

# Lecture 11

*Dinakar Ramakrishnan*

(The odd numbered lectures are given by D. Ramakrishnan, and the even ones by R. Tanner.)

## 0.1 A quadratic approximation at $s = s_0$

This section is not delicate as the previous ones, since the  $s$ -derivatives of  $v \frac{dp}{ds}$  are all well defined and easily calculated at  $s_0$  (unlike at  $s = 0$ ). Nevertheless, the formulae below are useful in the following section. As before, we will write  $s'$  for  $\frac{ds}{dt}$ ,  $c' = \frac{dc}{dt}$ , etc.

Lemma *At the point  $s = s_0$ , the following values hold:*

$$(a) \quad s' = -k_2 s_0 e_0, \quad c' = k_1 s_0 e_0, \quad \text{and} \quad e' = k_1 s_0 e_0.$$

$$(b) \quad \frac{dv}{ds} = -k_3.$$

$$(c) \quad \frac{d^2 v}{ds^2} = -\frac{k_3^2}{k_1 s_0 e_0}.$$

Consequently, the quadratic Taylor approximation to  $v$  near  $s = s_0$  is given by

$$v = -k_3(s - s_0) - \frac{k_3^2}{2k_1 s_0 e_0}(s - s_0)^2 + O((s - s_0)^3).$$

*Proof.* (a): This follows directly from the basic differential equations by evaluation at  $s_0$ .

(b): We saw in the proof of Lemma 2.1 that

$$\frac{dc}{ds} = -1 - k_3 \frac{c}{s'}.$$

Since  $v = k_3 c$  and  $c = e_0 - e$  is zero at  $s_0$ , we get  $\frac{dv}{ds} = -k_3$ .

(c): Differentiating relative to  $t$ ,

$$\frac{d}{dt} \left( \frac{dc}{ds} \right) = -k_3 \frac{s' c' - s'' c}{(s')^2}.$$

## 0.2 Approximations to $s_p$

Now that we have expansions for  $v$  at 0 and at  $s_0$ , we can find a series of approximations  $s_{p,n}$  to  $s_p$ , which will be good for small  $s_0$ , by equating the  $n$ -th order terms of the respective expansions.

### Proposition

(a)  $s_{p,1} = \frac{k_3 s_0}{m+k_3}$ ;

(b)  $s_{p,2}$  satisfies a quadratic equation:

$$AX^2 + BX + C = 0,$$

with

$$A = \left( \frac{k_3^2}{2k_1 s_0 e_0} - \frac{(k_3 + m)k_1 m}{k_3^2 + k_3 + m k_2} \right),$$

$$B = \left( \frac{k_3}{2k_1 e_0} - m - k_3 \right),$$

and

$$C = \left( \frac{k_3^2}{2k_1 e_0} - k_3 s_0 \right) \left( \frac{k_3}{2k_1 s_0 e_0} - 1 \right).$$

Note that  $s_{p,1}$  corresponds to the  $s$ -coordinate of the point obtained by intersecting the tangent lines to the  $(v, s)$ -curve at  $s = 0$  and  $s = s_0$ . On the other hand,  $s_{p,2}$  denotes the  $s$ -coordinate of the meeting of the quadratic approximations to the  $(v, s)$ -curve at 0 and  $s_0$ , which provides a better approximation.