

Hypothesis Testing

CB: chapter 8; section 10.3



Hypothesis: statement about an unknown population parameter.

In hypothesis testing, you are interested in testing between two mutually exclusive hypotheses, called the **null hypothesis** (denoted H_0) and the **alternative hypothesis** (denoted H_1).

H_0 and H_1 are complementary hypotheses, in the following sense:

If the parameter being hypothesized about is θ , and the parameter space (i.e., possible values for θ) is Θ , then the null and alternative hypotheses form a partition of Θ :

$$H_0: \theta \in \Theta_0 \subset \Theta$$

$$H_1: \theta \in \Theta_0^c \text{ (the complement of } \Theta_0 \text{ in } \Theta).$$

Examples:

1. $H_0: \theta = 0$ vs. $H_1: \theta \neq 0$
2. $H_0: \theta \leq 0$ vs. $H_1: \theta > 0$

1 Definitions of test statistics

A **test statistic**, similarly to an estimator, is just some real-valued function $T_n \equiv T(X_1, \dots, X_n)$ of your data sample X_1, \dots, X_n . Clearly, a test statistic is a random variable.

A **test** is a function mapping values of the test statistic into $\{0, 1\}$, where

- “0” implies that you accept the null hypothesis $H_0 \Leftrightarrow$ reject the alternative hypothesis H_1 .
- “1” implies that you reject the null hypothesis $H_0 \Leftrightarrow$ accept the alternative hypothesis H_1 .

The subset of the real line \mathcal{R} for which the test is equal to 1 is called the rejection (or “critical”) region. The complement of the critical region (in the support of the test statistic) is the acceptance region.

In what follows, we refer to a test as a combination of both (i) a test statistic; and (ii) the mapping from realizations of the test statistic to $\{0, 1\}$.

Next we consider several key test statistics.



1.1 Likelihood Ratio Test

Let: $\vec{X} = X_1, \dots, X_n \sim i.i.d. f(X|\theta)$, and likelihood function $L(\theta|\vec{X}) = \prod_{i=1}^n f(x_i|\theta)$.

Define: the **likelihood ratio test statistic** for testing $H_0 : \theta \in \Theta_0$ vs. $H_1 : \theta \in \Theta_0^c$ is

$$\lambda(\vec{X}) \equiv \frac{\sup_{\theta \in \Theta_0} L(\theta|\vec{X})}{\sup_{\theta \in \Theta} L(\theta|\vec{X})}.$$

The numerator of $\lambda(\vec{X})$ is the “restricted” likelihood function, and the denominator is the unrestricted likelihood function.

The support of the LR test statistic is $[0, 1]$.

Intuitively speaking, if H_0 is true (i.e., $\theta \in \Theta_0$), then $\lambda(\vec{X}) = 1$ (since the restriction of $\theta \in \Theta_0$ will not bind). However, if H_0 is false, then $\lambda(\vec{X})$ can be small (close to zero).

So an LR test should be one which rejects H_0 when $\lambda(\vec{X})$ is small; for example, $\mathbf{1}(\lambda(\vec{X}) < 0.75)$



Example: $X_1, \dots, X_n \sim i.i.d. N(\theta, 1)$

Test $H_0 : \theta = 2$ vs. $H_1 : \theta \neq 2$.

Then

$$\lambda(\vec{X}) = \frac{\exp\left(-\frac{1}{2} \sum_i (X_i - 2)^2\right)}{\exp\left(-\frac{1}{2} \sum_i (X_i - \bar{X}_n)^2\right)}$$

(the denominator arises because \bar{X}_n is the unrestricted MLE estimator for θ .)

Example: $X_1, \dots, X_n \sim U[0, \theta]$.

(i) Test $H_0 : \theta = 2$ vs. $H_1 : \theta \neq 2$.

Restricted likelihood function

$$L(\vec{X}|2) = \begin{cases} \left(\frac{1}{2}\right)^n & \text{if } \max(X_1, \dots, X_n) \leq 2 \\ 0 & \text{if } \max(X_1, \dots, X_n) > 2. \end{cases}$$

Unrestricted likelihood function

$$L(\vec{X}|\theta) = \begin{cases} \left(\frac{1}{\theta}\right)^n & \text{if } \max(X_1, \dots, X_n) \leq \theta \\ 0 & \text{if } \max(X_1, \dots, X_n) > \theta \end{cases}$$

which is maximized at $\theta_n^{MLE} = \max(X_1, \dots, X_n)$.

Hence the denominator of the LR statistic is $\left(\frac{1}{\max(X_1, \dots, X_n)}\right)^n$, so that

$$\lambda(\vec{X}) = \begin{cases} 0 & \text{if } \max(X_1, \dots, X_n) > 2 \\ \left(\frac{\max(X_1, \dots, X_n)}{2}\right)^n & \text{otherwise} \end{cases}$$

LR test would be: $\mathbf{1}(\lambda(\vec{X}) \leq c)$. Critical region consists of two disconnected parts.

(ii) Test $H_0 : \theta \in [0, 2]$ vs. $H_1 : \theta > 2$.

In this case: the restricted likelihood is

$$\sup_{\theta \in [0, 2]} L(\vec{X}|\theta) = \begin{cases} \left(\frac{1}{\max(X_1, \dots, X_n)} \right)^n & \text{if } \max(X_1, \dots, X_n) \leq 2 \\ 0 & \text{otherwise.} \end{cases}$$

so

$$\lambda(\vec{X}) = \begin{cases} 1 & \text{if } \max(X_1, \dots, X_n) \leq 2 \\ 0 & \text{otherwise.} \end{cases} \quad (1)$$

So now LR test is $\mathbf{1}(\lambda(\vec{X}) \leq c) = \mathbf{1}(\max(X_1, \dots, X_n) > 2)$.

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1.2 Wald Tests

A second way of generating test statistics is to consider the *distance* between the estimated value of a parameter $\hat{\theta}_n$ and a postulated value under the null H_0 , call this θ_0 . This is the Wald testing approach.

In the scalar case, consider the distance $(\hat{\theta}_n - \theta_0)$. A typical situation is when $\hat{\theta}_n$ is asymptotically normal, with some asymptotic variance V (eg. MLE). Let the null be $H_0 : \theta = \theta_0$. Then, if the null were true, the scaled distance:

$$\frac{(\hat{\theta}_n - \theta_0)}{\sqrt{\frac{1}{n}V}} \xrightarrow{d} N(0, 1). \quad (2)$$

The quantity on the LHS is the **T-test statistic**.

Note: in most cases, the asymptotic variance V will not be known, and will also need to be estimated. However, if we have an estimator \hat{V}_n such that $\hat{V}_n \xrightarrow{p} V$, then the statement

$$Z_n \equiv \frac{(\hat{\theta}_n - \theta_0)}{\sqrt{\frac{1}{n}\hat{V}_n}} \xrightarrow{d} N(0, 1)$$

still holds (using the plim operator and Slutsky theorems). In what follows, therefore, we assume for simplicity that we know V .

We consider two cases:

(i) Two-sided test: $H_0 : \theta = \theta_0$ vs. $H_1 : \theta \neq \theta_0$.

Under H_0 : the CLT holds, and the t-stat is $N(0, 1)$

Under H_1 : assume that the true value is some $\theta_1 \neq \theta_0$. Then the t-stat can be written as

$$\frac{(\hat{\theta}_n - \theta_0)}{\sqrt{\frac{1}{n}V}} = \frac{(\hat{\theta}_n - \theta_1)}{\sqrt{\frac{1}{n}V}} + \frac{(\theta_1 - \theta_0)}{\sqrt{\frac{1}{n}V}}.$$

The first term $\xrightarrow{d} N(0, 1)$, but the second (non-stochastic) term diverges to ∞ or $-\infty$, depending on whether the true θ_1 exceeds or is less than θ_0 . Hence the t-stat diverges to $-\infty$ or ∞ with probability 1.

Hence, in this case, your test should be $\mathbf{1}(|Z_n| > c)$, where c should be some number in the tails of the $N(0, 1)$ distribution.

(ii) One-sided test: $H_0 : \theta \leq \theta_0$ vs. $H_1 : \theta > \theta_0$.

Here the null hypothesis specifies a whole range of true θ ($\Theta_0 = (-\infty, \theta_0]$), whereas the t-test statistic is evaluated at just one value of θ .

Just as for the two-sided test, the one-sided t-stat is evaluated at θ_0 , so that $Z_n = \frac{\hat{\theta}_n - \theta_0}{\sqrt{\frac{1}{n}V}}$.

Under H_0 and $\theta < \theta_0$: Z_n diverges to $-\infty$ with probability 1. Under H_0 and $\theta = \theta_0$: the CLT holds, and the t-stat is $N(0, 1)$.

Under H_1 : Z_n diverges to ∞ with probability 1.

Hence, in this case, you will reject the null only for very large values of Z_n . Correspondingly, your test should be $\mathbf{1}(Z_n > c)$, where c should be some number in the right tail of the $N(0, 1)$ distribution.

Later, we will discuss how to choose c .

Multivariate version: θ is K -dimensional, and asymptotic normal, so that under H_0 , we have

$$\sqrt{n}(\theta_n - \theta_0) \xrightarrow{d} N(0, \Sigma).$$

Then we can test $H_0 : \theta = \theta_0$ vs. $H_1 : \theta \neq \theta_0$ using the quadratic form

$$Z_n \equiv n \cdot (\theta_n - \theta_0)' \Sigma^{-1} (\theta_n - \theta_0) \xrightarrow{d} \chi_k^2.$$

Test takes the form: $\mathbf{1}(Z_n > c)$.

Multivariate version for one-sided or composite hypotheses are advanced, and beyond the scope of this class.

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1.3 Score test

Consider a model with log-likelihood function $\log L(\theta|\vec{X}) = \frac{1}{n} \sum_i \log f(x_i|\theta)$.

Let $H_0 : \theta = \theta_0$. The *sample score* function evaluated at θ_0 is

$$S(\theta_0) \equiv \frac{\partial}{\partial \theta} \log L(\theta|\vec{X})|_{\theta=\theta_0} = \frac{1}{n} \sum_i \frac{\partial}{\partial \theta} \log f(x_i|\theta)|_{\theta=\theta_0}.$$

Define $W_i = \frac{\partial}{\partial \theta} \log f(x_i|\theta)|_{\theta=\theta_0}$. Under the null hypothesis, $S(\theta_0)$ converges to

$$\begin{aligned} E_{\theta_0} W_i &= \int \frac{\frac{d}{d\theta} f(x|\theta)|_{\theta=\theta_0}}{f(x|\theta_0)} f(x|\theta_0) dx \\ &= \frac{\partial}{\partial \theta} \int f(x|\theta) dx \\ &= \frac{\partial}{\partial \theta} \cdot 1 = 0 \end{aligned}$$

(the information inequality). Hence,

$$V_{\theta_0} W_i = E_{\theta_0} W_i^2 = E_{\theta_0} \left(\frac{\partial}{\partial \theta} \log f(X|\theta)|_{\theta=\theta_0} \right)^2 \equiv I_0.$$

(Note that $\frac{1}{I_0}$ is the usual variance matrix for MLE, which is the CRLB. I_0 is called the “Fisher information.”)

Therefore, you can apply the CLT to get that, under H_0 ,

$$\frac{S(\theta_0)}{\sqrt{\frac{1}{n} I_0}} \xrightarrow{d} N(0, 1).$$

(If we don’t know I_0 , we can use some consistent estimator \hat{I}_0 of it.)

So a test of $H_0 : \theta = \theta_0$ could be formulated as $\mathbf{1} \left(\left| \frac{\frac{1}{n} S(\theta_0)}{\sqrt{\frac{1}{n} I_0}} \right| > c \right)$, where c is in the right tail of the $N(0, 1)$ distribution.

Multivariate version: if θ is K -dimensional:

$$S_n \equiv n S(\theta_0)' I_0^{-1} S(\theta_0) \xrightarrow{d} \chi_k^2.$$

$I_0^{-1} = V_0$, the asymptotic variance matrix for MLE (CRLB).

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Under the null hypothesis $H_0 : \theta = \theta_0$, the Wald and Score tests are asymptotically identically distributed (in both the univariate and multivariate cases). (Later, you will also see

that the Likelihood Ratio Test statistic, suitably normalized, also has the same asymptotic distribution.) This shows that they are asymptotically equivalent tests.

However, the LR, Wald, and Score tests (the “trinity” of test statistics) require different models to be estimated.

- LR test requires both the restricted and unrestricted models to be estimated
- Wald test requires only the unrestricted model to be estimated.
- Score test requires only the restricted model to be estimated.

2 Methods of evaluating tests

We are worried when a test is wrong. Since the test itself is a random variable, we cannot guarantee that a test is never wrong, but we can characterize how often it would be wrong.

There are two types of mistakes that we are worried about:

- **Type I error:** rejecting H_0 when it is true.
- **Type II error:** Accepting H_0 when it is false.

Let $T_n \equiv T(X_1, \dots, X_n)$ denote the sample test statistic. Consider a test with rejection region R (i.e., test is $\mathbf{1}(T_n \in R)$). Then:

$$\begin{aligned} P(\text{type I error}) &= P(T_n \in R \mid \theta \in \Theta_0) \\ P(\text{type II error}) &= P(T_n \notin R \mid \theta \in \Theta_0^c) \end{aligned}$$



Power function

Type I and type II errors are summarized in the **power function**.

Definition: the *power function* of a hypothesis test with a rejection region R is the function of θ defined by $\beta(\theta) = P(T_n \in R \mid \theta)$. ■

- Power function gives the Type I error probabilities, for any singleton null hypothesis $H_0 : \theta = \theta_0$.
- $1 - \beta(p)$ gives you the Type II error probabilities, for any point alternative hypothesis
- **Important:** power function is specific to a given test $\mathbf{1}(T_n \in R)$, regardless of the specific hypotheses that the test may be used for.

Example: $X_1, X_2 \sim i.i.d.$ Bernoulli, with probability p . Consider the test $\mathbf{1}(\frac{X_1+X_2}{2} \neq 1)$.

$$\beta(p) = P\left(\frac{X_1 + X_2}{2} \neq 1 | p\right) = 1 - p^2.$$

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Example: $X_1, \dots, X_n \sim U[0, \theta]$.

Test $H_0 : \theta \leq 2$ vs. $H_1 : \theta > 2$. Derive $\beta(\theta)$ for the LR test $\mathbf{1}(\lambda(\vec{X}) < c)$.

Recall our earlier derivation of LR test in Eq. (1). Hence,

$$\begin{aligned} \beta(\theta) &= P(\lambda(\vec{X}) < c | \theta) \\ &= P(\max(X_1, \dots, X_n) > 2 | \theta) \\ &= 1 - P(\max(X_1, \dots, X_n) < 2 | \theta) \\ &= \begin{cases} 0 & \text{for } \theta \leq 2 \\ 1 - \left(\frac{2}{\theta}\right)^n & \text{for } \theta > 2. \end{cases} \end{aligned}$$

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In practice, researchers often concerned about Type I error (i.e., don't want to reject H_0 unless evidence overwhelming against it): "conservative bias"?

But if this is so, then you want a test with a power function $\beta(\theta)$ which is low for $\theta \in \Theta_0$, but high elsewhere:

This motivates the definition of *size* and *level* of a test.

- For $0 \leq \alpha \leq 1$, a test with power function $\beta(\theta)$ is a **size** α test if $\sup_{\theta \in \Theta_0} \beta(\theta) = \alpha$.
- For $0 \leq \alpha \leq 1$, a test with power function $\beta(\theta)$ is a **level** α test if $\sup_{\theta \in \Theta_0} \beta(\theta) \leq \alpha$.
 - Note that a size α test is also level α ; a level α test has size $\leq \alpha$.
- The $\theta \in \Theta_0$ at which the "sup" is achieved is called the "least favorable value" of θ under the null, for this test. It is the value of $\theta \in \Theta_0$ for which the null holds, but which is most difficult to distinguish (in the sense of having the highest rejection probability) from any alternative parameter $\theta \notin \Theta_0$.

Reflecting perhaps the "conservative" bias, researcher often use tests of size $\alpha = 0.05$, or 0.10.

Example: $X_1, \dots, X_n \sim i.i.d. N(\mu, 1)$. Then $\bar{X}_n \sim N(\mu, 1/n)$, and $Z_n(\mu) \equiv \sqrt{n}(\bar{X}_n - \mu) \sim N(0, 1)$.

- Consider the hypotheses $H_0 : \mu \leq 2$ vs. $H_1 : \mu > 2$.
- Consider the test statistic $1(Z_n(2) > c)$
- The power function

$$\begin{aligned}\beta(\mu) &= P(\sqrt{n}(\bar{X}_n - 2) > c | \mu) \\ &= P(\sqrt{n}(\bar{X}_n - \mu) > c + \sqrt{n}(2 - \mu) | \mu) \\ &= 1 - \Phi(c + \sqrt{n}(2 - \mu))\end{aligned}$$

where $\Phi(\cdot)$ is the standard normal CDF. Note that $\beta(\mu)$ is increasing in μ .

- Size of test = $\sup_{\mu \leq 2} 1 - \Phi(c + \sqrt{n}(2 - \mu))$. Since $\beta(\mu)$ is increasing in μ , the supremum occurs at $\mu = 2$, so that size is $\beta(2) = 1 - \Phi(c)$.
- Assume you want a test with size α . Then you want to set c such that

$$1 - \Phi(c) = \alpha \Leftrightarrow c = \Phi^{-1}(1 - \alpha).$$

c is the $(1 - \alpha)$ -th quantile of the standard normal distribution. You can get these from the usual tables.

For $\alpha = 0.025$, then $c^* = 1.96$. For $\alpha = 0.05$, then $c^* = 1.64$.



Now consider the above test, with $c^* = 1.96$, but change the hypotheses to $H_0 : \mu = 2$ vs. $H_1 : \mu \neq 2$.

Test still has size $\alpha = 0.025$.

But there is something intuitively wrong about this test. You are unlikely to reject when $\mu < 2$. So the Type II error is very high for the alternatives $\mu < 2$. We say this test is *biased*.

Definition: a test with power function $\beta(\theta)$ is **unbiased** if $\beta(\theta') \geq \beta(\theta'')$ for every pair (θ', θ'') where $\theta' \in \Theta_0^c$ and $\theta'' \in \Theta_0$.

Definition: Let C be a class of tests for testing $H_0 : \theta \in \Theta_0$ vs. $H_1 : \theta \in \Theta_0^c$. A test in class C , with power function $\beta(\theta)$, is **uniformly most powerful (UMP)** in class C if, for every other test in class C with power function $\tilde{\beta}(\theta)$

$$\beta(\theta) \geq \tilde{\beta}(\theta), \text{ for every } \theta \in \Theta_0^c.$$

Often, the classes you consider are test of a given size α . The power function for a UMP test lies above the upper envelope of power functions for all other tests in the class, for $\theta \in \Theta_0^c$.

2.1 UMP tests in special case: two simple hypotheses

In general, we don't know what form a UMP test takes. But in the case where both the null and alternative hypotheses are simple hypotheses, we can appeal to the following result.

Theorem 8.3.12 (Neyman-Pearson Lemma): Consider testing

$$H_0 : \theta = \theta_0 \text{ vs. } H_1 : \theta = \theta_1$$

(so both the null and alternative are singletons). The pdf or pmf corresponding to θ_i is $f(\vec{X}|\theta_i)$, for $i = 0, 1$. The test has a rejection region R which satisfies:

$$\begin{aligned} \vec{X} \in R & \quad \text{if } f(\vec{X}|\theta_1) > k \cdot f(\vec{X}|\theta_0) \\ \vec{X} \in R^c & \quad \text{if } f(\vec{X}|\theta_1) < k \cdot f(\vec{X}|\theta_0) \end{aligned} \quad (3)$$

and

$$\alpha = P(\vec{X} \in R|\theta_0). \quad (4)$$

Then:

1. (Sufficiency) Any test satisfying (3) and (4) is a UMP test with level α .
2. (Necessity) If there exists a test satisfying (3) and (4) with $k > 0$, then every UMP level α test is a size α test (satisfying (4)) and every UMP level α test satisfies (3).

Proof: (sufficiency) Let $T(x) \equiv \mathbf{1}(x \in R)$ denote the test corresponding to the rejection region in (3), and let $\tilde{T}(x)$ denote any other test of level α ; that is, $E_0\tilde{T}(x) \leq \alpha = E_0T(x)$ by (4). For convenience let us consider the case where x is continuously distributed, so that the knife-edge event $\{x : f(x|\theta_1) = kf(x|\theta_0)\}$ has zero probability. The key equation is the following:

$$(T(x) - \tilde{T}(x))(f(x|\theta_1) - kf(x|\theta_0)) \geq 0, \quad \text{for all } x \text{ in the sample space.}$$

To see this, denote by R^+ and R^- the sets in the sample space where $T(x) - \tilde{T}(x) > 0$ and < 0 respectively. If x is in R^+ , $T(x) > 0$ and $f(x|\theta_1) > kf(x|\theta_0)$; in the same way $f(x|\theta_1) < kf(x|\theta_0)$ for all $x \in R^-$. For all x in neither R^+ nor R^- , $T(x) = \tilde{T}(x)$. Then:

$$\begin{aligned} & \int (T(x) - \tilde{T}(x))(f(x|\theta_1) - kf(x|\theta_0))dx \geq 0 \\ & \rightarrow E_1(T(x) - \tilde{T}(x)) \geq kE_0(T(x) - \tilde{T}(x)) \\ & \rightarrow \geq 0 \quad (\text{by } E_0\tilde{T}(x) \leq E_0T(x)). \end{aligned} \quad (5)$$

Hence $E_1T(x) \geq E_1\tilde{T}(x)$ and $T(x)$ is UMP level- α .

(necessity) Let $\tilde{T}(x)$ denote any UMP-level α test, and $T(x)$ denote a test satisfying (3) and (4). By the Sufficiency part, $T(x)$ must also be UMP-level α , hence $E_1 T(x) = E_1 \tilde{T}(x)$. Now from the previous display (5), we have $0 \leq E_1 T(x) - \tilde{T}(x) - k(E_0 T(x) - E_1 \tilde{T}(x))$ and since both T and \tilde{T} are UMP, and $k > 0$, we have $E_0 T(x) - E_0 \tilde{T}(x) = \alpha - E_0 \tilde{T}(x) \leq 0$ or $E_0 \tilde{T}(x) \geq \alpha$. But since \tilde{T} is level α , we require $E_0 \tilde{T}(x) \leq \alpha$ implying $E_0 \tilde{T}(x) = \alpha$. Hence the previous display (5) must hold with equality. But since the integrand is non-negative, the integral equals zero iff the integrand is zero pointwise, implying $T(x) = \tilde{T}(x)$ for all x . ■

Example: return to 2-coin toss again. Test $H_0 : p = \frac{1}{2}$ vs. $H_1 : p = \frac{3}{4}$.

The likelihood ratios for the three possible outcomes $\sum_i X_i = 0, 1, 2$ are:

$$\begin{aligned} \frac{f(0|p = \frac{3}{4})}{f(0|p = \frac{1}{2})} &= \frac{1}{4} \\ \frac{f(1|p = \frac{3}{4})}{f(1|p = \frac{1}{2})} &= \frac{3}{4} \\ \frac{f(2|p = \frac{3}{4})}{f(2|p = \frac{1}{2})} &= \frac{9}{4}. \end{aligned}$$

Let $l(\vec{X}) = \frac{f(\sum_i X_i | p = \frac{3}{4})}{f(\sum_i X_i | p = \frac{1}{2})}$. Hence, there are 4 possible rejection regions, for values of $l(\vec{X})$:

- (i) $(\frac{9}{4}, +\infty)$ (size $\alpha = 0$)
- (ii) $(\frac{3}{4}, +\infty)$ (size $\alpha = \frac{1}{4}$)
- (iii) $(\frac{1}{4}, +\infty)$ (size $\alpha = \frac{3}{4}$)
- (iv) $(-\infty, +\infty)$ (size $\alpha = 1$).

At other values for α (eg. 0.5), no value of k satisfies (*) exactly, and so the test above are level- α tests. This is due to the discreteness of this example. But if we can randomize between rejection regions, then we can achieve any size $\in (0, 1)$.

Example A: $X_1, \dots, X_n \sim N(\mu, 1)$. Test $H_0 : \mu = \mu_0$ vs. $H_1 : \mu = \mu_1$. (Assume $\mu_1 > \mu_0$.)

By the NP-Lemma, the UMP test has rejection region characterized by

$$\frac{\exp(-\frac{1}{2} \sum_i (X_i - \mu_1)^2)}{\exp(-\frac{1}{2} \sum_i (X_i - \mu_0)^2)} > k.$$

Taking logs of both sides:

$$\begin{aligned} (\mu_1 - \mu_0) \sum_i X_i &> \log k + \frac{n}{2}(\mu_1 - \mu_0)^2 \\ \Leftrightarrow \frac{1}{n} \sum_i X_i &> \frac{\frac{1}{n} \log k + \frac{1}{2}(\mu_1 - \mu_0)^2}{(\mu_1 - \mu_0)} \equiv d. \end{aligned}$$

where d is determined such that $P(\bar{X}_n > d) = \alpha$, where α is the desired size. This makes intuitive sense: you reject the null when the sample mean is too large (because $\mu_1 > \mu_0$).

Under the null, $\sqrt{n}(\bar{X}_n - \mu_0) \sim N(0, 1)$, so for $\alpha = 0.05$, you want to set $d = \mu_0 + 1.64/\sqrt{n}$.

2.2 Extension of NP Lemma: models with monotone likelihood ratio

The case covered by NP Lemma— that both null and alternative hypotheses are simple — is somewhat artificial. For instance, we may be interested in the *one-sided* hypotheses $H_0 : \theta \leq \theta_0$ vs. $H_1 : \theta \geq \theta_0$, where θ is scalar. It turns out UMP for one-sided hypotheses exists under an additional assumption on the family of density functions $\{f(\vec{X}|\theta)\}_\theta$:

Definition: the family of densities $f(\vec{X}|\theta)$ has *monotone likelihood ratio in $T(\vec{X})$* if there exists a function $T(\vec{X})$ such that for any pair $\theta < \theta'$ the densities $f(\vec{X}|\theta)$ and $f(\vec{X}|\theta')$ are distinct and the ratio $f(\vec{X}|\theta')/f(\vec{X}|\theta)$ is a nondecreasing function of $T(\vec{X})$. That is, there exists a nondecreasing function $g(\cdot)$ and function $T(\vec{X})$ such that $f(\vec{X}|\theta')/f(\vec{X}|\theta) = g(T(\vec{X}))$.

For instance: let $\vec{X} = x$ and $T(x) = x$, then MLR in x means that $f(x|\theta')/f(x|\theta)$ is nondecreasing in x . Roughly speaking: larger x 's are more “likely” under larger θ 's.

Theorem: Let θ be scalar, and let $f(\vec{X}|\theta)$ have MLR in $T(\vec{X})$. Then:

(i) For testing $H_0 : \theta \leq \theta_0$ vs. $H_1 : \theta \geq \theta_0$, there exists a UMP test $\phi(\vec{X})$, which is given by

$$\phi(\vec{X}) = \begin{cases} 1 & \text{when } T(\vec{X}) > C \\ \gamma & \text{when } T(\vec{X}) = C \\ 0 & \text{when } T(\vec{X}) < C \end{cases}$$

where (γ, C) are chosen to satisfy $E_{\theta_0}\phi(\vec{X}) = \alpha$.

(ii) The power function $\beta(\theta) = E_\theta\phi(\vec{X})$ is strictly increasing for all points θ for which $0 < \beta(\theta) < 1$.

(iii) For all θ' , the test described in part *i* is UMP for testing $H'_0 : \theta \leq \theta'$ vs. $H'_1 : \theta \geq \theta'$ at size $\alpha = \beta(\theta')$. ■

*Sketch of Proof:*¹ Consider testing θ_0 vs. any point $\theta_1 > \theta_0$. By NP Lemma, this depends on ratio $f(\vec{X}|\theta_1)/f(\vec{X}|\theta_0)$. Given MLR condition, this ratio can be written $g(T(\vec{X}))$ where $g(\cdot)$ is nondecreasing. Then UMP test rejects when $f(\vec{X}|\theta_1)/f(\vec{X}|\theta_0)$ is large, which is when $T(\vec{X})$ is large; this is test $\phi(\vec{X})$. Since this test does not depend on θ_1 , $\phi(\vec{X})$ is also UMP-size α for testing $H_0 : \theta = \theta_0$ vs. $H_1 : \theta > \theta_0$ (the composite alternative).

¹Lehmann and Romano, Testing Statistical Hypotheses, pg. 65.

Now since MLR holds for all $(\theta', \theta''; \theta'' > \theta')$, the test $\phi(\vec{X})$ is also UMP-size $E_{\theta'} \phi(\vec{X})$ for testing θ' vs. θ'' . Hence $\beta(\theta'') \geq \beta(\theta')$, otherwise $\phi(\vec{X})$ cannot be UMP². Furthermore, the distinctiveness of $f(\vec{X}|\theta'')$ and $f(\vec{X}|\theta')$ rules out $\beta(\theta'') = \beta(\theta')$. Hence we get (ii).

Then since the power function is monotonic increasing in θ , the UMP-size α feature of $\phi(\vec{X})$ for testing $H_0 : \theta = \theta_0$ vs. $H_1 : \theta > \theta_0$ extends to the composite null hypothesis $H_0 : \theta \leq \theta_0$ vs. $H_1 : \theta > \theta_0$, which is (i). (iii) follows immediately.

■■■

Example A cont'd: From above, we see that for $\mu_1 > \mu_0$, the likelihood ratio simplifies to $\exp((\mu_1 - \mu_0) \sum_i X_i - \frac{n}{2}(\mu_1^2 - \mu_0^2))$ which is increasing in \bar{X}_n . Hence, this satisfies MLR with $T(\vec{X}) = \bar{X}_n$.

Using the theorem above, the one-sided T-test which rejects when

$$\bar{X}_n > \mu_0 + \frac{1.64}{\sqrt{n}}$$

is also UMP for size $\alpha = 0.05$ for the one-sided hypotheses $H_0 : \mu \leq \mu_0$ vs. $H_1 : \mu > \mu_0$. Call this “test 1”.

Taking this example further, we have that for the one-sided hypotheses $H_0 : \mu > \mu_0$ vs. $H_1 : \mu < \mu_0$, the one-sided T-test which rejects when $\bar{X}_n < \mu_0 - \frac{1.64}{\sqrt{n}}$ will be UMP for size $\alpha = 0.05$. Call this “test 2”.

Now consider testing

$$H_0 : \mu = \mu_0 \text{ vs. } H_1 : \mu \neq \mu_0. \quad (*)$$

The alternative hypothesis is equivalent to “ $\mu < \mu_0$ or $\mu > \mu_0$ ”. Can we find an UMP size- α test?

Note that both Test 1 and Test 2 are size- α tests for hypotheses (*). So we consider each in turn.

For any alternative point $\mu_1 > \mu_0$, test 1 is UMP, implying that $\beta_1(\mu_1)$ is maximal among all size- α tests. For $\mu_2 < \mu_0$, however, test 2 is UMP, implying that $\beta_2(\mu_2)$ is maximal. Furthermore, $\beta_1(\mu_2) < \alpha < \beta_2(\mu_2)$ from part (ii) of theorem above, so neither test can be uniformly most powerful for all $\mu \neq \mu_0$. And indeed there is no UMP size- α test for problem (*).

But note that both Test 1 and Test 2 are biased for the hypotheses (*). It turns out that the two-sided T-test which rejects when $\bar{X}_n > \mu_0 + 1.96/\sqrt{n}$ or $\bar{X}_n < \mu_0 - 1.96/\sqrt{n}$ is UMP among size- α unbiased tests. See discussion in CB, pp. 392-395.

²Because the purely random test $\phi(\vec{X}) = 1$ with probability α has power $\beta(\theta) = \alpha$ for all θ .

3 Large-sample properties of tests

In practice, we use large-sample theory — that is, LLN's and CLT's — in order to determine the approximate critical regions for the most common test statistics.

Why? Because finite-sample properties can be difficult to determine:

Example: $X_1, \dots, X_n \sim i.i.d.$ Bernoulli with prob. p .

Want to test $H_0 : p \leq \frac{1}{2}$ vs. $H_1 : p > \frac{1}{2}$, using the test stat $\bar{X}_n = \frac{1}{n} \sum_i X_i$.

n is finite. The exact finite-sample distribution for \bar{X}_n is the distribution of $\frac{1}{n}$ times a $B(n, p)$ random variable, which is:

$$\left\{ \begin{array}{ll} 0 & \text{with prob } \binom{n}{0}(1-p)^n \\ \frac{1}{n} & \text{with prob } \binom{n}{1}p(1-p)^{n-1} \\ \frac{2}{n} & \text{with prob } \binom{n}{2}p^2(1-p)^{n-2} \\ \dots & \dots \\ 1 & \text{with prob } p^n \end{array} \right.$$

Assume your test is of the following form: $\mathbf{1}(\bar{X}_n > c)$, where the critical value c is to be determined such that the size $\sup_{p \leq \frac{1}{2}} P(\bar{X}_n > c|p) = \alpha$, for some specified α .³ This equation is difficult to solve for!

On the other hand, by the CLT, we know that $\frac{\sqrt{n}(X_n - p)}{\sqrt{p(1-p)}} \xrightarrow{d} N(0, 1)$. Hence, consider the

T-test statistic $Z_n \equiv \sqrt{n}(\bar{X}_n - \frac{1}{2}) / \sqrt{\frac{1}{4}} = 2\sqrt{n}(\bar{X}_n - \frac{1}{2})$.

Under any $p \leq \frac{1}{2}$ in the null hypothesis,

$$P(Z_n > \Phi^{-1}(1 - \alpha)) \leq \alpha,$$

for n large enough. (In fact, this equation holds with equality for $p = \frac{1}{2}$, and holds with strict inequality for $p < \frac{1}{2}$.)

Corresponding to this test, you can derive the *asymptotic* power function, which is $\beta^a(p) \equiv \lim_{n \rightarrow \infty} P(Z_n > c)$, for $c = \Phi^{-1}(1 - \alpha)$:

(Graph)

³The Clopper-Pearson (1934) confidence intervals for p are based on inverting this exact finite-sample test.

- Note that the asymptotic power function is equal to 1 at all values under the alternative. This is the notion for **consistency** for a test: that it has asymptotic power 1 under every alternative.
- Note also that asymptotic power (rejection probability) is zero under every p of the null, except $p = \frac{1}{2}$.
- (skip) Accordingly, we see that asymptotic power, vs. *fixed alternatives*, is not a sufficiently discerning asymptotic criterion for distinguishing between tests. We can deal with this by considering *local alternatives* of the sort $\tilde{p} = \frac{1}{2} + h/\sqrt{n}$. Under additional smoothness assumptions on the distributional convergence of $\frac{\sqrt{n}(\bar{X}_n - p)}{\sqrt{p(1-p)}}$ around $p = \frac{1}{2}$, we can obtain asymptotic power functions under these local alternatives.

3.1 Likelihood Ratio Test Statistic: asymptotic distribution

Theorem 10.3.1 (Wilks Theorem): For testing $H_0 : \theta = \theta_0$ vs. $H_1 : \theta \neq \theta_0$, if $X_1, \dots, X_n \sim i.i.d. f(X|\theta)$, and $f(X|\theta)$ satisfies the regularity conditions in Section 10.6.2. Then under H_0 , as $n \rightarrow \infty$:

$$-2 \log \lambda(\vec{X}) \xrightarrow{d} \chi_1^2.$$

Note: χ_1^2 denotes a random variable from the Chi-squared distribution with 1 degree of freedom. By Lemma 5.3.2 in CB, if $Z \sim N(0, 1)$, then $Z^2 \sim \chi_1^2$. Clearly, χ^2 random variables only have positive support.

Proof: Assume null holds. Use Taylor-series expansion of log-likelihood function around the MLE estimator $\hat{\theta}_n$:

$$\begin{aligned} \sum_i \log f(x_i|\theta_0) &= \sum_i \log f(X_i|\hat{\theta}_n) + \sum_i \frac{\partial}{\partial \theta} \log f(X_i|\theta)|_{\theta=\hat{\theta}_n} \cdot (\theta_0 - \hat{\theta}_n) \\ &\quad + \frac{1}{2} \sum_i \frac{\partial^2}{\partial \theta^2} \log f(X_i|\theta)|_{\theta=\hat{\theta}_n} \cdot (\theta_0 - \hat{\theta}_n)^2 + \dots \\ &= \sum_i \log f(X_i|\hat{\theta}_n) + \frac{1}{2} \sum_i \frac{\partial^2}{\partial \theta^2} \log f(X_i|\theta)|_{\theta=\hat{\theta}_n} \cdot (\theta_0 - \hat{\theta}_n)^2 + \dots \end{aligned} \tag{6}$$

where the second term disappeared because the MLE $\hat{\theta}_n$ sets the first-order condition $\sum_i \frac{\partial}{\partial \theta} \log f(X_i|\theta)|_{\theta=\hat{\theta}_n} = 0$; and the remainder term [...] is asymptotically negligible. This is a second-order Taylor expansion.

Rewrite the above as:

$$-2 \sum_i \log \left(\frac{f(x_i|\theta_0)}{f(X_i|\hat{\theta}_n)} \right) = -\frac{1}{n} \sum_i \frac{\partial^2}{\partial \theta^2} \log f(X_i|\theta)|_{\theta=\hat{\theta}_n} \cdot \left[\sqrt{n}(\theta_0 - \hat{\theta}_n) \right]^2 + o_p(1).$$

Now

$$-\frac{1}{n} \sum_i \frac{\partial^2}{\partial \theta^2} \log f(X_i|\theta) \Big|_{\theta=\hat{\theta}_n} \xrightarrow{p} -E_{\theta_0} \frac{\partial^2}{\partial \theta^2} \log f(X_i|\theta_0) = \frac{1}{V_0(\theta_0)},$$

where $V_0(\theta_0)$ denotes the asymptotic variance of the MLE estimator (CRLB).

Finally, we note that $\frac{\sqrt{n}(\hat{\theta}_n - \theta_0)}{\sqrt{V_0(\theta_0)}} \xrightarrow{d} N(0, 1)$. Hence, by the definition of the χ_1^2 random variable:

$$-2 \log \lambda(\vec{X}) \xrightarrow{d} \chi_1^2.$$

■■■

In the multivariate case (θ being k -dimensional), the above says that

$$-2 \log(\lambda(\vec{X})) \stackrel{a}{=} n(\theta_0 - \theta_n) V(\theta_0)^{-1} (\theta_0 - \theta_n) \sim \chi_k^2.$$

where $V(\theta_0)^{-1}$ denotes the Fisher information matrix (inverse of CRLB). Hence, LR-statistic is asymptotically equivalent to Wald and Score tests.

■■■

Example: $X_1, \dots, X_N \sim i.i.d.$ Bernoulli with prob. p . Test $H_0 : p = \frac{1}{2}$ vs. $H_1 : p \neq \frac{1}{2}$. Let Y_n denote the number of 1's.

$$\lambda(\vec{X}) = \frac{\binom{n}{y_n} \left(\frac{1}{2}\right)^{y_n} \left(\frac{1}{2}\right)^{n-y_n}}{\binom{n}{y_n} \left(\frac{y_n}{n}\right)^{y_n} \left(\frac{n-y_n}{n}\right)^{n-y_n}}.$$

For test with asymptotic size α :

$$\begin{aligned} \alpha &= P(\lambda(\vec{X}) \leq c) \quad (c < 1) \\ &= P(-2 \log \lambda(\vec{X}) \geq -2 \log c) \\ &= P(\chi_1^2 \geq -2 \log c) \\ &= 1 - F_{\chi_1^2}(-2 \log c) \\ \Rightarrow c &= \exp\left(-\frac{1}{2} F_{\chi_1^2}^{-1}(1 - \alpha)\right). \end{aligned}$$

For instance, for $\alpha = 0.05$, then $F_{\chi_1^2}^{-1}(1 - \alpha) = 3.841$; $\alpha = 0.10$, then $F_{\chi_1^2}^{-1}(1 - \alpha) = 2.706$.

INTERVAL ESTIMATION

CB ch. 9, 10.4



In *point estimation*, we recover a point values for an unknown parameter.

But knowing the point value is not enough, we also want to know *how close to the truth* it is. Using *interval estimation*, we make statements that the true parameter lies within some region (typically depending on the point estimate) with some prescribed probability.

Consider a model $f(\vec{X}|\theta)$, with data \vec{X} and unknown θ .

In interval estimation, we make statements like:

$$\theta \in C(\vec{X}) \subset \Theta,$$

where $C(\vec{X})$ is an interval estimate, which depends on the observed data \vec{X} . $C(\vec{X})$ is an interval on the real line (or a connected region in multidimensional Euclidean space).

Definition 9.1.1: an interval estimate for a real-valued parameter θ based on a sample $\vec{X} \equiv (X_1, \dots, X_n)$ is a *pair of functions* $L(\vec{X})$ and $U(\vec{X})$ so that $L(\vec{X}) \leq U(\vec{X})$ for all \vec{X} . For the observed data \vec{X}^o , the inference $L(\vec{X}^o) \leq \theta \leq U(\vec{X}^o)$ is made.

- Both $L(\vec{X})$ and $U(\vec{X})$ are random variables, so that $C(\vec{X}) \equiv [L(\vec{X}), U(\vec{X})]$ is a random interval.
- $[L(\vec{X}), U(\vec{X})]$ is a two-sided interval. Sometimes, you seek $(-\infty, U(\vec{X})]$ or $[L(\vec{X}), \infty)$, which are one-sided intervals.

Definition 9.1.4: the **coverage probability** of an interval estimator is $P_\theta (\theta \in [L(\vec{X}), U(\vec{X})])$.

This is the probability that the random interval $[L(\vec{X}), U(\vec{X})]$ “covers” the true θ .

Important: in the expression for the coverage probability, θ is not random, but $L(\vec{X})$ and $U(\vec{X})$ are. So $P_\theta (\theta \in [L(\vec{X}), U(\vec{X})])$ means $P_\theta (L(\vec{X}) \leq \theta, U(\vec{X}) \geq \theta)$.

Note that the coverage probability can vary depending on what θ is.

Definition 9.1.5: For an interval estimator $[L(\vec{X}), U(\vec{X})]$ of a parameter θ , the **confidence coefficient** $\equiv \inf_\theta P_\theta (\theta \in [L(\vec{X}), U(\vec{X})])$.

The confidence coefficient does not depend on θ .

Usually, we use the term **confidence interval** to refer to a combination of an interval estimate, along with a measure of confidence (such as the confidence coefficient). Hence, a confidence interval is a statement like “ θ is between 1.5 and 2.8 with probability 80%.”



Example: $X_1, \dots, X_n \sim i.i.d. U[0, \theta]$, and $Y_n \equiv \max(X_1, \dots, X_n)$ (the sample maximum). Consider two interval estimators

1. $[aY_n, bY_n]$, where $1 \leq a < b$
2. $[Y_n + c, Y_n + d]$, where $0 \leq c < d$.

What is the confidence coefficient of each?

(1) The coverage probability

$$\begin{aligned} P_\theta(\theta \in [aY_n, bY_n]) &= P_\theta(aY_n \leq \theta \leq bY_n) \\ &= P_\theta\left(\frac{\theta}{b} \leq y \leq \frac{\theta}{a}\right). \end{aligned}$$

From before, we know that density of Y_n is $f(y) = \frac{1}{\theta^n}ny^{n-1}$, for $y \in [0, \theta]$, so that

$$\begin{aligned} P_\theta\left(\frac{\theta}{b} \leq y \leq \frac{\theta}{a}\right) &= \frac{1}{\theta^n} \int_{\frac{\theta}{b}}^{\frac{\theta}{a}} ny^{n-1} dy \\ &= \frac{1}{\theta^n} \left[\left(\frac{\theta}{a}\right)^n - \left(\frac{\theta}{b}\right)^n \right]. \end{aligned}$$

Since coverage probability is not a function of θ , then this is also confidence coefficient.

(2) The coverage probability

$$\begin{aligned} P_\theta(\theta \in [Y_n + c, Y_n + d]) &= P_\theta(Y_n + c \leq \theta \leq Y_n + d) \\ &= P_\theta\left(1 - \frac{d}{\theta} \leq \frac{y}{\theta} \leq 1 - \frac{c}{\theta}\right) \\ &= P_\theta(\theta - d \leq y \leq \theta - c) \\ &= \frac{1}{\theta^n} \int_{\theta-d}^{\theta-c} ny^{n-1} dy = \frac{1}{\theta^n} ((\theta - c)^n - (\theta - d)^n) \end{aligned}$$

so that coverage probability depends on θ .



Methods of Finding Interval Estimators

General principle: “invert” a test statistic

Testing tells you: under a given $H_0 : \theta = \theta_0$,

$$P_{\theta_0}(T_n \in R) = \alpha \Leftrightarrow P_{\theta_0}(T_n \notin R) = 1 - \alpha,$$

where T_n is a test statistic.

We can use this to construct a $(1 - \alpha)$ confidence interval:

- Define acceptance region $A = \mathbb{R} \setminus R$.
- If you *fix* α , but vary the null hypothesis θ_0 , then you obtain $R(\theta_0)$, a rejection region for each θ_0 such that, by construction:

$$\forall \theta_0 \in \Theta : P_{\theta_0}(T_n \notin R(\theta_0)) = P_{\theta_0}(T_n \in A(\theta_0)) = 1 - \alpha.$$

- Now, for a given sample $\vec{X} \equiv X_1, \dots, X_n$, consider the set

$$C(\vec{X}) \equiv \left\{ \theta : T_n(\vec{X}) \in A(\theta) \right\}.$$

By construction:

$$P_{\theta}(\theta \in C(\vec{X})) = P_{\theta}(T_n(\vec{X}) \in A(\theta)) = 1 - \alpha, \forall \theta \in \Theta.$$

Therefore, $C(\vec{X})$ is a $(1 - \alpha)$ confidence interval for θ .

- The confidence interval $C(\vec{X})$ is the set of θ 's such that, for the given data \vec{X} and for each $\theta_0 \in C(\vec{X})$, you would not be able to reject the null hypothesis $H_0 : \theta = \theta_0$.
- In hypothesis testing, acceptance region is set of \vec{X} which are very likely for a fixed θ_0 .

In interval estimation, confidence interval is set of θ 's which make \vec{X} very likely, for a fixed \vec{X} .

This “inversion” exercise is best illustrated graphically.



Example: $X_1, \dots, X_n \sim i.i.d. N(\mu, 1)$.

We want to construct a 95% CI for μ by inverting the T-test.

- We know that, under each null $H_0 : \mu = \mu_0$, $\sqrt{n}(\bar{X}_n - \mu_0) \sim N(0, 1)$.
- Hence, for each μ_0 , a 95% acceptance region is

$$\begin{aligned} & \left\{ -1.96 \leq \sqrt{n}(\bar{X}_n - \mu_0) \leq 1.96 \right\} \\ \Leftrightarrow & \left\{ \bar{X}_n - \frac{1}{\sqrt{n}}1.96 \leq \mu_0 \leq \bar{X}_n + \frac{1}{\sqrt{n}}1.96 \right\} = C(\bar{X}_n) \end{aligned}$$

- Graph:

- Now consider what happens when we invert one-sided test. Consider the hypotheses $H_0 : \mu \leq \mu_0$ vs. $H_1 : \mu > \mu_0$. Then a 95% acceptance region is

$$\begin{aligned} & \{ \sqrt{n} (\bar{X}_n - \mu_0) \leq 1.645 \} \\ \Leftrightarrow & \left\{ \mu_0 \leq \bar{X}_n - \frac{1}{\sqrt{n}} 1.65 \right\} = C(\bar{X}_n) \end{aligned}$$

- Graph:



Example: $X_1, \dots, X_n \sim U[0, \theta]$. Construct a confidence set based on inverting the LRT.

- Consider the one-sided hypotheses $H_0 : \theta \leq \theta_0$ vs. $H_1 : \theta > \theta_0$.
- As derived before: $\lambda(\vec{X}) = \begin{cases} 0 & \text{if } \max(X_1, \dots, X_n) > \theta_0 \\ 1 & \text{otherwise.} \end{cases}$
- So acceptance region is $\{Y_n \equiv \max(X_1, \dots, X_n) \leq \theta_0\}$ and confidence set is $\{\theta_0 : \theta_0 \geq Y_n\} = C(Y_n)$.

- Graph

- What is confidence coefficient? $P_{\theta}(\theta \in C(Y_n)) = P_{\theta}(\theta \geq Y_n) = 1$, for all θ !

Additional topics

3.2 [SKIP] Discussion of NP Lemma

Rather than present a proof of NP Lemma (you can find one in CB), let's consider some intuition for the NP test. In doing so, we will derive an interesting duality between Bayesian and classical approaches to hypothesis testing (the NP Lemma being a key result of the latter).

Start by considering a Bayesian approach to this testing problem. Assume that decision-maker incurs loss γ_1 if he mistakenly chooses H_1 when H_0 is true, and γ_2 if he mistakenly chooses H_0 when H_1 is true. Then, given data observations \vec{x} , he will

$$\text{Reject } H_0 \text{ (=accept } H_1) \Leftrightarrow \gamma_1 P(\theta_0|\vec{x}) < \gamma_2 P(\theta_1|\vec{x}) \quad (*)$$

where $P(\theta_0|\vec{x})$ denotes the posterior probability of the null hypothesis given data \vec{x} . In other words, this Bayesian's rejection region R_0 is given by

$$R_0 = \left\{ \vec{x} : \frac{P(\theta_1|\vec{x})}{P(\theta_0|\vec{x})} > \frac{\gamma_1}{\gamma_2} \right\}.$$

If we multiply and divide the ratio of posterior probabilities by $f(\vec{x})$, the (marginal) joint density of \vec{x} , and use the laws of probability, we get:

$$\begin{aligned} R_0 &= \left\{ \vec{x} : \frac{P(\theta_1|\vec{x})f(\vec{x})}{P(\theta_0|\vec{x})f(\vec{x})} > \frac{\gamma_1}{\gamma_2} \right\} \\ &= \left\{ \vec{x} : \frac{L(\vec{x}|\theta_1)P(\theta_1)}{L(\vec{x}|\theta_0)P(\theta_0)} > \frac{\gamma_1}{\gamma_2} \right\} \\ &= \left\{ \vec{x} : \frac{L(\vec{x}|\theta_1)}{L(\vec{x}|\theta_0)} > \frac{\gamma_1 P(\theta_0)}{\gamma_2 P(\theta_1)} \equiv c \right\}. \end{aligned}$$

In the above, $P(\theta_0)$ and $P(\theta_1)$ denote the prior probabilities for, respectively, the null and alternative hypotheses. This is the likelihood ratio form of the NP rejection region.

Next we show a duality between the Bayesian and classical approaches to finding the "best" test. In the case of two simple hypotheses, a best test should be such that for a given size α , it should have the smallest type 2 error β (these are called "admissible" tests). For any testing scenario, the frontier (in (β, α) space) of tests is convex. (Why?) Both the Bayesian and the classical statistician want to choose a test that is on the frontier, but they might differ in the one they choose.

First consider the Bayesian. She wishes to employ a test, equivalently, choose a rejection region R , to minimize expected loss

$$\min_R \phi(R) \equiv \gamma_1 P(\theta_0|\vec{X} \in R)P(\vec{X} \in R) + \gamma_2 P(\theta_1|\vec{X} \in \bar{R})P(\vec{X} \in \bar{R}).$$

We will show that the region R_0 defined above optimizes this problem. Consider any other region R_1 . Recall that $R_0 = (R_0 \cap R_1) \cup (R_0 \cap \bar{R}_1)$. Then we can rewrite

$$\begin{aligned}\phi(R_0) = & \gamma_1 P(\theta_0 | R_0 \cap R_1) P(R_0 \cap R_1) + \gamma_1 P(\theta_0 | R_0 \cap \bar{R}_1) P(R_0 \cap \bar{R}_1) \\ & + \gamma_2 P(\theta_1 | \bar{R}_0 \cap R_1) P(\bar{R}_0 \cap R_1) + \gamma_2 P(\theta_1 | \bar{R}_0 \cap \bar{R}_1) P(\bar{R}_0 \cap \bar{R}_1).\end{aligned}$$

$$\begin{aligned}\phi(R_1) = & \gamma_1 P(\theta_0 | R_1 \cap R_0) P(R_1 \cap R_0) + \gamma_1 P(\theta_0 | R_1 \cap \bar{R}_0) P(R_1 \cap \bar{R}_0) \\ & + \gamma_2 P(\theta_1 | \bar{R}_1 \cap R_0) P(\bar{R}_1 \cap R_0) + \gamma_2 P(\theta_1 | \bar{R}_1 \cap \bar{R}_0) P(\bar{R}_1 \cap \bar{R}_0).\end{aligned}$$

First and fourth terms of equations above are identical. From the definition of R_0 above, we know that $\phi(R_0)_{ii} < \phi(R_1)_{iii}$. That is, for all $\vec{x} \in R_0 \supseteq R_0 \cap \bar{R}_1$, we know from (*) that $\gamma_1 P(\theta_0 | \vec{x}) < \gamma_2 P(\theta_1 | \vec{x})$. Similarly, we know that $\phi(R_0)_{iii} < \phi(R_1)_{ii}$, implying that $\phi(R_0) < \phi(R_1)$. This shows that the optimal Bayesian test takes a likelihood-ratio form.

Moreover, using the laws of probability, we can re-express for any rejection region R

$$\phi(R) = \gamma_1 P(\theta_0) P(R | \theta_0) + \gamma_2 P(\theta_1) P(\bar{R} | \theta_1) \equiv \eta_0 \alpha_R + \eta_1 \beta_R$$

with $\eta_0 = \gamma_1 P(\theta_0)$ and $\eta_1 = \gamma_2 P(\theta_1)$. In (β, α) space, the “iso-loss” curves are parallel lines with slope $-\eta_0/\eta_1$, decreasing towards the origin. Hence, the optimal test (with region R_0) lies at tangency of (α, β) frontier with a line with slope $-\eta_0/\eta_1$.

Now consider the classical statistician. He doesn't want to specify priors $P(\theta_0)$, $P(\theta_1)$, so η_0 , η_1 are not fixed. But he is willing to specify a desired size α^* . Hence the optimal test is the one with a rejection region characterized by the slope of the line tangent at α^* in the (β, α) space. This is in fact the NP test. From the above calculations, we know that this slope is equivalent to $-c$. That is, the NP test corresponds to an optimal Bayesian test with $\eta_0/\eta_1 = c$.

3.3 Power calculations

In design of experiments, a typical exercise which is done is a *power calculation*. The idea is the following: given likely values of a treatment effect, how large does the sample size need to be in order to reliably detect the treatment effect?

As an example, consider an “A/B test” (randomized controlled trial) run at Facebook to test a new ad strategy. There are N Facebook users who are presented with a conventional ad, while N other users are randomly presented with a new ad. From each user we observe a binary outcome, which is whether they click on the ad. The aggregate outcome is the “click-through rate” (CTR) in both the treatment and control samples. Ex ante, we need to figure out how large N should be in order to reliably detect an increase in CTR between the control and treatment samples.

The exogenous parameters in the calculation are: (i) the likely hypothetical *effect size*; (ii) the reject prob under the null of no effect (*size*); (iii) the acceptance probability under the alternative (*power*). For power calculations, the null hypothesis is the false idea that the effect size=0, while the alternative hypothesis is the true idea that the effect size \neq 0, but potentially very small (and thus hard to distinguish from zero).

For our example, let's pick (i) the hypothetical effects are $CTR_C = 0.01$, $CTR_T = 0.011$ so the effect size is $\Delta CTR = 0.001$ (10% increase in CTR); (ii) size=0.05; (iii) power=0.8.

Let \overline{CTR}_i for $i = C, T$ denote the estimated CTR in the control and treatment samples, respectively, and $\overline{\Delta CTR} \equiv \overline{CTR}_T - \overline{CTR}_C$ thhe estimated effect size. For N large enough, we can use the asymptotic approximation to get that, under the alternative H_1 ($\Delta CTR = 0.001$), we have

$$\overline{\Delta CTR} \sim N(0.001, V/n)$$

where $V = CTR_C(1 - CTR_C) + CTR_T(1 - CTR_T) = 0.01(1 - 0.01) + 0.011(1 - 0.011)$ is the asymptotic variance.

Next we use a T-test to test for treatment effect significance. That is, we reject the null of no effect if $\sqrt{N} \frac{\overline{\Delta CTR}}{\sqrt{V}} > 1.65$ (a one-sided 5% test). Then the power requirement implies we want to reject the null under the alternative with probability at least 80% ie. we have

$$\begin{aligned} 0.8 &\leq Pr_{H_1} \left(\sqrt{N} \frac{\overline{\Delta CTR}}{\sqrt{V}} > 1.65 \right) \\ &= Pr_{H_1} \left(\sqrt{N} \frac{\overline{\Delta CTR} - \Delta CTR}{\sqrt{V}} > 1.65 - \frac{\sqrt{N} \Delta CTR}{\sqrt{V}} \right) \\ &\approx Pr \left(N(0, 1) > 1.65 - \frac{\sqrt{N} \Delta CTR}{\sqrt{V}} \right) \\ &= 1 - \Phi \left(1.65 - \frac{\sqrt{N} \Delta CTR}{\sqrt{V}} \right). \end{aligned}$$

Rearranging, we have $\Phi \left(1.65 - \frac{\sqrt{N} \Delta CTR}{\sqrt{V}} \right) \leq 0.2$ or

$$\sqrt{N} \geq \left[\frac{\sqrt{V}}{\Delta CTR} \right] (1.65 - \Phi^{-1}(0.2)) \approx 1080$$

so we require N to be larger than 1080^2 observations.

3.4 Multiple hypotheses and Bonferroni corrections

Let H_1, \dots, H_m be a collection of hypotheses and p_1, \dots, p_m their corresponding p -values. That is, for the case of a one-sided T-test, p_i is the probability $P(Z \geq T_m)$ where $Z \sim$

$N(0,1)$ and T_m is the usual T-statistic. Hence, for a size- α test, we reject a hypothesis when $p_i < \alpha$.

When testing multiple hypotheses simultaneously, we need to redefine the notion of “size” (corresponding to Type 1 error, or false rejection of a null hypothesis). A common notion is the *familywise error rate (FWER)*, defined as the probability of rejecting at least one true H_i , that is, of making at least one type I error. This corresponds to the event that at least one of the p-values fails to exceed α , ie. $\{\cup_{m=1}^m (p_m \leq \alpha)\}$. Under the joint null that all the hypotheses are true, if we were to test each hypothesis at size α , we have (using Boole’s inequality)

$$FWER = P_0 \{ \cup_{m=1}^m (p_m \leq \alpha) \} \leq \sum_{m=1}^m P_0 (p_m \leq \alpha) = m\alpha$$

which gives us an intolerably high bound on the FWER. If we want to reduce this bound on the FWER to α , then we should reject each individual null hypothesis at $p_m \leq \alpha/m$. This is known as the **Bonferroni correction**.

In the case of a one-sided T-test, it implies that we should reject when $T_m \geq \Phi^{-1}(1 - \alpha/m)$. For $\alpha = 0.05$: the critical values $\Phi^{-1}(1 - \alpha/m)$ are:

m	critical values
1	1.645
2	1.96
5	2.326
10	2.575
100	3.29
1000	3.98

That is, the critical value increases the more hypotheses you are simultaneously testing. Effectively, you become *more conservative* for each individual hypothesis, only rejecting when the evidence is more overwhelming.

Applications: combining randomized-control trials (meta-analysis), genomics