

Data Analysis Software Project

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- Obtain data in useful units (i.e., get $S(\vec{Q}, E)$).
- Focus of my talk – Connect data to models and simulations.
 - *Big idea*: Full experiment simulations
 - *Mid-Size idea*: Invert dynamical models.

$S(\vec{Q}, \omega)$ **Approach**

- $S(Q, \omega)$ is a minimum standard for what users need to take home
- Absolute units [barns, meV, $\text{\AA}^{-1}$]
- Efficient instrument calibration
- How to handle E , $\vec{Q}$ resolution and background?
- Special considerations for single crystals ($\vec{Q}$, not Q)
 - Real-time information on locations of dispersive excitations (guidance of goniometer?)
 - Data visualization

Magnetic Dynamics (local model)

$$\frac{d^2\sigma}{d\Omega dE} \propto \sum_{\alpha,\beta} (\delta_{\alpha\beta} - \hat{Q}_\alpha \hat{Q}_\beta) \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} e^{i(\vec{Q}\cdot\vec{r}-\omega t)} \Gamma_{\alpha\beta}(\vec{r}, t) d\vec{r} dt$$

$$\Gamma_{\alpha\beta}(\vec{r}, t) = \sum_l \sum_{l'} \langle \hat{S}_l^\alpha \hat{S}_{l'}^\beta(t) \rangle \int_{-\infty}^{\infty} \delta(\vec{r} + \vec{R}_l - \vec{r}') \delta(\vec{r}' - \vec{R}_{l'}(t)) d\vec{r}' dt$$

spin correlations nuclear correlations

- Need simulations of magnetic and lattice dynamics, using both exchange forces and springs.
- To scatter from simulations, transform to wavepackets:

$$e^{i(\vec{k}\cdot\vec{r}-\omega t)} \rightarrow G^{\Delta r}(\vec{r}) G^{\Delta t}(t) e^{i(\vec{k}\cdot\vec{r}-\omega t)}$$

$$e^{i(\vec{k}'\cdot\vec{r}-\omega' t)} \rightarrow G^{\Delta r'}(\vec{r}) G^{\Delta t'}(t) e^{i(\vec{k}'\cdot\vec{r}-\omega' t)}$$

In $\{E, \vec{Q}\}$, this is equivalent to convolutions of broadened incident and scattered wavepackets.

Magnetic Dynamics (susceptibility approach)

$$\frac{d^2\sigma}{d\Omega dE} \propto (1 + n(\omega)) \sum_{\alpha,\beta} (\delta_{\alpha,\beta} - \hat{Q}_\alpha \hat{Q}_\beta) \mathcal{I}m[\bar{\chi}_{\vec{Q}}^{\alpha\beta}(-\omega)]$$

$$\bar{\chi}_{\vec{Q}}^{\alpha\beta}(-\omega) = \int_{-\infty}^{\infty} e^{i\omega t} \langle [\hat{T}_{\vec{Q}}^\alpha(t), \hat{T}_{\vec{Q}}^\beta(0)] \rangle dt$$

$$\hat{T}_{\vec{Q}}^\alpha(t) = \sum_l e^{-W(\vec{Q})} e^{i\vec{Q} \cdot \vec{l}} G^{\Delta t}(t) G^{\vec{\Delta}l}(\vec{l}) \hat{S}_l^\alpha$$

- Should we modify $\bar{\chi}$ by the Δt , $\vec{\Delta}l$, or should we modify the $d^2\sigma/d\Omega dE$?
- Does the susceptibility approach belong in the $S(\vec{Q}, E)$ approach, or the full experiment simulation approach?
- Can we provide a seamless user interface across both approaches?

Simulations

- Monte Carlo Simulations of Dynamics
(true simulation – iterate parameters of simulation)
 - Molecular dynamics packages exist.
(Should we pick one for phonon scattering?)
 - What about realistic magnetic dynamics packages?
(Can we find a suitable classical dynamics model with, for example, magnetovibrational coupling?
Is there interest from theorists in a quantum dynamics simulation?)

Models

- Inversions of Analytical Models
(not a true “simulation” – iterate parameters of model)
 - Lattice dynamics – Well underway, example below.
 - Magnetic dynamics – Your ideas and opinions are solicited!

Born–von Kármán Inversions of Phonon DOS

- No problem from “neutron weighting” by σ/m
(use dynamics to calculate actual data, including neutron weights)
- Extreme case – inelastic nuclear resonant x-ray scattering from ^{57}Fe – for $\text{Pt}_3^{57}\text{Fe}$, $\sigma_{\text{Pd}}/m_{\text{Pd}} = 0$

Invert the ^{57}Fe Phonon Partial DOS of $\text{Pt}_3^{57}\text{Fe}$

- Definition of phonon DOS

$$g(\varepsilon) \equiv \sum_j^{\text{modes}} \delta(\varepsilon - \varepsilon_j)$$

- Definition of Fe phonon partial DOS

$$g^{\text{Fe}}(\varepsilon) \equiv \sum_j^{\text{modes}} |\vec{\sigma}_{\vec{q}}^{\text{Fe}}|^2 \delta(\varepsilon - \varepsilon_j)$$

- Using normalization of $1|\vec{\sigma}_{\vec{q}}^{\text{Fe}}|^2 + 3|\vec{\sigma}_{\vec{q}}^{\text{Pd}}|^2 = 1$
for four-atom unit cell of Pt_3Fe

$$g(\varepsilon) = 1g^{\text{Fe}}(\varepsilon) + 3g^{\text{Pd}}(\varepsilon)$$

- We measure only $g^{\text{Fe}}(\varepsilon)$. To calculate $g^{\text{Fe}}(\varepsilon)$, we must have the full lattice dynamics. We therefore get $g^{\text{Pd}}(\varepsilon)$ as a byproduct. Is this $g^{\text{Pd}}(\varepsilon)$ reliable?

Neutron Simulation Codes

- NISP
 - FORTRAN
 - LANL
- MSLICE
 - Matlab
 - ISIS
 - closer to $S(\vec{q}, \omega)$ approach
- Vitess
 - tcl
 - HMI
- McStas
 - C
 - Riso
- ISAW
 - java
 - ANL

Caltech Activity – Hardware

- Beowulf Cluster (partly tested)
 - 16 node, each with one 1.4 GHz Athlon processor, 512 MB RAM, 40 GB HD, box
 - switched ethernet interconnection
 - 240 GB Raid drive
 - Red Hat Linux

Caltech Activity – Software

- DOS inversions $g_{Fe}(\varepsilon) \rightarrow \{\phi_{\alpha\beta}^{jj'}(\varepsilon)\}$
 - On Beowulf cluster, each node runs same code but different parameter set
 - Each inversion iteration (32 parameters) requires about 8 h on 0.4 GHz node
 - Two days for robust analysis

Summary of Directions for Software Project

- Develop a software framework for data analysis.
 - Establish the scope of capabilities.
 - Can we provide a common front-end to integrate simulations, models, direct analysis of data?
 - Assess existing neutron simulation packages. Repackage to fit in the framework.
- Magnetic Scattering
 - Assess classes of theoretical models.
 - Workgroup volunteers needed.
- Phonon Scattering
 - Born–von Kármán inversions: Weight in phonon dispersion data. Test the role of noise. $S(\vec{Q}, \omega)$ with mixed coherent/incoherent scattering.
 - Select molecular dynamics package. Timing tests for wavepacket scattering.
- Science
 - Money for science must be used wisely.
 - Must be done to leverage an integrated software development effort.