

## Circuit Equations

Choose as the dynamical variables:

- $V_1$ : the voltage across capacitor  $C_1$  (and the nonlinear resistance)
- $V_2$ : the voltage across capacitor  $C_2$  (and the voltage across the inductor)
- $I$ : the current through the inductor.

Kirchoff's laws then give

$$\begin{aligned} C_1 \frac{dV_1}{dt} &= R^{-1} (V_2 - V_1) - g(V_1) \\ C_2 \frac{dV_2}{dt} &= -R^{-1} (V_2 - V_1) + I \\ L \frac{dI}{dt} &= -rI - V_2 \end{aligned}$$

where  $g(V)$  is the nonlinear current-voltage characteristic for the effective nonlinear resistor (and is a negative quantity for the circuit). If we scale resistances by  $R_1$ , times by  $C_1 R_1$ , measure voltages with respect to the switch point  $V_c$  in  $g(V)$ , and currents with respect to  $V_c/R_1$ , we get the equations

$$\begin{aligned} \frac{dX}{dt} &= a(Y - X) - \bar{g}(X) \\ \frac{dY}{dt} &= \sigma[-a(Y - X) + Z] \\ \frac{dZ}{dt} &= -c(Y + \bar{r}Z) \end{aligned}$$

with  $X = V_1/V_c$ ,  $Y = V_2/V_c$ ,  $Z = R_1 I/V_c$ , and then the parameters of the equations are:

$a$	$R_1/R$	0.923
$b$	$1 - R_1/R_2$	0.636
$c$	$C_1 R_1^2/L$	0.779
$\sigma$	$C_1/C_2$	0.066
$\bar{r}$	$r/R_1$	0.071

with the third column giving the values for the initial parameters of the applet. The nonlinear conductance is

$$\bar{g}(X) = \begin{cases} -X & |X| < 1 \\ [-1 + b(|X| - 1)] \operatorname{sgn}(X) & 1 < |X| < 10 \\ [10(|X| - 10) + (9b - 1)] \operatorname{sgn}(X) & |X| > 10 \end{cases}$$

where the expression for  $|X| > 10$  is needed for stability, and corresponds to complicated saturation effects in the actual circuit. Note that the slope is  $-1$  for  $|X| < 1$ ,  $-b$  for  $1 < |X| < 10$ , and  $10$  for  $|X| > 10$ .

The time independent solutions are at

$$X = \pm \frac{1-b}{\frac{a}{1+\bar{r}a} - b} \simeq \pm \frac{1-b}{a-b}, \quad Y = \frac{a\bar{r}}{1+\bar{r}a} X \simeq 0, \quad Z = -\frac{a}{1+\bar{r}a} X \simeq -aX \quad .$$

Linearizing about the fixed points gives solutions varying as  $e^{\lambda t}$  with  $\lambda$  given by the eigenvalues of the stability matrix

$$\begin{bmatrix} -a+b & a & 0 \\ \sigma a & -\sigma a & \sigma \\ 0 & -c & -\bar{r}c \end{bmatrix}$$

and positive  $\lambda$  means the stationary solutions are unstable.

Some examples of the eigenvalues  $\lambda_1$ ,  $\lambda_2$ , and  $\lambda_3$ :

$a$	$b$	$c$	$\sigma$	$\bar{r}$	$\lambda_1$	$\lambda_{2,3}$
0.923	0.636	0.779	0.066	0.071	-.40191	$-6.5991 \times 10^{-4} \pm .17715i$
1	0.636	0.779	0.066	0.071	-.48631	$5.0174 \times 10^{-4} \pm .1836i$
0.923	0.636	0.779	0.066	0	-.40617	$2.9125 \times 10^{-2} \pm .18836i$
1	0.636	0.779	0.066	0	-.48897	$2.9486 \times 10^{-2} \pm .1934i$

In each case there is one decaying (negative) eigenvalue, and a pair of oscillating (complex) eigenvalues, with an imaginary part around 0.2, corresponding roughly to the  $1/\sqrt{LC_2}$  oscillation frequency, and a real part that is either slightly negative (decaying oscillation) as for the parameters of the applet (first row) or slightly positive (growing oscillation) for the other rows.