
- Disparity between atomistic and continuum cohesive strengths, critical opening displacements.
- Multiscale modeling:
  - Cohesive models and discrete dislocation models
  - Chemistry, impurity diffusion
- Transonic cracks



#### Stress corrosion cracking



Cohesive free energy density:

$$F = F(\delta, \Gamma^{\pm})$$

Limiting values:

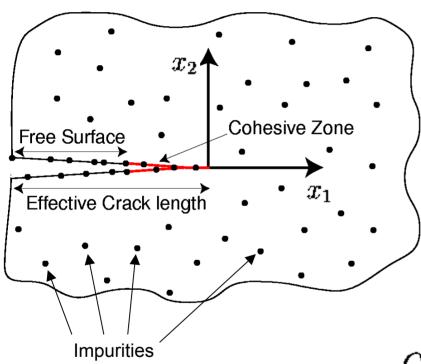
$$egin{aligned} &\lim_{\delta o\infty}F(\delta,\Gamma^\pm)=\gamma_s(\Gamma^+)+\gamma_s(\Gamma^-) \ &\lim_{\delta o0}F(\delta,\Gamma^\pm)=\gamma_b(\Gamma^++\Gamma^-) \end{aligned}$$

Equilibrium with environment:

$$rac{\partial F}{\partial \Gamma^{\pm}}(\delta,\Gamma^{\pm})=\mu^{
m env}$$



#### Stress corrosion cracking



Diffusion equation:

$$C_{,t} + \nabla \cdot \mathbf{J} = 0$$

- Impurity flux:  $\mathbf{J} = -M C \nabla \mu$
- Chemical potential:

$$\mu = G + RT \log(\gamma V_m C) + E$$

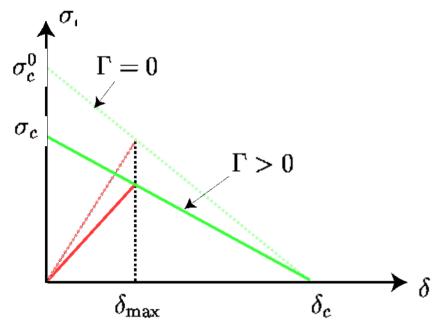
- Elastic energy:  $E = p \triangle V$
- Diffusion equation:

$$C_{,t} = D \nabla^2 C + (M \triangle V) \nabla \cdot (C \nabla p)$$

Equilibrium at crack flanks:  $\mu=rac{\partial F}{\partial \Gamma^\pm}(\delta,\Gamma^\pm), \quad x_2=0^\pm$ 



#### Stress corrosion cracking



 Segregant embrittlement: (Wang and Rice, 1989):

$$2\gamma_s(\Gamma) = 2\gamma_s^0 - (\Delta g_b^0 - \Delta g_s^0) \Gamma$$

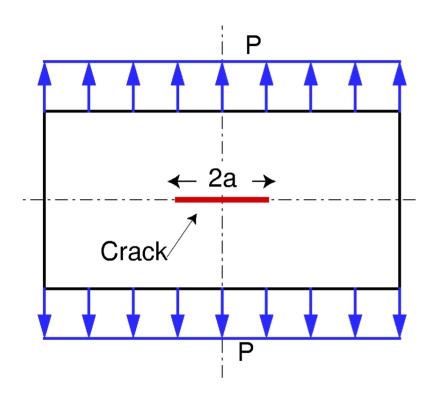
Effect on cohesive law:

$$\sigma_c(\Gamma) = \sigma_c^0 - \frac{(\Delta g_b^0 - \Delta g_s^0)}{\delta_c} \left(\Gamma^+ + \Gamma^-\right)$$

Impurity	$-\Delta g_s^0$	$-\Delta g_b^0$	$\Delta g_b^0 - \Delta g_s^0$
C	73 to 85	50 to 75	-2 to 35
P	76 to 80	32 to 41	35 to 48
Sb	83 to 130	8 to 25	58 to 122
S	165 to 190	50 to 58	107 to 140



# Case study: Hydrogen embrittlement



Material properties (H, steel):

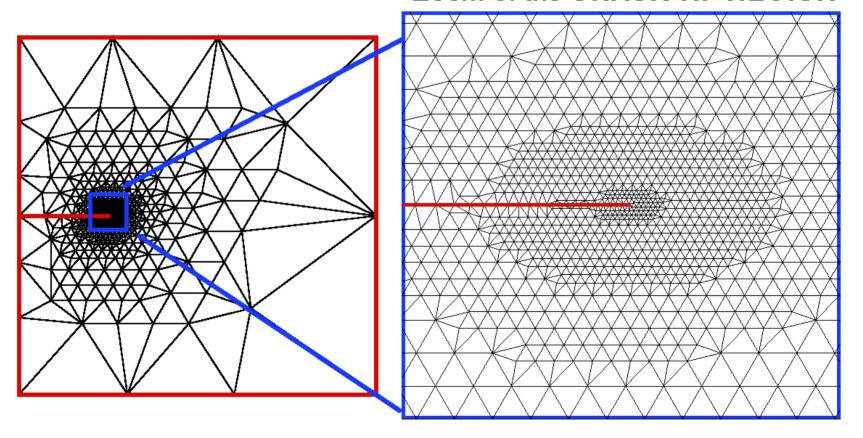
lacksquare	207 GPa
ν	0.3
$G_c$	$1,260 \text{ J/m}^2$
$\sigma_c$	840 MPa
$\delta_c$	$3 \times 10^{-6} \text{ m}$
D	$1.27 \times 10^{-8} \text{ m}^2/\text{s}$
$V_m$	$7.116 \times 10^{-6} \text{ m}^3/\text{mol}$
$\Delta V$	$2 \times 10^{-6} \text{ m}^3/\text{mol}$
$C_0$	$2.084 \times 10^{21} \text{ m}^{-3}$

Center-crack panel geometry. Initial crack length = 0.25 mm. Applied stress = 260 MPa.



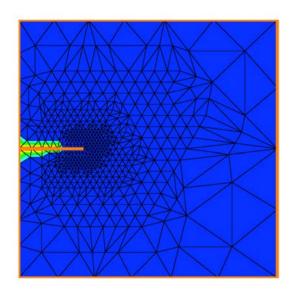
# Case study: Hydrogen embrittlement

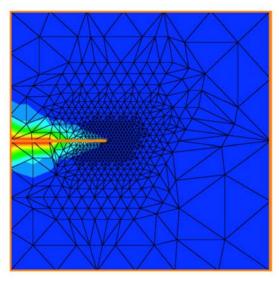
#### **Zoom of the CRACK TIP REGION**

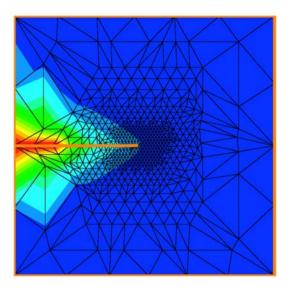




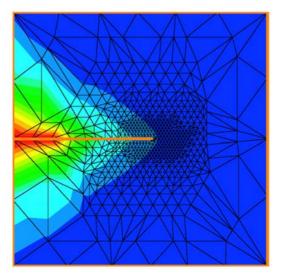
# Case study: Hydrogen embrittlement







Evolution of hydrogen concentration



(Movie)

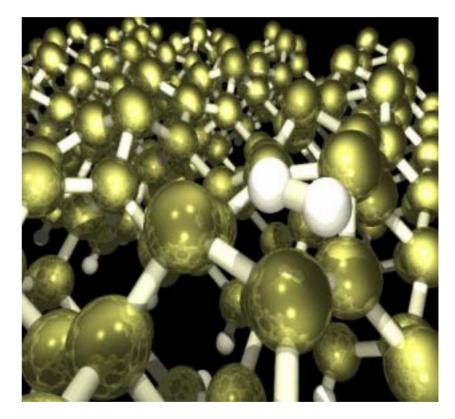


#### Condensed matter quantum chemistry

(Courtesy of Emily Carter)

#### Challenges:

- High dimensionality
- Singular, long-range interaction potentials
- Breadth of length & time scales
- Ultimate Impact:
  - Efficient & accurate simulations of complex chemistry
  - Mapping to macro-scopic mechanics



Adsorption of H molecule by Si surface. (Radehe and Carter, Ann. Rev. Phys. Chem., 1997)



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