

Collective Effects
in
Equilibrium and Nonequilibrium Physics

Website: <http://cncs.bnu.edu.cn/mccross/Course/>

Caltech Mirror: <http://haides.caltech.edu/BNU/>

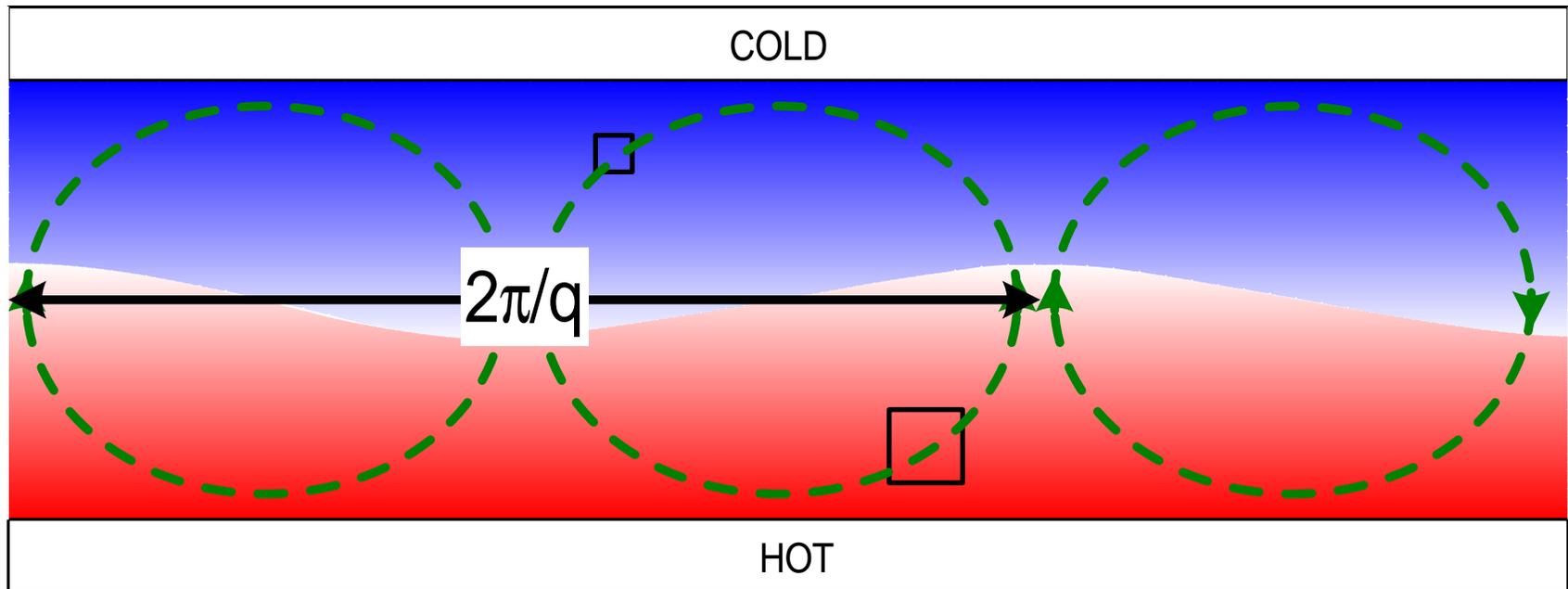
Today's Lecture: Nonlinear Theory of Patterns near Onset

Outline

- Review: linear instability towards patterns
- Qualitative picture of nonlinear, spatially periodic patterns
- General Patterns Near Onset
 - ◇ One dimensional amplitude equation
 - ◇ Generalizations to two dimensions

Analogies to and differences from equilibrium phase transition to broken symmetry state

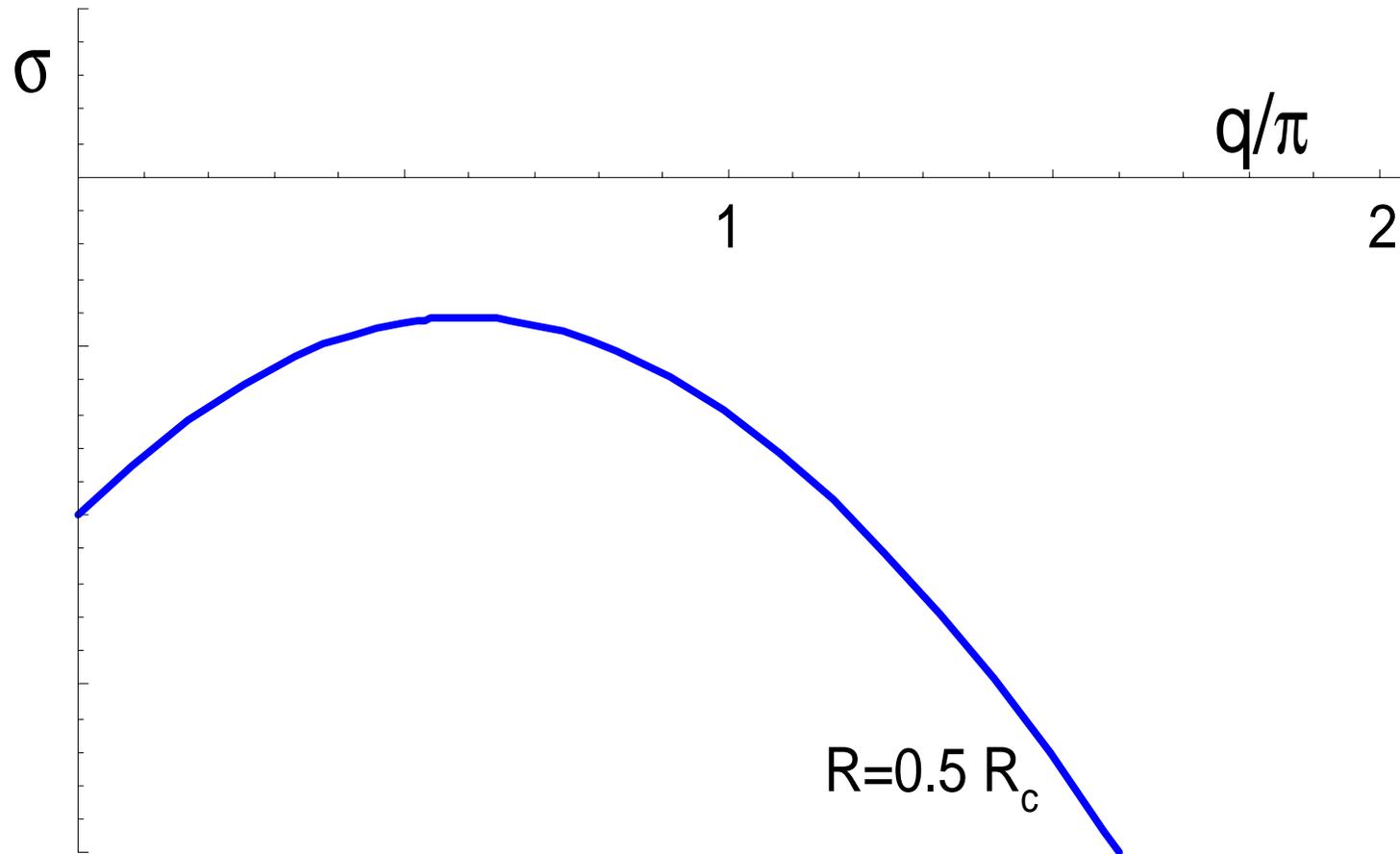
Review of Rayleigh-Bénard Instability



Linear Stability Analysis

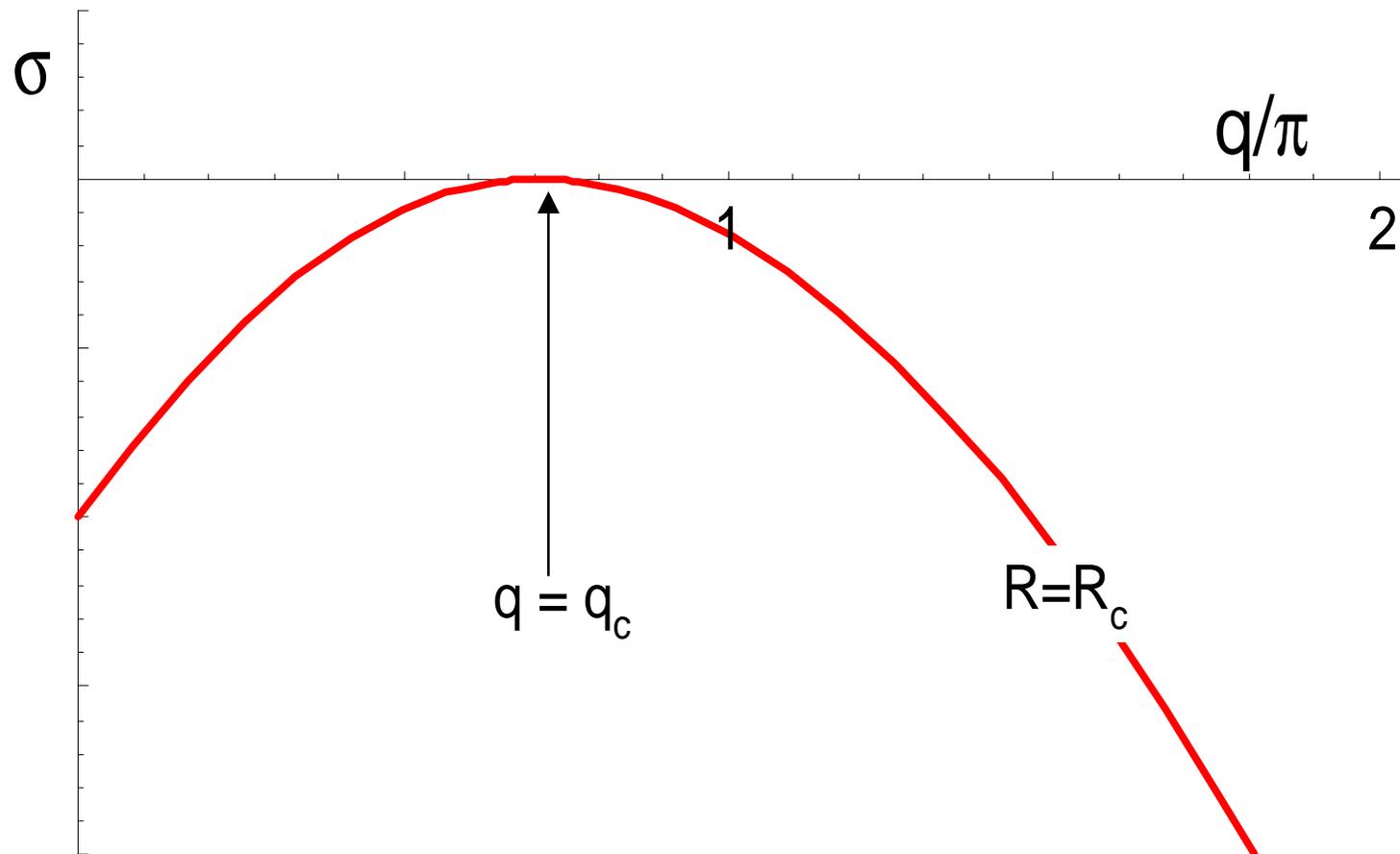
- Driving strength: Rayleigh number $R \propto \Delta T$
- Look for linear mode $u, \theta \propto e^{\sigma(q)t} \cos(qx)$
- Calculate $\sigma(q)$ as a function of R
- $\sigma(q) > 0$ indicates exponential growth, i.e., instability towards a pattern with periodicity $2\pi/q$

Rayleigh's Growth Rate (for $\mathcal{P} = 1$)



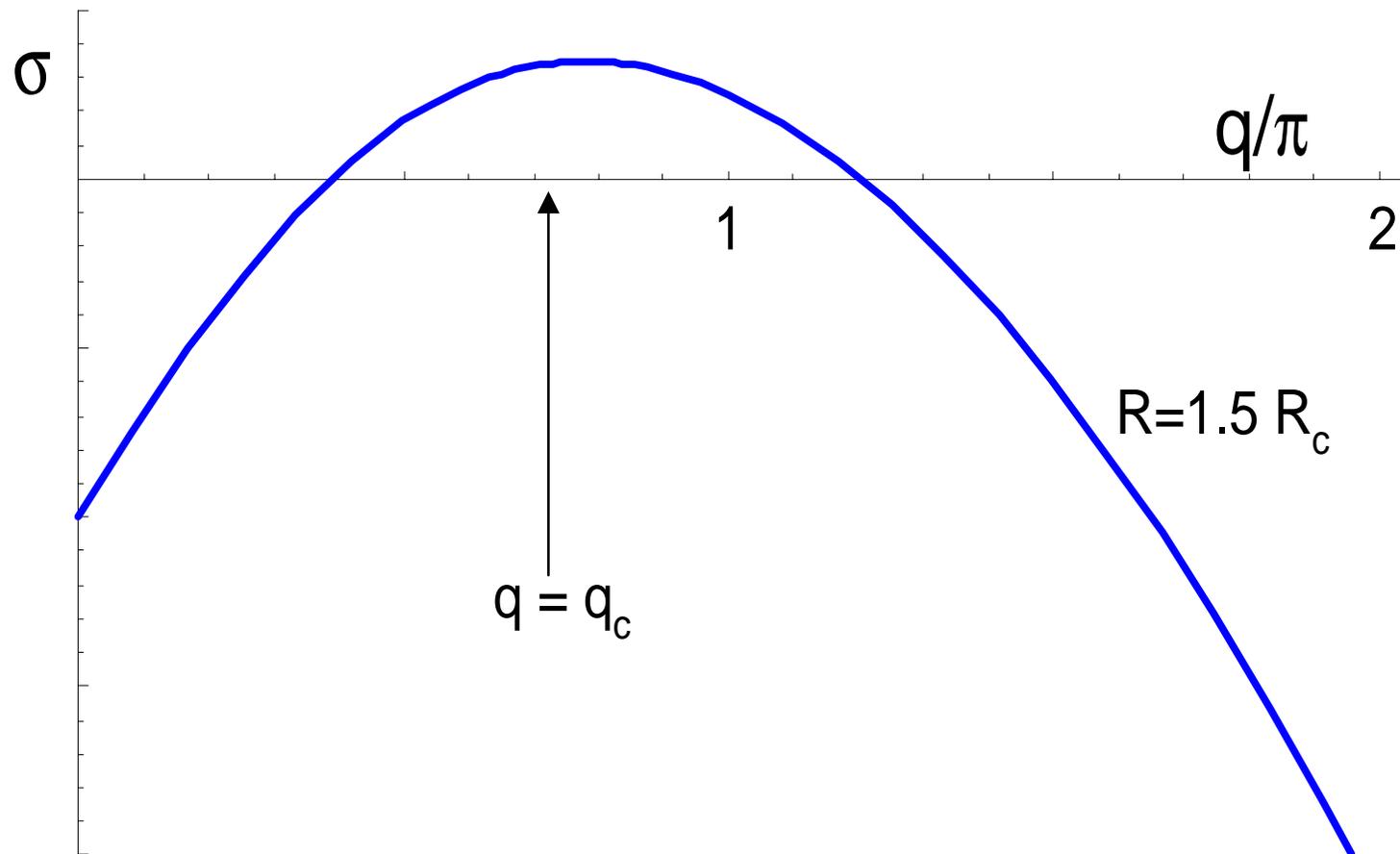
$$R_c = \frac{27\pi^4}{4}, \quad q_c = \frac{\pi}{\sqrt{2}}$$

Rayleigh's Growth Rate (for $\mathcal{P} = 1$)



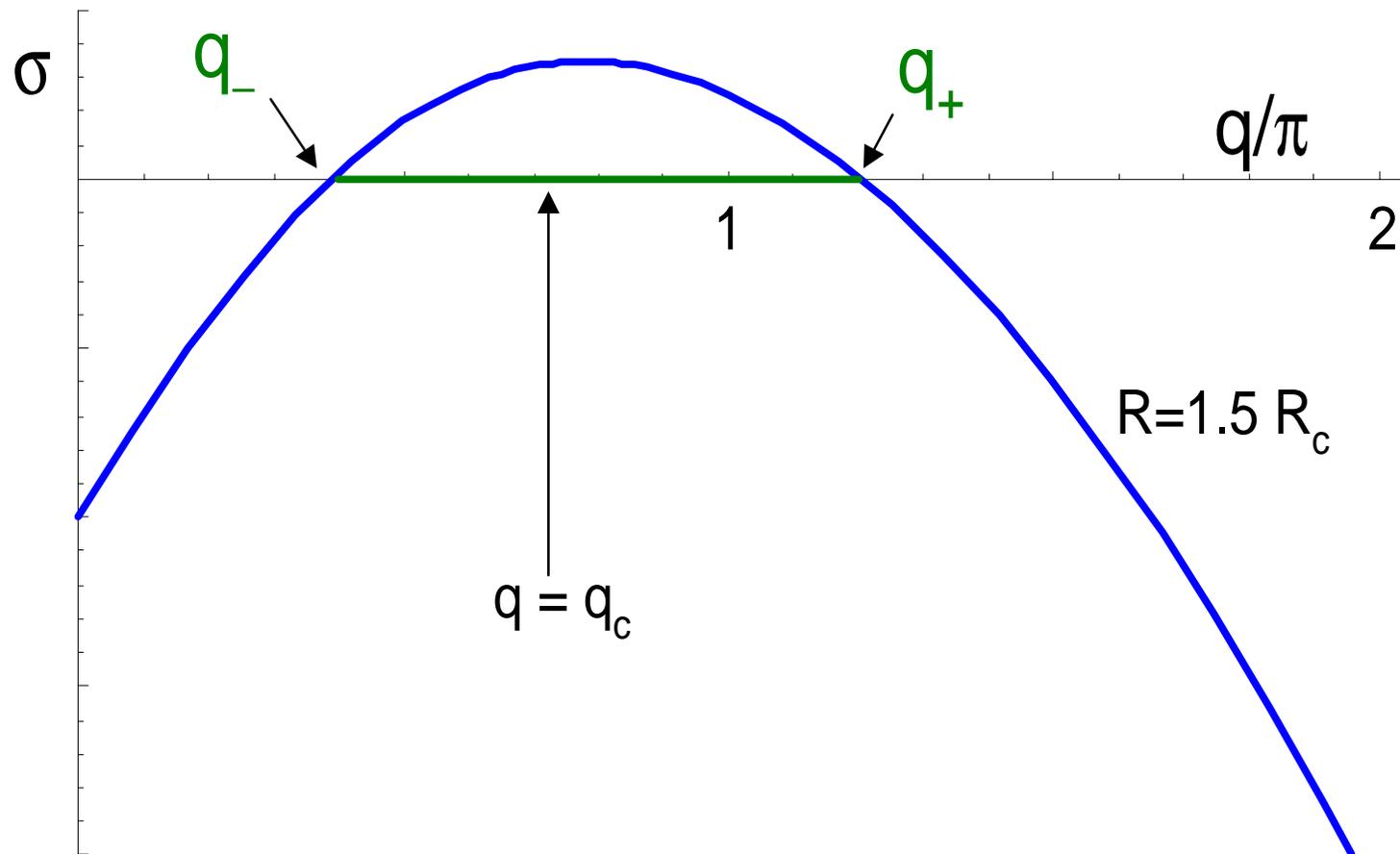
$$R_c = \frac{27\pi^4}{4}, \quad q_c = \frac{\pi}{\sqrt{2}}$$

Rayleigh's Growth Rate (for $\mathcal{P} = 1$)



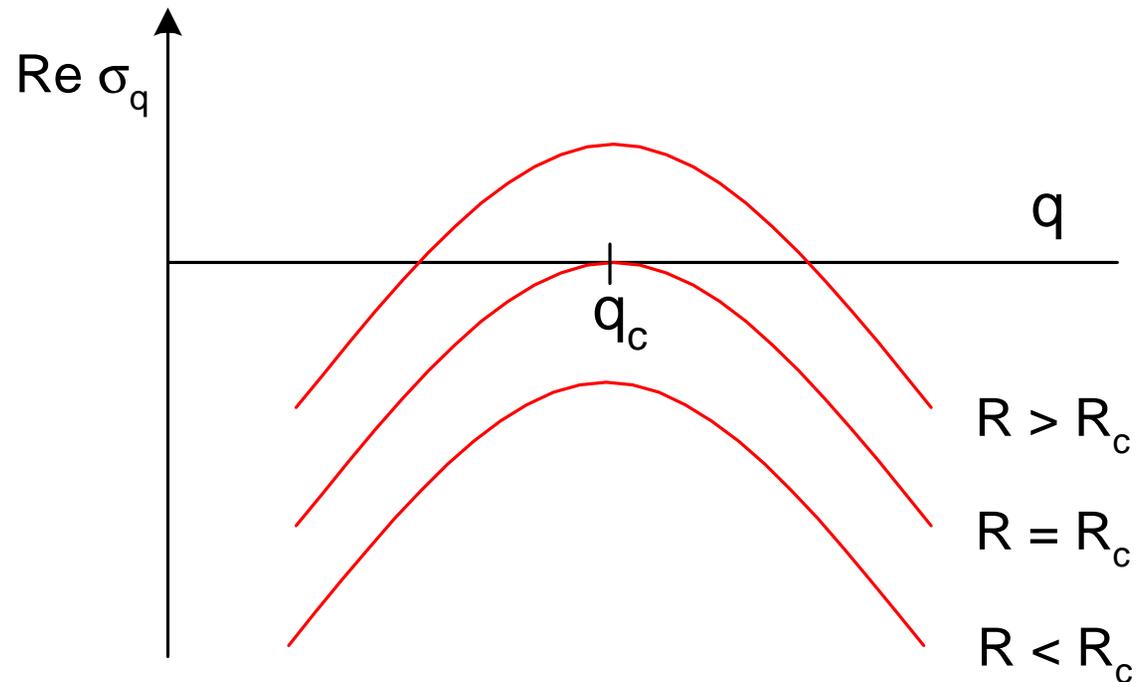
$$R_c = \frac{27\pi^4}{4}, \quad q_c = \frac{\pi}{\sqrt{2}}$$

Rayleigh's Growth Rate (for $\mathcal{P} = 1$)



$$R_c = \frac{27\pi^4}{4}, \quad q_c = \frac{\pi}{\sqrt{2}}$$

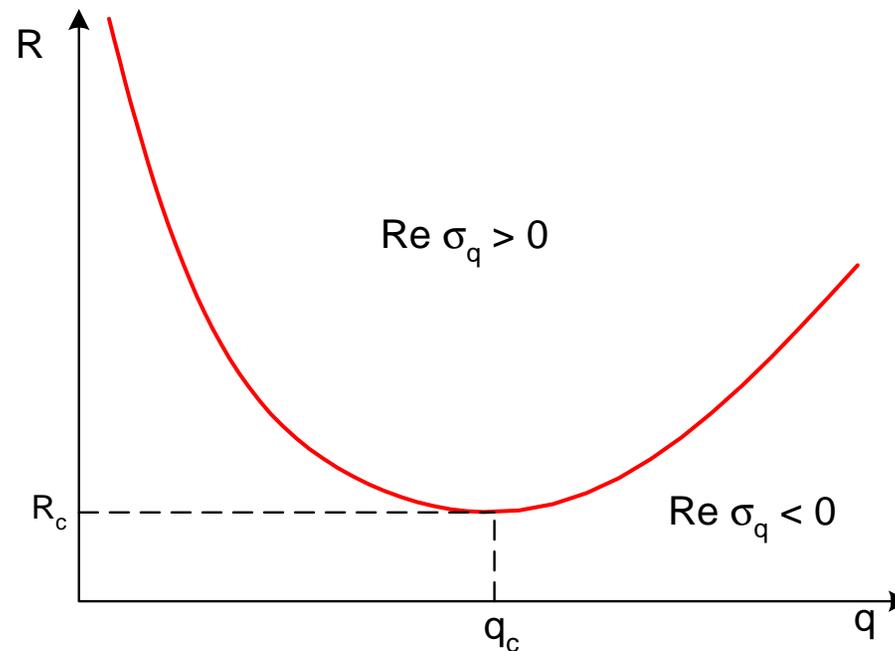
Parabolic approximation near maximum



For R near R_c and q near q_c

$$\text{Re } \sigma(q) = \tau_0^{-1} [\varepsilon - \xi_0^2 (q - q_c)^2] \quad \text{with} \quad \varepsilon = \frac{R - R_c}{R_c}$$

Neutral stability curve



$\text{Re } \sigma(q) = 0$ defines the **neutral stability curve** $R = R_c(q)$ or $q = q_N(R)$

$$\text{Rayleigh : } R_c(q) = \frac{(q^2 + \pi^2)^3}{q^2}$$

Linear Stability Analysis

Linear stability theory is often a useful first step in understanding pattern formation:

- Often is quite easy to do either analytically or numerically
- Displays the important physical processes
- Gives the length scale of the pattern formation $1/q_c$

Linear Stability Analysis

Linear stability theory is often a useful first step in understanding pattern formation:

- Often is quite easy to do either analytically or numerically
- Displays the important physical processes
- Gives the length scale of the pattern formation $1/q_c$

But:

- Leaves us with unphysical exponentially growing solutions

Linear Stability Analysis

Linear stability theory is often a useful first step in understanding pattern formation:

- Often is quite easy to do either analytically or numerically
- Displays the important physical processes
- Gives the length scale of the pattern formation $1/q_c$

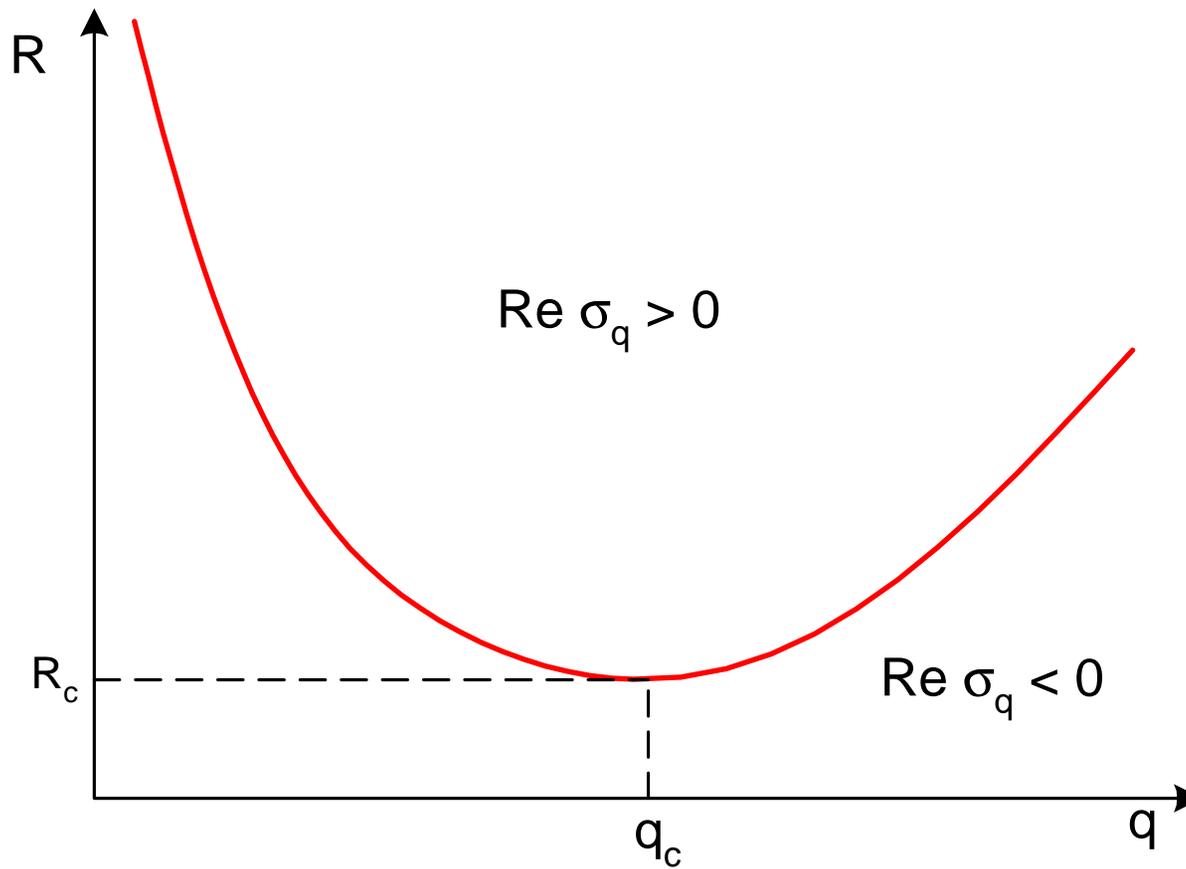
But:

- Leaves us with unphysical exponentially growing solutions

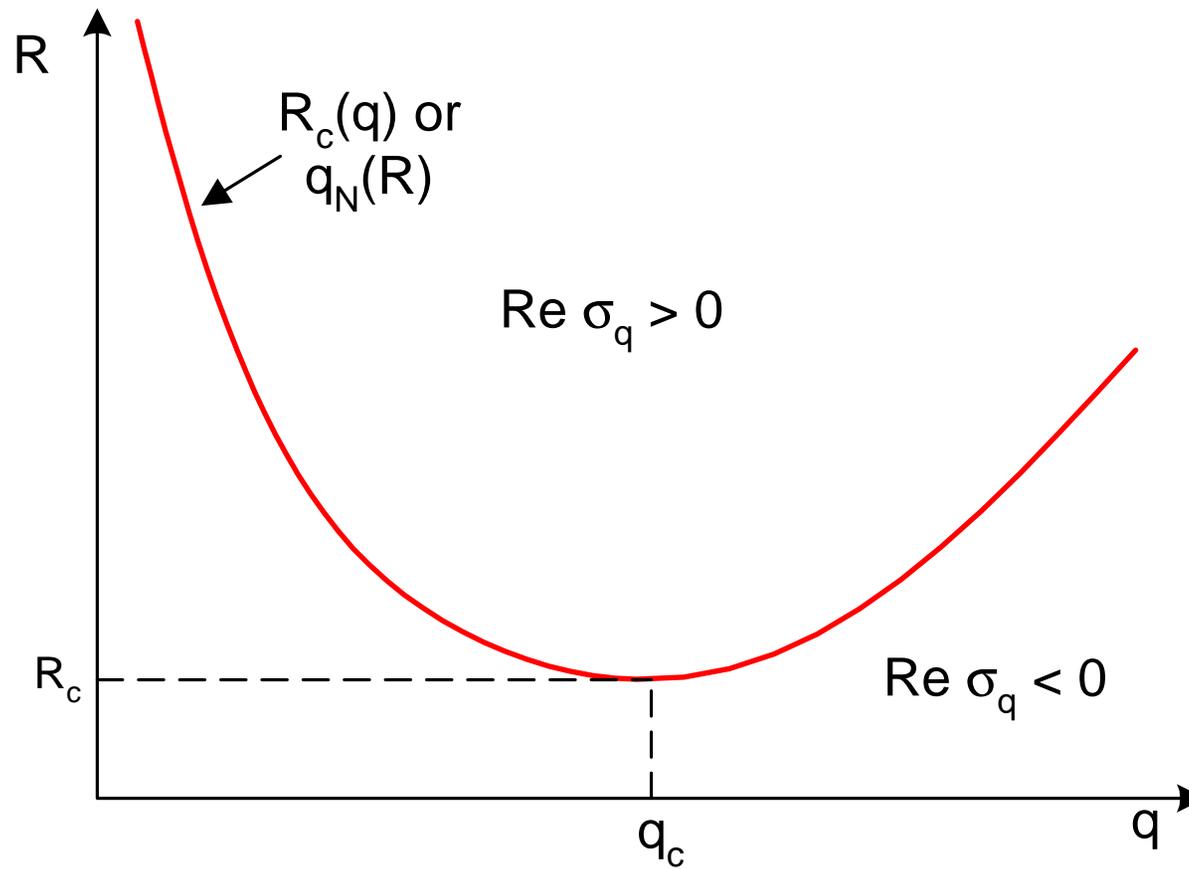
Nonlinear Theory

- Saturation of spatially periodic solution (bifurcation theory)
- General patterns (cf., broken symmetry at phase transitions)

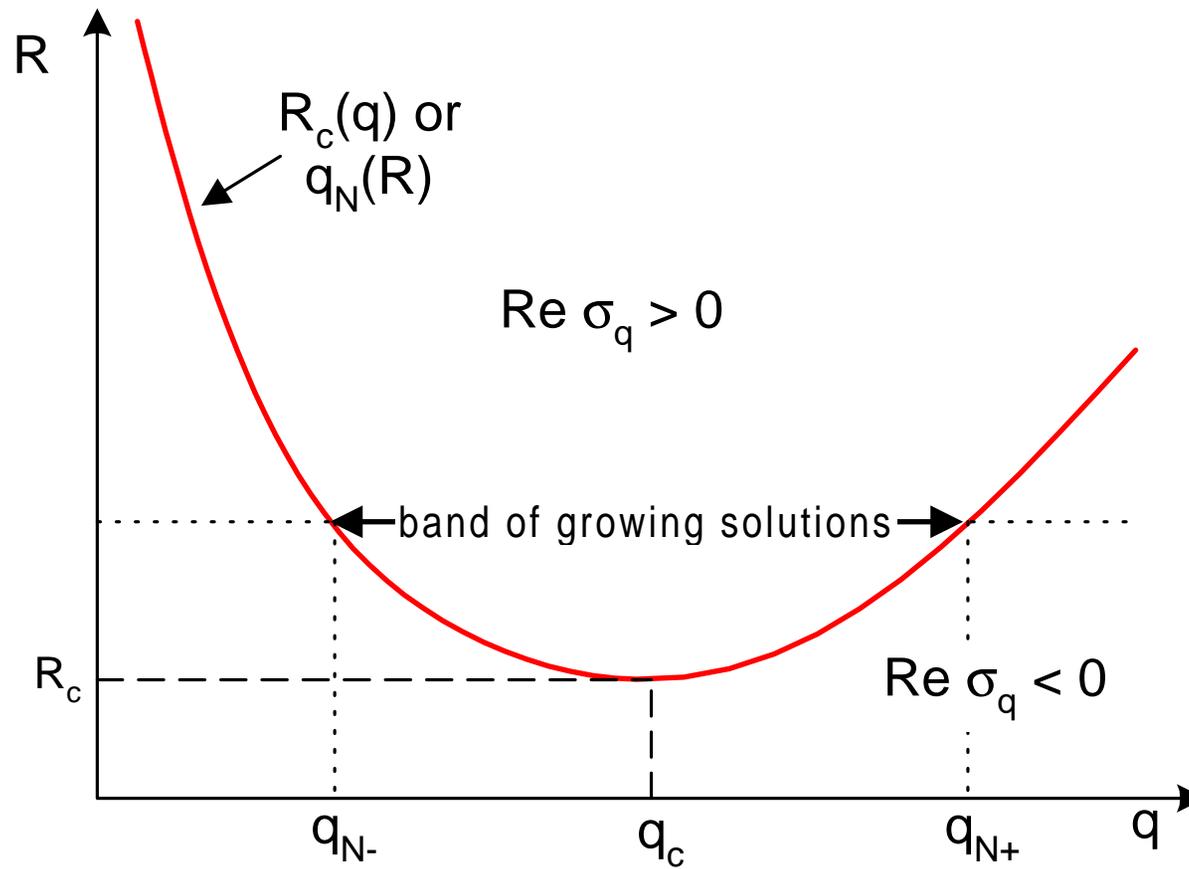
Qualitative Picture of Nonlinear States



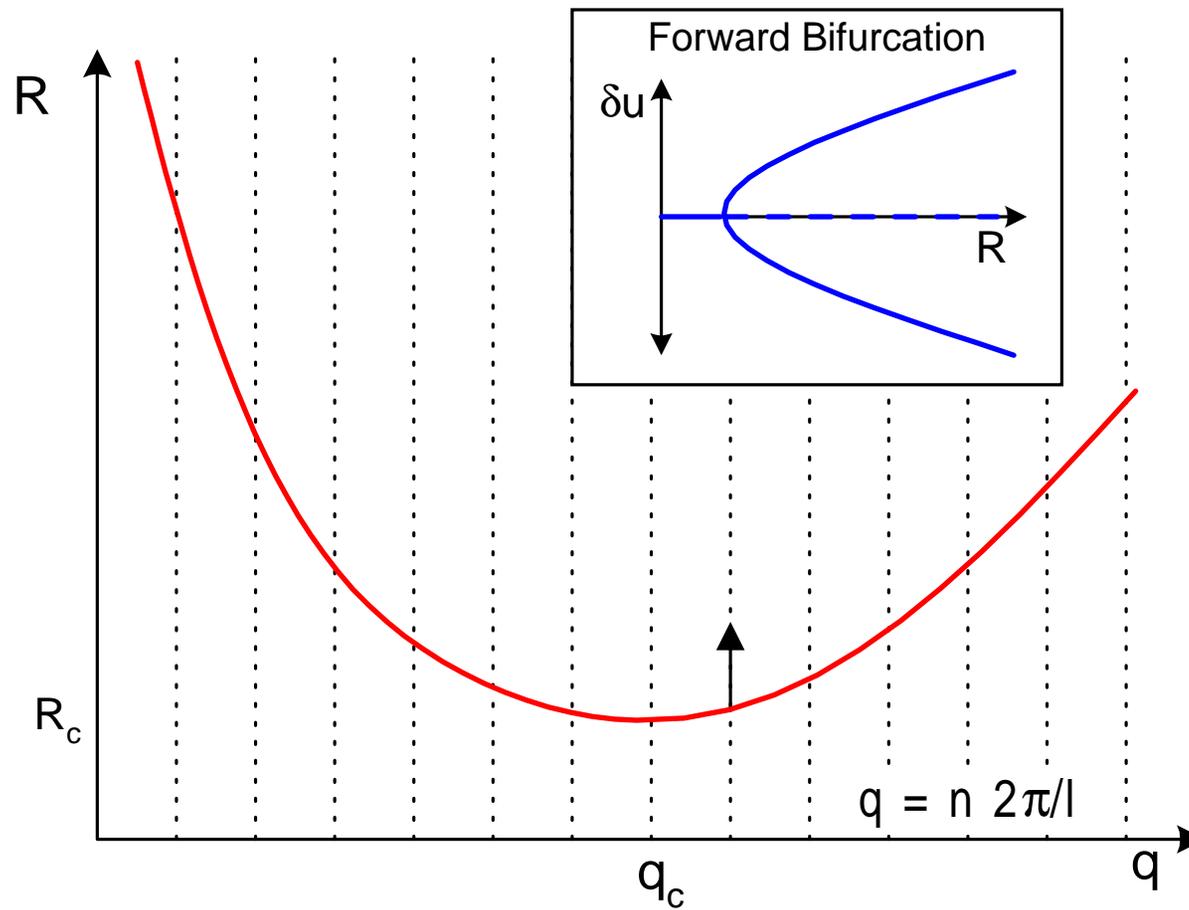
Qualitative Picture of Nonlinear States



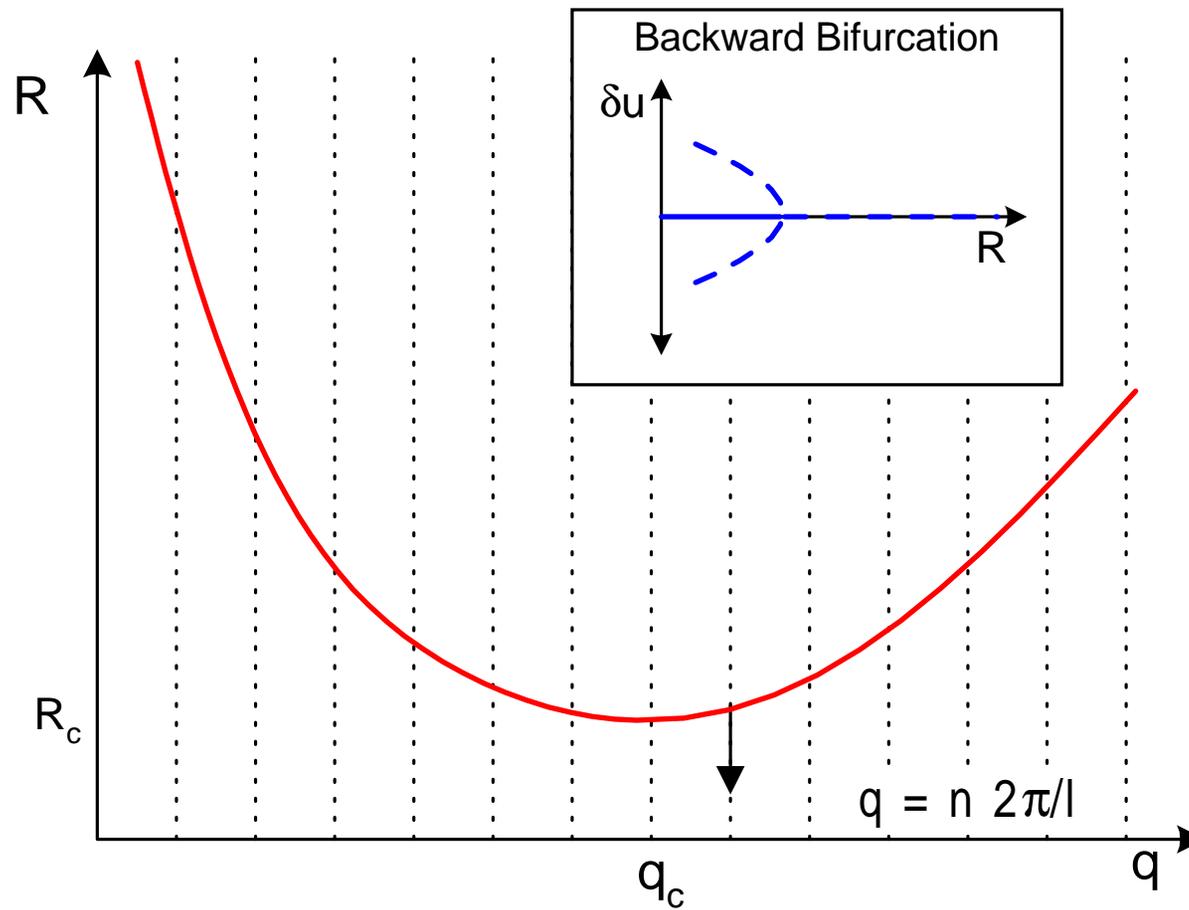
Qualitative Picture of Nonlinear States



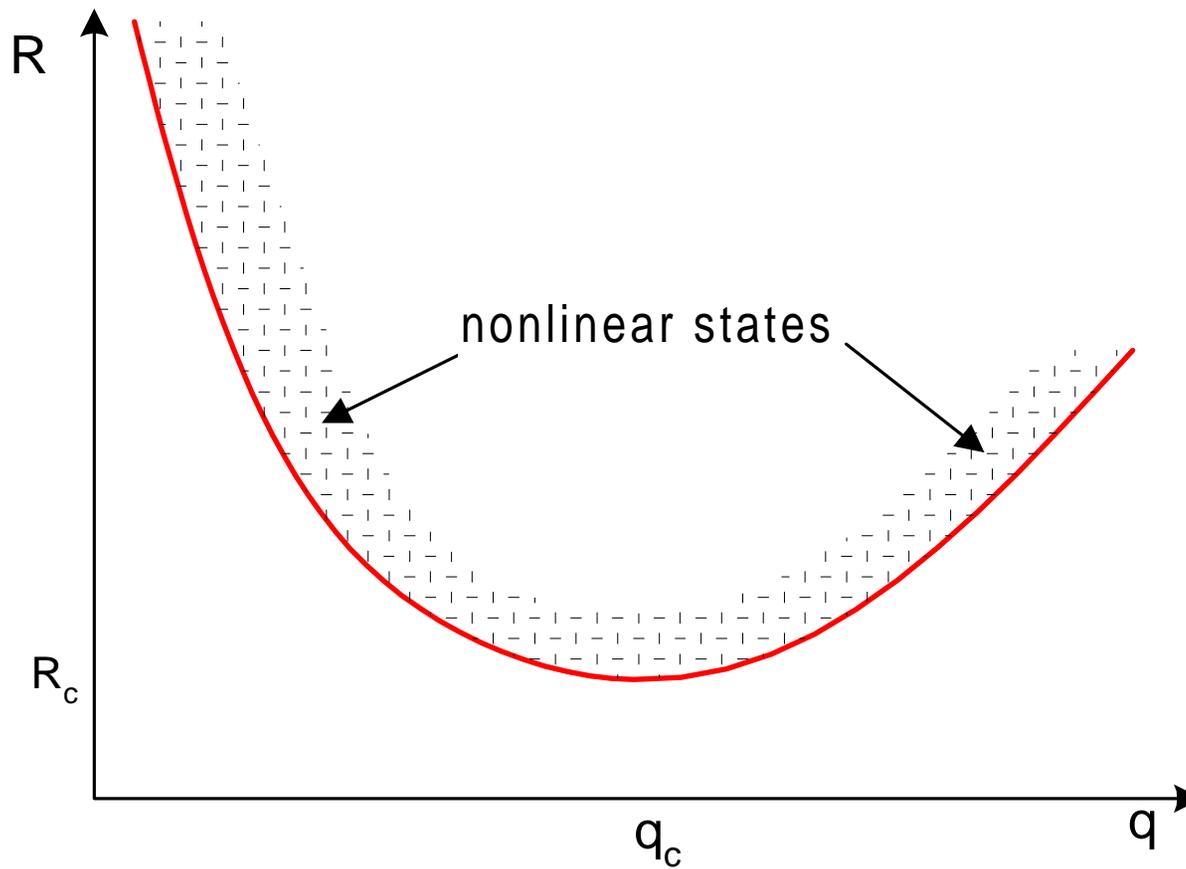
Qualitative Picture of Nonlinear States: Periodic BC



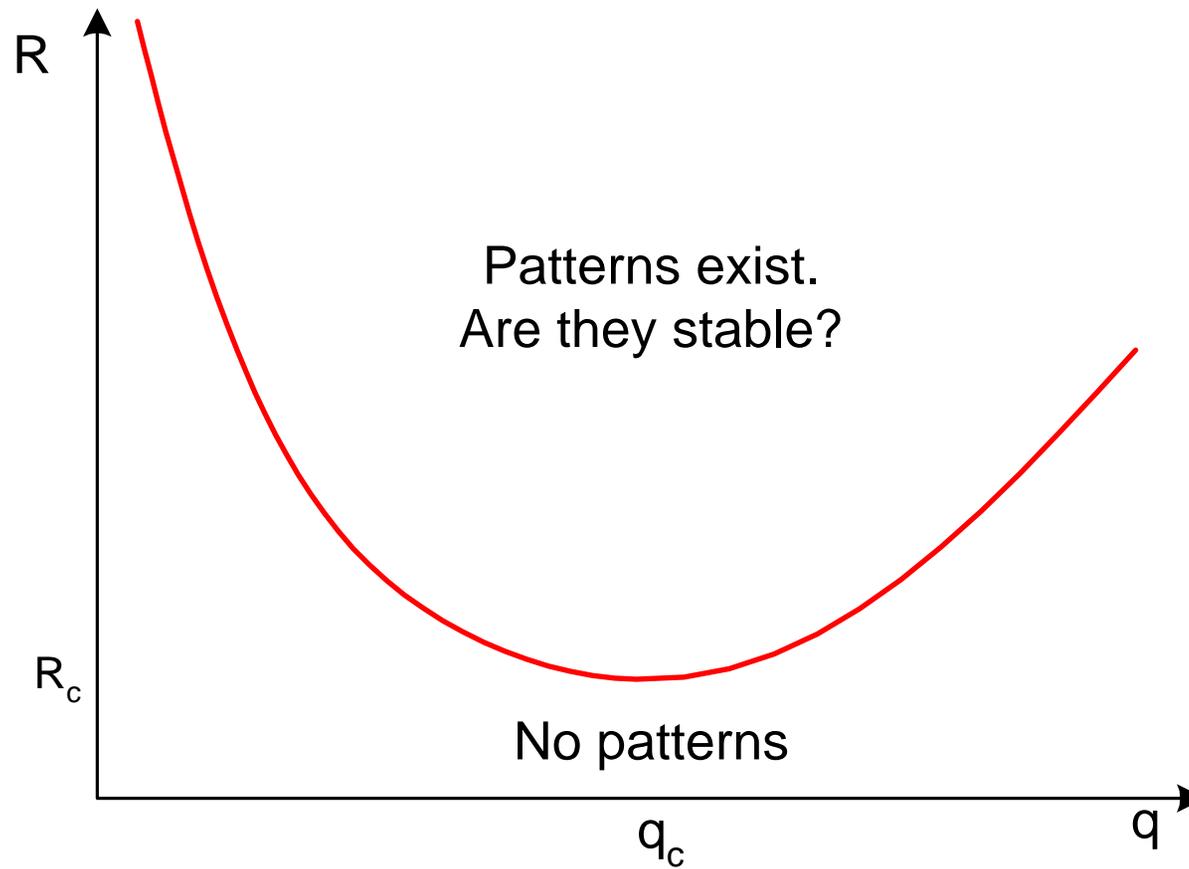
Qualitative Picture of Nonlinear States: Periodic BC



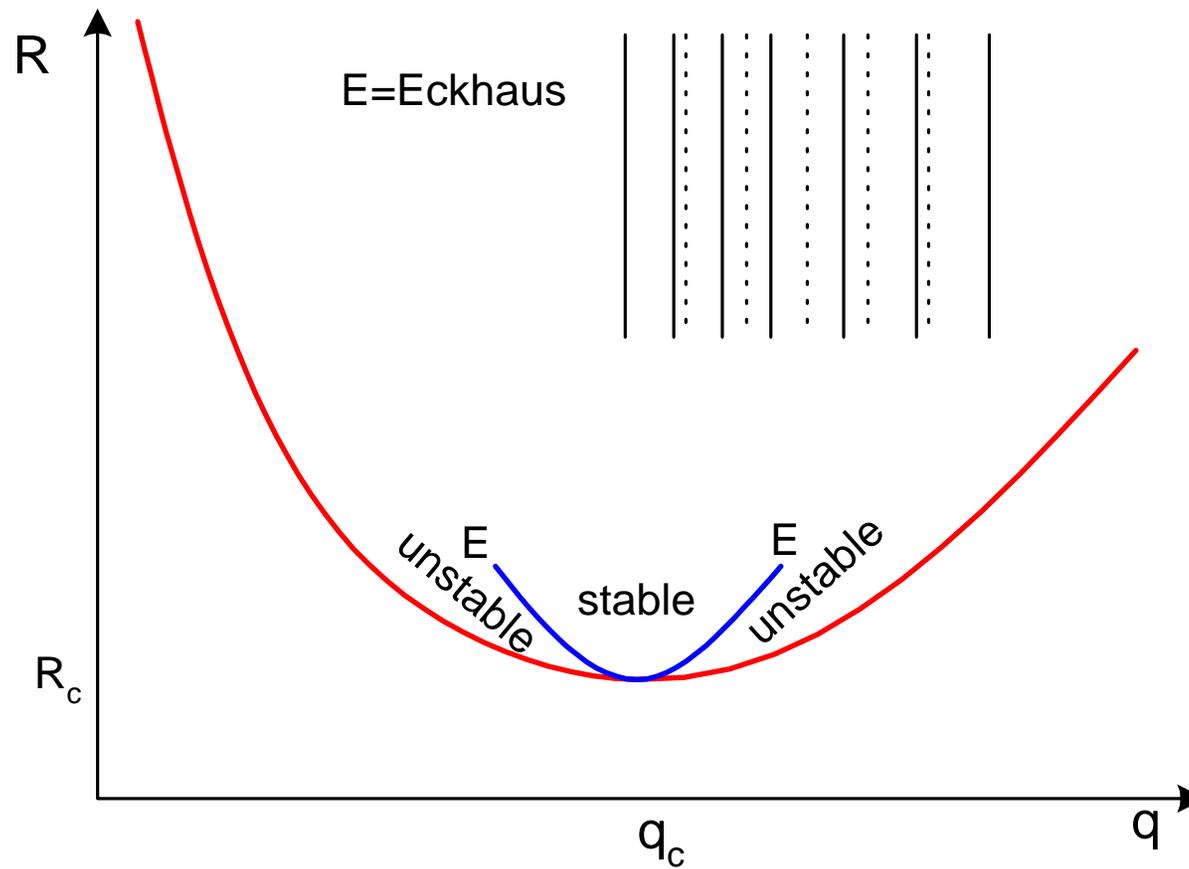
Qualitative Picture of Nonlinear States: Infinite System



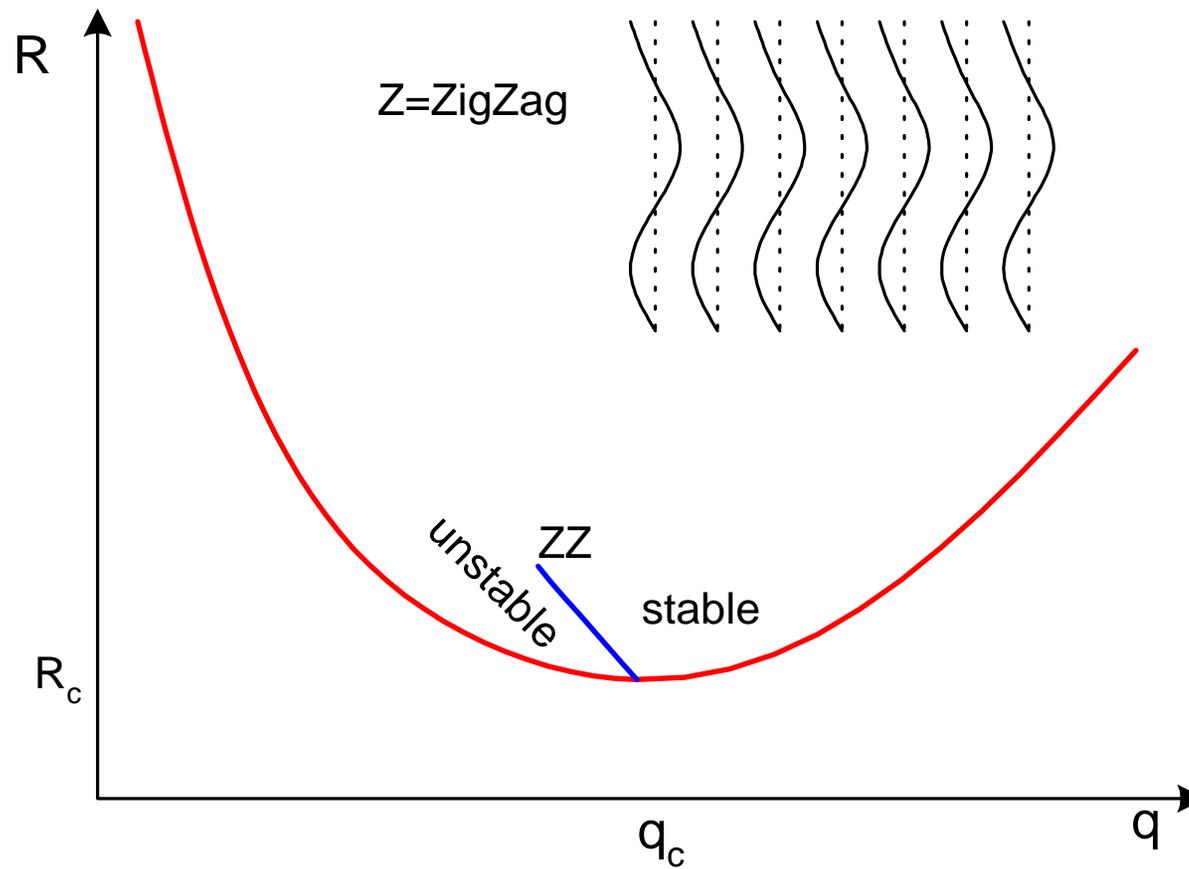
Qualitative Picture of Nonlinear States



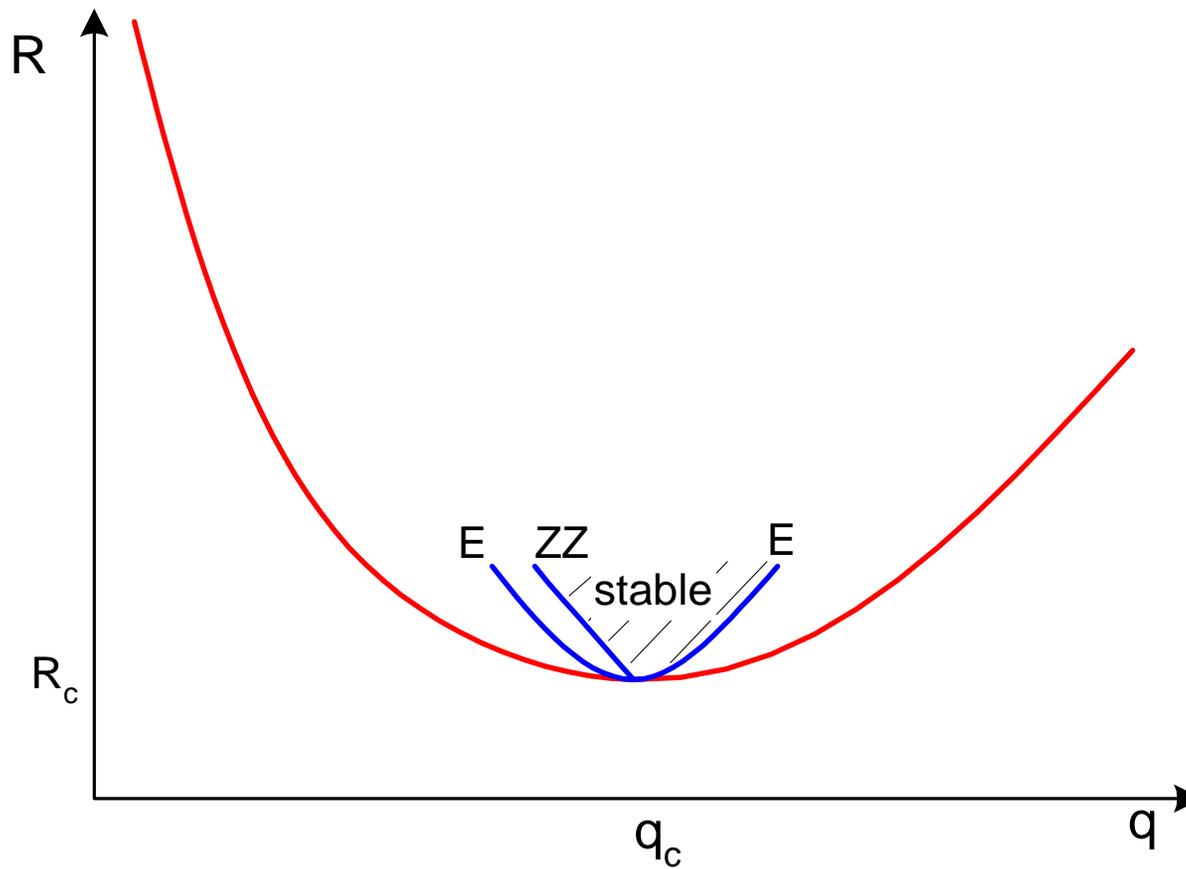
Qualitative Picture of Nonlinear States: Instability of Stripes



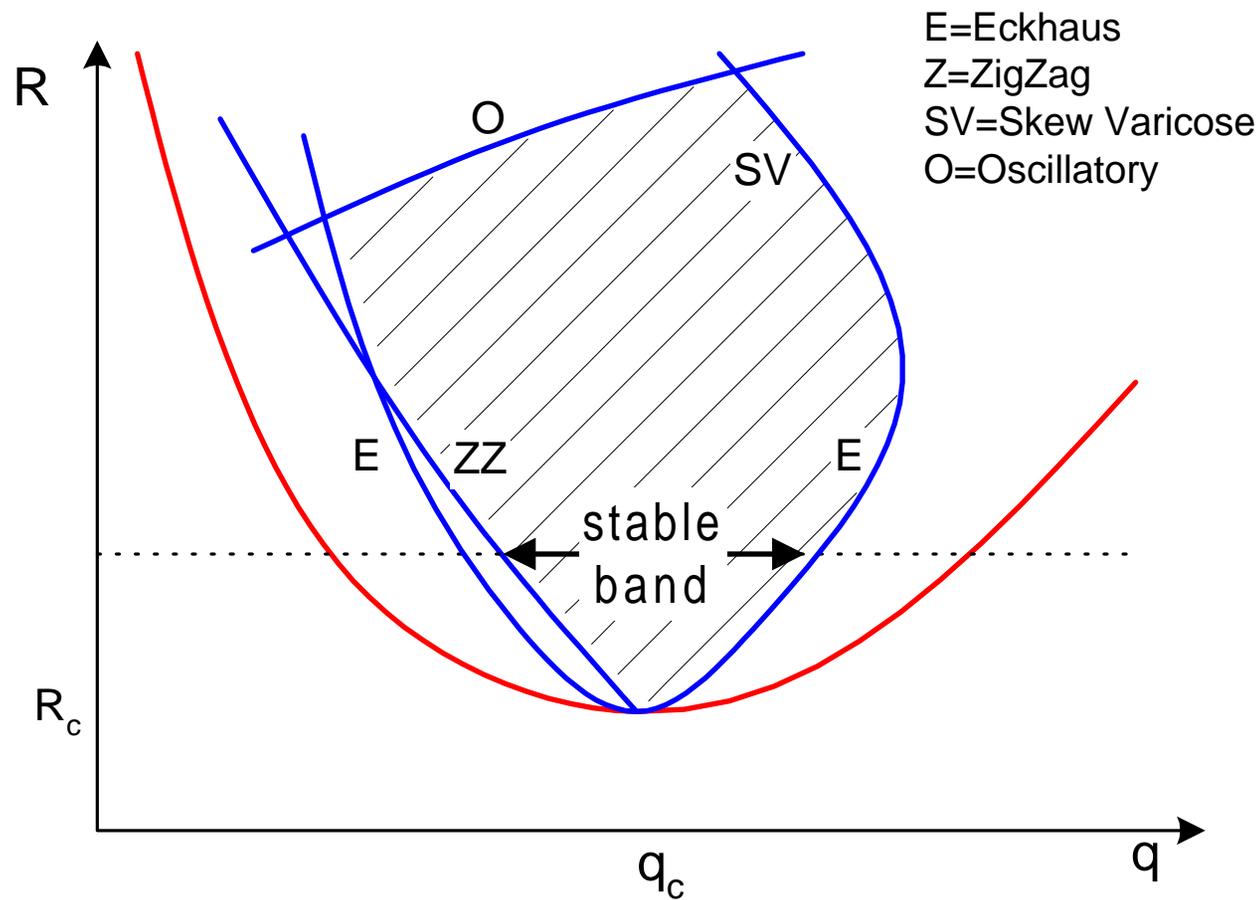
Qualitative Picture of Nonlinear States: Instability of Stripes



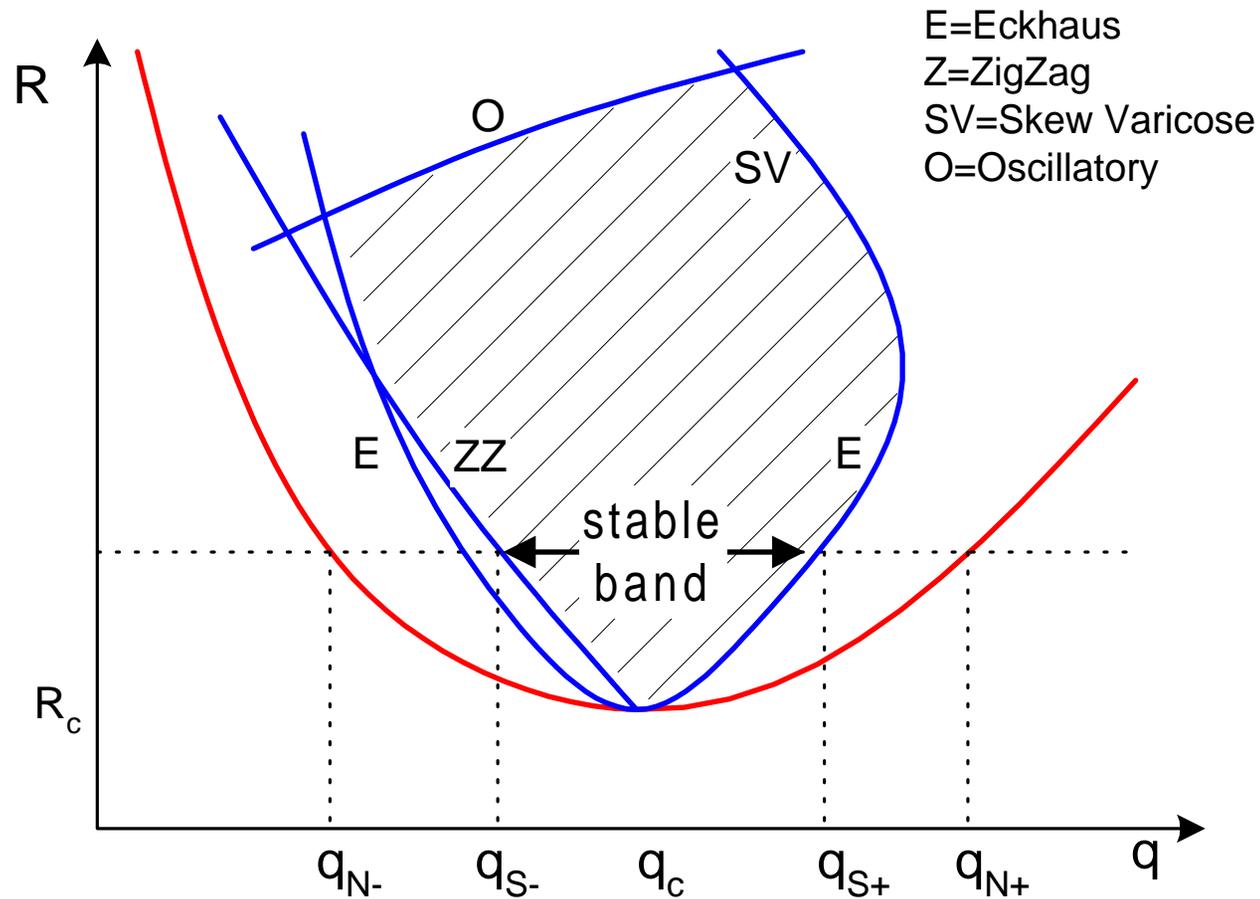
Qualitative Picture of Nonlinear States: Instability of Stripes



Qualitative Picture of Nonlinear States: Stability Balloon



Qualitative Picture of Nonlinear States: Stability Balloon

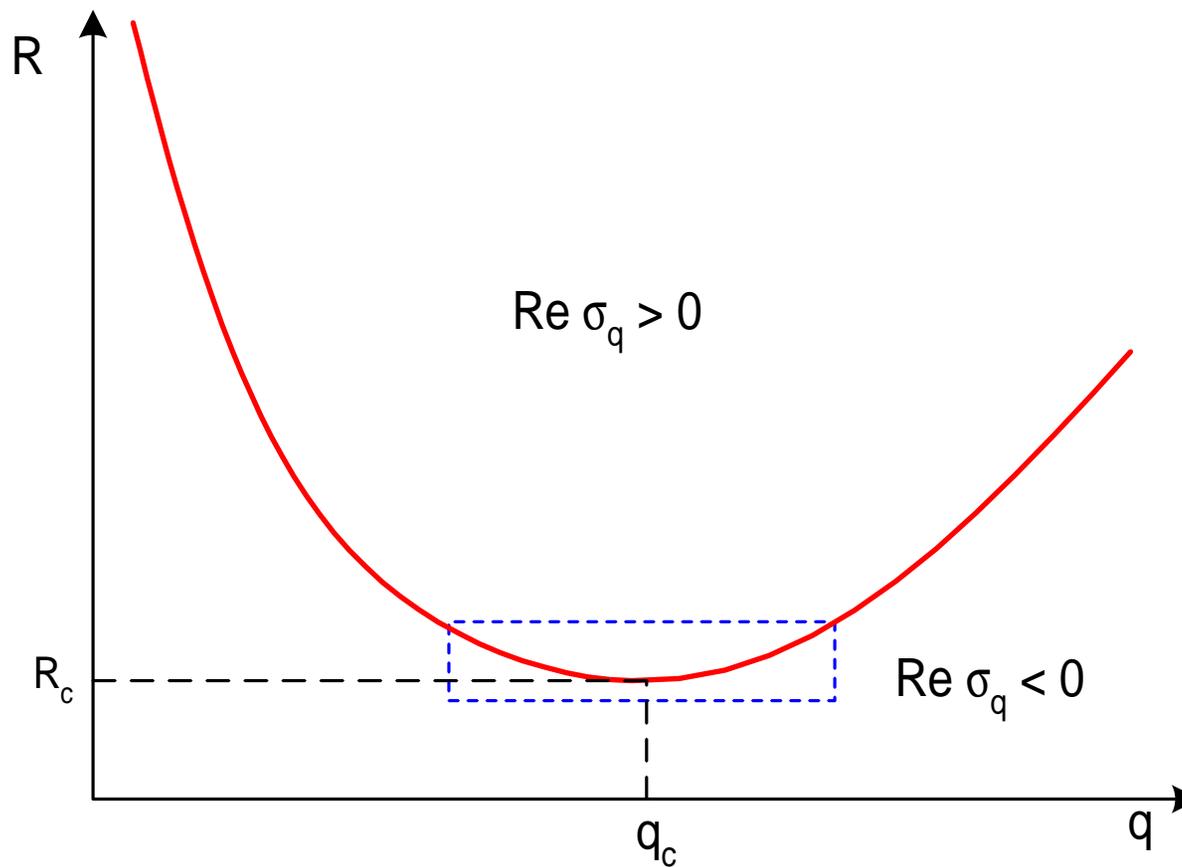


Tools for the Nonlinear Problem

- The instability to a pattern is another example of a **broken symmetry transition**, now in the context of nonequilibrium systems
- The same basic ideas we discussed in the context of equilibrium phase transitions apply:
 - ◇ near the transition ($R \simeq R_c$, $q \simeq q_c$ or slow modulations of a pattern at q_c) describe the behavior using an **order parameter**
 - ◇ away from the transition use a **phase variable** description to describe the behavior resulting from the broken symmetry
- There will be similar general behavior:
 - ◇ new rigidity
 - ◇ Goldstone modes
 - ◇ importance of topological defects
- There will be important differences in formulation and behavior because we cannot start from a free energy, but must consider directly the dynamics

Amplitude Equations

Systematic approach for describing weakly nonlinear solutions near onset for solutions near a stripe state



Amplitude Equations

Linear onset solution for stripes

$$\delta \mathbf{u}_{\mathbf{q}}(\mathbf{x}_{\perp}, z, t) = \left[a_0 e^{i(\mathbf{q} - \mathbf{q}_c) \cdot \mathbf{x}_{\perp}} e^{\text{Re } \sigma_{\mathbf{q}} t} \right] \times \left[\mathbf{u}_{\mathbf{q}}(z) e^{i \mathbf{q}_c \cdot \mathbf{x}_{\perp}} \right] + \text{c.c.}$$

Small terms near onset
Onset solution

Amplitude Equations

Linear onset solution for stripes

$$\delta \mathbf{u}_{\mathbf{q}}(\mathbf{x}_{\perp}, z, t) = \left[a_0 e^{i(\mathbf{q} - \mathbf{q}_c) \cdot \mathbf{x}_{\perp}} e^{\text{Re} \sigma_{\mathbf{q}} t} \right] \times \left[\mathbf{u}_{\mathbf{q}}(z) e^{i \mathbf{q}_c \cdot \mathbf{x}_{\perp}} \right] + \text{c.c.}$$

Small terms near onset Onset solution

Weakly nonlinear, slowly modulated, solution

$$\delta \mathbf{u}(\mathbf{x}_{\perp}, z, t) \approx \mathbf{A}(\mathbf{x}_{\perp}, t) \times \left[\mathbf{u}_{\mathbf{q}_c}(z) e^{i \mathbf{q}_c \cdot \mathbf{x}_{\perp}} \right] + \text{c.c.}$$

Complex amplitude Onset solution

Amplitude Equations

Linear onset solution for stripes

$$\delta \mathbf{u}_{\mathbf{q}}(\mathbf{x}_{\perp}, z, t) = \left[a_0 e^{i(\mathbf{q} - \mathbf{q}_c) \cdot \mathbf{x}_{\perp}} e^{\text{Re} \sigma_{\mathbf{q}} t} \right] \times \left[\mathbf{u}_{\mathbf{q}}(z) e^{i \mathbf{q}_c \cdot \mathbf{x}_{\perp}} \right] + \text{c.c.}$$

Small terms near onset Onset solution

Weakly nonlinear, slowly modulated, solution

$$\delta \mathbf{u}(\mathbf{x}_{\perp}, z, t) \approx A(\mathbf{x}_{\perp}, t) \times \left[\mathbf{u}_{\mathbf{q}_c}(z) e^{i \mathbf{q}_c \cdot \mathbf{x}_{\perp}} \right] + \text{c.c.}$$

Complex amplitude Onset solution

$A(\mathbf{x}_{\perp}, t)$ is the **order parameter** for the stripe state

Amplitude Equations

Linear onset solution for stripes

$$\delta \mathbf{u}_{\mathbf{q}}(\mathbf{x}_{\perp}, z, t) = \left[a_0 e^{i(\mathbf{q}-\mathbf{q}_c) \cdot \mathbf{x}_{\perp}} e^{\text{Re} \sigma_{\mathbf{q}} t} \right] \times \left[\mathbf{u}_{\mathbf{q}}(z) e^{i\mathbf{q}_c \cdot \mathbf{x}_{\perp}} \right] + \text{c.c.}$$

Small terms near onset Onset solution

Weakly nonlinear, slowly modulated, solution

$$\delta \mathbf{u}(\mathbf{x}_{\perp}, z, t) \approx A(\mathbf{x}_{\perp}, t) \times \left[\mathbf{u}_{\mathbf{q}_c}(z) e^{i\mathbf{q}_c \cdot \mathbf{x}_{\perp}} \right] + \text{c.c.}$$

Complex amplitude Onset solution

$A(\mathbf{x}_{\perp}, t)$ is the order parameter for the stripe state

$A(\mathbf{x}_{\perp}, t)$ satisfies the **amplitude equation**.

Amplitude Equations

Linear onset solution for stripes

$$\delta \mathbf{u}_{\mathbf{q}}(\mathbf{x}_{\perp}, z, t) = \underbrace{[a_0 e^{i(\mathbf{q}-\mathbf{q}_c) \cdot \mathbf{x}_{\perp}} e^{\text{Re} \sigma_{\mathbf{q}} t}]}_{\text{Small terms near onset}} \times \underbrace{[\mathbf{u}_{\mathbf{q}}(z) e^{i\mathbf{q}_c \cdot \mathbf{x}_{\perp}}]}_{\text{Onset solution}} + \text{c.c.}$$

Weakly nonlinear, slowly modulated, solution

$$\delta \mathbf{u}(\mathbf{x}_{\perp}, z, t) \approx \underbrace{A(\mathbf{x}_{\perp}, t)}_{\text{Complex amplitude}} \times \underbrace{[\mathbf{u}_{\mathbf{q}_c}(z) e^{i\mathbf{q}_c \cdot \mathbf{x}_{\perp}}]}_{\text{Onset solution}} + \text{c.c.}$$

$A(\mathbf{x}_{\perp}, t)$ is the order parameter for the stripe state

$A(\mathbf{x}_{\perp}, t)$ satisfies the amplitude equation. In 1d [$\mathbf{q}_c = q_c \hat{\mathbf{x}}$, $A = A(x, t)$]:

$$\tau_0 \partial_t A = \varepsilon A + \xi_0^2 \partial_x^2 A - g_0 |A|^2 A, \quad \varepsilon = (R - R_c)/R_c$$

Complex Amplitude

Magnitude and phase of A play very different roles

$$A(x, y, t) = a(x, y, t)e^{i\theta(x, y, t)}$$

$$\delta\mathbf{u}(\mathbf{x}_\perp, z, t) = ae^{i\theta} \times e^{iq_c x} \mathbf{u}_{\mathbf{q}_c}(z) + c.c.$$

Complex Amplitude

Magnitude and phase of A play very different roles

$$A(x, y, t) = a(x, y, t)e^{i\theta(x, y, t)}$$

$$\delta\mathbf{u}(\mathbf{x}_\perp, z, t) = ae^{i\theta} \times e^{iq_c x} \mathbf{u}_{\mathbf{q}_c}(z) + c.c.$$

- magnitude $a = |A|$ gives strength of disturbance

Complex Amplitude

Magnitude and phase of A play very different roles

$$A(x, y, t) = a(x, y, t)e^{i\theta(x, y, t)}$$

$$\delta\mathbf{u}(\mathbf{x}_\perp, z, t) = ae^{i\theta} \times e^{iq_c x} \mathbf{u}_{\mathbf{q}_c}(z) + c.c.$$

- magnitude $a = |A|$ gives strength of disturbance
- phase change $\delta\theta$ gives shift of pattern (by $\delta x = \delta\theta/q_c$)

Complex Amplitude

Magnitude and phase of A play very different roles

$$A(x, y, t) = a(x, y, t)e^{i\theta(x, y, t)}$$

$$\delta\mathbf{u}(\mathbf{x}_\perp, z, t) = ae^{i\theta} \times e^{iq_c x} \mathbf{u}_{\mathbf{q}_c}(z) + c.c.$$

- magnitude $a = |A|$ gives strength of disturbance
- phase change $\delta\theta$ gives shift of pattern (by $\delta x = \delta\theta/q_c$)— **symmetry!**

Complex Amplitude

Magnitude and phase of A play very different roles

$$A(x, y, t) = a(x, y, t)e^{i\theta(x, y, t)}$$

$$\delta\mathbf{u}(\mathbf{x}_\perp, z, t) = ae^{i\theta} \times e^{iq_c x} \mathbf{u}_{\mathbf{q}_c}(z) + c.c.$$

- magnitude $a = |A|$ gives strength of disturbance
- phase change $\delta\theta$ gives shift of pattern (by $\delta x = \delta\theta/q_c$)— symmetry!
- x-gradient $\partial_x\theta$ gives change of wave number $q = q_c + \partial_x\theta$

$$A = ae^{ikx} \text{ corresponds to } q = q_c + k$$

Complex Amplitude

Magnitude and phase of A play very different roles

$$A(x, y, t) = a(x, y, t)e^{i\theta(x, y, t)}$$

$$\delta\mathbf{u}(\mathbf{x}_\perp, z, t) = ae^{i\theta} \times e^{iq_c x} \mathbf{u}_{\mathbf{q}_c}(z) + c.c.$$

- magnitude $a = |A|$ gives strength of disturbance
- phase change $\delta\theta$ gives shift of pattern (by $\delta x = \delta\theta/q_c$)— symmetry!
- x-gradient $\partial_x\theta$ gives change of wave number $q = q_c + \partial_x\theta$
 $A = ae^{ikx}$ corresponds to $q = q_c + k$
- y-gradient $\partial_y\theta$ gives rotation of wave vector through angle $\partial_y\theta/q_c$
 (plus $O[(\partial_y\theta)^2]$ change in wave number)

The amplitude equation describes

$$\tau_0 \partial_t A = \varepsilon A - g_0 |A|^2 A + \xi_0^2 \partial_x^2 A$$

growth

saturation

dispersion/diffusion

Parameters

$$\tau_0 \partial_t A = \varepsilon A + \xi_0^2 \partial_x^2 A - g_0 |A|^2 A,$$

- control parameter $\varepsilon = (R - R_c)/R_c$

Parameters

$$\tau_0 \partial_t A = \varepsilon A + \xi_0^2 \partial_x^2 A - g_0 |A|^2 A,$$

- control parameter $\varepsilon = (R - R_c)/R_c$
- system specific constants τ_0, ξ_0, g_0

Parameters

$$\tau_0 \partial_t A = \varepsilon A + \xi_0^2 \partial_x^2 A - g_0 |A|^2 A,$$

- control parameter $\varepsilon = (R - R_c)/R_c$
- system specific constants τ_0, ξ_0, g_0
 - ◇ τ_0, ξ_0 fixed by matching to linear growth rate $A = a e^{i\mathbf{k}\cdot\mathbf{x}_\perp} e^{\sigma_{\mathbf{q}} t}$
gives pattern at $\mathbf{q} = \mathbf{q}_c \hat{x} + \mathbf{k}$)

$$\sigma_{\mathbf{q}} = \tau_0^{-1} [\varepsilon - \xi_0^2 (q - q_c)^2]$$

Parameters

$$\tau_0 \partial_t A = \varepsilon A + \xi_0^2 \partial_x^2 A - g_0 |A|^2 A,$$

- control parameter $\varepsilon = (R - R_c)/R_c$
- system specific constants τ_0, ξ_0, g_0
 - ◇ τ_0, ξ_0 fixed by matching to linear growth rate $A = a e^{i\mathbf{k}\cdot\mathbf{x}_\perp} e^{\sigma_{\mathbf{q}} t}$
gives pattern at $\mathbf{q} = \mathbf{q}_c \hat{x} + \mathbf{k}$

$$\sigma_{\mathbf{q}} = \tau_0^{-1} [\varepsilon - \xi_0^2 (q - q_c)^2]$$

- ◇ g_0 by calculating nonlinear state at small ε and $q = q_c$.

Scaling

$$\tau_0 \partial_t A = \varepsilon A + \xi_0^2 \partial_x^2 A - g_0 |A|^2 A, \quad \varepsilon = \frac{R - R_c}{R_c}$$

Scaling

$$\tau_0 \partial_t A = \varepsilon A + \xi_0^2 \partial_x^2 A - g_0 |A|^2 A, \quad \varepsilon = \frac{R - R_c}{R_c}$$

Introduce scaled variables

$$x = \varepsilon^{-1/2} \xi_0 X$$

$$t = \varepsilon^{-1} \tau_0 T$$

$$A = (\varepsilon/g_0)^{1/2} \bar{A}$$

Scaling

$$\tau_0 \partial_t A = \varepsilon A + \xi_0^2 \partial_x^2 A - g_0 |A|^2 A, \quad \varepsilon = \frac{R - R_c}{R_c}$$

Introduce scaled variables

$$x = \varepsilon^{-1/2} \xi_0 X$$

$$t = \varepsilon^{-1} \tau_0 T$$

$$A = (\varepsilon/g_0)^{1/2} \bar{A}$$

This reduces the amplitude equation to a *universal* form

$$\partial_T \bar{A} = \bar{A} + \partial_X^2 \bar{A} - |\bar{A}|^2 \bar{A}$$

Scaling

$$\tau_0 \partial_t A = \varepsilon A + \xi_0^2 \partial_x^2 A - g_0 |A|^2 A, \quad \varepsilon = \frac{R - R_c}{R_c}$$

Introduce scaled variables

$$x = \varepsilon^{-1/2} \xi_0 X$$

$$t = \varepsilon^{-1} \tau_0 T$$

$$A = (\varepsilon/g_0)^{1/2} \bar{A}$$

This reduces the amplitude equation to a *universal* form

$$\partial_T \bar{A} = \bar{A} + \partial_X^2 \bar{A} - |\bar{A}|^2 \bar{A}$$

Since solutions to this equation will develop on scales $X, Y, T, \bar{A} = O(1)$ this gives us scaling results for the physical length scales.

Derivation

$$\tau_0 \partial_t A = \varepsilon A + \xi_0^2 \partial_x^2 A - g_0 |A|^2 A, \quad \varepsilon = \frac{R - R_c}{R_c}$$

Derivation

$$\tau_0 \partial_t A = \varepsilon A + \xi_0^2 \partial_x^2 A - g_0 |A|^2 A, \quad \varepsilon = \frac{R - R_c}{R_c}$$

- Expand dynamical equation in powers of A and use symmetry arguments (cf., equilibrium phase transitions where we expand free energy).

Derivation

$$\tau_0 \partial_t A = \varepsilon A + \xi_0^2 \partial_x^2 A - g_0 |A|^2 A, \quad \varepsilon = \frac{R - R_c}{R_c}$$

- Expand dynamical equation in powers of A and use symmetry arguments (cf., equilibrium phase transitions where we expand free energy). Equation must be invariant under:
 - ◇ $A(\mathbf{x}_\perp) \rightarrow A(\mathbf{x}_\perp) e^{i\Delta}$ with Δ a constant, corresponding to a physical translation
 - ◇ $A(\mathbf{x}_\perp) \rightarrow A^*(-\mathbf{x}_\perp)$, corresponding to inversion of the horizontal coordinates (parity symmetry)

Derivation

$$\tau_0 \partial_t A = \varepsilon A + \xi_0^2 \partial_x^2 A - g_0 |A|^2 A, \quad \varepsilon = \frac{R - R_c}{R_c}$$

- Expand dynamical equation in powers of A and use symmetry arguments (cf., equilibrium phase transitions where we expand free energy). Equation must be invariant under:
 - ◇ $A(\mathbf{x}_\perp) \rightarrow A(\mathbf{x}_\perp) e^{i\Delta}$ with Δ a constant, corresponding to a physical translation
 - ◇ $A(\mathbf{x}_\perp) \rightarrow A^*(-\mathbf{x}_\perp)$, corresponding to inversion of the horizontal coordinates (parity symmetry)
- Multiple scales perturbation theory (Newell and Whitehead, Segel 1969)
- Mode projection (MCC 1980)

Amplitude Equation = Ginzburg Landau equation

$$\tau_0 \partial_t A = \varepsilon A + \xi_0^2 \partial_x^2 A - g_0 |A|^2 A,$$

Familiar from other branches of physics:

- Good: take intuition from there
- Bad: no *really* new effects

e.g. equation is relaxational (potential, Lyapunov)

$$\tau_0 \partial_t A = -\frac{\delta V}{\delta A^*}, \quad V = \int dx \left[-\varepsilon |A|^2 + \frac{1}{2} g_0 |A|^4 + \xi_0^2 |\partial_x A|^2 \right]$$

This leads to

$$\frac{dV}{dt} = -\tau_0^{-1} \int dx |\partial_t A|^2 \leq 0$$

and dynamics runs “down hill” to a minimum of V —no chaos!

- We have arrived at the same Landau type formulation with an effective “potential” or “free energy” V !
- This is not fundamental, and is “luck” resulting from our expansion in ε to lowest order
 - ◇ no effective potential at higher order
 - ◇ no effective potential for some side-wall boundary conditions
 - ◇ no effective potential for rotating convection (and there is chaos at onset!)

Applications

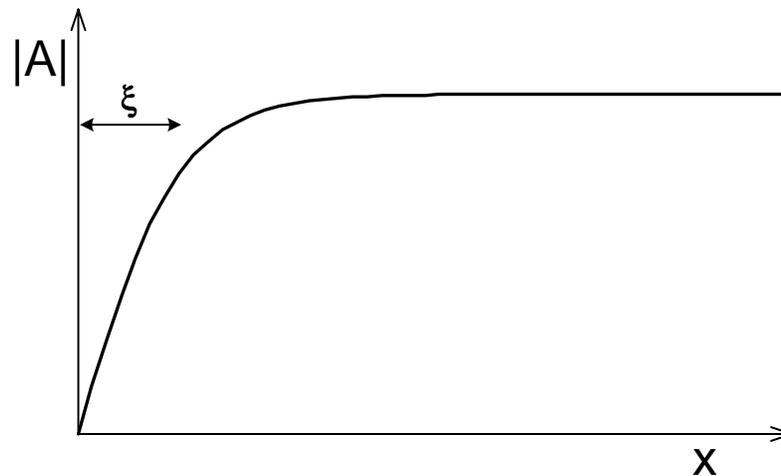
What we can calculate:

- Effect of distant sidewalls
- Eckhaus instability
- Propagation of pattern into no pattern region (e.g., from localized initial condition)
- Evolution from random initial condition
- ...

Example: Effect of Distant Sidewalls

One dimensional geometry with sidewalls that suppress the pattern
(e.g. rigid walls in a convection system)

$$\partial_T \bar{A} = \bar{A} + \partial_X^2 \bar{A} - |\bar{A}|^2 \bar{A} \quad \bar{A}(0) = 0$$

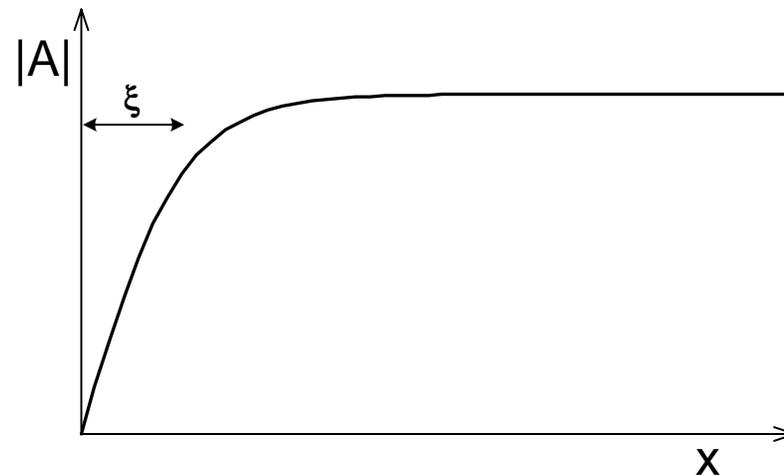


$$\bar{A} = e^{i\theta} \tanh(X/\sqrt{2})$$

Example: Effect of Distant Sidewalls

One dimensional geometry with sidewalls that suppress the pattern
(e.g. rigid walls in a convection system)

$$\partial_T \bar{A} = \bar{A} + \partial_X^2 \bar{A} - |\bar{A}|^2 \bar{A} \quad \bar{A}(0) = 0$$



$$\bar{A} = e^{i\theta} \tanh(X/\sqrt{2})$$

Unscaled variables:

$$A = e^{i\theta} (\varepsilon/g_0)^{1/2} \tanh(x/\xi) \quad \text{with} \quad \xi = \sqrt{2} \varepsilon^{-1/2} \xi_0$$

Solution

$$A = e^{i\theta} (\varepsilon/g_0)^{1/2} \tanh(x/\xi)$$

- suppression of pattern over length $\varepsilon^{-1/2}\xi_0$
- arbitrary position of rolls
- asymptotic wave number is $k = 0$, giving $q = q_c$: no band of existence

Solution

$$A = e^{i\theta} (\varepsilon/g_0)^{1/2} \tanh(x/\xi)$$

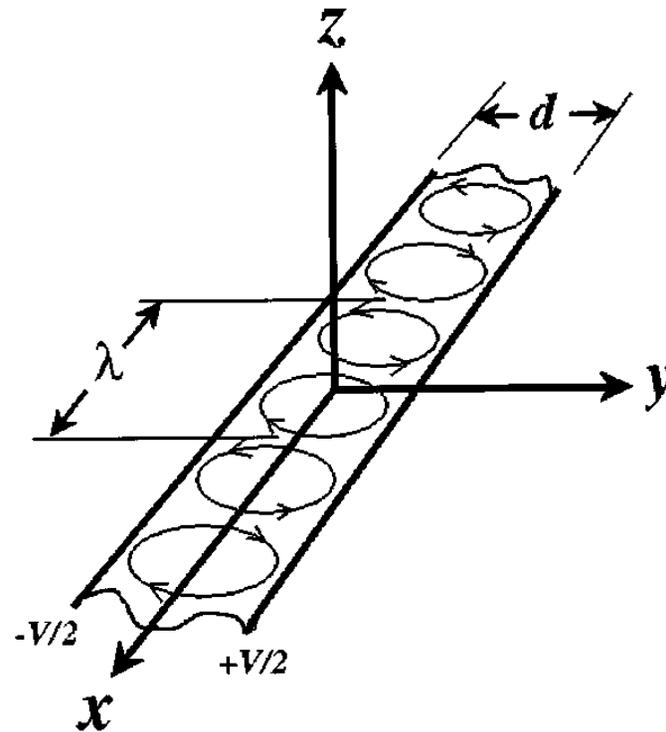
- suppression of pattern over length $\varepsilon^{-1/2}\xi_0$
- arbitrary position of rolls
- asymptotic wave number is $k = 0$, giving $q = q_c$: no band of existence

Extended amplitude equation to next order in ε (MCC, Daniels, Hohenberg, and Siggia 1980) shows

- discrete set of roll positions
- solutions restricted to a narrow $O(\varepsilon^1)$ wave number band with wave number far from the wall

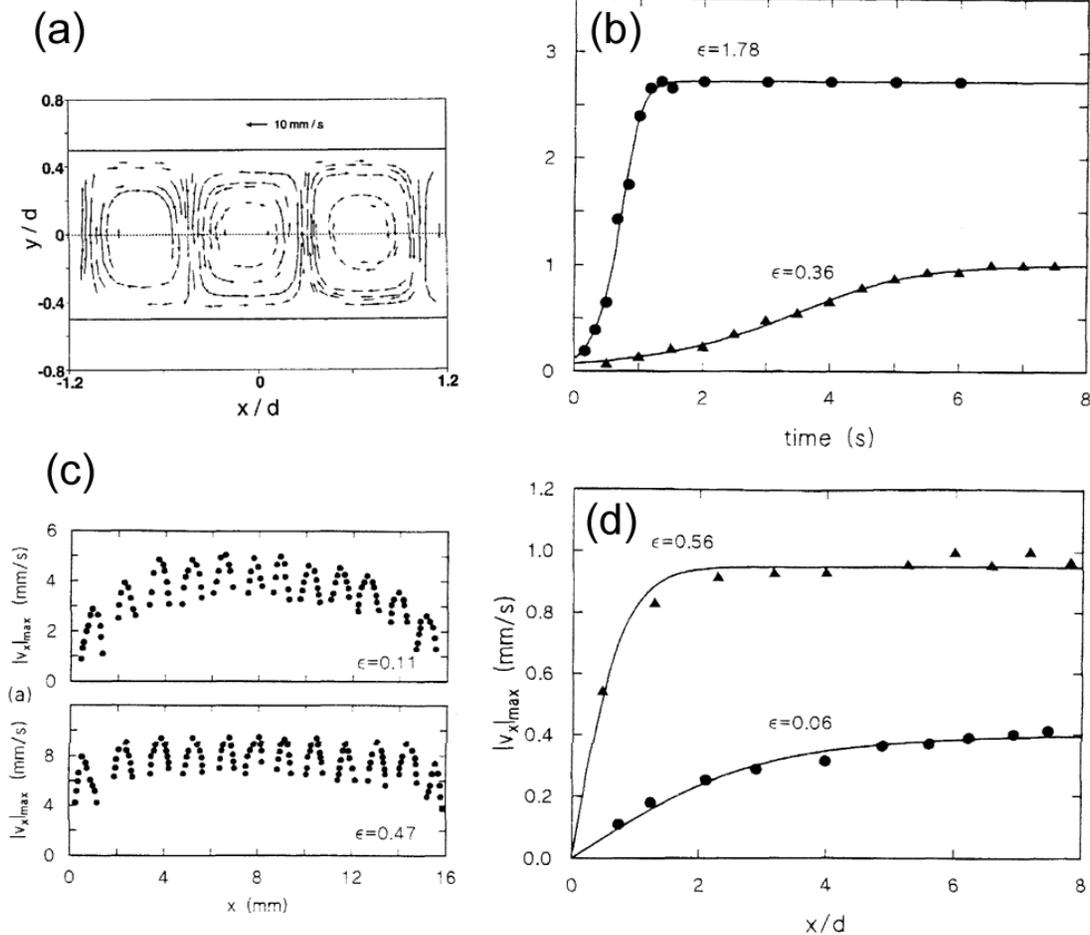
$$\alpha_- \varepsilon < q - q_c < \alpha_+ \varepsilon$$

Electroconvection in a Smectic Film



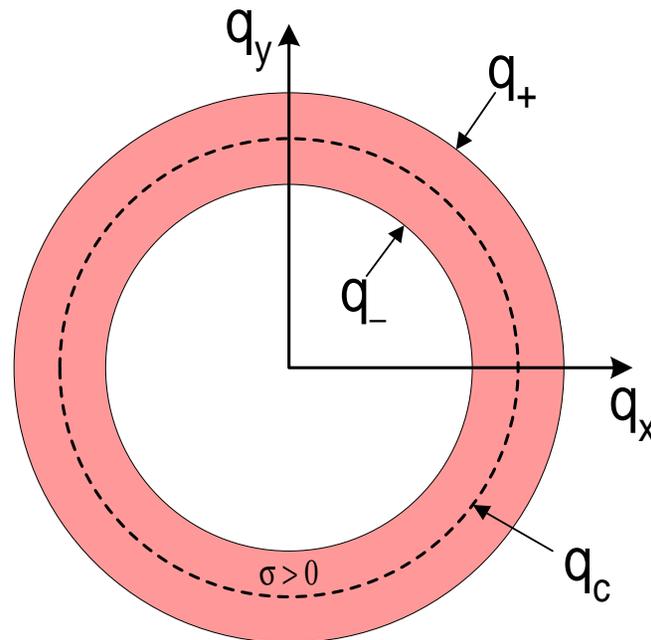
V. B. Deyirmenjian, Z. A. Daya, and S. W. Morris (1997)

Electroconvection in a Smectic Film



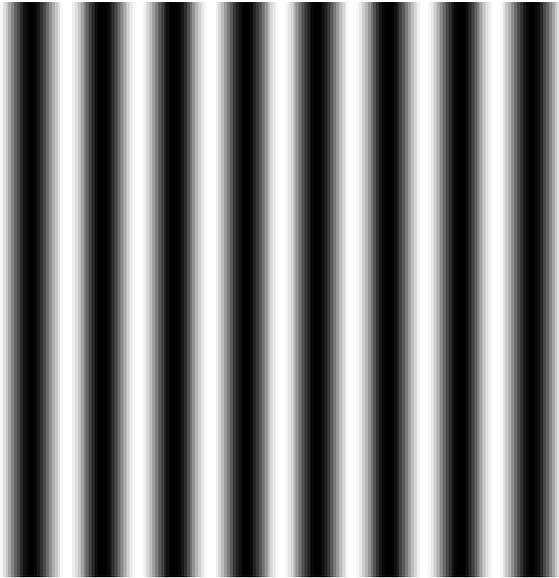
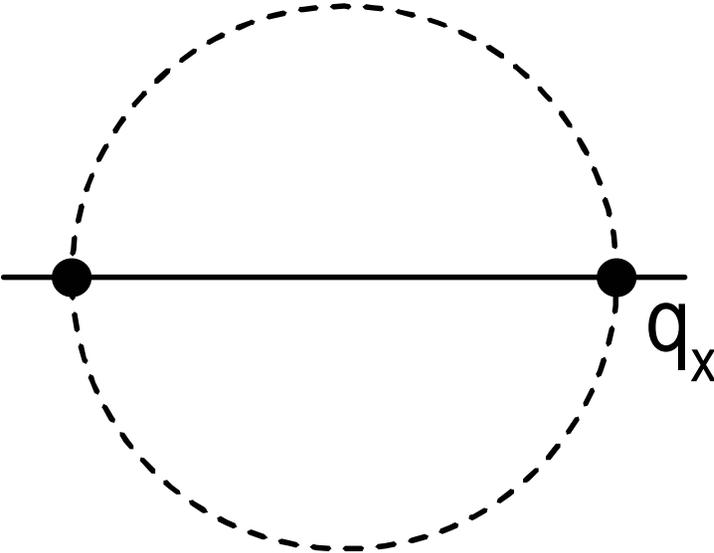
From Morris et al. (1991) and Mao et al. (1996)

Onset in Systems with Rotational Symmetry



- Two dimensional amplitude equation for stripes
- Amplitude equations for lattice states
- Rotationally invariant “model equation”

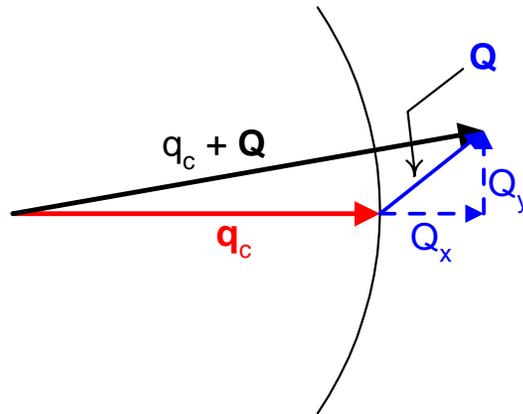
Stripe state



Rotational symmetry: amplitude equation for stripes

For a 2d, rotationally invariant system the gradient term is more complicated

$$\tau_0 \partial_t A = \varepsilon A + \xi_0^2 \left(\partial_x - \frac{i}{2q_c} \partial_y^2 \right)^2 A - g_0 |A|^2 A$$

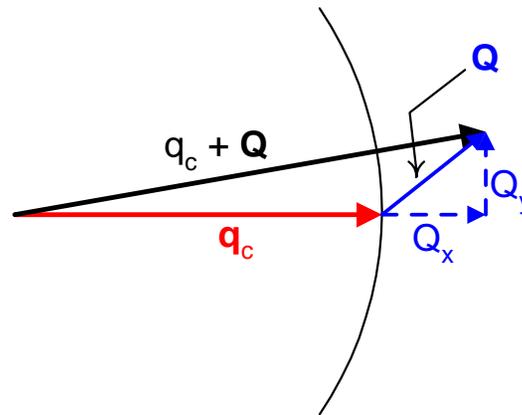


$$q - q_c = \sqrt{(q_c + Q_x)^2 + Q_y^2} - q_c \approx Q_x + \frac{Q_y^2}{2q_c}$$

Rotational symmetry: amplitude equation for stripes

For a 2d, rotationally invariant system the gradient term is more complicated

$$\tau_0 \partial_t A = \varepsilon A + \xi_0^2 \left(\partial_x - \frac{i}{2q_c} \partial_y^2 \right)^2 A - g_0 |A|^2 A$$



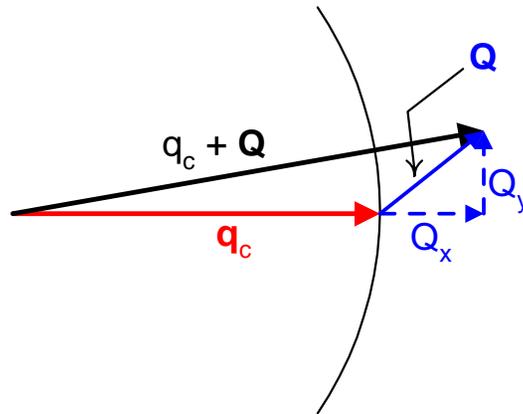
$$q - q_c = \sqrt{(q_c + Q_x)^2 + Q_y^2} - q_c \approx Q_x + \frac{Q_y^2}{2q_c}$$

Note: the complex amplitude can only describe *small* reorientations of the stripes.

Rotational symmetry: amplitude equation for stripes

For a 2d, rotationally invariant system the gradient term is more complicated

$$\tau_0 \partial_t A = \varepsilon A + \xi_0^2 \left(\partial_x - \frac{i}{2q_c} \partial_y^2 \right)^2 A - g_0 |A|^2 A$$

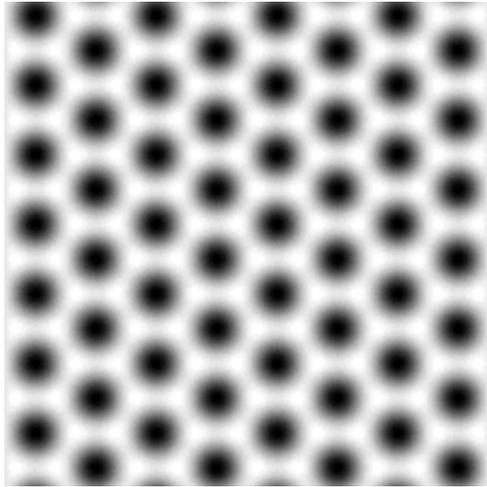
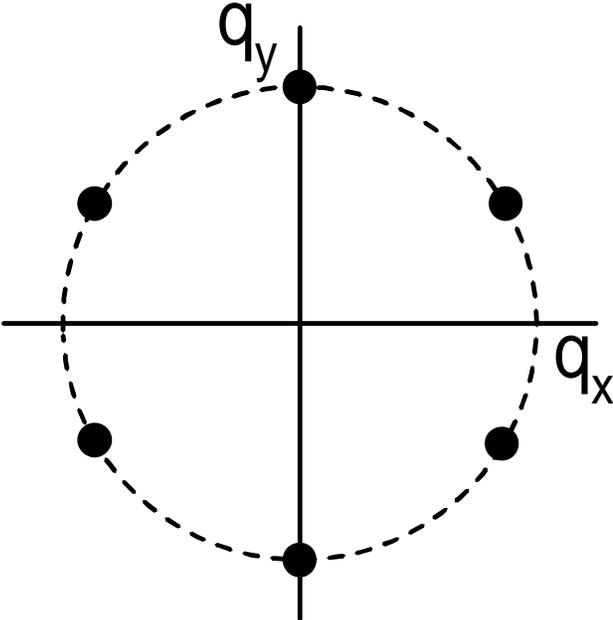


$$q - q_c = \sqrt{(q_c + Q_x)^2 + Q_y^2} - q_c \approx Q_x + \frac{Q_y^2}{2q_c}$$

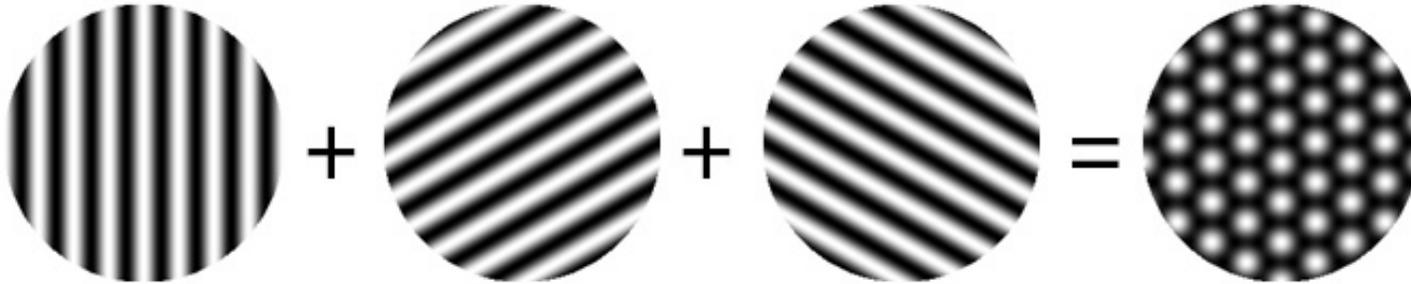
Note: the complex amplitude can only describe *small* reorientations of the stripes.

Isotropic system gives anisotropic scaling: $x = \varepsilon^{-1/2} \xi_0 X$; $y = \varepsilon^{-1/4} (\xi_0/q_c)^{1/2} Y$

Hexagonal state



Amplitude theory of hexagons



Amplitudes of rolls at 3 orientations $A_i(\mathbf{r}, t)$, $i = 1 \dots 3$

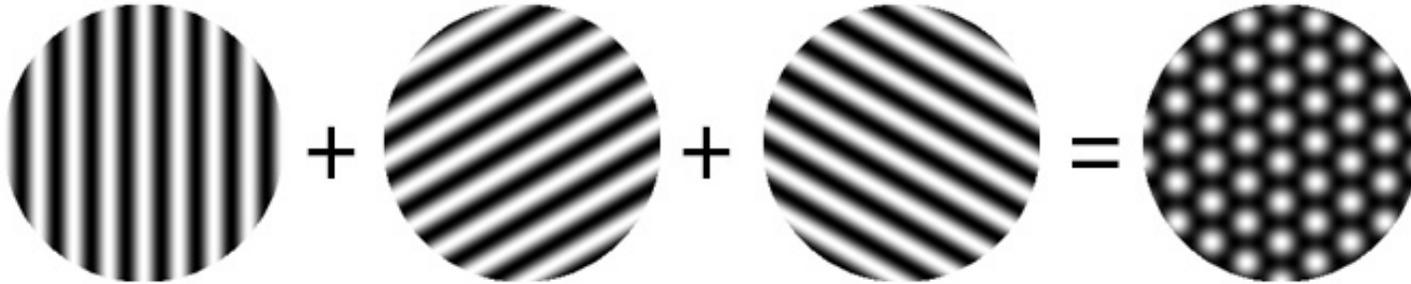
$$dA_1/dt = \varepsilon A_1 - A_1(A_1^2 + gA_2^2 + gA_3^2) + \gamma A_2 A_3$$

$$dA_2/dt = \varepsilon A_2 - A_2(A_2^2 + gA_3^2 + gA_1^2) + \gamma A_3 A_1$$

$$dA_3/dt = \varepsilon A_3 - A_3(A_3^2 + gA_1^2 + gA_2^2) + \gamma A_1 A_2$$

- $A_1 \neq 0, A_2 = A_3 = 0$ gives stripes
- $A_1 = A_2 = A_3 \neq 0$ gives hexagons

Amplitude theory of hexagons



Amplitudes of rolls at 3 orientations $A_i(\mathbf{r}, t)$, $i = 1 \dots 3$

$$dA_1/dt = \varepsilon A_1 - A_1(A_1^2 + gA_2^2 + gA_3^2) + \gamma A_2 A_3$$

$$dA_2/dt = \varepsilon A_2 - A_2(A_2^2 + gA_3^2 + gA_1^2) + \gamma A_3 A_1$$

$$dA_3/dt = \varepsilon A_3 - A_3(A_3^2 + gA_1^2 + gA_2^2) + \gamma A_1 A_2$$

- $A_1 \neq 0, A_2 = A_3 = 0$ gives stripes
- $A_1 = A_2 = A_3 \neq 0$ gives hexagons

For $A_i \rightarrow -A_i$ symmetry, $\gamma = 0$ and stripes v. hexagons depends on g

For no $A_i \rightarrow -A_i$ symmetry, $\gamma \neq 0$ and always get hexagons at onset

Swift-Hohenberg Equation

Rotationally invariant formulation in terms of a scalar field $\psi(x, y, t)$ that captures the same physics as the amplitude equation

$$\partial_t \psi = \left[\varepsilon - (\nabla_{\perp}^2 + 1)^2 \right] \psi - \psi^3 \quad [\nabla_{\perp} = (\partial/\partial x, \partial/\partial y)]$$

Swift-Hohenberg Equation

Rotationally invariant formulation in terms of a scalar field $\psi(x, y, t)$ that captures the same physics as the amplitude equation

$$\partial_t \psi = \left[\varepsilon - (\nabla_{\perp}^2 + 1)^2 \right] \psi - \psi^3 \quad [\nabla_{\perp} = (\partial/\partial x, \partial/\partial y)]$$

- originally introduced to investigate *universal* aspects of the transition to stripes

Swift-Hohenberg Equation

Rotationally invariant formulation in terms of a scalar field $\psi(x, y, t)$ that captures the same physics as the amplitude equation

$$\partial_t \psi = \left[\varepsilon - (\nabla_{\perp}^2 + 1)^2 \right] \psi - \psi^3 \quad [\nabla_{\perp} = (\partial/\partial x, \partial/\partial y)]$$

- originally introduced to investigate *universal* aspects of the transition to stripes
- later used to study qualitative aspects of stripe pattern formation

Swift-Hohenberg Equation

Rotationally invariant formulation in terms of a scalar field $\psi(x, y, t)$ that captures the same physics as the amplitude equation

$$\partial_t \psi = \left[\varepsilon - (\nabla_{\perp}^2 + 1)^2 \right] \psi - \psi^3 \quad [\nabla_{\perp} = (\partial/\partial x, \partial/\partial y)]$$

- originally introduced to investigate *universal* aspects of the transition to stripes
- later used to study qualitative aspects of stripe pattern formation
- no systematic derivation: model rather than controlled approximation

Swift-Hohenberg Equation

Rotationally invariant formulation in terms of a scalar field $\psi(x, y, t)$ that captures the same physics as the amplitude equation

$$\partial_t \psi = \left[\varepsilon - (\nabla_{\perp}^2 + 1)^2 \right] \psi - \psi^3 \quad [\nabla_{\perp} = (\partial/\partial x, \partial/\partial y)]$$

- originally introduced to investigate *universal* aspects of the transition to stripes
- later used to study qualitative aspects of stripe pattern formation
- no systematic derivation: model rather than controlled approximation
- equation is again relaxational

$$\partial_t \psi = -\frac{\delta V}{\delta \psi}, \quad V = \iint dx dy \left\{ -\frac{1}{2} \varepsilon \psi^2 + \frac{1}{2} \left[(\nabla_{\perp}^2 + 1) \psi \right]^2 + \frac{1}{4} \psi^4 \right\}$$

Motivation

- Mode amplitude $\psi_{\mathbf{q}}(t)$ at wave vector \mathbf{q} satisfies linear equation (for $q \simeq q_c$)

$$\dot{\psi}_{\mathbf{q}} = \tau_0^{-1} [\varepsilon - \xi_0^2 (q - q_c)^2] \psi_{\mathbf{q}}$$

- To be able to write this as a local equation for the Fourier transform $\psi(x, y, t)$ approximate this by

$$\dot{\psi}_{\mathbf{q}} = \tau_0^{-1} [\varepsilon - (\xi_0^2/4q_c^2)(q^2 - q_c^2)^2] \psi_{\mathbf{q}}$$

- In real space this gives

$$\tau_0 \dot{\psi}(x, y, t) = \varepsilon \psi - (\xi_0^2/4q_c^2)(\nabla_{\perp}^2 + q_c^2)^2 \psi$$

Simplest linear pde that gives the **ring of unstable modes** (for $\varepsilon > 0$)

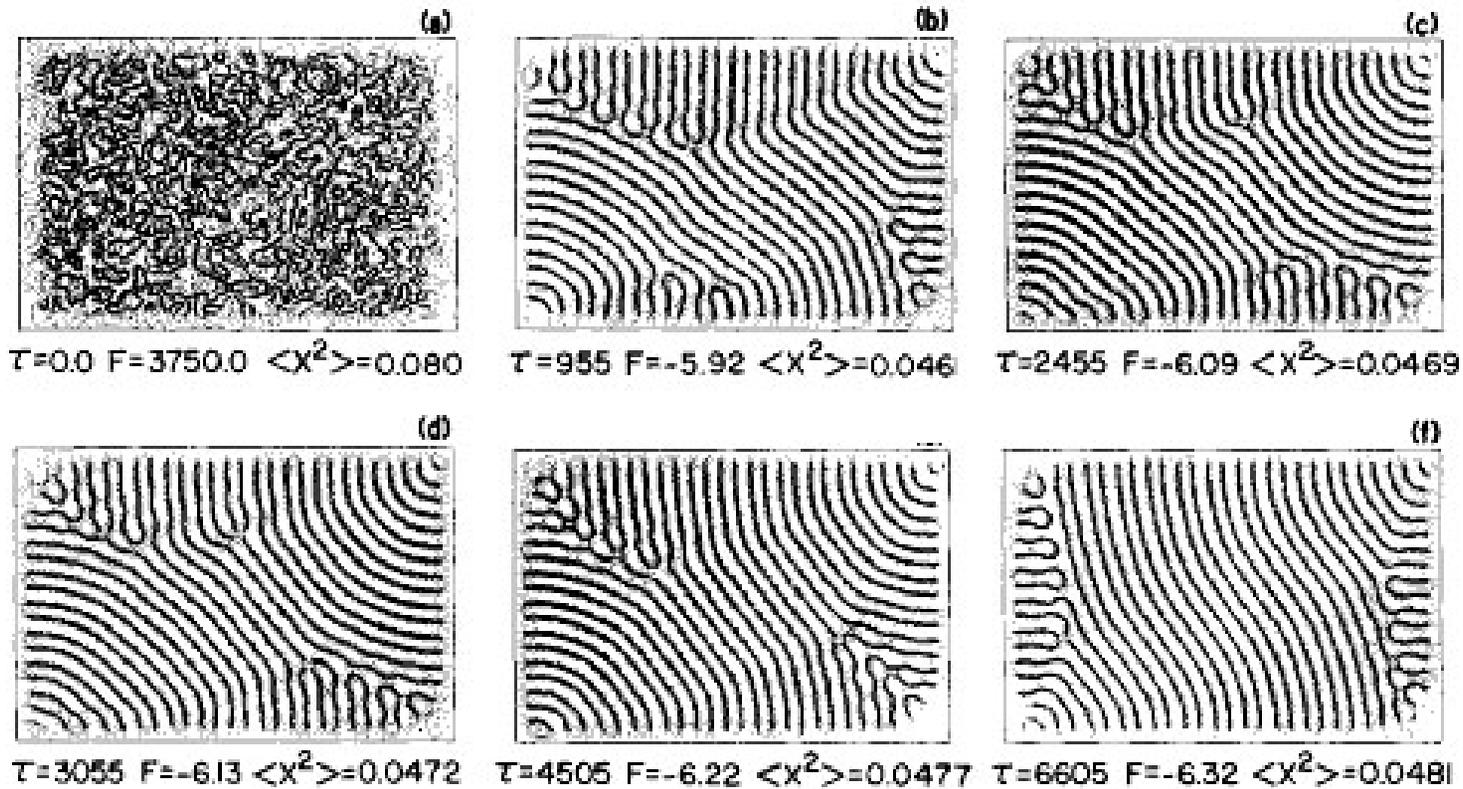
- Add simplest possible nonlinear saturating term

$$\tau_0 \dot{\psi}(x, y, t) = \varepsilon \psi - (\xi_0^2/4q_c^2)(\nabla_{\perp}^2 + q_c^2)^2 \psi - g_0 \psi^3$$

- Alternative motivation:

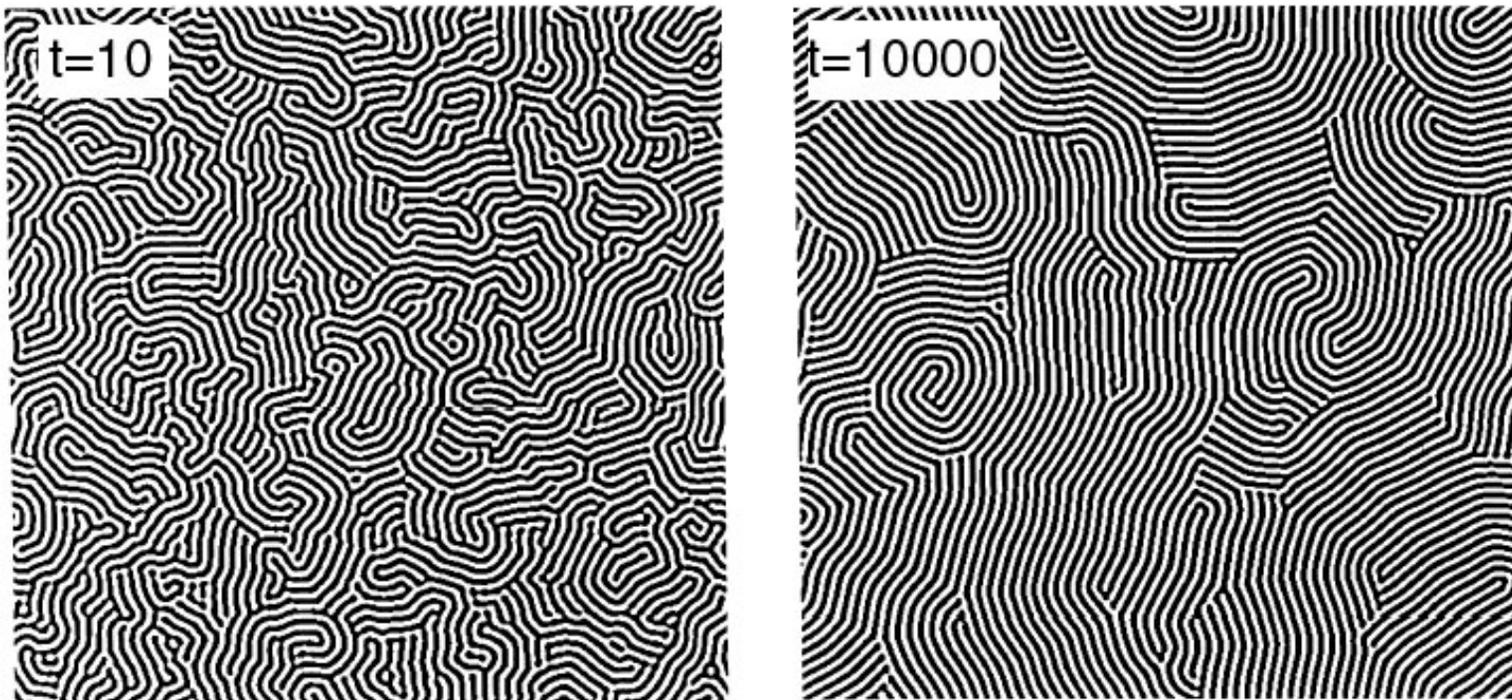
$$A(x, y) e^{iq_c x} \Rightarrow \psi(x, y)$$

Relaxation to steady state



(from Greenside and Coughran, 1984)

Coarsening in a periodic geometry



(From Elder, Vinals, and Grant 1992)

Generalized Swift-Hohenberg models

Qualitatively include other physics:

Generalized Swift-Hohenberg models

Qualitatively include other physics:

- break $\psi \rightarrow -\psi$ symmetry

$$\partial_t \psi = \left[r - (\nabla_{\perp}^2 + 1)^2 \right] \psi + \gamma \psi^2 - \psi^3$$

Generalized Swift-Hohenberg models

Qualitatively include other physics:

- break $\psi \rightarrow -\psi$ symmetry

$$\partial_t \psi = \left[r - (\nabla_{\perp}^2 + 1)^2 \right] \psi + \gamma \psi^2 - \psi^3$$

- change nonlinearity to make equation non-potential, e.g.

$$\partial_t \psi = \left[r - (\nabla_{\perp}^2 + 1)^2 \right] \psi + (\nabla_{\perp} \psi)^2 \nabla_{\perp}^2 \psi$$

Generalized Swift-Hohenberg models

Qualitatively include other physics:

- break $\psi \rightarrow -\psi$ symmetry

$$\partial_t \psi = \left[r - (\nabla_{\perp}^2 + 1)^2 \right] \psi + \gamma \psi^2 - \psi^3$$

- change nonlinearity to make equation non-potential, e.g.

$$\partial_t \psi = \left[r - (\nabla_{\perp}^2 + 1)^2 \right] \psi + (\nabla_{\perp} \psi)^2 \nabla_{\perp}^2 \psi$$

- model effects of rotation

$$\partial_t \psi = \left[r - (\nabla_{\perp}^2 + 1)^2 \right] \psi - \psi^3 + \\ g_2 \hat{\mathbf{z}} \cdot \nabla_{\perp} \times [(\nabla_{\perp} \psi)^2 \nabla_{\perp} \psi] + g_3 \nabla_{\perp} \cdot [(\nabla_{\perp} \psi)^2 \nabla_{\perp} \psi]$$

Conclusions

I have introduced the ideas and methods used to understand nonlinear patterns, focussing on the regime near threshold.

Next Lecture: Symmetry Aspects of Nonlinear Patterns

- Analogies with and differences from equilibrium phase transitions
- Phase variable description
- Topological defects